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I helped Daniel to setup the raspberry pi and assisted Ann in designing the circuit. We came across a problem that we will run out of pins if we need to control 6 servo motors on receiver side. So I did some research on Arduino and found that the analog input pins can also be used as digital I/O pins. So we do not need another Arduino on receiver side. On the other hand, I and Jinlun did some experiments on GPS and fixed the known bugs. The stepper now can follow the object.