

# MPhil in Computational Biology 2016/17 Course: Functional Genomics

Lecture 16 (Wednesday 30th November 2016)

### Classification

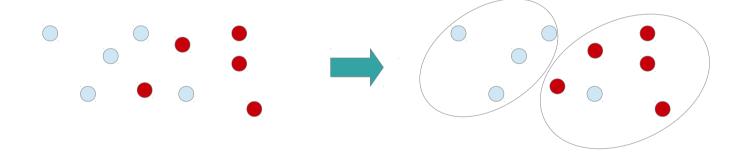
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### Refresher

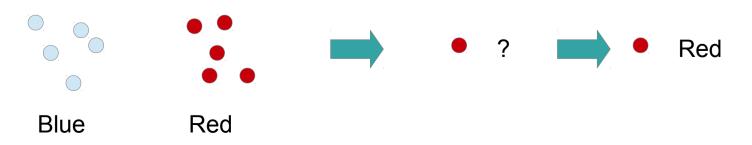
Unsupervised learning (e.g. clustering)

Algorithms operate on unlabelled examples

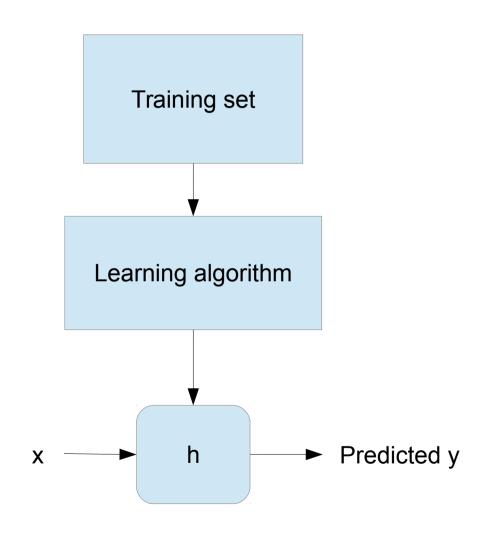


Supervised learning (e.g. classification)

Algorithms are trained on labelled examples



### Introduction to classification



### Some useful notation for classification

- $x_{(i)}$  to denote input, also known as features
- $y_{(i)}$  to denote output, target variable
- A pair  $(x_{(i)}, y_{(i)})$  is known as a training example
- A list of m training examples
   {(x<sub>(i)</sub>, y<sub>(i)</sub>); i =1, . . . ,m} is called a training set.
- X denote the space of input values, and Y the space of output values.
- Our learning process is to learn the function
   h: X → Y, so that h(x) is a good predictor of y
- In our examples we will use a binary classifier Y → {-1,1}

## Types of classifiers

### **Generative (or class-conditional) classifiers**

- Learn models for  $p(x | y_k)$ , use Bayes rule to find decision boundaries
- Examples: naïve Bayes models, Gaussian classifiers

### **Regression-based classifiers**

- Learn a model for p(y<sub>k</sub> | x) directly
- Example: logistic regression, neural networks

#### Discriminative classifiers

- No probabilities
- Learn the decision boundaries directly
- Examples:
  - Linear boundaries: perceptrons, linear SVMs
  - Piecewise linear boundaries: decision trees, nearest-neighbor classifiers
  - Non-linear boundaries: non-linear SVMs

### Performance

## Measuring performance

### **Predicted label**

		Positive	Negative
True Label	Positive	True positive	False negative
	Negative	False positive	True Negative

- True positive = correctly identified (TP)
- False positive = incorrectly identified (FP) Type I error
- True negative = correctly rejected (TN)
- False negative = incorrectly rejected (FN) Type II error

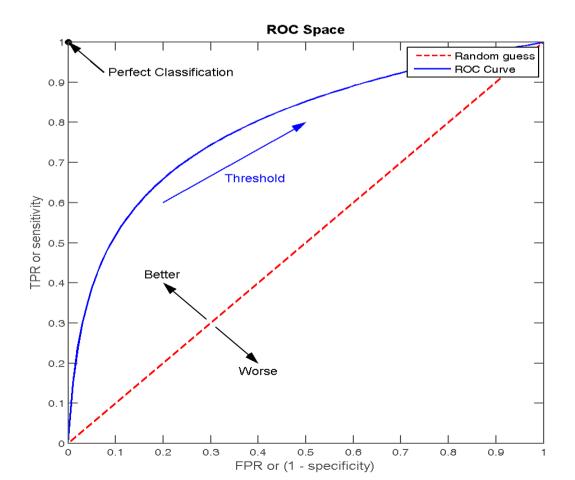
### Some common metrics

```
Accuracy
  (TP+TN)/(TP+FP+TN+FN)
Sensitivity / recall / true positive rate
  TP/(TP+FN)
False positive rate
  1-TN/(TN+FP)
Specificity
  TN/(TN+FP)
Precision / Positive predicted value
```

TP/(TP+FP)

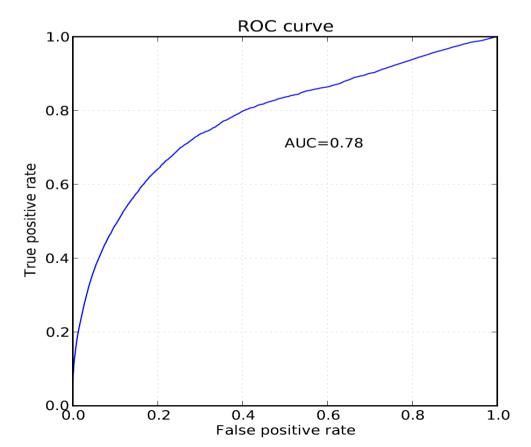
### The trade-off between two metrics

- Increasing specificity usually comes at the cost of a decrease in sensitivity
- The Receiver Operating Characteristic Curve shows the trade off between Sensitivity (TPR) and 1-Specificity (FPR)



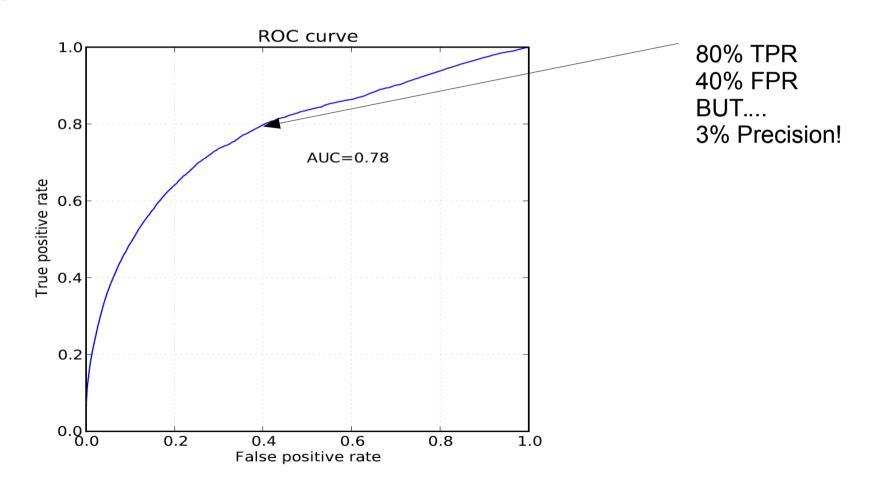
### Area under the curve

- What if we don't care about a threshold?
- Or if we want to know the average performance of a classifier?

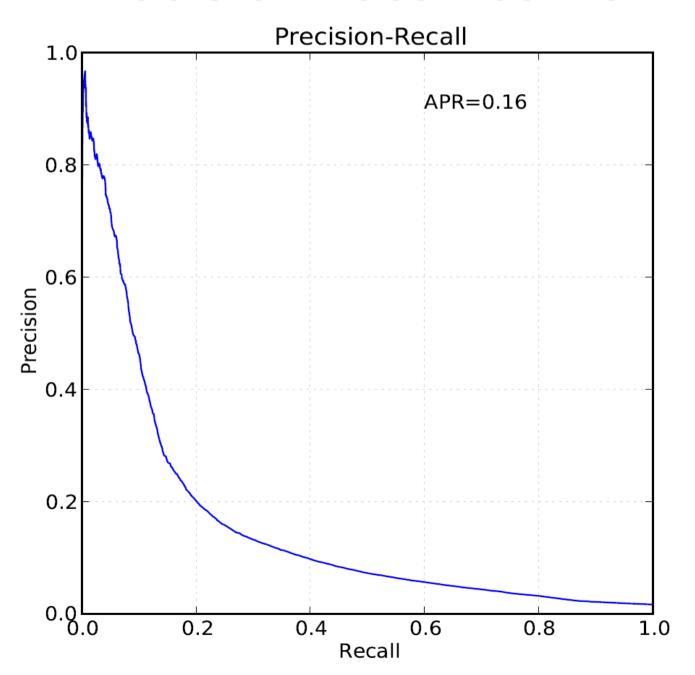


### What happens with imbalanced data?

 Few positive examples embedded in a sea of negative examples



### Precision-recall curve



## Performance summary

- Area under the curve can be used to assess and optimise classifier performance
- ROC curve best used when
  - Class labels are balanced
  - TP, FP, TN and FN are known
- PR curve best used when
  - Class labels are imbalanced
  - TN are not known

### Training

# Introduction to training (concept learning)

### Basic idea:

- Given:
  - a set of training examples with labels
  - a parameterised hypothesis/model
- Use each training example to find values for model parameters which *improves* ability to predict correct class label

### Typical approach:

- Divide your data into a training set (80%) and a test set
   (20%)
- Train the algorithm on the training set and assess performance using the *independent* test set

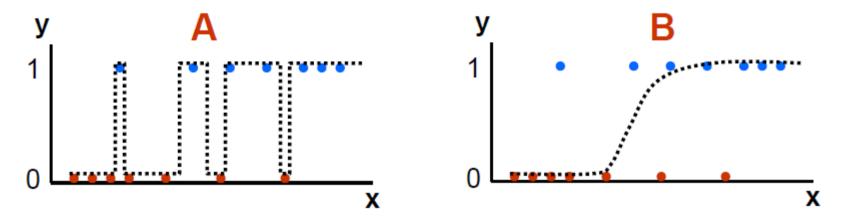
### DANGER - Biased training and testing

- Biased training is where all the data available is used for training and testing
- May result in over-fitting......

## Over-fitting

- Over-fitting is where an algorithm is trained too well on a specific dataset and does not generalise
- Can result from
  - Biased training
  - Small training sets
  - Over parameterised models

## Over-fitting



Model A gives a smaller classification error on the training set.

Model B is obviously better for predicting future values.

# A good training strategy – cross-validation

Divide your data into three sets

- Training (50%)
- Validation (25%)
- Test (25%)

Validation and training set may be divided multiple times and training performed each time. This is called cross-validation training.

Cross-validation training improves the ability of your model to generalise to new data.

### Bayesian inference

## Why bayesian?

- Can incorporate prior knowledge
- Models hypotheses in terms of probabilities
- When to use
  - Moderate or large training set available
  - Attributes that describe instances are conditionally independent given classification
- Successful applications:
  - Diagnosis
  - Classifying text documents

## Bayesian approaches

- Focuses on P(H|D), probability of a hypothesis given the data
- (Frequentist approach focuses on P(D|H))
- This means that the data is fixed
- and that they hypotheses are random
- (The hypotheses may be true or false with some probability)
- Can't calculate P(H|D) directly BUT we can using Bayes Theorem

## Bayes theorem

$$P(h|D) = \frac{P(D|h)P(h)}{P(D)}$$

- P(h) = prior probability of hypothesis h
- P(D) = prior probability of training data D
- P(h|D) = probability of h given D
- P(D|h) = probability of D given h

## Bayesian learning

- We want to find the best hypothesis h, given the observed training data D
- We want the maximium a posteriori hypothesis
- We can use Bayes theorem to find this:

$$h_{MAP} = \arg \max_{h \in H} P(h|D)$$

$$= \arg \max_{h \in H} \frac{P(D|h)P(h)}{P(D)}$$

$$= \arg \max_{h \in H} P(D|h)P(h)$$

 P(D) is removed as it is a constant independent of h

### An example

- Does a patient have cancer or not?
  - A patient takes a lab test and the result comes back positive. The test returns a correct positive result in 98% of the cases in which the disease is actually present, and a correct negative result in 97% of the cases in which the disease is not present. Furthermore, 0.008 of the entire population have this cancer
- Should we conclude the patient has cancer?

```
P(cancer) = P(!cancer) = P(!cancer) = P(+ | cancer) = P(- | cancer) = P(+ | !cancer) = P(- | !cancer) = P(
```

```
P(cancer) = 0.008 P(!cancer) = P(+ | cancer) = P(- | cancer) = P(+ | !cancer) = P(- | !
```

```
P(cancer) = 0.008 \quad P(!cancer) = 0.992

P(+ | cancer) = P(- | cancer) = 0.992

P(+ | !cancer) = P(- | !cancer) = 0.992
```

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```

```
P(cancer) = 0.008 \quad P(!cancer) = 0.992

P(+ | cancer) = 0.98 \quad P(- | cancer) = 0.02

P(+ | !cancer) = P(- | !cancer) =
```

```
P(cancer) = 0.008 \quad P(!cancer) = 0.992

P(+ | cancer) = 0.98 \quad P(- | cancer) = 0.02

P(+ | !cancer) = 0.03 \quad P(- | !cancer) = 0.97
```

### Should we conclude the patient has cancer?

$$P(cancer) = 0.008 \quad P(!cancer) = 0.992$$
  
 $P(+ | cancer) = 0.98 \quad P(- | cancer) = 0.02$   
 $P(+ | !cancer) = 0.03 \quad P(- | !cancer) = 0.97$ 

### **Hypothesis 1: Patient has cancer**

 $h_1(+) = P(+ | cancer)P(cancer) = 0.98x0.008 = 0.0078$ 

### Hypothesis 2: Patient doesn't have cancer

$$h_2(+) = P(+ | !cancer)P(!cancer) = 0.03x0.992 = 0.0298$$

$$h_{MAP}$$
 = !cancer

## Bayesian classification

The previous example dealt with "what is the most probable *hypothesis* given the training data"

We are usually interested in "what is the most probable *classification* of a new instance given the training data"

# Why not just apply MAP?

Answer:  $h_{MAP}(x)$  is not the most probable classification!

### Consider:

Three possible hypotheses:

$$P(h_1|D) = 0.4$$
;  $P(h_2|D) = 0.3$ ;  $P(h_3|D) = 0.3$ 

- Given new instance x,

$$h_1(x) = + ; h_2(x) = - ; h_3(x) = -$$

What's most probable classification of x?

## Bayes Optimal Classifier

In general, the most probable classification of a new instance is obtained by combining predictions of all hypotheses, weighted by their posterior probabilities

$$\arg\max_{v_j \in V} \sum_{h_i \in H} P(v_j|h_i) P(h_i|D)$$

the optimal classification of a new instance is the value  $v_j$  for which  $P(v_j|D)$  is maximum (theorem of total probability).

### Example:

$$P(h_1|D) = .4$$
,  $P(-|h_1) = 0$ ,  $P(+|h_1) = 1$   
 $P(h_2|D) = .3$ ,  $P(-|h_2) = 1$ ,  $P(+|h_2) = 0$   
 $P(h_3|D) = .3$ ,  $P(-|h_3) = 1$ ,  $P(+|h_3) = 0$ 

therefore

$$\sum_{h_i \in H} P(+|h_i)P(h_i|D) = .4$$

$$\sum_{h_i \in H} P(-|h_i)P(h_i|D) = .6$$

and

$$\arg\max_{v_j \in V} \sum_{h_i \in H} P(v_j|h_i) P(h_i|D) = -$$

### Bayes optimal classifier

No other classification methods using the same hypothesis space and same prior knowledge can outperform this approach.

But.....

It is VERY costly as it computes the posterior probability for EVERY hypothesis.

→ Bad if your hypothesis space is large

### Naive Bayes Classifier

Assume target function  $f: X \to V$ , where each instance x described by attributes  $\langle a_1, a_2 \dots a_n \rangle$ . Most probable value of f(x) is:

$$v_{MAP} = \underset{v_j \in V}{\operatorname{argmax}} P(v_j | a_1, a_2 \dots a_n)$$

$$v_{MAP} = \underset{v_j \in V}{\operatorname{argmax}} \frac{P(a_1, a_2 \dots a_n | v_j) P(v_j)}{P(a_1, a_2 \dots a_n)}$$

$$= \underset{v_j \in V}{\operatorname{argmax}} P(a_1, a_2 \dots a_n | v_j) P(v_j)$$

Naive Bayes assumption:

$$P(a_1, a_2 \dots a_n | v_j) = \prod_i P(a_i | v_j)$$

which gives

Naive Bayes classifier:  $v_{NB} = \underset{v_j \in V}{\operatorname{argmax}} P(v_j) \prod_i P(a_i|v_j)$ 

## Naive Bayes Algorithm

Naive\_Bayes\_Learn(examples)

For each target value  $v_j$ 

$$\hat{P}(v_j) \leftarrow \text{estimate } P(v_j)$$

For each attribute value  $a_i$  of each attribute a

$$\hat{P}(a_i|v_j) \leftarrow \text{estimate } P(a_i|v_j)$$

Classify\_New\_Instance(x)

$$v_{NB} = \operatorname*{argmax}_{v_j \in V} \hat{P}(v_j) \prod_{a_i \in x} \hat{P}(a_i | v_j)$$

## Example

Day	Outlook	Temperature	Humidity	Wind	PlayTennis
D1	Sunny	Hot	High	Weak	No
D2	$\operatorname{Sunny}$	$\operatorname{Hot}$	$\operatorname{High}$	Strong	No
D3	Overcast	$\operatorname{Hot}$	$\operatorname{High}$	Weak	Yes
D4	$\operatorname{Rain}$	Mild	$\operatorname{High}$	Weak	Yes
D5	$\operatorname{Rain}$	Cool	Normal	Weak	Yes
D6	$\operatorname{Rain}$	Cool	Normal	Strong	No
D7	Overcast	Cool	Normal	Strong	Yes
D8	$\operatorname{Sunny}$	Mild	$\operatorname{High}$	Weak	No
D9	$\operatorname{Sunny}$	Cool	Normal	Weak	Yes
D10	$\operatorname{Rain}$	Mild	Normal	Weak	Yes
D11	$\operatorname{Sunny}$	Mild	Normal	Strong	Yes
D12	Overcast	Mild	$\operatorname{High}$	Strong	Yes
D13	Overcast	$\operatorname{Hot}$	Normal	Weak	Yes
D14	Rain	Mild	$\operatorname{High}$	Strong	No

#### Consider a new instance

 $\langle Outlk = sun, Temp = cool, Humid = high, Wind = strong$ 

Want to compute:

$$v_{NB} = \operatorname*{argmax}_{v_j \in V} P(v_j) \prod_i P(a_i | v_j)$$

$$P(y) P(sun|y) P(cool|y) P(high|y) P(strong|y) = .005$$

$$P(n) P(sun|n) P(cool|n) P(high|n) P(strong|n) = .021$$

$$\rightarrow v_{NB} = n$$

### naive Bayes subtleties

- Conditional independence assumption is often violated.....but works well anyway!
- Problem: what if none of the training instances with target value v<sub>j</sub> have attribute value a<sub>i</sub>?

$$\hat{P}(a_i|v_j) = 0$$
, and...  
 $\hat{P}(v_j) \prod_i \hat{P}(a_i|v_j) = 0$ 

Typical solution is Bayesian estimate for  $\hat{P}(a_i|v_j)$ 

$$\hat{P}(a_i|v_j) \leftarrow \frac{n_c + mp}{n + m}$$

$$\hat{P}(a_i|v_j) = 0$$
, and...  
 $\hat{P}(v_j) \prod_i \hat{P}(a_i|v_j) = 0$ 

Typical solution is Bayesian estimate for  $\hat{P}(a_i|v_j)$ 

$$\hat{P}(a_i|v_j) \leftarrow \frac{n_c + mp}{n + m}$$

where

- n is number of training examples for which  $v = v_j$ ,
- $n_c$  number of examples for which  $v = v_j$  and  $a = a_i$
- p is prior estimate for  $\hat{P}(a_i|v_j)$
- m is weight given to prior (i.e. number of "virtual" examples)

Biomarker discovery

#### Biomarker discovery

- Concerned with finding the minimal set of measurable biological features that allow prediction of:
  - Diagnosis
  - Prognosis
  - Response to drug
  - .....
- Examples:
  - Gene expression
  - Protein expression
  - Metabolite levels
  - Lipid levels
  - ......

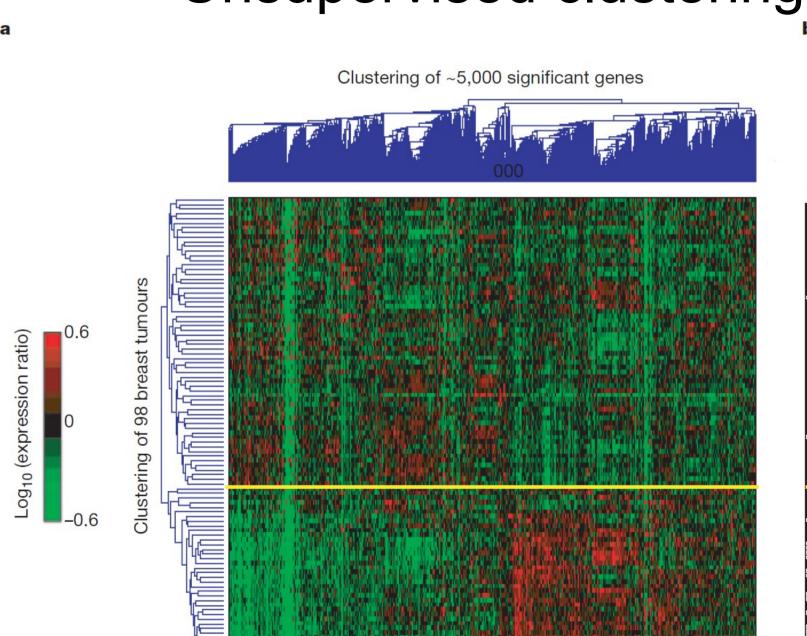
Case study: identification of biomarkers which predict clinical outcome in breast cancer

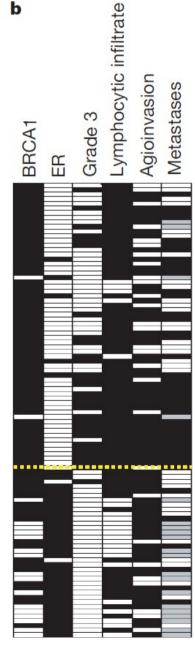
# Gene expression profiling predicts clinical outcome of breast cancer

Laura J. van 't Veer\*†, Hongyue Dai†‡, Marc J. van de Vijver\*†, Yudong D. He‡, Augustinus A. M. Hart\*, Mao Mao‡, Hans L. Peterse\*, Karin van der Kooy\*, Matthew J. Marton‡, Anke T. Witteveen\*, George J. Schreiber‡, Ron M. Kerkhoven\*, Chris Roberts‡, Peter S. Linsley‡, René Bernards\* & Stephen H. Friend‡

### Study overview

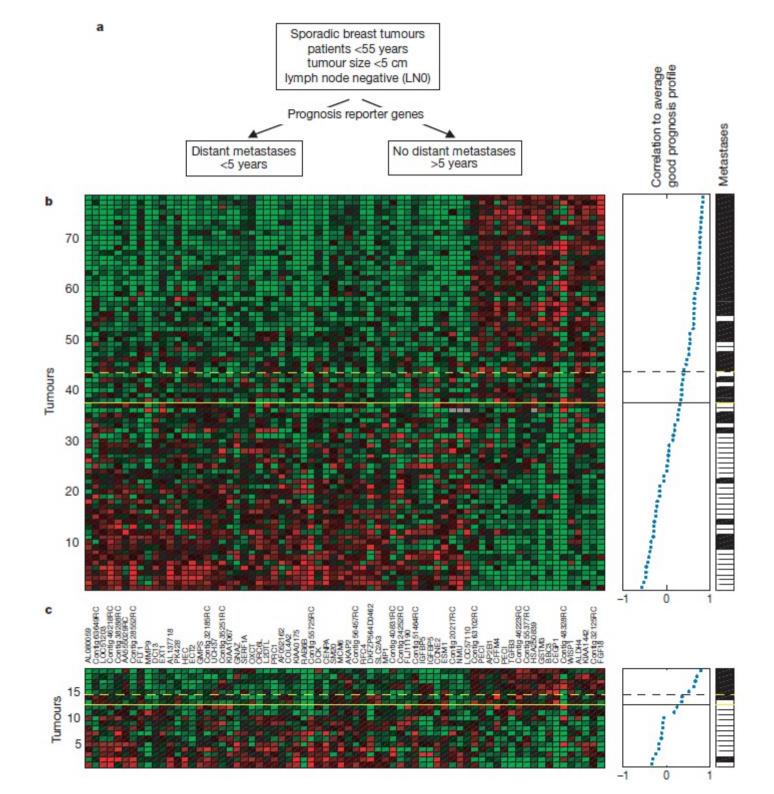
- Performed gene expression profiling on 98 primary breast tumours from young individuals
  - 34 who got metastases < 5 years</li>
  - 44 who were disease free after 5 years
  - 18 BRCA1 carriers
  - 2 BRCA2 carriers
- Recorded their progression time to metastasis
- Short progression time = poor prognosis
- Performed unsupervised clustering and showed a potential to separate samples based on good and poor prognosis
- Used supervised classification to identify a 70 gene signature which accurately predicts poor prognosis





#### Supervised classification

- Used a correlation co-efficient based method to select a subset of 231 genes where expression correlated with outcome
  - → putative biomarkers
- Used a leave-one-out cross validation procedure to determine error of 'classifier'
- Repeated procedure adding 5 genes at a time until error increased
  - → 70 genes remained (biomarkers)
- Overall 83% accuracy



#### References

- Tom M. Mitchell. *Machine Learning*. WCB/McGraw-HIII
- Gene expression profiling predicts clinical outcome of breast cancer. van 't Veer, Laura J.; Dai, Hongyue; van de Vijver, Marc J.; He, Yudong D.; Hart, Augustinus A. M. et al. Nature (2002)
- Supervised learning in R: https://en.wikibooks.org/wiki/Data\_Mining\_Algorith ms In R