```
; **** USART Module : Polling Transmission
2
   3
   ; DEFINITIONS
   4
5
         PROCESSOR PIC16F628
6
         #include <P16F628.INC>
7
                  _CP_OFF & _MCLRE_ON & INTRC_OSC_NOCLKOUT & _LVP_OFF
          CONFIG
         & WDT OFF
8
   #define NL 0x0A ; New Line
                 ; Form feed
9
   10
                  ; Carriage return
11
   ; VARAIBLES
13
14
   cblock 0x20
15
16
            count
17
            count0
18
            count1
19
            count2
20
            temp
21
            buffer
22
            index
23
         endc
25 ; RESET and INTERRUPT VECTORS
27
         ORG
28
         goto main
29
         ORG
               0 \times 04
30
         retfie
31
32 Main: call
               init
33 Message loop:
34
         movlw 0x00
35
         movwf index
36
         call send message1
37
38
         movlw .250
39
         call
               DelaymS
40
  RX_loop:
41
42
         btfss PIR1, RCIF
43
         goto
               RX loop
44
45
         movf
               RCREG,w ; Save the recieved character in 'temp'
46
         movwf
47
48
         ; Send the reply message back to the computer
49
         movlw
              0 \times 00
         movwf index
50
51
         call send message2
52
53
         movf
               temp, w
         movwf TXREG
54
55
         btfss PIR1,TXIF
56
         goto
               $-1
57
              CR
         movlw
58
         movwf TXREG
59
         btfss PIR1,TXIF
60
         goto
               $-1
               RX loop
61
         goto
62
63
  ; this subroutine sends a string of many characters from a look-up table
   'message'
64
  send message1:
65
         movf
               index, w
66
         call
                        ; get character from the message table
               message1
```

```
67
             movwf
                   buffer
 68
             movlw 0xFF
 69
             subwf buffer,w
                                 ; check if we are at the end of message?
 70
             btfsc STATUS, Z
 71
             return
                    index,f
 72
             incf
73 TX1:
             btfss PIR1,TXIF ; TXIF='1' if the TXREG is empty
             goto
                    TX1
 74
 75
             movf
                    buffer, w
 76
             movwf TXREG
 77
             goto
                    send message1 ; go back and do it again
 78
    send message2:
 79
 80
             movf
                     index,w
 81
             call
                     message2
                                   ; get character from the message table
 82
             movwf buffer
 83
             movlw
                     0xFF
 84
                    buffer,w
                                ; check if we are at the end of message?
             subwf
             btfsc STATUS, Z
 85
 86
             return
 87
                    index,f
             incf
            btfss PIR1,TXIF ; TXIF='1' if the TXREG is empty
 88 TX2:
89
                    TX2
             goto
 90
                    buffer,w
             movf
 91
             movwf TXREG
 92
             goto
                    send message2; go back and do it again
 93
 94 message1:
 95
             addwf PCL, f
 96
                    NL, "Press any keys to get response from
             PIC16F628A", NL, CR, 0xFF
 97
98 message2:
99
             addwf PCL, f
100
             DT NL, "You press: ", 0xFF
101
102 init:
             ; Initialization of USART module
103
104
             banksel CMCON
105
             movlw .7
106
                     CMCON
             movwf
                           ; disable analog comparator
107
             banksel TRISA
108
             movlw
109
             movwf
                     TRISA
; Bits 1 and 2 of Port B are multiplexed as TX/CK and RX/DT for USART
     operation.
111
     ; These bits must be set to input in the TRISB register.
112
             bcf TRISB, 2 ; RB2 as output (Tx pin)
                     TRISB, 1; RB1 as input (Rx pin)
113
             bsf
114
     ; The asynchronous baud rate(ABR) is calculated as follows:
115
116
     ; ABR = Fosc/{S*(x+1)}
117
     ; x is value in SPBRG register.
118
     ; S is 64 if high baud rate select bit(BRGH) in the TXSTA control register
     is clear (slow-speed baud rate).
     ; S is 16 if the BRGH bit is set (high-speed baud rate).
     ; For setting to 9600 baud rate using a 4MHz oscillator at a high-speed
     baud rate the formula is:
121
    ; At high speed (BRGH=1)
122
     ; 9600 = 4,000,000/\{16*(x+1)\}
123
     x = 25.041 -> use x=25
    ; calculate baud rate from x=25 to find %error
124
125
    ; baud rate = 4,000,000/\{16*(25+1)\} = 9,615 (0.16% error)
126
    ; At slow speed (BRGH=0)
    ; baud rate = 4,000,000/\{64*(25+1)\} = 2,403.85 (0.16% error)
127
128
129
130
            banksel SPBRG
```

```
131
              movlw
                      .25
                             ; 2400 baud rate at 4MHz crystal
132
              movwf
                     SPBRG ; Place in baud rate generator
133
        TXSTA (Transmit Status and Control Register) bit map:
134
                 5
                       4
                           3
                                  1 0 <== bits
              6
                               2
                                              Tx9D 9nth data bit on
135
                  Τ
                       Ī
                           Τ
                                   (used for parity)
136
                       TRMT Transmit Shift Register
137
                       Τ
138
                                                1 = TSR empty
      ;
                                              * 0 = TSR full
139
                       Τ
      ;
140
                       Τ
                                                BRGH High Speed Baud Rate
      ;
141
                       Τ
                                                (Asynchronous mode only)
      ;
142
                       Τ
                                                1 = high speed (*4)
      ;
143
                                              * 0 = low speed
      ;
144
                                            NOT USED
      ;
145
      ;
                                            SYNC USART Mode Select
146
      ;
                                            1 = synchronous mode
147
                                            0 = asynchronous mode
      ;
148
                                            TXEN Transmit Enable
      ;
149
                                            1 = transmit enable
      ;
150
                                            0 = transmit disable
      ;
151
                                            TX9 Enable 9-bit Transmit
      ;
152
                                            1 = 9-bit transmission mode
153
                                            0 = 8 - bit mode
154
                                            CSRC Clock Source Select
155
                                            Not used in asynchronous mode
156
                                            Synchronous mode:
157
                                               1 = Master Mode (internal clock)
158
                                             * 0 = Slave Mode (external clock)
159
        Setup value = 0010 \ 0000 = 0x20
160
              banksel TXSTA ; TXEN = '1', BRGH = '0'
161
              movlw
                     0x20
                               ; Enable transmission and low speed baud rate
162
              movwf
                      TXSTA
163
        RCSTA (Receive Status and Control Register) bit map:
                 5
                          3
164
                      4
                               2 1 0 <== bits
              6
165
                                               RX9D 9th data bit received
166
                                                (can be parity parity)
167
                                                OERR Overrun error
168
                                                1 = error clear by software
169
                                                FERR Framing error
170
                                                1 = error
      ;
171
                                            NOT USED
      ;
172
                                            CREN Continuous Receive Enable
      ;
173
                                                Asynchronous mode
      ;
174
                                                 * 1 = Enable continuous receive
      ;
                                                   0 = Disable continuous receive
175
      ;
176
                                                Synchronous mode
      ;
177
                                                   1 = Enables until CREN cleared
      ;
178
                                                   0 = Disables continuous receive
      ;
179
                                             SREN Single Receiver Enable
      ;
180
                                                Asynchronous mode = don't care
      ;
181
                                                Synchronous mode
                                                   1 = Enables single receiver
182
183
                                                   0 = Disables single receiver
      ;
184
                                             RX9 9-bit Receive Enable
      ;
                                               1 = 9-bit reception
185
      ;
                                             * 0 = 8-bit reception
186
      ;
187
                                             SPEN Serial Port Enable
      ;
188
                                             * 1 = RX/DT and TX/CK are serial pins
      ;
189
                                               0 = Serial port disable
190
      ; Setput value: 1001\ 0000 = 0x90
191
              banksel RCSTA
192
              movlw
                       0 \times 90
                               ; Enable Serial port and continous reception
193
                      RCSTA
              movwf
194
195
              return
196
197
      DelaymS:
198
              movwf
                       count.2
```

```
199
            incf count2,f
     decfsz count2,f
200
           goto $+2
201
           goto $+3
202
            call Delay1mS goto $-4
203
204
205
            return
206
207 Delay1mS:
     movlw .50 ; 1 cyc movwf count1 ; 1 cyc
208
209
210 outterloop:
            211
212
213
214 innerloop:
            decfsz count0,F ; 1 cyc * count1 * count0
goto innerloop ; 2 cyc * count1 * count0
decfsz count1,F ; 1 cyc * count1
goto outterloop ; 2 cyc * count1
215
216
217
218
219
            return
                                ; 1 cyc
220
            ; total = 3 + (6+3.count0).count1
221
           ; count0 = 5 , count1 = 50, total = 1053 cyc ??
223
            END
```