```
· **************
    ;**** lab5 up down switch to 7 segment -> bounce
 2
 3
            PROCESSOR PIC16F628
 4
 5
            #include <P16F628.INC>
 6
            __CONFIG __CP_OFF & _MCLRE_OFF & _HS_OSC & _LVP_OFF & _WDT OFF
 7
 8
            cblock 0x20
 9
                temp
10
                temp1
11
                count
12
                count0
13
                count1
14
                count2
15
            endc
16
            ORG 0\times00 ; reset vector goto main ; vector to main program
17
18
19
20
21
   main:
22
            call
                   Init
23
24
   L1:
25
            btfsc PORTA, 0 ; is UP pressed?
26
            goto
27
28
            incf
                   temp,f
29
30 L2:
            btfsc PORTA, 1
                               ; is DOWN pressed?
31
            goto
                   L3
32
33
            decf
                   temp,f
34
35 L3
            movlw
                   .16
36
            subwf
                   temp, w
37
            btfss STATUS, Z
                               ;check if temp=16?
38
                   L4 ; No, check zero
            goto
39
40
                   temp
                                ; Yes, clear 'temp' back to zero
            clrf
41
                                ; Repeat the infinite loop
            goto
                    L5
42
43
   L4:
                    .255
44
            movlw
45
            subwf
                    temp, w
46
            btfss
                   STATUS, Z
                               ; check if temp=255?
47
            goto
                    L5
                                ; No, go back and do it again
48
49
            movlw
                    .15
50
            movwf
                    temp
                                ; yes, set temp = 16
51
                                ; Repeat the infinite loop
            goto
                    L5
52
53
54 L5:
            movf
                                ;use [Temp] to call 'Table7seg'
                    temp, w
55
                   Table7seg
            call
56
            movwf PORTB
                               ; Send the obtain 7 seg pattern to PORTB
57
58
            movlw
                    .250
59
            call
                   DelayMS
60
61
            goto
                   L1
62
63
64
   ;Loopup table for 7segments LED Patterns
65
   Table7seg:
66
            addwf
                   PCL, F
67
            ;Segments .GFEDBA
68
            retlw B'001111111'
                                 ;Number0
```

```
69
             retlw B'00000110'
                                     ;Number1
 70
             retlw B'01011011'
                                     ;Number2
             retlw B'01001111'
 71
                                     ;Number3
             retlw B'01100110'
 72
                                     ;Number4
             retlw B'01101101'
 73
                                     ;Number5
             retlw B'01111101'
 74
                                     ;Number6
             retlw B'00000111'
                                     ;Number7
 75
                                     ;Number8
 76
             retlw B'01111111'
                                     ;Number9
 77
             retlw B'01101111'
              retlw B'01110111'
                                     ; A
 78
              retlw
                                     ;B
 79
                     B'01111100'
                                     ;C little
 80
              ;retlw B'01011000'
 81
              retlw B'00111001'
                                     ;C big
 82
              retlw
                     B'01011110'
                                     ; D
              retlw B'01011110'
retlw B'01111001'
retlw B'01110001'
retlw B'10000000'
                                     ; E
 83
 84
                                      ;F
 85
                                     ;dot-point
 86
 87
    DelayMS:
 88
              movwf count2
 89
                     count2,f
              incf
              decfsz count2, f
 90
 91
                     $+2
              goto
 92
              goto
                     $+3
 93
              call
                     Delay1MS
 94
              goto
                     $-4
 95
              return
 96
 97 Delay1MS:
 98
             movlw .50
                                     ; 1 cyc
 99
              movwf count1
                                     ; 1 cyc
100 outterloop:
                    . 5
101
              movlw
                                      ; 1 cyc * count1
102
              nop
                                      ; 1 cyc * count1
103
                                      ; 1 cyc * count1
              movwf count0
104 innerloop:
105
              decfsz count0,F
                                     ; 1 cyc * count1 * count0
106
              goto
                     innerloop
                                     ; 2 cyc * count1 * count0
107
              decfsz count1,F
                                      ; 1 cyc * count1
108
              goto
                      outterloop
                                      ; 2 cyc * count1
109
              return
                                      ; 1 cyc
110
              ; total = 3 + (6+3.count0).count1
111
              ; count0 = 5 , count1 = 50, total = 1053 cyc
112
    ; Time delay subroutine for 1.[\ensuremath{\mathbb{W}}] seconds by calling DelayMS subroutine DelayS:
113
114
115
              movwf
                      temp1
116
     delays 1:
117
                      .250
              movlw
118
              call
                      DelayMS
119
              movlw
                      .250
120
              call
                     DelayMS
121
                      .250
              movlw
              call
122
                     DelayMS
123
              movlw
                      .250
124
              call
                     DelayMS
125
              decfsz temp1, f
126
              goto
                      delays 1
127
              return
128
129 Init:
130
              movlw
                      . 7
131
             banksel CMCON
132
              movwf CMCON
                                  ; Disable analog comparator
133
              banksel TRISB
134
              movlw 0 \times 00
135
                     TRISB
                                  ; Set PORTB as output ports
             movwf
136
             movlw 0xFF
```

137 138 139 140 141 142	movwf banksel clrf clrf return	TRISA PORTB PORTB temp	;	Set	PORTA	as	input	ports
143 144 145 146 147 148	END							