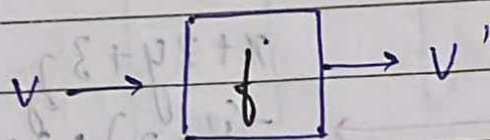


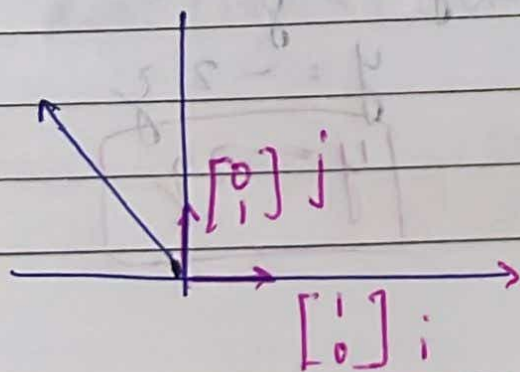
~~24/07~~

# LINEAR TRANSFORMATION

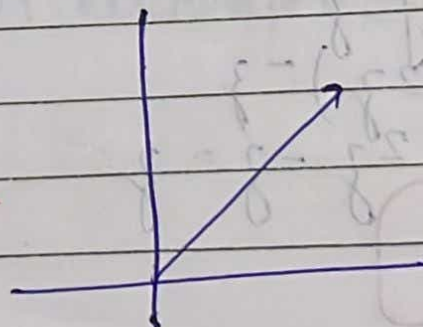
It is a fun<sup>n</sup> which takes vectors as i/p & o/p a vector

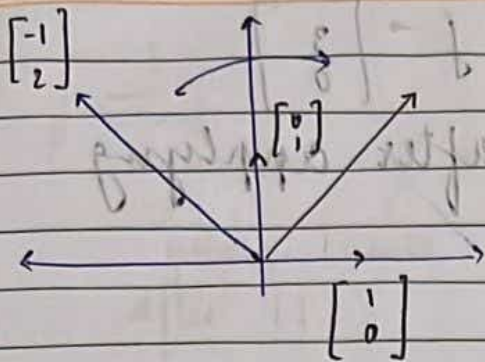


$$T(x) = y$$



→ Transform

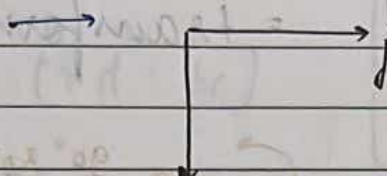
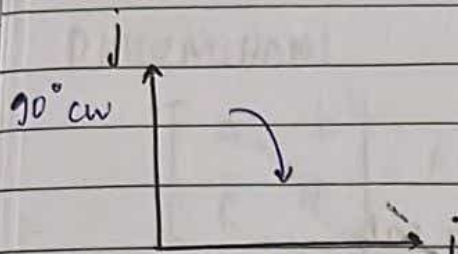




$$\begin{bmatrix} -1 \\ 2 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

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$$\left. \begin{aligned} c_1 &= -1 \\ c_2 &= 2 \end{aligned} \right\}$$



$$i = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$c_1 \begin{bmatrix} 0 \\ -1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$j = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\left. \begin{aligned} c_1 &= -1 \\ c_2 &= 2 \end{aligned} \right\}$$

$$-1 \begin{bmatrix} 0 \\ -1 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} -1 \\ 2 \end{bmatrix} \xrightarrow[\text{90° cw}]{\text{linear transf}} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\text{eg. } \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$2 \times 2 \quad 2 \times 1 = 2 \times 1$   
vector

Transf. of  $i$       Transf. of  $j$

when we do LT ~~the~~ the origin remains the same (fixed).

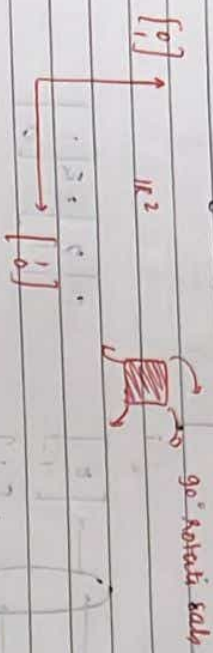


eg. v.  $\begin{bmatrix} 1 \\ 2 \end{bmatrix} \xrightarrow{-e^{i\pi/2}} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$   $\delta \rightarrow \begin{bmatrix} 3 \\ 0 \end{bmatrix}$

what will be the vector v after applying this transformation

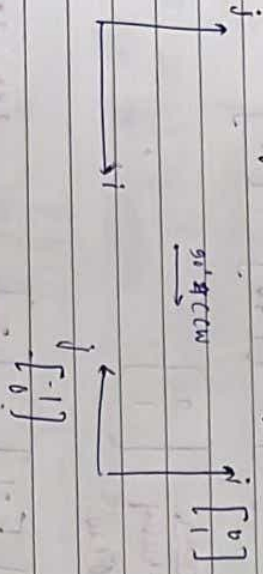
$$\begin{bmatrix} 1 & 3 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\begin{bmatrix} 5 \\ 2 \end{bmatrix} = \text{transform.}$$



1. If there is a vector  $v = \begin{bmatrix} x \\ y \end{bmatrix} \in \mathbb{R}^2$  in the

1st quadrant. what will be the resultant vector after rotating it  $90^\circ$  cw



$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -y \\ x \end{bmatrix}$$

Basis ka area kitne factor se scale hua hoga det hua

$$\delta \rightarrow \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$$

initial (area) this is initial  
after LT (area after LT)

DETERMINANT

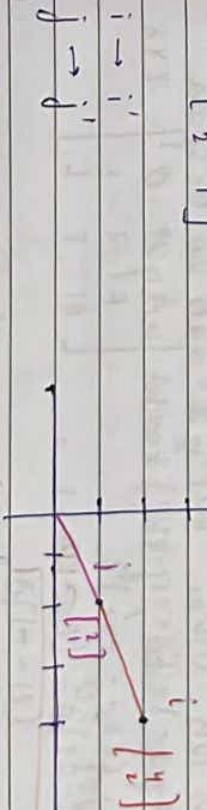
$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = (ad - bc) \quad \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix} = 6 - 0 = 6$$

In 2D basis vector ka area kitne factor se scale hua hoga det hua

DETERMINANT OF A TRANSFORMATION

After the LT of  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  the scaled area (in  $\mathbb{R}^2$ ) is known as det

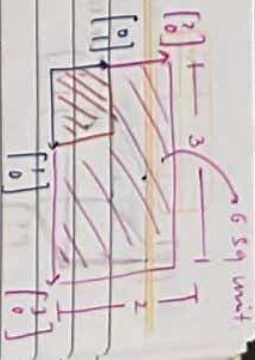
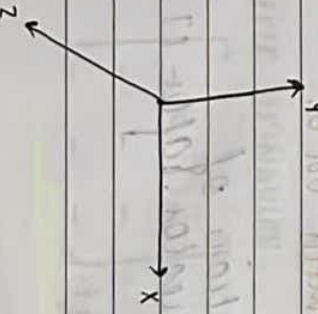
$$A = \begin{bmatrix} 4 & 2 \\ 2 & 1 \end{bmatrix} = 0$$



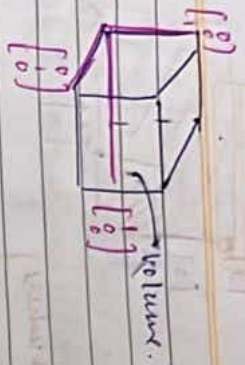
$\Delta = 0$

$$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}$$

$$v_i \in \mathbb{R}^3$$







$\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \}$   
 $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

eg  $\begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$   
 $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix}$

eg  $\begin{bmatrix} 1 & 4 & 5 \\ 2 & 5 & 7 \\ 3 & 7 & 10 \end{bmatrix}$   
 $\rightarrow$   $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$   $\rightarrow$   $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$   
 vol = 0

vector ton 3 but  $\mathbb{R}^2$  make no span  
 row per row, first row weight = 0  
 $\Rightarrow$  vol = 0

$\{v_1, v_2, \dots, 0\} \Rightarrow$  ok 0 row is sub ID  
 no guy with vol 0

sq. matrix is the representation of standard basis of a vector space

sq. matrix is collection of vectors after IT

# \* DETERMINANTS

Det is only calculated for sq. matrix

SYMBOL: for a given sq. matrix A we write  $\det(A)$  or  $|A|$

Det for a  $2 \times 2$  matrix.

$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$   $|A| = (ad - bc)$

eg  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$   $|A| = 4 - 6 = -2$

area considerations be negative  
 - we go original orientation / flip sign  
 the prob change flip above

$3 \times 3$   
 $\begin{bmatrix} 1 & 4 & 5 \\ 2 & 5 & 7 \\ 3 & 7 & 10 \end{bmatrix}$   $\det = 1(5 \times 10 - 7 \times 7) - 4(2 \times 10 - 7 \times 3) + 5(2 \times 7 - 5 \times 3)$   
 $= 1(50 - 49) - 4(20 - 21) + 5(14 - 15)$   
 $= 1 + 4 - 5 = 0$

$A_{11} = (-1)^{1+1} \det(-1)^3 = -1$   
 $A_{12} = (-1)^{1+2} \det(-1)^3 = 1$

UPPER TRIANGULAR.

$\begin{bmatrix} - & - & - \\ - & - & - \\ - & - & - \end{bmatrix}$



## RESULT

If we have any of these following matrices then  $\det$  is equal to product of diagonal elements.

- Diagonal matrix
- UTM
- LTM

$|A| = \text{pro. of diagonal elements.}$

eg:  $A = \begin{bmatrix} x & 0 & 0 \\ 0 & y & 0 \\ 0 & 0 & z \end{bmatrix}$   $|A| = xyz$

Q. Let  $V$  be a sq. matrix of order  $n$  st.

$$[V_{ij}]_{n \times n} = \begin{cases} 0 & \text{if } i > j \\ i+j & \text{if } i = j \\ k & \text{otherwise} \end{cases}$$

$\det = |V|$

$$\begin{bmatrix} 2 & k & k & \dots & k \\ 0 & 4 & k & \dots & k \\ 0 & 0 & 6 & \dots & k \\ 0 & 0 & 0 & \dots & k \\ \vdots & \vdots & \vdots & \ddots & \vdots \end{bmatrix}_{2n}$$

$$2 \times 4 \times 6 \dots (2n) = 2^n (1 \times 2 \times 3 \dots n) = 2^n n!$$

→ hae ek-term ki like common.