Lab 5 Exercise - A little Linear Regression

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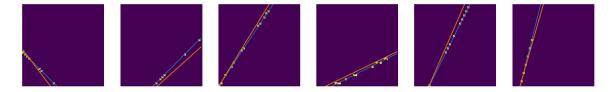
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This is the exercise that you need to work through **on your own** after completing the fifth lab session. You'll need to write up your results/answers/findings and submit this to ECS handin as a PDF document along with the other lab exercises near the end of the module (1 pdf document per lab).

You should use *no more* than one side of A4 to cover your responses to *this* exercise. This exercise is worth 5% of your overall module grade.

1 An initial attempt

In the lab exercise you built and trained a couple of CNNs for image classification. Your now going to try something different and build some CNNs for image-to-vector regression task - in particular you're going to implement a network that takes an image of a scatter plot, and predicts the parameters of the line of best fit.



The following code is used to generate the datasets for this task (get it in a useable form here: https://gist.github.com/jonhare/73a59dcc5416729548a086a983e81f07):

```
import torch
from torchvision import transforms
from torch.utils.data import Dataset
class MyDataset(Dataset):
  def __init__(self, size=5000, dim=40, random_offset=0):
        super(MyDataset, self).__init__()
        self.size = size
        self.dim = dim
        self.random\_offset = random\_offset
  def __getitem__(self , index):
      if index >= len(self):
          raise IndexError('{}_index_out_of_range'.format(self.__class__._name__))
      rng_state = torch.get_rng_state()
      torch.manual_seed(index + self.random_offset)
      while True:
        img = torch.zeros(self.dim, self.dim)
        dx = torch.randint(-10,10,(1,),dtype=torch.float)
        dy = torch.randint(-10,10,(1,),dtype=torch.float)
        c = torch.randint(-20,20,(1,), dtype=torch.float)
        params = torch.cat((dy/dx, c))
        xy = torch.randint(0,img.shape[1], (20, 2), dtype=torch.float)
```

```
xy[:,1] = xy[:,0] * params[0] + params[1]
       xy.round_()
        xy = xy[xy[:,1] > 0]
        xy = xy[xy[:,1] < self.dim]
        xy = xy[xy[:,0] < self.dim]
        for i in range (xy.shape[0]):
          x, y = xy[i][0], self.dim - xy[i][1]
          img[int(y), int(x)]=1
        if img.sum() > 2:
          break
      torch.set_rng_state(rng_state)
      return img.unsqueeze(0), params
 \mathbf{def} __len__(self):
      return self.size
train_data = MyDataset()
val_data = MyDataset(size=500, random_offset=33333)
test_data = MyDataset(size=500, random_offset=99999)
```

1.1 A simple CNN baseline (2 marks)

Implement the following CNN model, and train it using Adam (default parameters) for 100 epochs (use a GPU and be prepared to wait 6 or 7 minutes!). Use shuffled batches of 128 items. State the loss function you're using. **Comment** on the performance of the model.

```
\label{eq:convolution2D} Convolution2D \,, \ channels=48, \ size=3x3 \,, \ stride=1, \ padding=1 \\ ReLU \\ Linear \,, \ 128 \ outputs \\ ReLU \\ Linear \,, \ 2 \ outputs \\
```

2 A second attempt

Clearly the CNN implemented in Section 1 has many parameters in its final hidden layers. One common way of reducing this is to use Global Max Pooling to flatten the feature maps into a vector (called AdaptiveMaxPool2d in PyTorch).

2.1 A simple CNN with global pooling (1 mark)

Implement the following CNN model, and train it using Adam (default parameters) for 100 epochs. Use shuffled batches of 128 items. **Comment** on the model performance.

```
Convolution2D, channels=48, size=3x3, stride=1, padding=1 ReLU
Convolution2D, channels=48, size=3x3, stride=1, padding=1 ReLU
Global Max Pool
Linear, 128 outputs
ReLU
Linear, 2 outputs
```

3 Something that actually works?

The two models so far likely have a few issues. We're now going to try and fix this.

3.1 Let's regress (2 marks)

Modify the model from Section 2 as follows:

- 1. Modify the number of input channels to the first convolutional layer to be 3 instead of 1
- 2. In the forward pass, before the first convolution, modify the input, x, using the following code:

```
 \begin{array}{l} idxx = torch.repeat\_interleave (\\ torch.arange (-20,20,\ dtype=torch.float).unsqueeze (0) \ / \ 40.0\,,\\ repeats=40,\ dim=0).to (x.device)\\ idxy = idxx.clone ().t ()\\ idx = torch.stack ([idxx,\ idxy]).unsqueeze (0)\\ idx = torch.repeat\_interleave (idx,\ repeats=x.shape [0],\ dim=0)\\ x = torch.cat ([x,\ idx],\ dim=1) \end{array}
```

Train the modified model using Adam (default parameters) for 100 epochs. Use shuffled batches of 128 items. **Comment** on the model performance. **Describe** the rationale for the modification that was made.