

# SURAJ MANIYAR

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## EDUCATION

- **North Carolina State University, Raleigh, North Carolina** Expected May 2019  
Master of Science in Electrical Engineering GPA: 3.66/4.0  
Courses :- Data Science | Digital Imaging Systems | Probabilistic Graphical Models for Signal Processing and Computer Vision | Spatial and Temporal Data Mining | Design of a Robotic Computer Vision System for Autonomous Navigation | Computer Vision
- **Veermata Jijabai Technological Institute (VJTI), Mumbai, India** Jun 2013 – Jul 2017  
Bachelor of Technology in Electronics Engineering GPA: 7.72/10.0  
Courses :- Signal Processing | Robotics | Image Processing | Computer Programming | Embedded Systems | Control Systems

## TECHNICAL SKILLS

**Programming Languages** : Python, C++, Java, Linux Shell scripting  
**Frameworks & Libraries** : PyTorch, Tensorflow, Keras, OpenCV  
**Softwares & OS** : Robot Operating System (ROS), MATLAB, LabVIEW, Linux (Ubuntu), Windows  
**Hardware** : Raspberry Pi, Beaglebone Black, NI-myRio development board, AVR series microcontrollers

## PROJECTS

### **Design of a SLAM System for Autonomous Robot** (ROS, C++, Python, OpenCV) Jan 2018 – May 2018

- Localized aerial robot blimp using VINS-Mono and ORB SLAM2 algorithms separately
- Incorporated Visual and Odometric data to yield 3D point cloud of environment and real time localization of blimp
- Technology used: NVIDIA Jetson TX1, Raspberry Pi, BNO055 IMU, Raspberry PiCam, Point Cloud Library (PCL), ROS

### **Activity Recognition to Benchmark Hardware Accelerator** (Python, Keras) May 2018 - Aug 2018

#### **Independent Study**

- Implemented activity recognition using Convolutional and Recurrent Neural Net to benchmark custom made hardware accelerator
- Obtained an accuracy of **70%** for 7 different activities on UCF-101 Dataset

### **Deep Visual Attention Prediction** (Python, Keras, Tensorflow, OpenCV) Apr 2018

- Replicated the results from paper titled 'Deep Visual Attention Prediction' which predicts human eye fixation on view-free scenes
- Obtained an accuracy of **64%** by incorporating multi-level saliency predictions

### **Foraminifera Image Segmentation using Markov Random Field (MRF)** (Python, OpenCV) Dec 2017

- Used MRF based approach called Graph-Cut to segment chambers of a foraminifera (marine species) from its edge probability map
- Obtained an accuracy of **71.40%** using morphological refining and watershed transformation

### **Single View Metrology** (Python) Oct 2017

- Reconstructed 3D model of an object from its single 2D image using 3 point perspective
- Computed Homography matrices and projection matrix using vanishing points from the image
- Obtained texture maps for 3D model after applying affine transformation on the image using the obtained matrices

### **Task Learning Robot** (LabVIEW) Aug 2015 - Nov 2015

#### **National Instruments, India**

- Implemented a Computer-Vision based approach for 'Robot Learning from Demonstration' using industrial robotic arm Scorbot ER-VII
- Shortlisted in the **top 20 teams** for the **National Level Contest, NIYANTRA**, organized by National Instruments, India

### **Stock Trading using Machine Learning** (Python, Keras) Sept 2016 - May 2017

- Implemented a recommendation system to provide real time trading advice to investor
- Optimized the investor's portfolio and implemented technical analysis using Neural Networks and Reinforcement Learning separately to suggest best actions (buy, sell or hold) to the investor

### **Respiratory Rate Estimation** (Python, Keras) Nov 2017

- Estimated respiratory rate of a human based on accelerometer data, heart rate and body temperature using Ridge Regression and Neural Networks separately with a Root Mean Squared Error (RMSE) of **4.58**
- Reduced the RMSE to **3.68** by incorporating temporal dynamics using Hidden Markov Model (HMM)

## CO-CURRICULAR ACTIVITIES

- Senate member of **Society of Robotics and Automation (S.R.A.), V.J.T.I.** which deals with robotics, machine vision and automation
- Managed and conducted workshops with a team of 10, to teach students about line-following robots, embedded systems, Bluetooth technology and Internet of Things (IoT)