

# Suraj Nair

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| EDUCATION                   | <b>Stanford University</b> , Stanford, CA<br><i>Ph.D.</i> in Computer Science<br>Advisors: Chelsea Finn, Silvio Savarese   | 2018-Present              |
|                             | <b>California Institute of Technology</b> , Pasadena, CA<br><i>Bachelor of Science</i> in Computer Science<br>Advisor: Yisong Yue  | 2014-2018<br>GPA: 3.9/4.0 |
| EXPERIENCE                  | <b>Google Brain</b> , Research Intern/Student Researcher   | 2018-2019                 |
|                             | <b>Stanford Vision and Learning Lab</b> , Visiting Researcher  | 2017                      |
|                             | <b>Vizzario, Inc.</b> , Machine Learning Consultant  | 2017                      |
|                             | <b>Caltech DOLCIT</b> , Student Researcher   | 2016-2018                 |
|                             | <b>OpenFog Consortium</b> , Caltech Representative   | 2016-2018                 |
|                             | <b>General Electric, Current</b> , Software Development Intern   | 2016                      |
| PUBLICATIONS<br>& PREPRINTS | <b>KloudData, Inc.</b> , Software Engineering Intern   | 2015                      |
|                             | [14] Bohan Wu, <b>Suraj Nair</b> , Roberto Martin-Martin, Li Fei-Fei*, and Chelsea Finn*, Greedy Hierarchical Variational Autoencoders for Large-Scale Video Prediction, <i>IEEE Conference on Computer Vision and Pattern Recognition (CVPR)</i> . 2021   |                           |
|                             | [13] Stephen Tian, <b>Suraj Nair</b> , Frederik Ebert, Sudeep Dasari, Benjamin Eysenbach, Chelsea Finn, and Sergey Levine, Model-Based Visual Planning with Self-Supervised Functional Distances, <i>International Conference on Learning Representations (ICLR)</i> . 2021.   |                           |
|                             | [12] Annie Chen*, HyunJi Nam*, <b>Suraj Nair*</b> , Chelsea Finn. Batch Exploration with Examples for Scalable Robotic Reinforcement Learning. <i>Robotics and Automation Letters (RA-L)</i> and <i>IEEE International Conference on Robotics and Automation (ICRA)</i> . 2021   |                           |
|                             | [11] Brijen Thananjeyan*, Ashwin Balakrishna*, <b>Suraj Nair</b> , Michael Luo, Krishnan Srinivasan, Minh Hwang, Joey E. Gonzalez, Chelsea Finn, Ken Goldberg. Recovery RL: Safe Reinforcement Learning with Learned Recovery Zones. <i>Robotics and Automation Letters (RA-L)</i> and <i>IEEE International Conference on Robotics and Automation (ICRA)</i> . 2021 |                           |
|                             | [10] <b>Suraj Nair</b> , Silvio Savarese, Chelsea Finn. Goal-Aware Prediction: Learning to Model What Matters. <i>International Conference on Machine Learning (ICML)</i> . 2020.  |                           |
|                             | [9] Henrik Marklund*, <b>Suraj Nair*</b> , Chelsea Finn. Exact (Then Approximate) Dynamics Programming for Deep Reinforcement Learning <i>Workshop on Biases, Invariances, and Generalization in RL</i> , <i>International Conference on Machine Learning (ICML)</i> . 2020.   |                           |
|                             | [8] <b>Suraj Nair</b> , Chelsea Finn. Hierarchical Foresight: Self-Supervised Learning of Long-Horizon Tasks via Visual Subgoal Generation. <i>International Conference on Learning Representations (ICLR)</i> . 2020.   |                           |
|                             | [7] <b>Suraj Nair</b> , Mohammad Babaeizadeh, Chelsea Finn, Sergey Levine, Vikash Kumar. Time Reversal As Self-Supervision. <i>IEEE International Conference on Robotics and Automation (ICRA)</i> . 2020.   |                           |
|                             | [6] <b>Suraj Nair</b> , Yuke Zhu, Silvio Savarese, Li Fei-Fei. Causal Induction from Visual Obser-   |                           |

variations for Goal Directed Tasks, *Workshop on Causal Machine Learning, Neural Information Processing Systems (NeurIPS)*. 2019.

[5] Sudeep Dasari, Frederik Ebert, Stephen Tian, **Suraj Nair**, Bernadette Bucher, Karl Schmeckpeper, Siddharth Singh, Sergey Levine, Chelsea Finn. RoboNet: Large-Scale Multi-Robot Learning, *Conference on Robot Learning (CoRL)*. 2019.

[4] De-An Huang\*, **Suraj Nair\***, Danfei Xu\*, Yuke Zhu, Animesh Garg, Li Fei-Fei, Silvio Savarese, Juan Carlos Niebles. Neural Task Graphs: Generalizing to Unseen Tasks from a Single Video Demonstrations, *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*. 2019.

[3] Danfei Xu\*, **Suraj Nair\***, Yuke Zhu, Julian Gao, Animesh Garg, Li Fei-Fei, Silvio Savarese. Neural Task Programming: Learning to Generalize Across Hierarchical Tasks. *IEEE International Conference on Robotics and Automation (ICRA)*. 2018.

[2] Men-Andrin Meier, Zachary E Ross, Anshul Ramachandran, Ashwin Balakrishna, **Suraj Nair**, Peter Kundzicz, Zefeng Li, Jennifer Andrews, Egill Hauksson, Yisong Yue. Reliable RealTime Seismic Signal/Noise Discrimination With Machine Learning. *Journal of Geophysical Research: Solid Earth*. 2019.

[1] **Suraj Nair**, Anshul Ramachandran, Peter Kundzicz. Annotated Reconstruction of 3D Spaces Using Drones. *IEEE MIT URTC*. 2017. **Best Paper Presentation**.

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| <b>TALKS</b>                   | <b>Time Reversal as Self-Supervision</b>                               | 2018       |
|                                | Berkeley Robotic Artificial Intelligence and Learning Lab.             |            |
|                                | <b>Applying Neural Networks in IoT Use Cases</b>                       | 2017       |
|                                | Internet of Things World Congress 2017                                 |            |
| <b>TEACHING</b>                | <i>Teaching Assistant</i> , Stanford University                        | 2019, 2020 |
|                                | CS 330: Deep Multi-Task and Meta Learning                              |            |
|                                | <i>Teaching Assistant</i> , California Institute of Technology         | 2017       |
|                                | CS/EE 155: Machine Learning/Data Mining                                |            |
|                                | <i>Teaching Assistant</i> , California Institute of Technology         | 2016       |
| <b>AWARDS &amp; HONORS</b>     | CS 121: Introduction to Relational Databases                           |            |
|                                | National Science Foundation Graduate Research Fellowship               | 2018-2021  |
|                                | Best Paper Presentation - IEEE MIT URTC                                | 2017       |
|                                | Caltech Summer Undergraduate Research Fellowship Recipient             | 2017       |
| <b>PROFESSIONAL ACTIVITIES</b> | 1 <sup>st</sup> Place GE Digital Intern Hackathon                      | 2016       |
|                                | <i>Paper Reviewing:</i>  |            |
|                                | Neural Information Processing Systems (NeurIPS) 2020                   |            |
|                                | International Conference on Machine Learning (ICML) 2020               |            |
|                                | International Conference on Learning Representations (ICLR) 2019       |            |
|                                | IEEE International Conference on Robotics and Automation (ICRA) 2019   |            |
|                                | IEEE Conference on Computer Vision and Pattern Recognition (CVPR) 2019 |            |