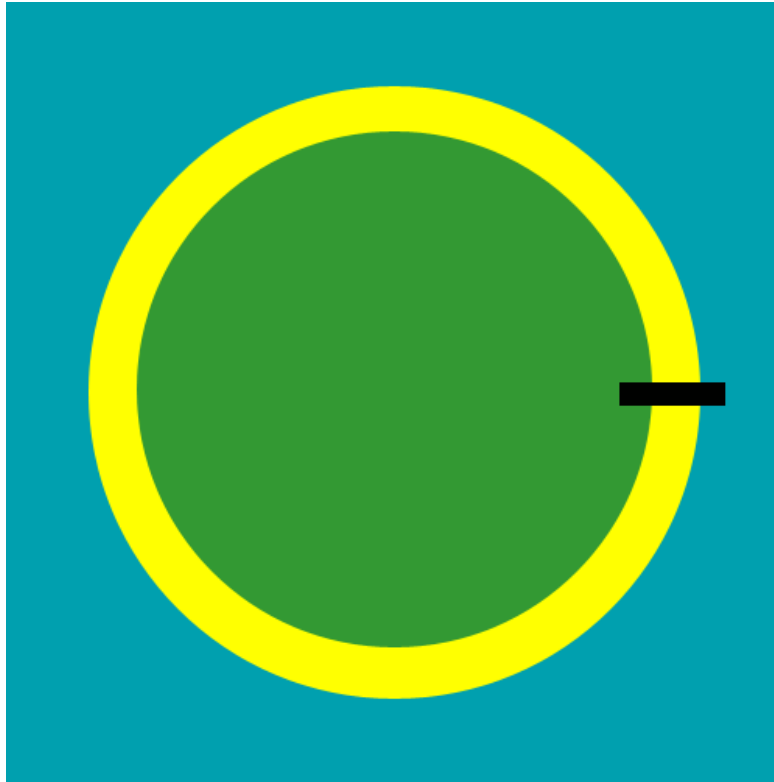


Robotics Mini Project

Aim: Create a robot which will move only on yellow path in given image.



Code: moveOnYellowPath.java

```
import ch.aplu.robotsim.*;

public class moveOnYellowPath {

    public moveOnYellowPath() {
        LegoRobot robot = new LegoRobot();
        Gear g = new Gear();
        LightSensor ls = new
LightSensor(SensorPort.S3);
```

```
robot.addPart(g);
robot.addPart(ls);

g.setSpeed(50);
g.forward();

while(true) {
    int value = ls.getValue();
    if(value >= 1000)
        g.forward();
    if(value < 1000)
        g.left();
    if(value < 100)
        g.stop();
}

static {
    RobotContext.setStartPosition(430, 230);

    RobotContext.useBackground("sprites/yellowpath.gif");
}

public static void main(String[] args) {

    moveOnYellowPath robo = new moveOnYellowPath();

}
```

Output: