

Generative Models for discrete data:

feature vector: \underline{x} \rightarrow classify using Bayes rule

generative classifiers: 8 form:

$$p(y=c | \underline{x}, \theta) \propto p(\underline{x} | y=c, \theta) p(y=c | \theta)$$

Posterior predictive distribution:

$$p(\hat{x} | D)$$

$\hat{x} \in C$ & its prob. given $\hat{x} \in D$; $\{1, 2, \dots, 100\}$

Likelihood: $p(D|h) = \left[\frac{1}{\text{size}(h)} \right]^N$

Prior: how prior for unknown concept $p(h)$

Posterior: likelihood times prior, normalized

$$p(h|D) = \frac{p(D|h) p(h)}{\sum_{h' \in H} p(D, h')} = \frac{p(h) \mathbb{I}(D \in h) / |h|^N}{\sum_{h' \in H} p(h') \mathbb{I}(D \in h') / |h'|^N}$$

$$\mathbb{I}(D \in h) \text{ is } \cdot$$

\Rightarrow

MAP estimate:-

$$p(h|D) \rightarrow \delta_{\hat{h}^{\text{MAP}}}(h)$$

~~\hat{h}^{MAP}~~ $\hat{h}^{\text{MAP}} = \arg\max_h p(h|D)$ = posterior mode

δ = Dirac measure

$$\delta_x(A) = \begin{cases} 1 & \text{if } x \in A \\ 0 & \text{if } x \notin A \end{cases}$$

MLE (Maximum Likelihood Estimate)

$$\hat{h}^{\text{MLE}} \triangleq \arg\max_h p(D|h) = \arg\max_h \log(p(D|h))$$

Next * The Beta Binomial model