#### ME19B79 and ME19B177

### Data Analysis and Plots

```
Code
In [1]: filename = "CS6700 PA1 Data.tar.xz"
In [2]: !ls -lh {filename} || gdown --fuzzy 'https://drive.google.com/file/d/1 jP8Ec6IpMdB10aJde
        -rw-r--r-- 1 suraj suraj 13M Feb 24 22:54 CS6700 PA1 Data.tar.xz
In [3]:
        !ls data > /dev/null || tar xf {filename}
In [4]: !ls -1 data | wc -l
        32
In [5]:
        !ls -1 data/AA qlearning False 0 4 1 EpsilonGreedy AA | wc -l
        125
        We have data from 32 different configurations.
        Each configuration should have data from 125 different hyperparameter combinations.
In [6]: import numpy as np
        import matplotlib.pyplot as plt
        import seaborn as sns
        sns.set style('darkgrid')
        from IPython.display import display, Markdown, Latex
        %matplotlib inline
```

```
In [7]: from pathlib import Path
        path = Path('./data')
        best_expt_by_id = {} # stores expt name, maps to object
        for config_id, config in enumerate(path.iterdir()):
            best expt by id[config id] = []
            reward = -np.inf
            for expt in config.iterdir():
                data = np.load(expt)
                temp = str(expt).split(' ')
                algorithm = temp[1]
                wind = temp[2] == "True"
                start_coord = np.fromiter(map(int, [temp[3], temp[4]]), int)
                p = float(temp[5])
                strategy = temp[6]
                alpha = float(temp[8])
                qamma = float(temp[9])
                heat or eps = float(temp[10])
                # tot rewards = data['r s'].sum()
```

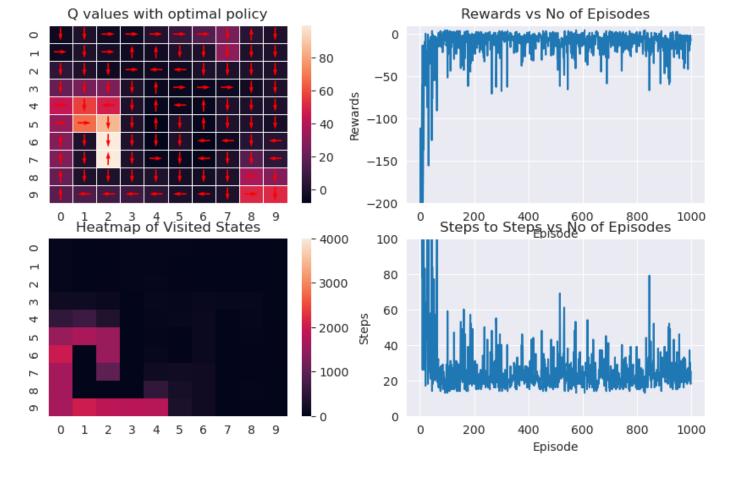
```
r = data['r'].sum()
                                       if r > reward:
                                                reward = r
                                                path = config / expt
                                                best expt by id[config id] = [algorithm, strategy, wind, start coord, p, alp
  In [8]: def sort order(item):
                             key, (algorithm, strategy, wind, start coord, p, alpha, gamma, heat or eps, path, to
                              return algorithm == "sarsa", start coord.sum(), p, wind,
                     best expt by id = dict(sorted(best expt by id.items(), key=sort order))
  In [9]: len(best expt by id)
  Out[9]: 32
In [10]: DOWN , UP, LEFT, RIGHT = 0, 1, 2, 3
                    x \ direct = np.array((0, 0, -1, 1))
                    y direct = np.array((-1, 1, 0, 0))
                    def plot Q(Q, ax, vmax=None):
                             sns.heatmap(Q.max(-1), edgecolors='k', linewidths=0.5, ax=ax)
                             policy = Q.argmax(-1)
                             policyx = x direct[policy]
                             policyy = y_direct[policy]
                             idx = np.indices(policy.shape)
                              ax.quiver(idx[1].ravel() + 0.5, idx[0].ravel() + 0.5, policyx.ravel(), policyy.ravel
In [11]: visits max = 4000
                    q max = 1000
                    def print(algo):
                             tick = 1
                             for key in best_expt_by_id.keys():
                                       expt info = best expt by id[key]
                                       [algorithm, strategy, wind, start coord, p, alpha, gamma, heat or eps, path, tot
                                       if algorithm != algo:
                                                continue
                                       display(Markdown(f'# Configuration {tick}'))
                                       outputs = (
                                                "| Reward | Algorithm | Exploration Strategy | Wind | Start Coors | P | . |
                                                "| :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: | :-: 
                                                f"| {tot rewards} | {algorithm} | {strategy} | {wind} | {start coord} | {p}
                                       display(Markdown("\n".join(outputs)))
                                       data = np.load(path)
                                       Q = data['q']
                                       Q = Q[::-1, :, :]
                                       visits = data['visits']
                                      visits = visits[::-1, ::]
                                       fig, axs = plt.subplots(2, 2, figsize=(10, 6))
                                       # Plot Optimal Policy
                                       plot Q(Q, axs[0, 0], vmax=q max)
                                       axs[0, 0].set title('Q values with optimal policy')
```

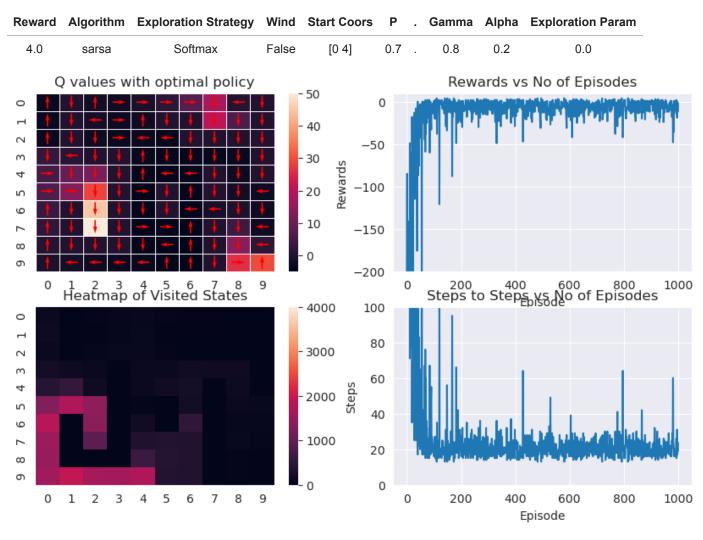
```
# Plotting Reward Curve
episodes = np.arange(data['r_s'].shape[0])
axs[0, 1].plot(episodes, data['r s'])
axs[0, 1].set title('Rewards vs No of Episodes')
axs[0, 1].set xlabel('Episode')
axs[0, 1].set ylabel('Rewards')
axs[0, 1].set ylim(-200, 10)
fig.show()
# Plotting Steps Curve
axs[1, 1].plot(episodes, data['s_s'])
axs[1, 1].set title('Steps to Steps vs No of Episodes')
axs[1, 1].set_xlabel('Episode')
axs[1, 1].set ylabel('Steps')
axs[1, 1].set ylim(0, 100)
# Plotting Heatmap of visited states
sns.heatmap(visits, ax=axs[1, 0], vmax=visits max)
axs[1, 0].set title('Heatmap of Visited States')
fig.show()
plt.pause(0.001)
tick += 1
```

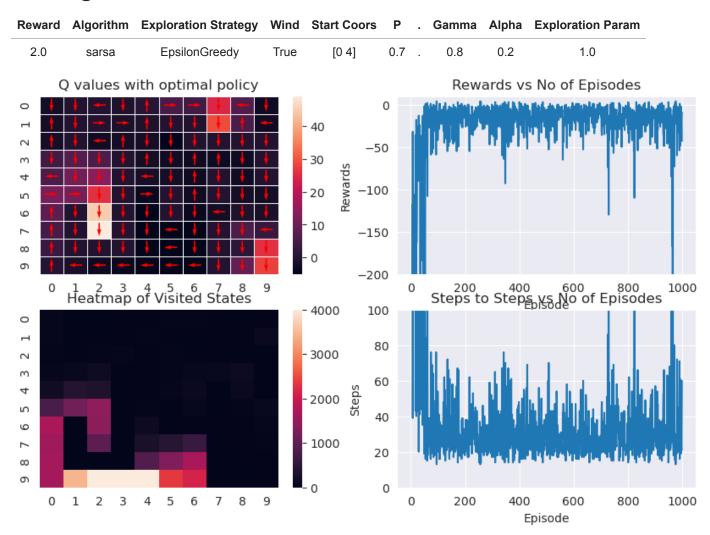
### SARSA

```
In [12]: print("sarsa")
```

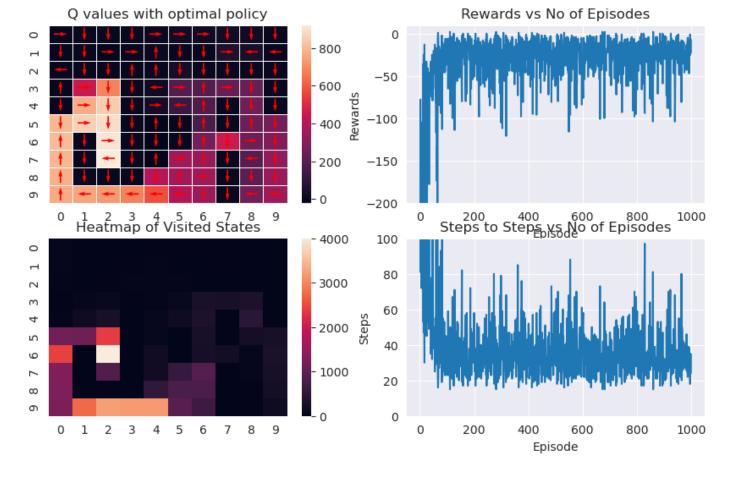
Reward	Algorithm	<b>Exploration Strategy</b>	Wind	Start Coors	Р	Gamma	Alpha	<b>Exploration Param</b>	
4.0	sarsa	EpsilonGreedy	False	[0 4]	0.7	0.9	0.5	2.0	
e://mature.	-	8072/2852134997.p inline.backend_ir	-		_	•			
e://mature.	-	8072/2852134997.p inline.backend_ir	-		_				

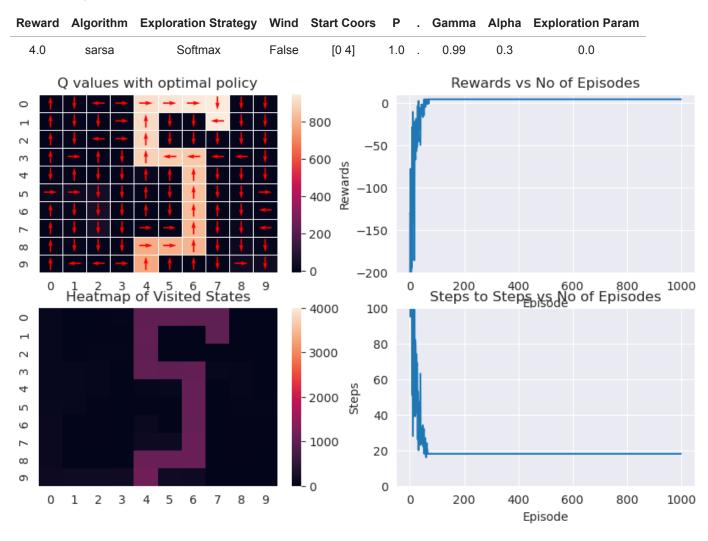


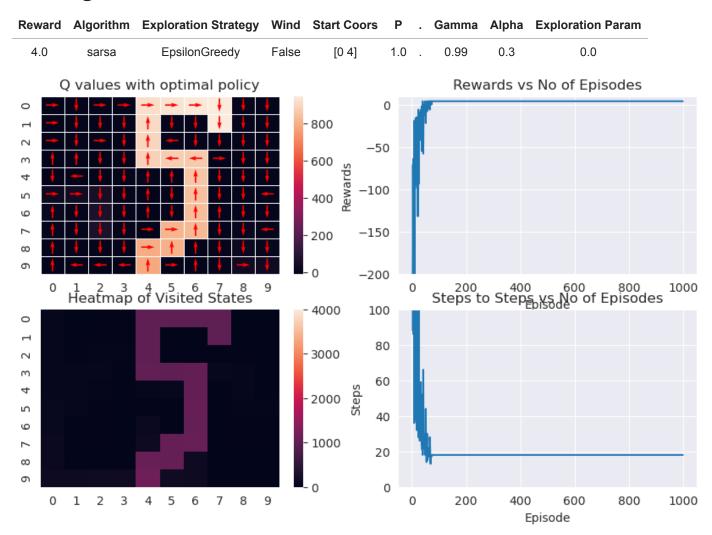




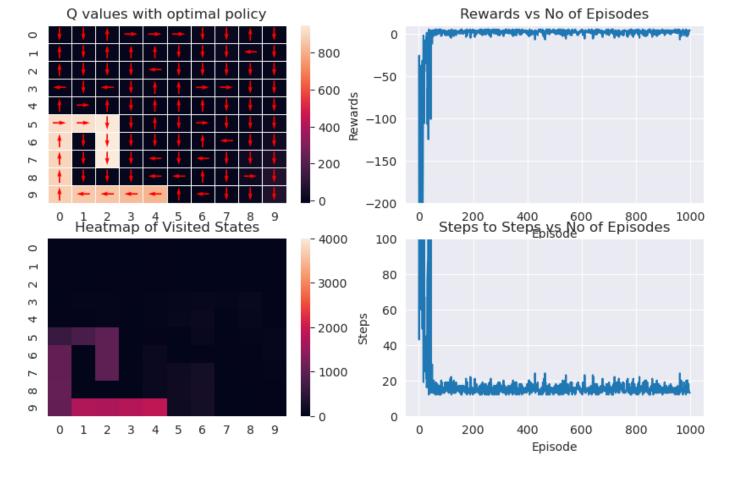
Reward	Algorithm	Exploration Strategy	Wind	Start Coors	Р	•	Gamma	Alpha	Exploration Param
2.0	sarsa	Softmax	True	[0 4]	0.7		0.99	0.3	0.0

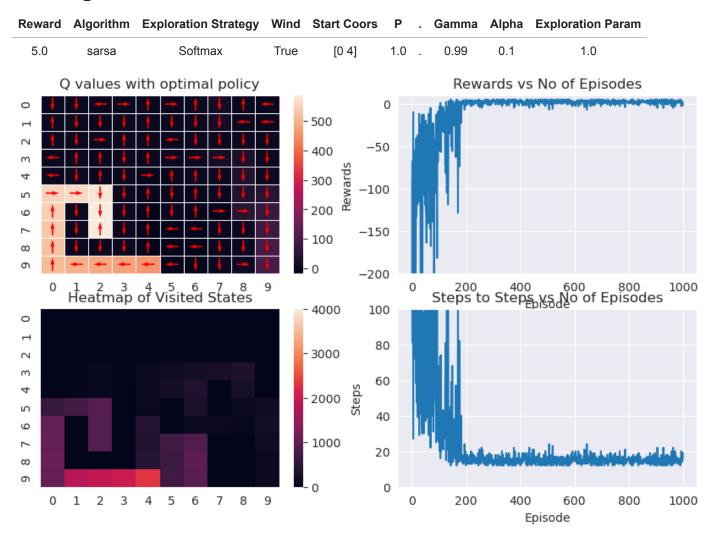


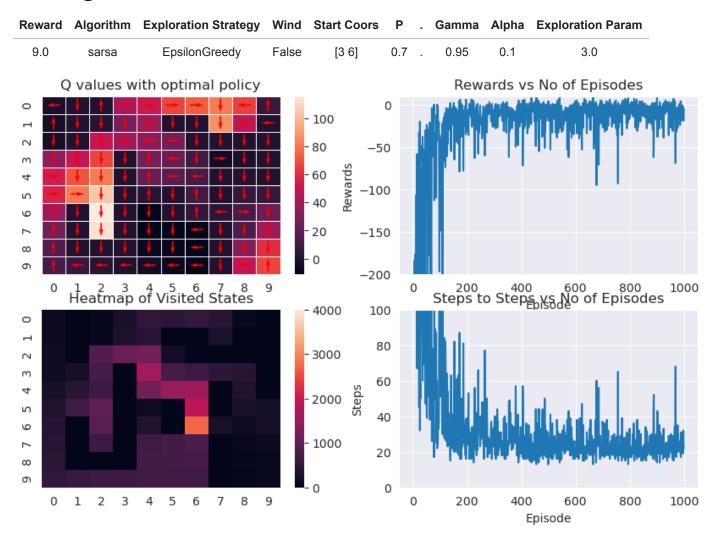




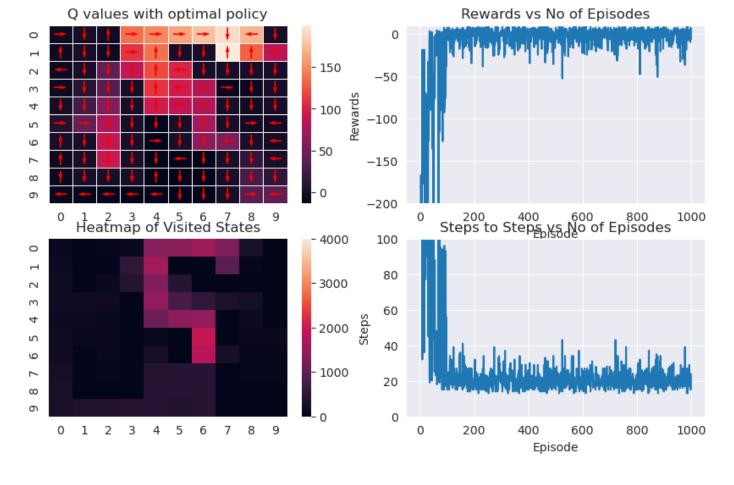
Reward	Algorithm	Exploration Strategy	Wind	Start Coors	Р	•	Gamma	Alpha	Exploration Param
5.0	sarsa	EpsilonGreedy	True	[0 4]	1.0		0.99	0.3	0.0

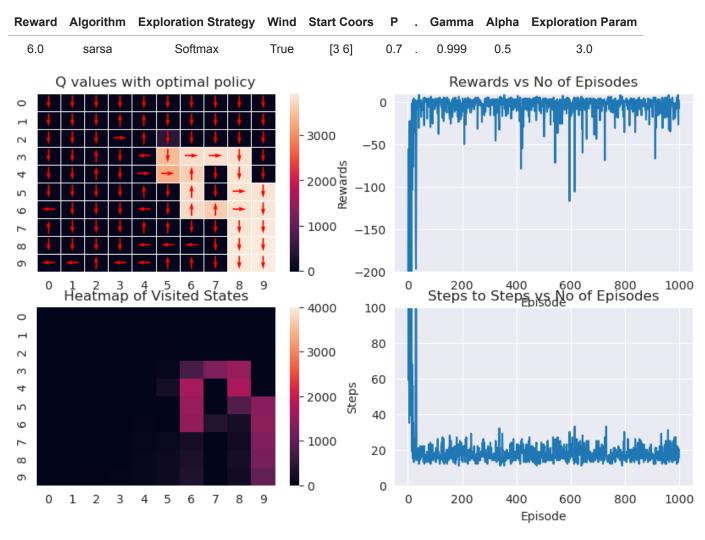


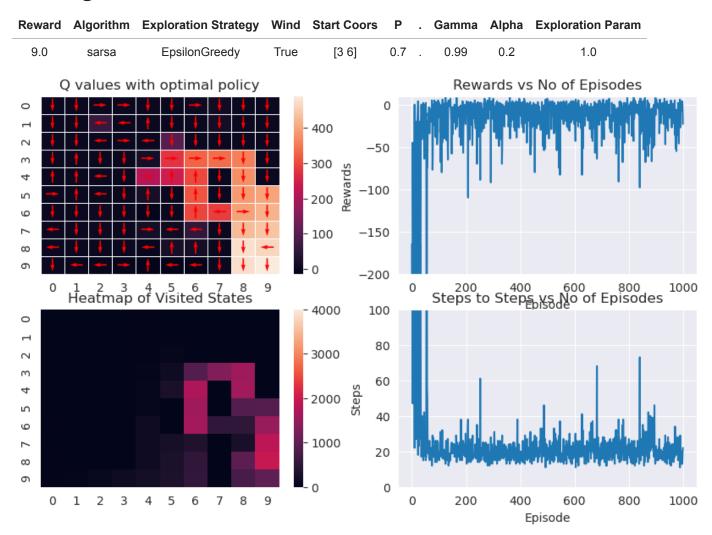




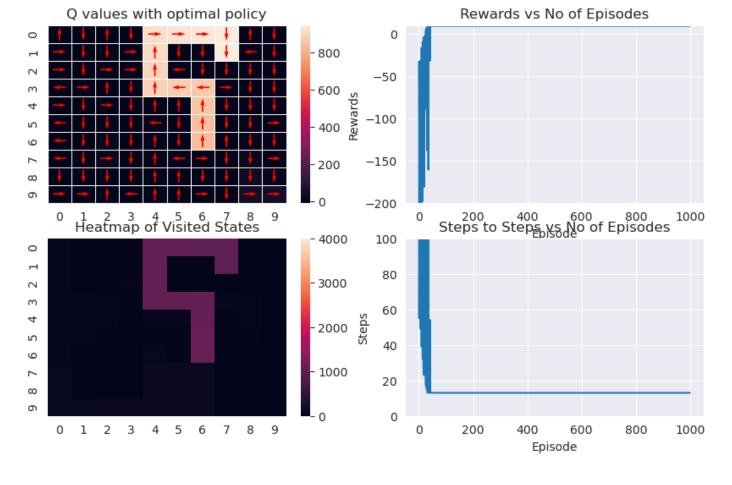
Reward	Algorithm	Exploration Strategy	Wind	Start Coors	Р	Gamma	Alpha	Exploration Param
9.0	sarsa	Softmax	False	[3 6]	0.7	0.95	0.2	1.0

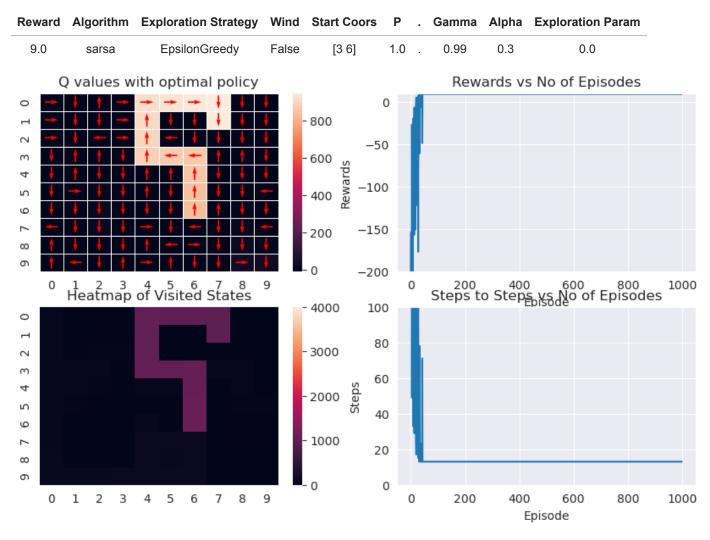


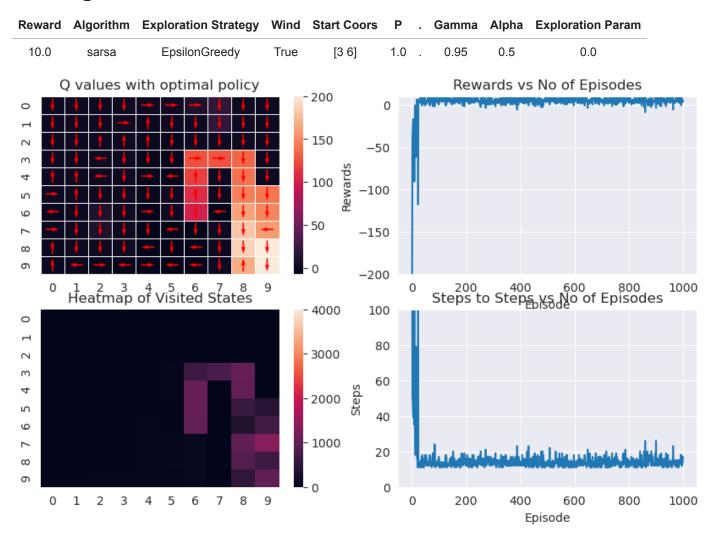




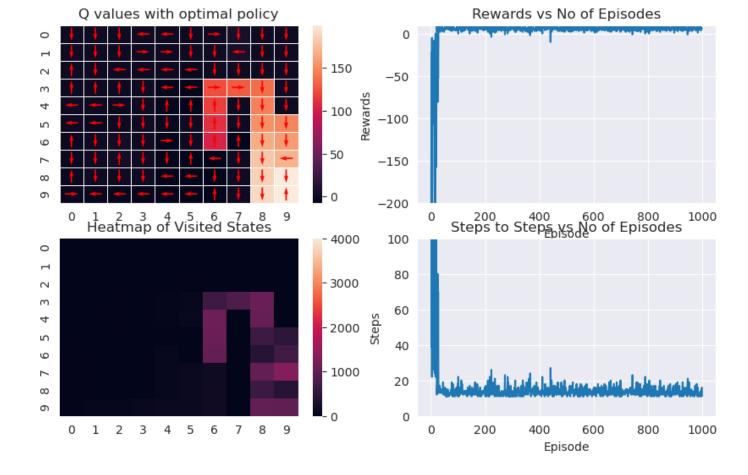
Reward	Algorithm	Exploration Strategy	Wind	Start Coors	Р	•	Gamma	Alpha	Exploration Param
9.0	sarsa	Softmax	False	[3 6]	1.0		0.99	0.3	0.0







Reward	Algorithm	Exploration Strategy	Wind	Start Coors	Р	•	Gamma	Alpha	Exploration Param
9.0	sarsa	Softmax	True	[3 6]	1.0		0.95	0.3	0.0



### **QLearning**

In [13]: print("qlearning")

### Configuration 1

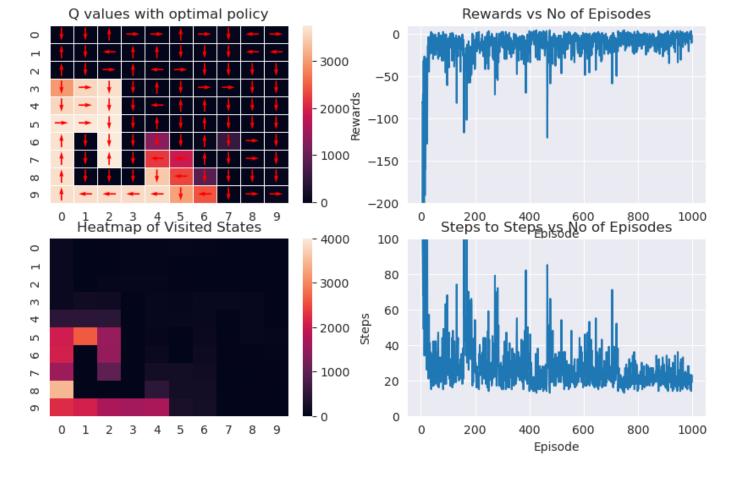
Reward	Algorithm	Exploration Strategy	Wind	Start Coors	Р	Gamma	Alpha	Exploration Param
3.0	qlearning	EpsilonGreedy	False	[0 4]	0.7	0.999	0.5	2.0

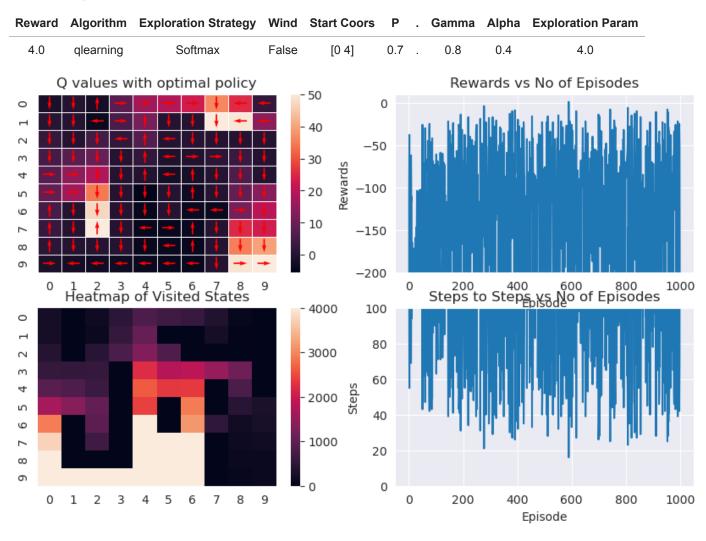
/tmp/ipykernel\_8072/2852134997.py:41: UserWarning: Matplotlib is currently using modul
e://matplotlib\_inline.backend\_inline, which is a non-GUI backend, so cannot show the fig
ure.

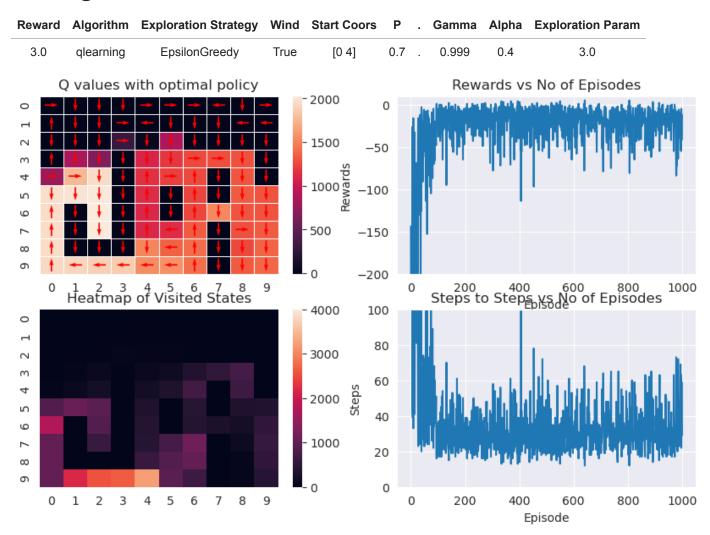
fig.show()

/tmp/ipykernel\_8072/2852134997.py:54: UserWarning: Matplotlib is currently using modul
e://matplotlib\_inline.backend\_inline, which is a non-GUI backend, so cannot show the fig
ure.

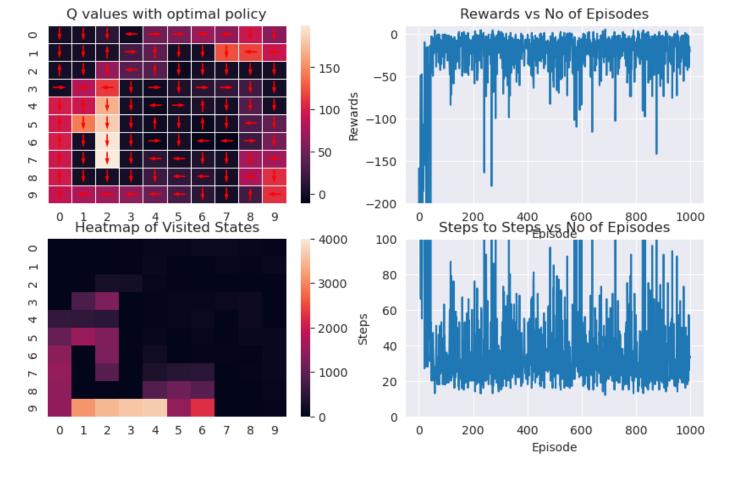
fig.show()

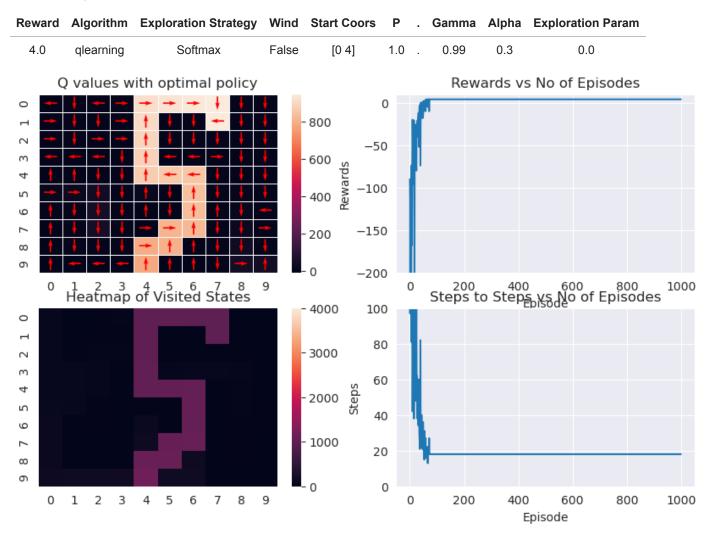


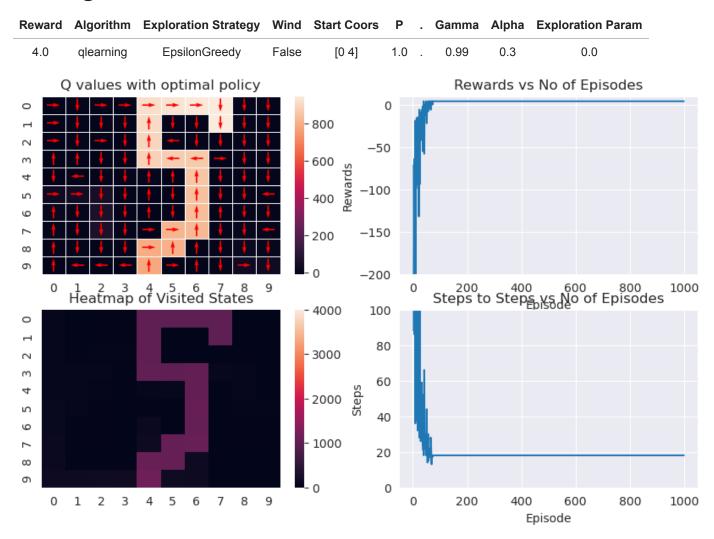




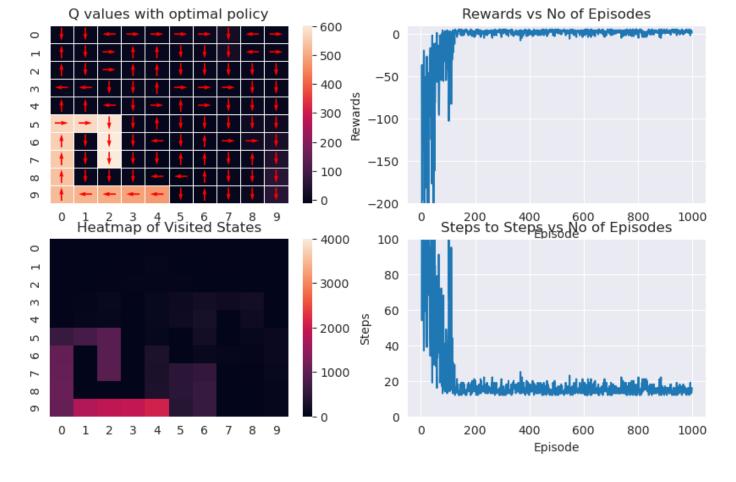
Reward	Algorithm	Exploration Strategy	Wind	Start Coors	Р	Gamma	Alpha	Exploration Param
3.0	qlearning	Softmax	True	[0 4]	0.7	0.95	0.4	0.0

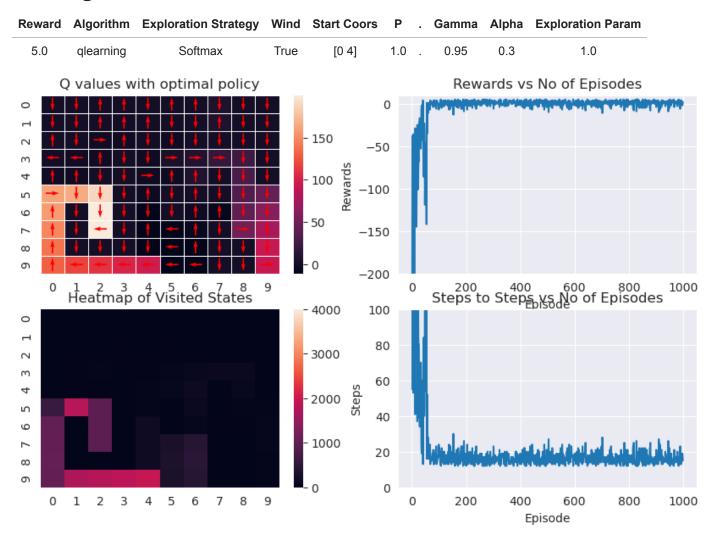


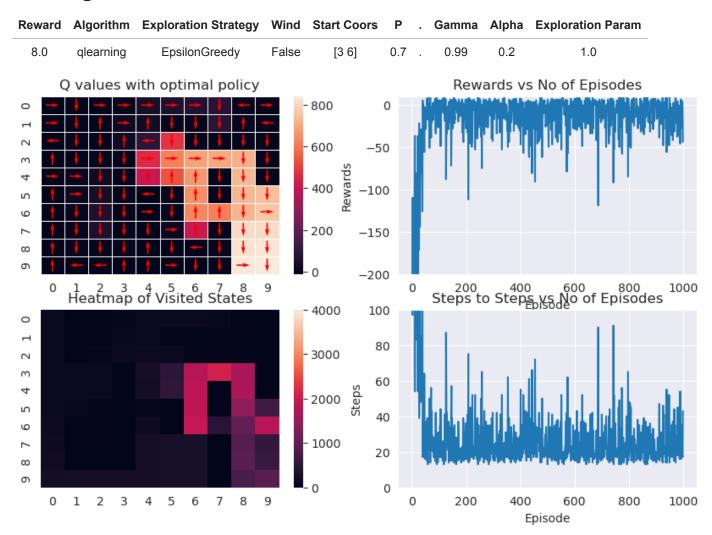




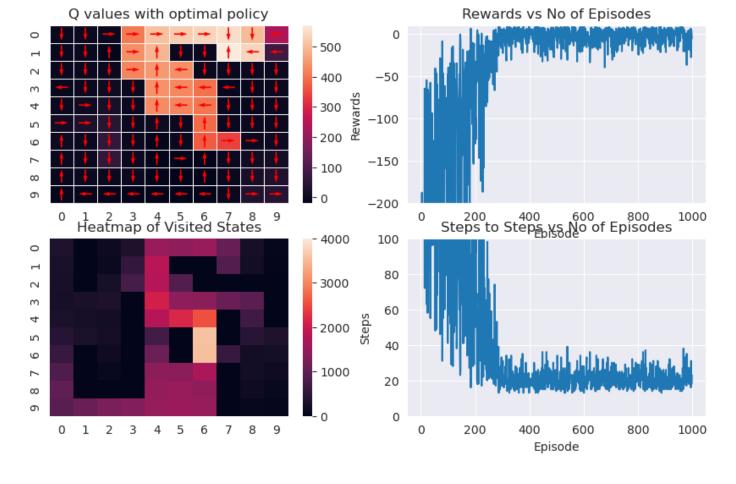
_	Reward	Algorithm	Exploration Strategy	Wind	Start Coors	Р	Gamma	Alpha	Exploration Param
	5.0	qlearning	EpsilonGreedy	True	[0 4]	1.0	0.99	0.1	0.0

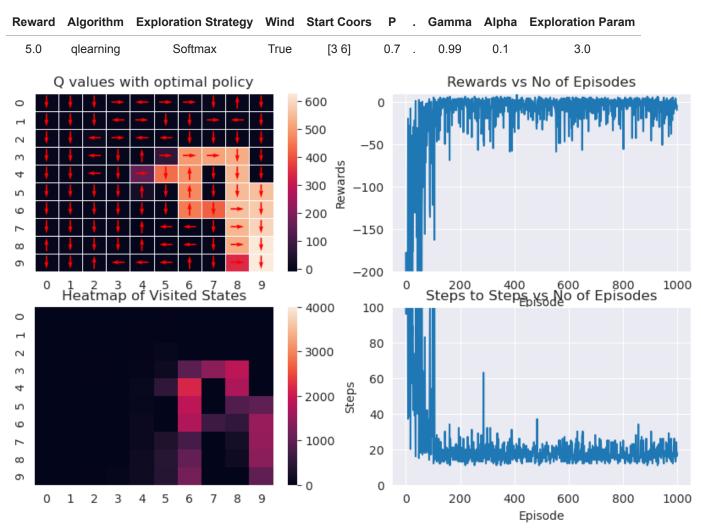


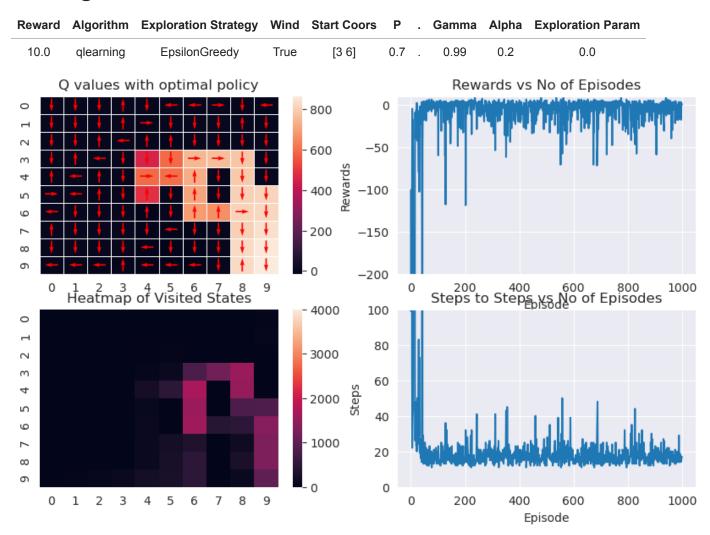




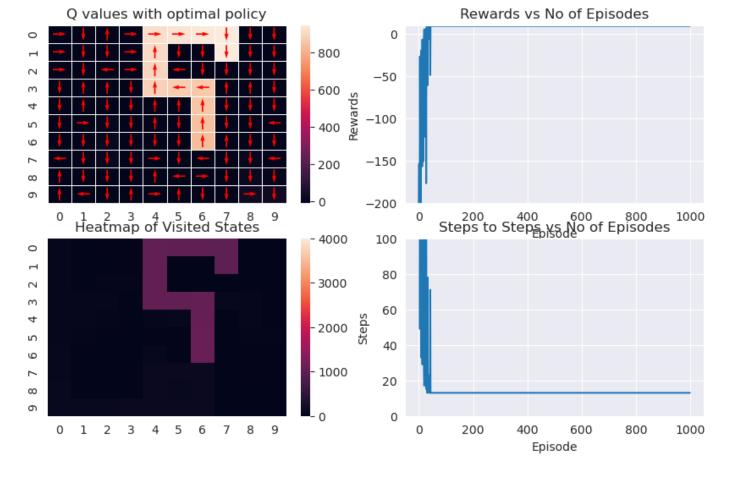
Reward	Algorithm	Exploration Strategy	Wind	Start Coors	Р	Gamma	Alpha	Exploration Param
9.0	qlearning	Softmax	False	[3 6]	0.7	0.99	0.1	4.0

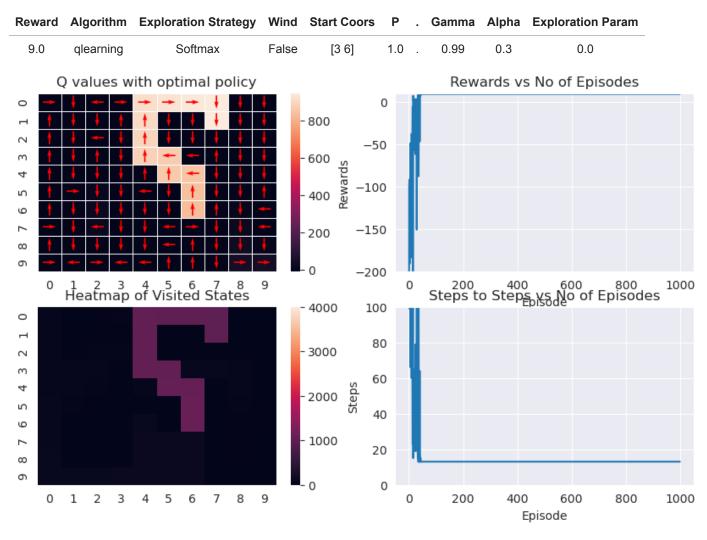


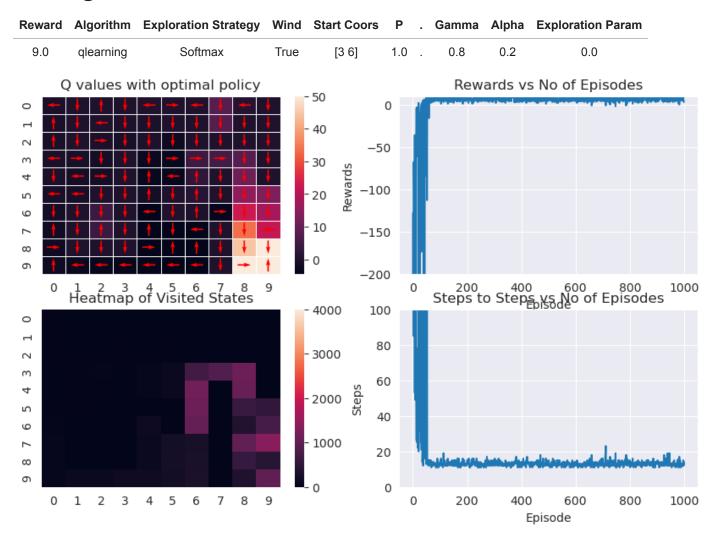




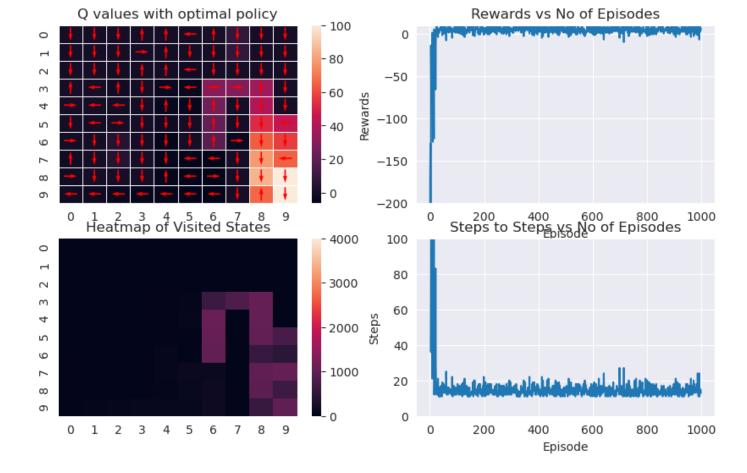
Reward	Algorithm	Exploration Strategy	Wind	Start Coors	Р	٠	Gamma	Alpha	Exploration Param
9.0	qlearning	EpsilonGreedy	False	[3 6]	1.0		0.99	0.3	0.0







Reward	Algorithm	Exploration Strategy	Wind	Start Coors	Р	Gamma	Alpha	Exploration Param
11.0	qlearning	EpsilonGreedy	True	[3 6]	1.0	0.9	0.4	0.0



In [ ]: