

PRINCIPLES OF MACHINE LEARNING

Exercise sheet 4 - fun with Frank-Wolfe

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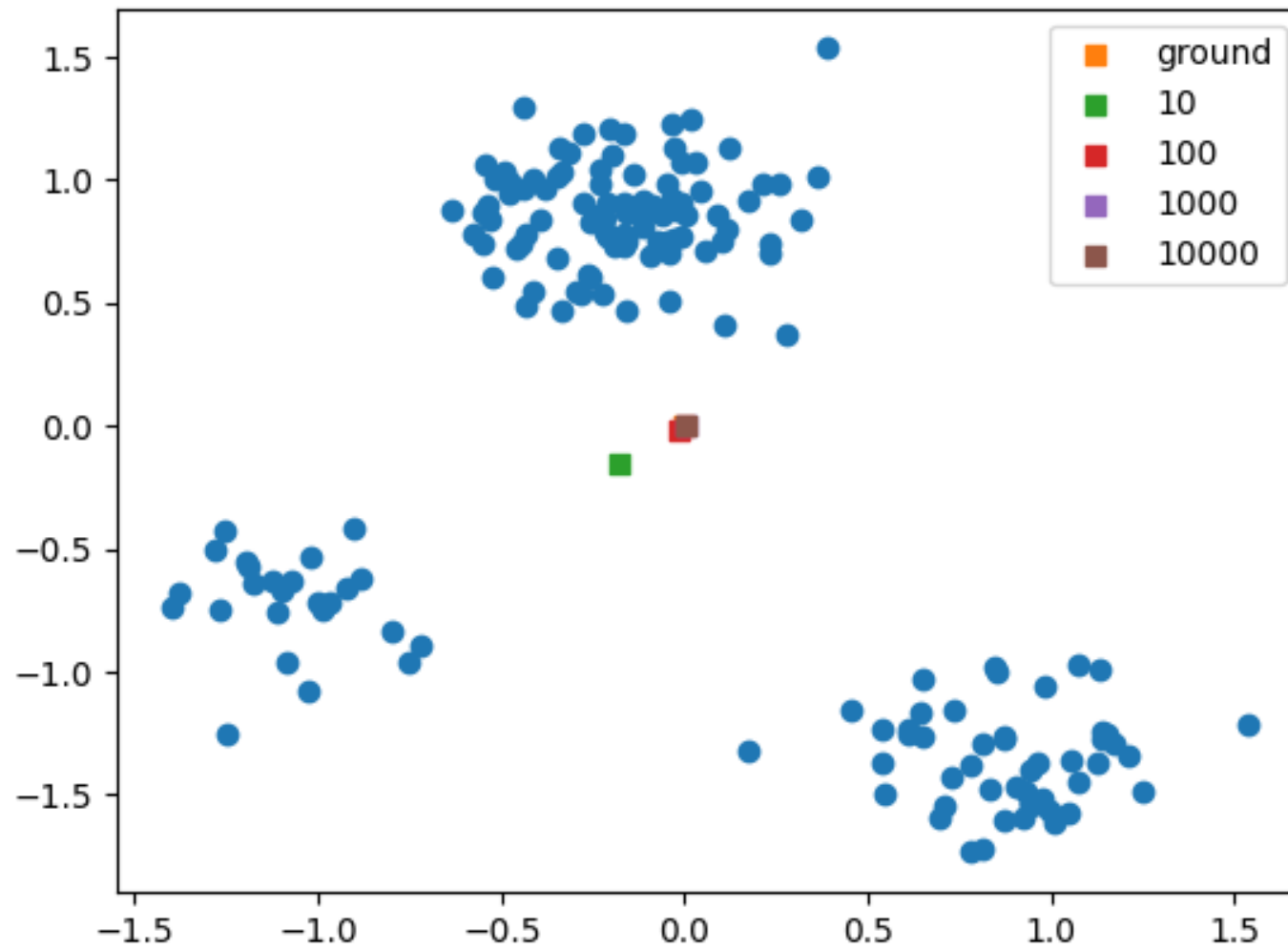
4.1: sample means (part 1)

Increase in the number of iterations results in increase of proximity/correctness of the estimated mean.

```
def gradientF(vector: np.ndarray, n: int, data: np.ndarray) -> np.ndarray:
    return 2 * data.transpose() @ data @ (vector - np.ones(n) / n)

def frank_wolfe(T:int, n: int, data: np.ndarray) -> np.ndarray:
    vecW = np.ones(n) / n # center of the standard simplex
    for t in tqdm(range(T)):
        beta = 2 / (t + 2)
        vecG = gradientF(vecW, n, data) imin = np.argmin(vecG)
        vecW *= (1 - beta)
        vecW[imin] += beta
    return data @ vecW
```

4.1: result



4.2: sample means (part 2)

Given that: $X \in \mathbb{R}^{m \times n}, X^T \in \mathbb{R}^{n \times m}, z \in \mathbb{R}^{n \times 1}, z^T \in \mathbb{R}^{1 \times n}, \omega \in \mathbb{R}^{n \times 1}, \omega^T \in \mathbb{R}^{1 \times n}$

Inferring: $X\omega \in \mathbb{R}^{n \times 1}, z\omega^T \in \mathbb{R}^{n \times n}, z\omega^T X^T X \omega \in \mathbb{R}^{n \times 1}, X\omega z^T \in \mathbb{R}^{n \times n}, \text{tr}[X^T X \omega z^T] \in \mathbb{R}^1, z^T X^T X \omega \in \mathbb{R}^1$

Proof: Let $v_1 = X^T X \omega$ and $v_2 = z^T$ in case 1 and $v_1 = z\omega^T X^T X \omega$ and $v_2 = z^T$ in case 2. Therefore:

The trace of the product $\mathbf{v}_2 \mathbf{v}_1$ is given by:

$$\text{Tr}(\mathbf{v}_2 \mathbf{v}_1)$$

The product $\mathbf{v}_2 \mathbf{v}_1$ results in an $n \times n$ matrix. Let's compute the product:

$$\mathbf{v}_2 \mathbf{v}_1 = \begin{bmatrix} v_{21} \\ v_{22} \\ \vdots \\ v_{2n} \end{bmatrix} \begin{bmatrix} v_{11} & v_{12} & \cdots & v_{1n} \end{bmatrix}$$

The resulting matrix $\mathbf{v}_2 \mathbf{v}_1$ is:

$$\begin{bmatrix} v_{21}v_{11} & v_{21}v_{12} & \cdots & v_{21}v_{1n} \\ v_{22}v_{11} & v_{22}v_{12} & \cdots & v_{22}v_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ v_{2n}v_{11} & v_{2n}v_{12} & \cdots & v_{2n}v_{1n} \end{bmatrix}$$

4.2: sample means (part 2)

Now, the trace is the sum of the diagonal elements:

$$\text{Tr}(\mathbf{v}_2 \mathbf{v}_1) = v_{21}v_{11} + v_{22}v_{12} + \cdots + v_{2n}v_{1n}$$

Now, let's consider the product $\mathbf{v}_1 \mathbf{v}_2$, which is a 1×1 matrix (a scalar):

$$\mathbf{v}_1 \mathbf{v}_2 = \begin{bmatrix} v_{11} \\ v_{12} \\ \vdots \\ v_{1n} \end{bmatrix} \begin{bmatrix} v_{21} & v_{22} & \cdots & v_{2n} \end{bmatrix}$$

The result is:

$$\mathbf{v}_1 \mathbf{v}_2 = v_{11}v_{21} + v_{12}v_{22} + \cdots + v_{1n}v_{2n}$$

Now, observe that these two expressions are the same:

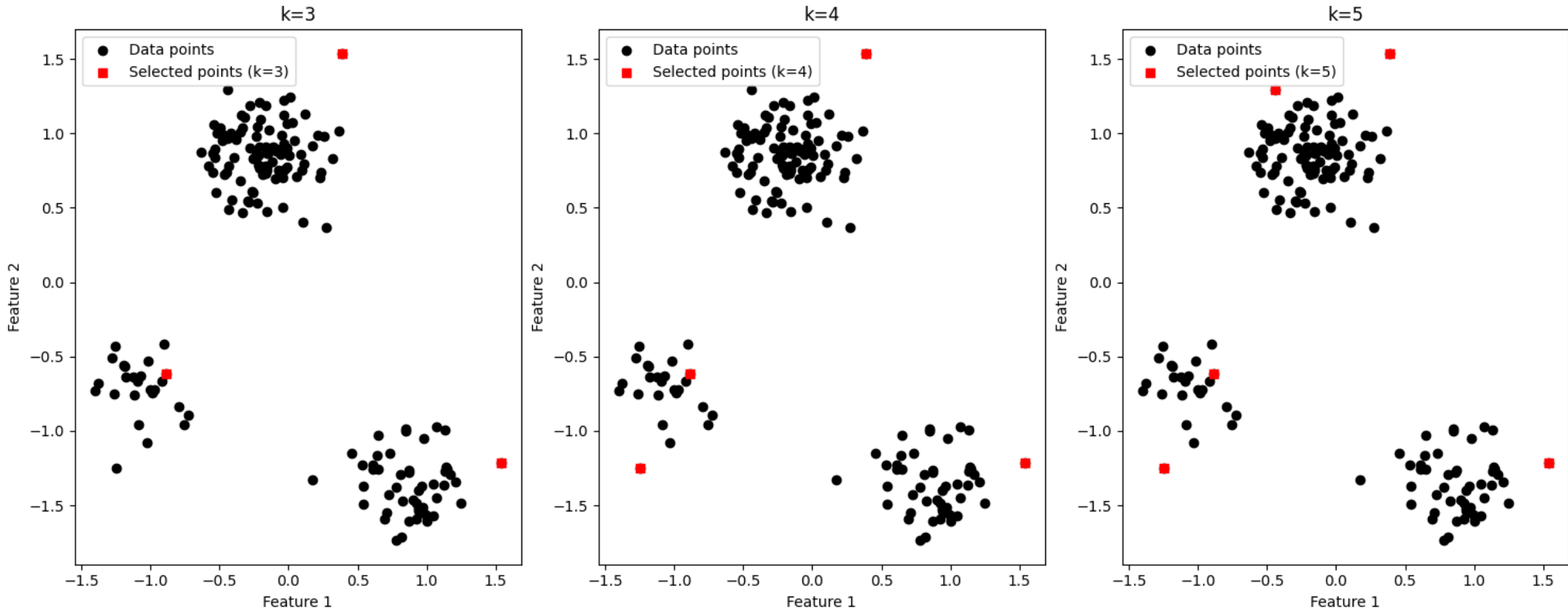
$$\text{Tr}(\mathbf{v}_2 \mathbf{v}_1) = \mathbf{v}_1 \mathbf{v}_2$$

Therefore, we have shown that the trace of the product $\mathbf{v}_2 \mathbf{v}_1$ is equal to the trace of the product $\mathbf{v}_1 \mathbf{v}_2$.

4.3: finding maximally different data points

```
def select_diverse_points(X, k):  
    if k >= X.shape[0]:  
        raise ValueError("k must be smaller than the number of data  
points")  
    selected_indices = []  
    for _ in range(k):  
        max_dist = 0  
        max_idx = -1  
        for i in range(X.shape[0]):  
            if i not in selected_indices:  
                dist_sum = sum(np.linalg.norm(X[i] - X[j]) for j in  
selected_indices)  
                if dist_sum > max_dist:  
                    max_dist = dist_sum  
                    max_idx = i  
        selected_indices.append(max_idx)  
    return selected_indices
```

4.3: finding maximally different data points



4.3: finding maximally different data points (4,9,16,25)



4.3: finding maximally different data points (k=49)



4.3: finding maximally different data points ($k=100$)



4.4.1: unconventional k-means clustering (part 1)

```
def FW_update_Z(X, M, tmax=1):  
    n = X.shape[1]    # Number of data points  
    k = M.shape[1]    # Number of clusters  
    Z = np.zeros((k, n)) # Initialize Z matrix  
  
    for t in range(tmax):  
        GZ = 2 * np.dot(np.dot(M.T, M), Z) - 2 * np.dot(M.T, X)  
        row_indices = np.argmin(GZ, axis=0)  
        Z = np.zeros_like(Z) # Reset Z  
        Z[row_indices, np.arange(n)] = 1 # Assign each data  
point to the closest centroid  
  
    return Z
```

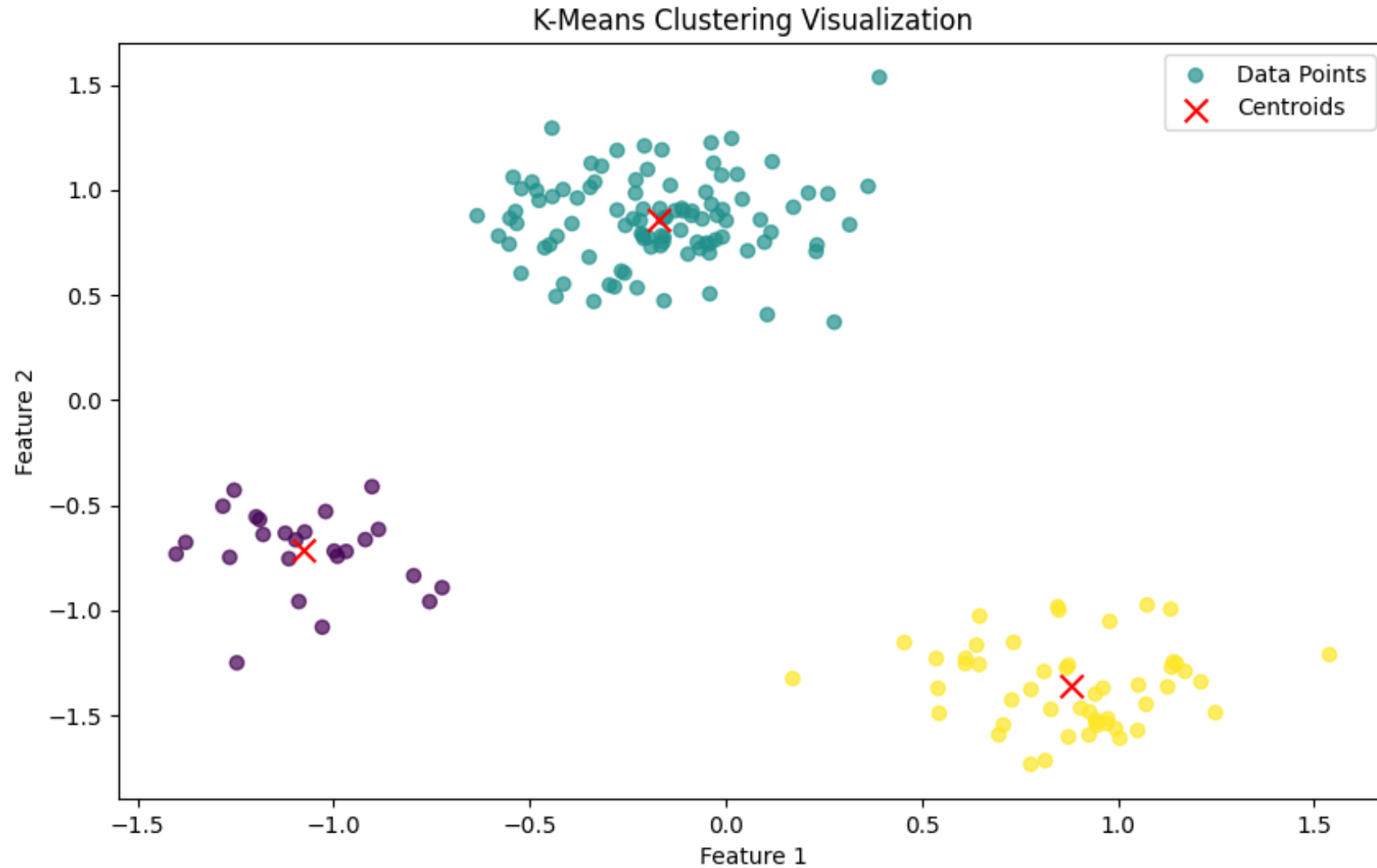
4.4.1: unconventional k-means clustering (part 1)

```
def FW_kMeans_Version1(X, k, Tmax=100):  
    m, n = X.shape  
    # Randomly initialize centroids by selecting k data points  
    indices = np.random.choice(n, k, replace=False)  
    M = X[:, indices]  
  
    for T in range(Tmax):  
        Z = FW_update_Z(X, M)  
        M = np.dot(X, Z.T) @ np.linalg.pinv(Z @ Z.T) # Update centroids  
  
    return M, Z
```

4.4.1: unconventional k-means clustering (part 1)

```
def FW_kMeans_Version1(X, k, Tmax=100):  
    m, n = X.shape  
    # Randomly initialize centroids by selecting k data points  
    indices = np.random.choice(n, k, replace=False)  
    M = X[:, indices]  
  
    for T in range(Tmax):  
        Z = FW_update_Z(X, M)  
        M = np.dot(X, Z.T) @ np.linalg.pinv(Z @ Z.T) # Update centroids  
  
    return M, Z
```

4.4.1: unconventional k-means clustering (part 1)



4.4.2: unconventional k-means clustering (part 1)

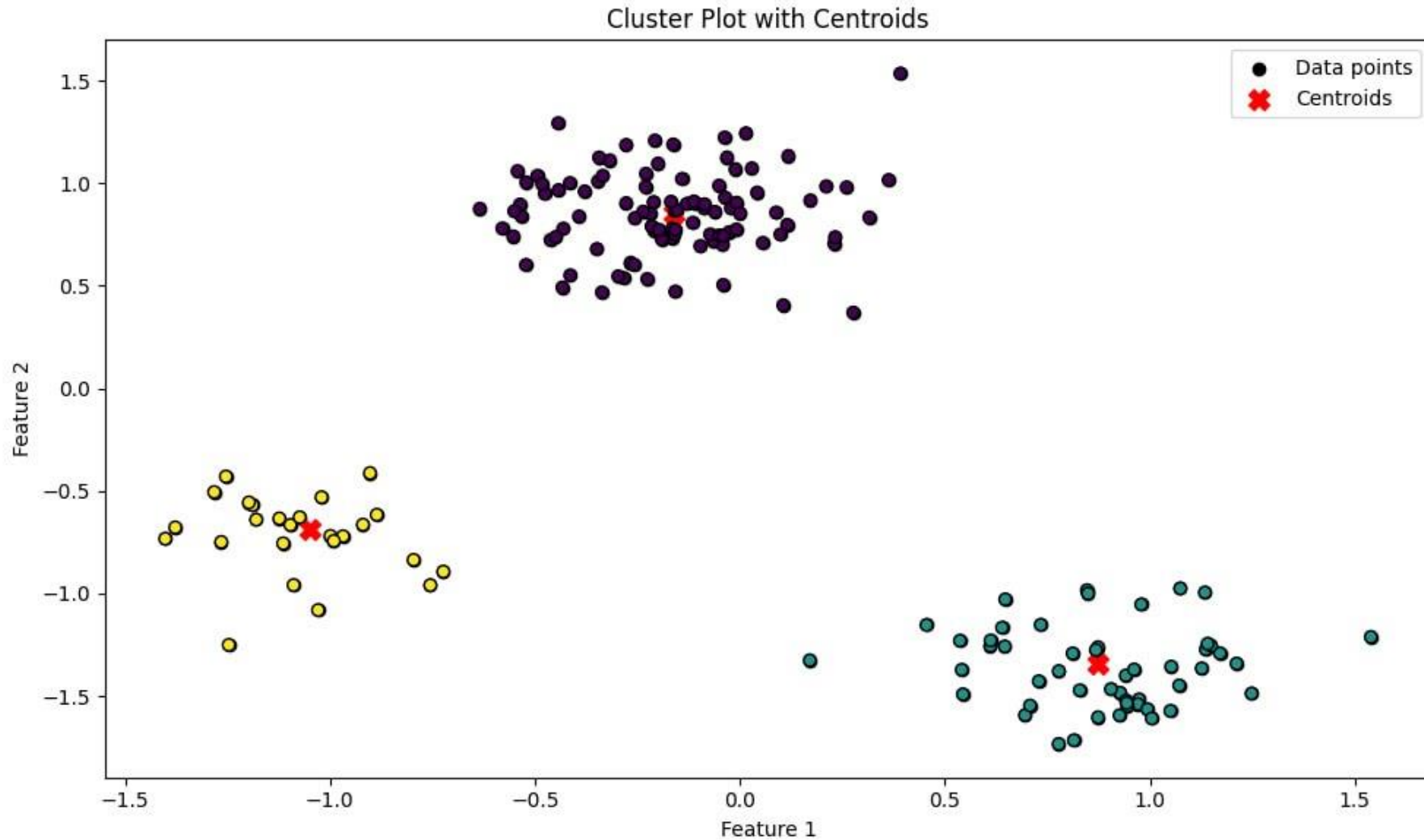


4.5: unconventional k-means clustering (part 2)

```
def FW_update_Y(X, Y, Z, t_max):  
    for t in range(t_max):  
        G_y = 2 * (X @ X.T @ Y @ Z @ Z.T - X @ X.T @ Z.T)  
        for i in range(Y.shape[1]):  
            o = np.argmin(G_y[:, i])  
            Y[:, i] = Y[:, i] + (2 / (t + 2)) * (np.eye(Y.shape[0])[o] - Y[:, i])  
    return Y
```

```
def FW_kMeans_Version2 (X, k, t_max):  
    n, m = X.shape  
    M = np.random.rand(m, k)  
    for _ in range(t_max):  
        Z = np.ones((k, n)) / k  
        Z = FW_UPDATE_Z(X, M, Z, t_max=1)  
        Y = np.ones((n, k)) / n  
        Y = FW_UPDATE_Y(X, Y, Z, t_max=100)  
        M = np.dot(X.T, Y)  
    return M, Y, Z
```

4.5: unconventional k-means clustering (part 2)



4.5: unconventional k-means clustering (part 2)



4.6: archetypal analysis

