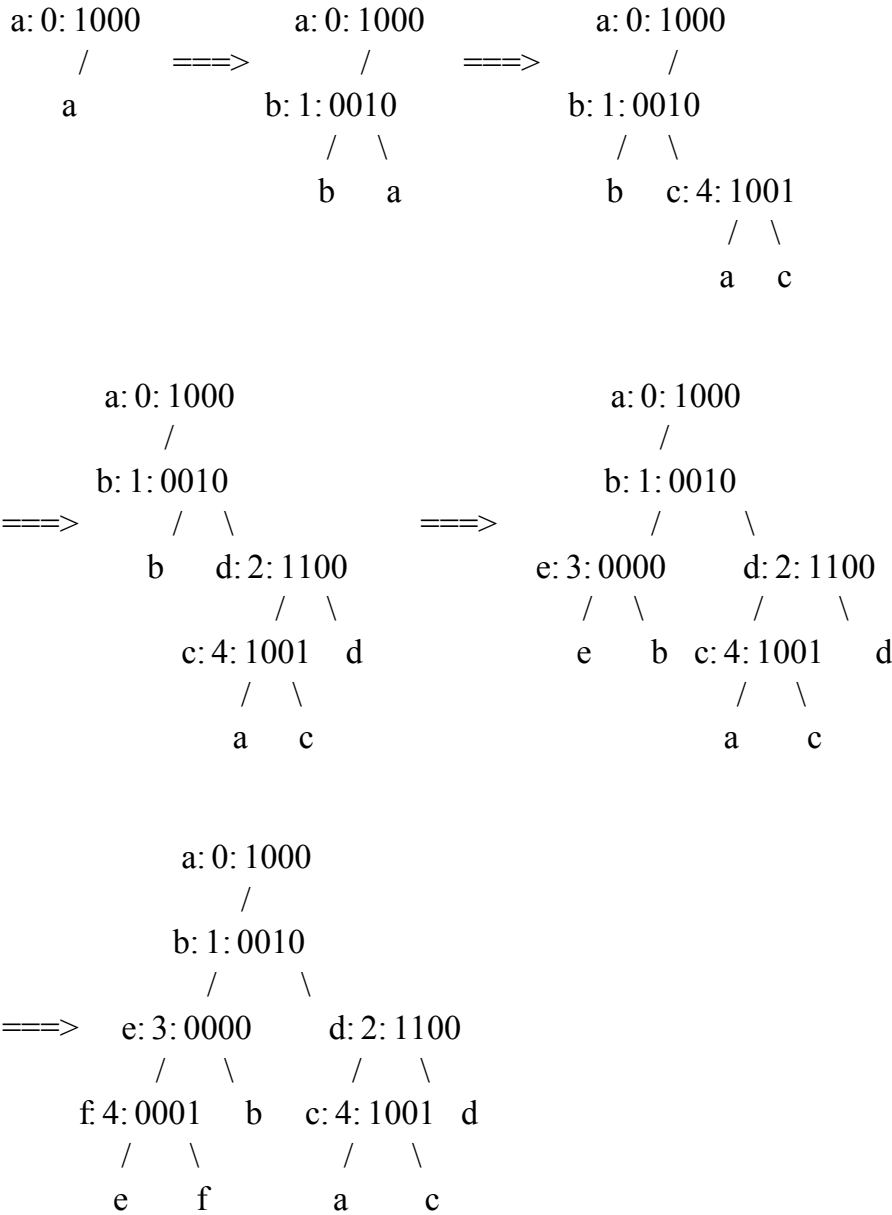


Sample Solution - Sample 2, Exam 3

1.

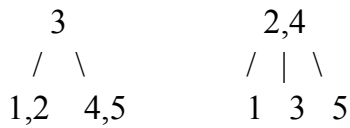


2.

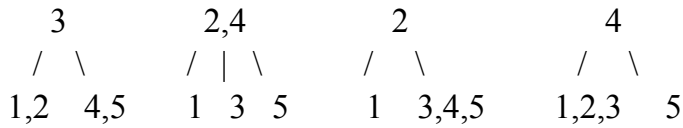
- (a) Searching for the insertion position takes h accesses (when the key is not there). We need h splits as we go back up the tree (cascading split in worst case). Each split takes 2 disk accesses (to write the new nodes). When we get back to the root and split it, there are 3 accesses: 2 for splitting the node (already accounted for) and 1 for writing the new root.

Therefore, the total number of disk accesses is $h + 2h + 1 = 3h + 1$.

(b) B-trees of order 3:



B-trees of order 4:



3.

```

insert(key) {
    key = concatenate(key, ' ');
    **p = &root;
    int i = 1;
    for( ; p is a branch node; p = &((*p)->link[c]). i++) {
        c = ith character of key;
    }
    if(*p == NULL) *p = new node(key);
    else {
        if(p->key == key) return;
        else {
            *temp = *p;
            *p = NULL;
            for ( ; p = &((*p)->link[c], i++) {
                *p = new branch_node( );
                c = ith character of key;
                c2 = ith character of temp->key;
                if(c != c2) {
                    (*p)->link[c] = new node(key);
                    (*p)->link[c2] = new node(temp->key);
                }
            }
            return;
        }
    }
}
  
```

4.

(a) Suffix Tree:

The problem of determining if string P is a substring of S is handled by:
 build a suffix tree from S and then search for P in the suffix tree (upto
 depth | P |).

(b) Bloom Filter:

A database master file is too large to fit in memory, so a differential file

is often used. A bloom filter avoids search time between the files by attempting to answer the question: "is the key present in the differential file?". The bloom filter will give 1 of 2 answers to the posed question: No or maybe.

(c) Quad Tree:

For image processing we need to look at points in space. A quad tree helps build relevant boundaries around points(cells) allowing for fast processing.

5. Followings are used for parts (a) and (b):

let m = memory in the system

let x = memory size

let y = address of memory

since we cannot repeat values, we use a transformation function,

$x = (\text{size of memory request}) * m + \text{memory address}.$

(a) Describe a best-fit scheme:

min x in rectangle (L , R , top) min to the left

(b) Describe a first-fit scheme:

min y in rectangle range(x_0 , x_1) bottom most point