

National Institute of Technology, Delhi

Name of the Examination: B. Tech.

Branch : B.Tech (ECE)

Semester : VI

Title of the Course : Digital Signal Processing

Course Code : ECB 352

Time: 3 Hours

Maximum Marks: 50

Note : Attempt all questions from Section-A, any four questions from Section-B and any two questions from Section-C.

SECTION- A [10 X 1 = 10 MARKS]

- A.1 What is Gibbs phenomenon?
 A.2 Define ROC.
 A.3 State initial and final value theorem of Z-transform.
 A.4 Determine whether the given system is causal or stable or both?

$$H(z) = \frac{3+z^{-1}}{1+z^{-1}-\frac{4}{9}z^{-2}}$$

- A.5 What is frequency warping?
 A.6 Find the energy of the given discrete time signal.

$$x(n) = \begin{cases} 4n^2 & 1 \leq n \leq 3 \\ 0 & \text{otherwise} \end{cases}$$

- A.7 Give the classification of discrete-time signals with example.
 A.8 Find the linear convolution using graphical method only.

$$x(n) = 2\delta(n+1) + \delta(n-2)$$

$$h(n) = 2^n, \quad \text{for } -1 \leq n \leq 1$$

 A.9 Compare the Impulse invariant method and bilinear transformation method of IIR digital filter design.
 A.10 Determine the inverse Z-transform of $X(z) = 2 + 3z^{-1} + 4z$.

SECTION- B [4 X 5 = 20 MARKS]

- B.1 Realize the following system function in (a) Direct form (b) Cascade form

$$H(z) = 1 + \frac{3}{4}z^{-1} + \frac{17}{8}z^{-2} + \frac{3}{4}z^{-3} + z^{-4}$$

- B.2 A system function is specified by its transfer function H(z) given by,

$$H(z) = \frac{z(z-1)(z-2)(z+1)}{\left[z - \left(\frac{1}{2} + j\frac{1}{2}\right)\right] \left[z - \left(\frac{1}{2} - j\frac{1}{2}\right)\right] \left(z - \frac{j}{4}\right) \left(z + \frac{j}{4}\right)}$$

Realize the system function in direct form-II.

- B.3** (a) State and proof circular time shift property of DFT.
 (b) If $X(k)$ is four point DFT of $x(n) = \{1, 2, 3, 4\}$, then without performing DFT and IDFT, determine the signal values which has DFT $X(k-2)$.
- B.4** Find the linear convolution of the sequence $x(n)$ and $h(n)$ using DFT
 $x(n) = \{1, 0, 2\}$ & $h(n) = \{1, 1\}$
- B.5** Find the Z-transform and ROC of
 $x(n) = 2 \left(\frac{5}{6}\right)^n u(-n-1) + 3 \left(\frac{1}{2}\right)^n u(n)$
 Sketch the ROC and pole-zero location.

SECTION- C [2 X 10 = 20 MARKS]

- C.1** Design an linear phase FIR filter using Kaiser window to meet the following specification:

$$0.98 \leq |H(e^{j\omega})| \leq 1.02, \quad 0 \leq |\omega| \leq 0.19\pi$$

$$|H(e^{j\omega})| \leq 0.01, \quad 0.21 \leq |\omega| \leq \pi$$
- C.2** Design the symmetric FIR low pass digital filter whose desired frequency response is given as

$$H_d(\omega) = \begin{cases} e^{-j\omega\tau}, & \text{for } |\omega| \leq 1 \\ 0, & \text{otherwise} \end{cases}$$

 The length of the filter is 7. Use Hanning window function.
- C.3** (a) Convert analog system function into digital system function using impulse invariant method.

$$H(s) = \frac{1}{(s+1)(s^2+s+2)}$$
- (b) Convert analog system function into digital system function using bilinear transformation method. The digital filter have the resonant frequency $\pi/2$.

$$H(s) = \frac{s+0.4}{(s+0.4)^2 + 4}$$