

# Computer Science & Information Systems

## DEEP NEURAL NETWORKS - LAB SHEET 5

### DEEP FEED-FORWARD NEURAL NETWORK FOR REGRESSION

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## 1 Objective

The objective is to

- Understand deep feed-forward neural networks (DFNN) with multiple hidden layers.
- Implement forward propagation, backpropagation, and mini-batch SGD from scratch.
- Apply ReLU activation for hidden layers and identity activation for output.
- Use Mean Squared Error (MSE) loss for regression tasks.
- Predict hourly bike rental demand using Seoul Bike Sharing dataset.
- Implement He initialization and early stopping techniques.

## 2 Steps to be Performed

- **Tool:** Python3
- **Libraries required:** numpy, matplotlib, pandas, sklearn
- **Input:** Seoul Bike Sharing Demand Dataset (UCI repository)
- **Deep Learning Model:** Deep Feed-Forward Neural Network (DFNN)
- **ANN Architecture:** Multi-layer network [17, 64, 32, 16, 1] with ReLU hidden layers
- **Implementation:** L5\_DFNN\_for\_Regression.ipynb

### 2.1 Steps

- Import required Python libraries (numpy, pandas, matplotlib, sklearn).
- Load the Seoul Bike Sharing Demand dataset (8,760 samples, 17 features).
- Understand the problem: Regression task to predict continuous bike rental count.
- Explore data: Visualize distribution, check for missing values, analyze features.
- Prepare the data: Extract features (weather, temporal) and target (bike count).

- Encode categorical variables: One-hot encode seasons, binary encode holiday/functioning day.
- Partition dataset into training (90%), validation (5%), and testing (5%) sets.
- Standardize features using StandardScaler (zero mean, unit variance).
- Standardize target variable for better optimization convergence.
- Define network architecture: 4 layers [17, 64, 32, 16, 1].
- Initialize parameters using He initialization for ReLU:  $W^{(\ell)} \sim \mathcal{N}(0, \sqrt{2/n_{\ell-1}})$ .
- Implement forward propagation with ReLU for hidden layers and identity for output.
- Compute Mean Squared Error (MSE) loss.
- Implement backpropagation using chain rule for gradient computation.
- Train model using mini-batch SGD with batch size 64.
- Apply early stopping: monitor validation loss, stop if no improvement for 15 epochs.
- Predict bike rental counts on test set.
- Inverse transform predictions to original scale.
- Compute evaluation metrics: MSE, RMSE, MAE,  $R^2$  score.
- Visualize training history (loss curves for train and validation).
- Generate predictions vs actual plots and residual analysis.
- Analyze feature importance using first layer weights.

## 2.2 Mathematical Formulation

### Network Architecture

$$\text{Input Layer: } \mathbf{x} \in \mathbb{R}^{17} \quad (1)$$

$$\text{Hidden Layer 1: } \mathbf{a}^{(1)} = \text{ReLU}(\mathbf{W}^{(1)}\mathbf{x} + \mathbf{b}^{(1)}), \quad \mathbf{a}^{(1)} \in \mathbb{R}^{64} \quad (2)$$

$$\text{Hidden Layer 2: } \mathbf{a}^{(2)} = \text{ReLU}(\mathbf{W}^{(2)}\mathbf{a}^{(1)} + \mathbf{b}^{(2)}), \quad \mathbf{a}^{(2)} \in \mathbb{R}^{32} \quad (3)$$

$$\text{Hidden Layer 3: } \mathbf{a}^{(3)} = \text{ReLU}(\mathbf{W}^{(3)}\mathbf{a}^{(2)} + \mathbf{b}^{(3)}), \quad \mathbf{a}^{(3)} \in \mathbb{R}^{16} \quad (4)$$

$$\text{Output Layer: } \hat{y} = \mathbf{W}^{(4)}\mathbf{a}^{(3)} + \mathbf{b}^{(4)}, \quad \hat{y} \in \mathbb{R} \quad (5)$$

### Activation Functions

$$\text{ReLU (Hidden Layers): } f(z) = \max(0, z) \quad (6)$$

$$\text{ReLU Derivative: } f'(z) = \begin{cases} 1 & \text{if } z > 0 \\ 0 & \text{otherwise} \end{cases} \quad (7)$$

$$\text{Identity (Output): } f(z) = z, \quad f'(z) = 1 \quad (8)$$

## Loss Function

$$\text{Mean Squared Error: } J(\Theta) = \frac{1}{2N} \sum_{i=1}^N (\hat{y}^{(i)} - y^{(i)})^2 \quad (9)$$

where  $\Theta = \{\mathbf{W}^{(1)}, \mathbf{b}^{(1)}, \mathbf{W}^{(2)}, \mathbf{b}^{(2)}, \mathbf{W}^{(3)}, \mathbf{b}^{(3)}, \mathbf{W}^{(4)}, \mathbf{b}^{(4)}\}$ .

## Forward Propagation (Vectorized for Mini-batch)

$$\mathbf{Z}^{(1)} = \mathbf{X}\mathbf{W}^{(1)} + \mathbf{b}^{(1)} \quad (\text{Linear transformation}) \quad (10)$$

$$\mathbf{A}^{(1)} = \text{ReLU}(\mathbf{Z}^{(1)}) \quad (\text{Non-linear activation}) \quad (11)$$

$$\mathbf{Z}^{(2)} = \mathbf{A}^{(1)}\mathbf{W}^{(2)} + \mathbf{b}^{(2)} \quad (12)$$

$$\mathbf{A}^{(2)} = \text{ReLU}(\mathbf{Z}^{(2)}) \quad (13)$$

$$\mathbf{Z}^{(3)} = \mathbf{A}^{(2)}\mathbf{W}^{(3)} + \mathbf{b}^{(3)} \quad (14)$$

$$\mathbf{A}^{(3)} = \text{ReLU}(\mathbf{Z}^{(3)}) \quad (15)$$

$$\mathbf{Z}^{(4)} = \mathbf{A}^{(3)}\mathbf{W}^{(4)} + \mathbf{b}^{(4)} \quad (16)$$

$$\hat{\mathbf{Y}} = \mathbf{Z}^{(4)} \quad (\text{Identity activation}) \quad (17)$$

where  $\mathbf{X} \in \mathbb{R}^{B \times 17}$  is a mini-batch of  $B$  samples.

## Backpropagation (Gradient Computation)

### Output Layer Gradient:

$$\frac{\partial J}{\partial \mathbf{Z}^{(4)}} = \frac{1}{B}(\hat{\mathbf{Y}} - \mathbf{Y}) \quad (18)$$

$$\frac{\partial J}{\partial \mathbf{W}^{(4)}} = (\mathbf{A}^{(3)})^T \frac{\partial J}{\partial \mathbf{Z}^{(4)}} \quad (19)$$

$$\frac{\partial J}{\partial \mathbf{b}^{(4)}} = \sum_{i=1}^B \frac{\partial J}{\partial z_i^{(4)}} \quad (20)$$

### Hidden Layer 3 Gradient:

$$\frac{\partial J}{\partial \mathbf{A}^{(3)}} = \frac{\partial J}{\partial \mathbf{Z}^{(4)}} (\mathbf{W}^{(4)})^T \quad (21)$$

$$\frac{\partial J}{\partial \mathbf{Z}^{(3)}} = \frac{\partial J}{\partial \mathbf{A}^{(3)}} \odot f'(\mathbf{Z}^{(3)}) \quad (\text{Element-wise ReLU derivative}) \quad (22)$$

$$\frac{\partial J}{\partial \mathbf{W}^{(3)}} = (\mathbf{A}^{(2)})^T \frac{\partial J}{\partial \mathbf{Z}^{(3)}} \quad (23)$$

$$\frac{\partial J}{\partial \mathbf{b}^{(3)}} = \sum_{i=1}^B \frac{\partial J}{\partial z_i^{(3)}} \quad (24)$$

**Hidden Layer 2 Gradient:**

$$\frac{\partial J}{\partial \mathbf{A}^{(2)}} = \frac{\partial J}{\partial \mathbf{Z}^{(3)}} (\mathbf{W}^{(3)})^T \quad (25)$$

$$\frac{\partial J}{\partial \mathbf{Z}^{(2)}} = \frac{\partial J}{\partial \mathbf{A}^{(2)}} \odot f'(\mathbf{Z}^{(2)}) \quad (26)$$

$$\frac{\partial J}{\partial \mathbf{W}^{(2)}} = (\mathbf{A}^{(1)})^T \frac{\partial J}{\partial \mathbf{Z}^{(2)}} \quad (27)$$

$$\frac{\partial J}{\partial \mathbf{b}^{(2)}} = \sum_{i=1}^B \frac{\partial J}{\partial z_i^{(2)}} \quad (28)$$

**Hidden Layer 1 Gradient:**

$$\frac{\partial J}{\partial \mathbf{A}^{(1)}} = \frac{\partial J}{\partial \mathbf{Z}^{(2)}} (\mathbf{W}^{(2)})^T \quad (29)$$

$$\frac{\partial J}{\partial \mathbf{Z}^{(1)}} = \frac{\partial J}{\partial \mathbf{A}^{(1)}} \odot f'(\mathbf{Z}^{(1)}) \quad (30)$$

$$\frac{\partial J}{\partial \mathbf{W}^{(1)}} = \mathbf{X}^T \frac{\partial J}{\partial \mathbf{Z}^{(1)}} \quad (31)$$

$$\frac{\partial J}{\partial \mathbf{b}^{(1)}} = \sum_{i=1}^B \frac{\partial J}{\partial z_i^{(1)}} \quad (32)$$

**Parameter Update (Mini-batch SGD)**

$$\mathbf{W}^{(\ell)} := \mathbf{W}^{(\ell)} - \eta \frac{\partial J}{\partial \mathbf{W}^{(\ell)}}, \quad \ell = 1, 2, 3, 4 \quad (33)$$

$$\mathbf{b}^{(\ell)} := \mathbf{b}^{(\ell)} - \eta \frac{\partial J}{\partial \mathbf{b}^{(\ell)}}, \quad \ell = 1, 2, 3, 4 \quad (34)$$

where  $\eta$  is the learning rate (typically 0.001).

**Evaluation Metrics**

$$\text{MSE} = \frac{1}{N} \sum_{i=1}^N (y^{(i)} - \hat{y}^{(i)})^2 \quad (35)$$

$$\text{RMSE} = \sqrt{\text{MSE}} \quad (36)$$

$$\text{MAE} = \frac{1}{N} \sum_{i=1}^N |y^{(i)} - \hat{y}^{(i)}| \quad (37)$$

$$R^2 = 1 - \frac{\sum_{i=1}^N (y^{(i)} - \hat{y}^{(i)})^2}{\sum_{i=1}^N (y^{(i)} - \bar{y})^2} \quad (38)$$

**3 Results**

- Deep feed-forward neural network successfully trained with 4 layers.

- Total parameters: 3,777 (significantly more capacity than linear regression).
- Model achieved Test RMSE  $\approx 335$  bikes/hour on Seoul bike dataset.
- Test MAE  $\approx 238$  bikes/hour indicates average prediction error.
- Test  $R^2$  score  $\approx 0.72$  shows model explains 72% of variance.
- Training converged in  $\approx 50$ -60 epochs with early stopping.
- Validation loss decreased smoothly, indicating no overfitting.
- ReLU activation prevented vanishing gradient problem in deep network.
- He initialization enabled stable training from the start.
- Mini-batch SGD (batch size 64) balanced speed and stability.
- Model predictions closely follow actual demand patterns.
- Feature importance analysis shows Solar Radiation and Wind Speed as top predictors.

## 4 Observation

- Multiple hidden layers enable learning of complex non-linear relationships.
- DFNN significantly outperforms linear regression on this dataset.
- ReLU activation is computationally efficient and prevents vanishing gradients.
- Identity activation in output layer allows continuous value predictions.
- Backpropagation efficiently computes gradients through multiple layers using chain rule.
- Mini-batch SGD provides good balance: faster than batch GD, more stable than SGD.
- Feature standardization is critical for fast and stable convergence in deep networks.
- Early stopping prevents overfitting by monitoring validation loss.
- He initialization (designed for ReLU) maintains gradient scale through layers.
- Progressive dimensionality reduction ( $17 \rightarrow 64 \rightarrow 32 \rightarrow 16 \rightarrow 1$ ) works well for this problem.
- Model captures temporal patterns (hour of day) and weather dependencies effectively.
- Residual plot shows relatively random scatter, indicating good model fit.
- Deeper networks require more careful hyperparameter tuning than shallow models.
- Network provides hierarchical feature learning: low  $\rightarrow$  mid  $\rightarrow$  high level patterns.
- Model suitable for smart city applications requiring real-time demand prediction.

## 5 Key Differences from Linear Regression

- **Architecture:** Multiple hidden layers vs single layer.
- **Non-linearity:** ReLU activations vs no activation (identity only).
- **Capacity:** 3,777 parameters vs  $\approx 18$  parameters.
- **Learning:** Backpropagation through layers vs direct gradient.
- **Expressiveness:** Can model complex non-linear functions vs linear only.
- **Training time:** Longer training but better performance.
- **Initialization:** He initialization critical for deep networks.
- **Optimization:** Mini-batch SGD with early stopping vs simple GD.

## 6 Applications

- **Smart Cities:** Real-time bike-sharing demand prediction and rebalancing.
- **Transportation:** Traffic flow prediction, ride-sharing demand forecasting.
- **Energy:** Electricity load forecasting, renewable energy prediction.
- **Finance:** Stock price prediction, portfolio optimization.
- **Healthcare:** Patient readmission prediction, treatment response modeling.
- **Retail:** Sales forecasting, inventory optimization.
- **Manufacturing:** Predictive maintenance, quality control.
- **Weather:** Temperature prediction, precipitation forecasting.