## Machine Learning using GPGPU

Logistic Regression, Multi-Layer Perceptron, Convolutional Neural-Net

#### Final Project report for

# Advanced Computer Architecture (ECEN 5593)

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## Table of Contents

Introduction	3
History	3
Analysis – Open Source Development platforms	4
Machine Learning Techniques used in the scope of this project	4
Softmax	4
Cost function/ Loss Function	6
How to Train the model?	6
Stochastic Gradient Descent	7
Loading the Data set	8
CUDA Shared Variable	8
How to not over-fit the model with training dataset?	8
How to load/save the pre trained model?	8
Machine Learning Algorithms Implemented	9
Logistic Regression	9
Multi-Layer Perceptron (MLP)	9
Convolutional Neural Network	10
Implementation	11
Platform	11
NVidia Jetson TK1 (Tegra)	11
Janus – GPU Node	12
Results	13
Quad core ARM Cortex A15 CPU	13
Quad core ARM Cortex A15 CPU + Kepler GPU	13
12 Core Intel Xeon 5660 CPU	13
12 Core Intel Xeon 5660 CPU + NVIDIA Tesla M2070 GPU	13
Analysis	14
Future Development	14
Codes	15
Logistic Regression	15
Multi Layer Perceptron	20
Convolutional Neural Net	24

#### Introduction

In 1959 Arthur Samuel defined machine learning as a field of study that gives computers the ability to learn without being explicitly programmed<sup>1</sup>.

Machine Learning has evolved over the years and the accuracy rate started surpassing the human error rate. It's all because of the evolution in computational power of the devices and open sourced libraries. Without knowing we are using machine learning and artificial intelligence applications in our day to day life. Google uses machine learning algorithms to search content according the user. Facebook uses its algorithms to show customized ads on our wall according to user preference.

Machine learning became so popular because of its capability to learn things from the wide range of datasets. In simple words this is like teaching something to a kid from the scratch. More the training more the accuracy is. Since it is handling gigabytes of data to train the model it needs lot of computing power to train it fast. Typically, it takes days to train a convolutional neural network in CPUs to get the accuracy to surpass the human error rate. Machine learning is nothing but a set of mathematical equations running on a dataset and updating the weights according to the labelled and predicted output. It can be generalized as a matrix operation.

The scope of this project is to implement the hand written code recognition using different machine learning algorithms such as Logistic Regression, Multi-Layer Perceptron and Convolutional Neural-net on different GPUs and CPUs. GPUs are efficient in doing Matrix (throughput) operations and CPUs are efficient in doing things fast(Latency). This project is all about the basic machine learning algorithms, implementation of algorithms in CPU/GPU and comparing the time taken for CPU/GPU to train a dataset.

## History

In 1950 – Alan Turing creates "Turing test" to determine if a computer has intelligence to fool a human into believing it as a human. In 1952 - Arthur Samuel wrote the first computer learning program for IBM to play the game of checkers. It improved the game by 0.37% for every game it played by studying the winning strategies and incorporating the strategies into its program. In 1957 – Frank Rosenblatt designed the first neural network(Perceptron) inspired by human brain. In 1967 – The "nearest neighbor" algorithm was written, this allows computer to recognize very basic pattern recognition. In 1979 - Stanford university students invented "Stanford Cart" which can navigate obstacles in a room on its own. In 1981 - Gerald Dejong introduces Explanation based Learning (EBL), analyses training data and creates general rule. In 1985 – Terry Sejnowski invents NetTalk, program which learns to pronounce words the same way baby does. In 1990-Knowledge driven approach to Data driven approach to draw conclusions. In 1997 – IBM's Deep Blue beats the world champion at chess. In 2006 – Geoffrey Hinton coins the term "Deep Learning". In 2010 - Microsoft Kinect can track human features at a rate of 30 times per second. In 2011 - IBM's Watson beats its human competitors at jeopardy, Google Brain was developed. In 2012 - Google's X lab develops an algorithm which automatically browse and detects cat videos in the youtube. In 2014 – Facebook develops Deepface, able to recognize individuals on photos. In 2015 – Over 3000 AI and Robotics researchers endorsed by Stephen Hawking, Elon Musk and Steve Wozniak Sign an open letter of the

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<sup>&</sup>lt;sup>1</sup> https://en.wikipedia.org/wiki/Machine\_learning

danger of autonomous weapons which select and engage targets without human intervention. In 2016 – Google's AlphaGo algorithm defeated the champion of Chinese board game Go.<sup>2</sup>

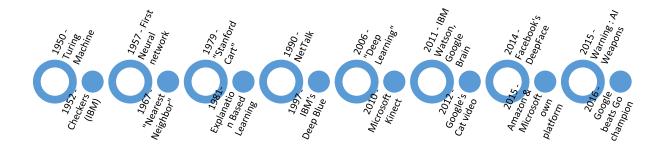


Figure 1: History of Machine Learning

### Analysis – Open Source Development platforms

The reason behind the progress in machine learning is because, most of the famous algorithms from big companies like Google and Facebook are open sourced. The tools that are used for machine learning (i.e) Libraries, Toolkits are open sourced. Google Open-Sourced its platform TensorFlow. Lot of libraries contributed by University of Berkeley(Caffe), University of Montreal(Theano), New York University(Torch). Since most of the algorithms are open sourced, it attracts the open source contributors to learn and contribute to the code. It is easy for the researchers to have progress in their research rather than keeping it proprietary.

This project is implemented using Theano (Python Library by University of Montreal). Theano has good documentation compared to other platforms.

## Machine Learning Techniques used in the scope of this project Softmax

This soft max equation helps normalizing the data. This softmax function acts as the activation link for the classifier. Each pixel data from the image is multiplied with its corresponding weights and the result is being computed using the softmax function.

$$\begin{split} P(Y = i | x, W, b) &= softmax_i(Wx + b) \\ &= \frac{e^{W_i x + b_i}}{\sum_j e^{W_j x + b_j}} \end{split}$$

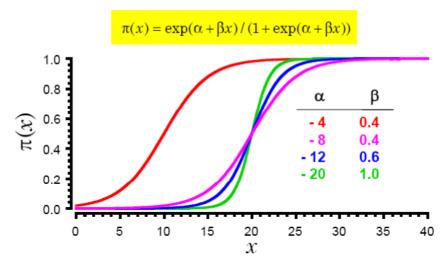
self.p\_y\_given\_x = T.nnet.softmax(T.dot(input, self.W) + self.b)

Surjith Bhagavath Singh

 $<sup>^2\</sup> http://www.forbes.com/sites/bernardmarr/2016/02/19/a-short-history-of-machine-learning-every-manager-should-read/\#5a1539ea323f$ 

## Parameters control shape and location of sigmoid curve

- α controls location of midpoint
- β controls slope of rise



When  $x = -\alpha/\beta$ ,  $\alpha + \beta x = 0$  and hence  $\pi(x) = 1/(1+1) = 0.5$ 

Figure 2: Softmax activation function

Each pixel has a corresponding weight associated with it. In mNIST Data, an image(dataset) looks like the figure shown below.

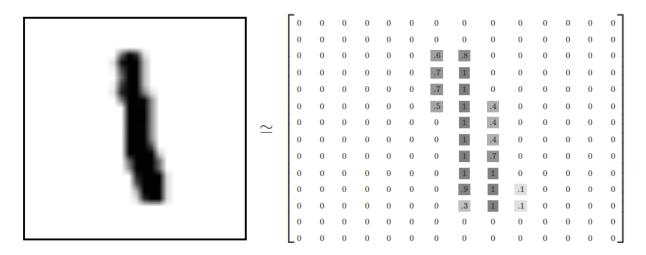


Figure 3: mNIST Dataset - sample dataset<sup>3</sup>

This entire 2 dimensional dataset is converted into one single vector for making the computation easier. We can flatten this array into a vector of 28x28 = 784 numbers ( $\mathcal{X}_i$ ). Our primary aim is to classify the hand written number codes which has numbers from 0 to 9. So it has 10 weight matrices( $W_{ij}$ ) with the

Surjith Bhagavath Singh

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<sup>&</sup>lt;sup>3</sup> https://www.tensorflow.org/versions/r0.7/images/MNIST-Matrix.png

dimension of the image set. Where i= 784 and j=10. Bias elements play an important role in designing the model. Even bias elements will be updated during the training.

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \text{softmax} \begin{bmatrix} \begin{bmatrix} W_{1,1} & W_{1,2} & W_{1,3} \\ W_{2,1} & W_{2,2} & W_{2,3} \\ W_{3,1} & W_{3,2} & W_{3,3} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

#### Cost function/ Loss Function

In order to train the model, some parameter has to be defined to check how good is the model. in machine learning it has been defined what it means for a model to be bad, called the cost or loss, and then try to minimize how bad it is. But the two are equivalent.

One very common, very nice cost function is "cross-entropy." Surprisingly, cross-entropy arises from thinking about information compressing codes in information theory but it winds up being an important idea in lots of areas, negative log likelihood,

Since the zero-one loss is not differentiable, optimizing it for large models (thousands or millions of parameters) is prohibitively expensive (computationally). We thus maximize the log-likelihood of our classifier given all the labels in a training set.

The likelihood of the correct class is not the same as the number of right predictions, but from the point of view of a randomly initialized classifier they are pretty similar. Remember that likelihood and zero-one loss are different objectives; you should see that they are correlated on the validation set but sometimes one will rise while the other falls, or vice-versa. Since we usually speak in terms of minimizing a loss function, learning will thus attempt to minimize the negative log-likelihood (NLL), defined as:<sup>4</sup>

$$NLL(\theta, \mathcal{D}) = -\sum_{i=0}^{|\mathcal{D}|} \log P(Y = y^{(i)}|x^{(i)}, \theta)$$

This is the parameter which decides whether to update the weight or not. This parameter tells how good/bad the model is. The code snippet for this function in Theano is.

$$NLL = -T.sum(T.log(p_y_given_x)[T.arange(y.shape[0]), y])$$

#### How to Train the model?

All the trick is there in the weight matrix, How do we initialize the weight matrix? Here in my implementation I have initialized it to random numbers. So for the first dataset it checks for the y1 value and it compares with the label. If that matches it would not update the weights for it. If it doesn't it will

Surjith Bhagavath Singh

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<sup>&</sup>lt;sup>4</sup> http://deeplearning.net/tutorial/deeplearning.pdf

increment the weight matrix by a small factor, so during the training it can reach an optimal point where it can converge and give accurate results. Here comes the cost function.

#### Stochastic Gradient Descent<sup>5</sup>

It is a simple algorithm in which we repeatedly make small steps downward on an error surface defined by a loss function of some parameters. For the purpose of ordinary gradient descent we consider that the training data is rolled into the loss function. Then the pseudocode of this algorithm can be described as:

```
# GRADIENT DESCENT
while True:
      loss = f(params)
      d_loss_wrt_params = ... # compute gradient
      params -= learning_rate * d_loss_wrt_params
      if <stopping condition is met>:
            return params
```

Stochastic gradient descent (SGD) works according to the same principles as ordinary gradient descent, but proceeds more quickly by estimating the gradient from just a few examples at a time instead of the entire training set. In its purest form, we estimate the gradient from just a single example at a time:

```
#STOCHASTIC GRADIENT DESCENT
for (x_batch,y_batch) in train_batches:
      # imagine an infinite generator
      # that may repeat examples
      loss = f(params, x batch, y batch)
      d_loss_wrt_params = ... # compute gradient using theano
      params -= learning_rate * d_loss_wrt_params
      if <stopping condition is met>:
            return params
```

<sup>&</sup>lt;sup>5</sup> This section is taken from http://deeplearning.net/tutorial/deeplearning.pdf

There is a tradeoff in the choice of the minibatch size B. The reduction of variance and use of SIMD instructions helps most when increasing B from 1 to 2, but the marginal improvement fades rapidly to nothing. With large B, time is wasted in reducing the variance of the gradient estimator, that time would be better spent on additional gradient steps. An optimal B is model-, dataset-, and hardware-dependent, and can be anywhere from 1 to maybe several hundreds. In the tutorial we set it to 20, but this choice is almost arbitrary.

#### Loading the Data set

This is the code snippet for loading the modified NIST Data for hand written code recognition.

```
import cPickle, gzip, numpy

# Load the dataset

f = gzip.open('mnist.pkl.gz', 'rb')

train_set, valid_set, test_set = cPickle.load(f)

f.close()
```

#### **CUDA Shared Variable**

In order to make the memory access fast, the data has to be there in the shared memory with faster access. Else the entire time will be wasted in copying data back and forth from GPU to CPU. This "theano.shared" function helps theano optimize the code for GPU implementation.

#### How to not over-fit the model with training dataset?

When we have to stop training the model? Early stopping stops the model from over-fitting to the training data set. It validates the dataset from the validation set, which is not involved in training. It doesn't involve in any gradient descent. There is a possibility for improvement as well as decline in the performance. It properly handles when to increase geometrically the patience to train the dataset.

#### How to load/save the pre trained model?

It takes hours to train the big model like convolutional neural net. There is a simple way to load/save the weights in python. There is a library called cPickle in python, which makes this task simpler. Here is a code snippet for this operation

```
#To save the weights w
import cPickle
save_file = open('path', 'wb')
cPickle.dump(w.get_value(borrow=True), save_file, -1)
#To load the weights w
import cPickle
save_file = open('path')
w.set_value(cPickle.load(save_file), borrow=True)
```

## Machine Learning Algorithms Implemented

#### Logistic Regression

This is the straight forward probabilistic mathematical model, it has an input layer and an output layer. No intermediate hidden layers. This makes the model simpler and it can achieve an accuracy of 94% over 75 epochs.

Entire image is converted into a single vector an acts as an input layer for this model. Weight matrix of order 784\*10, is multiplied with the input vector of order 1\*784. The results are fed into the activation function (Softmax) to give a binary result.

The weights are updated by stochastic gradient descent method mentioned above. Detailed diagram can be found below.

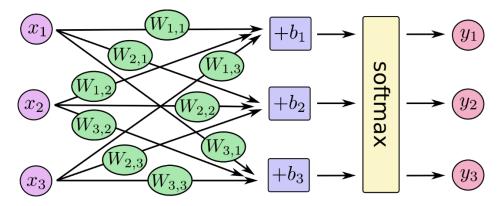


Figure 4: Logistic Regression Model<sup>6</sup>

#### Multi-Layer Perceptron (MLP)

This model is similar to logistic regression model but it has few hidden layers, which makes it improve the accuracy of the results. As the number of layer increases, accuracy increases. Because it can store lot more weights and the model becomes intelligent enough to store more details.

Surjith Bhagavath Singh

<sup>&</sup>lt;sup>6</sup> https://www.tensorflow.org/versions/r0.7/tutorials/mnist/beginners/index.html

This has an input layer, output layer and few hidden layers. Training time increases as the number of layer increases. Weights are updated according to stochastic gradient descent (SGD). Detailed diagram can be found below.

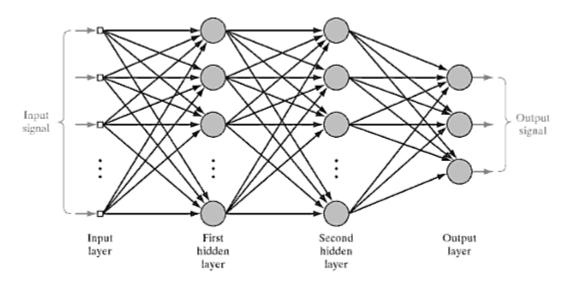


Figure 5: Multi-layer perceptron model (MLP)<sup>7</sup>

#### Convolutional Neural Network<sup>8</sup>

This model is the combination of the above mentioned models and a little bit of modification. Instead of calculating every pixel, this does the feature extraction using Convolution. It has five layers in it. Input layer, Convolution Layer, Sub Sample Layer and Fully Connected Layer.

INPUT [28\*28] will hold the raw pixel values of the image, in this case an image of width 28, height 28.

CONV layer will compute the output of neurons that are connected to local regions in the input, each computing a dot product between their weights and the region they are connected to in the input volume. Then the layer is sub sampled .

CONV layer will compute the output of neurons that are connected to local regions in the first convolutional layer, each computing a dot product between their weights and the region they are connected to in the previous layers volume. This has been sub sampled and the sub sample results in (10\*10).

FC (i.e. fully-connected) layer will compute the class scores, resulting in volume of size [1x1x10], where each of the 10 numbers correspond to a class score, such as among the 10 categories of MNIST. As with ordinary Neural Networks and as the name implies, each neuron in this layer will be connected to all the numbers in the previous volume.

<sup>&</sup>lt;sup>7</sup> https://elogeel.files.wordpress.com/2010/05/050510 1627 multilayerp1.png

<sup>8</sup> http://cs231n.github.io/convolutional-networks/#case

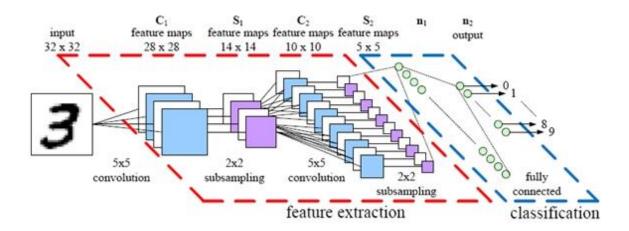


Figure 6: Convolutional Neural Network – Sample Model<sup>9</sup>

#### Implementation

These machine learning algorithms are implemented in two platforms CPU and GPGPU in Server node(Janus) and Embedded platform(NVidia Jetson — TK1). Both uses the same code. In this implementation Theano libraries are used for doing mathematical operations. Theano uses numpy libraries for matrix operations, which is the most optimized library. GPUs are good at doing floating point matrix operations. Theano has backend support of CUDA and it generates CUDA code for GPU operations. The implementation and platform details are mentioned below.

#### Platform

Two different platforms are chosen for the implementation of these models. Mobile-Embedded platform (NVidia Jetson) and Super Computer node (Janus). Reason for choosing two extreme platforms is to explore and compare their performances for these complex machine learning algorithms.

#### NVidia Jetson TK1 (Tegra) 10

This development kit is a famous SoC mobile embedded platform with an ARM Cortex A15 Quadcore CPU with 192 core Kepler GPU with a clock of 2.3GHz. This core is used in Google Nexus 7 tablet. It is a powerful and power efficient SoC suitable for mobile phone chips. The capacity of this machine is 300 GFLOPS(Maximum)<sup>11</sup> according to its datasheet specifications. It has on 16 GB 4.51 eMMC Memory. It has a 2 GB RAM Memory with 64-bit Width. Theano flags for CPU/GPU

<sup>&</sup>lt;sup>9</sup> http://parse.ele.tue.nl/cluster/2/CNNArchitecture.jpg

<sup>&</sup>lt;sup>10</sup> http://www.nvidia.com/object/jetson-tk1-embedded-dev-kit.html

<sup>&</sup>lt;sup>11</sup> FLOPS\_CPU = (CPU speed in Hz) x (number of CPU cores) x (CPU instruction per cycle) x (number of CPUs per node)

THEANO\_FLAGS=mode=FAST\_RUN,device=cpu,floatX=float32 python mlp.py
THEANO FLAGS=mode=FAST RUN,device=gpu,floatX=float32 python mlp.py

#### Janus<sup>12</sup> – GPU Node<sup>13</sup>

Janus is a super computer available for all CU Students and it is one of the powerful computers in Central America. It boasts the capabilities of having a 12 core Intel Xeon X5660 State of the art CPU(For each node) and a State of the art 448 core NVIDIA Tesla GPU with a clock of 2.8GHz. The capacity of the node is 649 GFLOPS. <sup>14</sup> It has 1368 Compute nodes, It's overall capacity is 184 TFLOPS. It has 24GB RAM per node.

A set of packages has to be loaded in order to run the program.

ml intel

ml CUDA/7.0.28

ml python/2.7.3

ml numpy

ml scipy

ml slurm

These packages are needed for the super computer node to run the program file. The shell script to run in the GPU/ CPU has been attached below.

#!/bin/bash

#SBATCH --nodes 1

#SBATCH --output hello-world.out

#SBATCH -- qos gpu

#SBATCH --partition crc-gpu

export

PYTHONPATH=\$PYTHONPATH:/projects/subh6068/python\_packages/lib/python2.7/site-packages

export CUDA\_ROOT=\$CUDA\_ROOT:/curc/tools/x86\_64/rh6/software/cuda/7.0.28
export

LD\_LIBRARY\_PATH=\$LD\_LIBRARY\_PATH:/curc/tools/x86\_64/rh6/software/cuda/7.0.28/lib

THEANO\_FLAGS=mode=FAST\_RUN,device=gpu,floatX=float32 python mlp.py

<sup>12</sup> https://www.rc.colorado.edu/resources/compute/janus

<sup>&</sup>lt;sup>13</sup> https://www.rc.colorado.edu/resources/compute/gpunodes

<sup>&</sup>lt;sup>14</sup> FLOPS\_GPU= no of cores \* no of SIMD units \* ((no of mul-add units\*2) + ( no of mul units)) \* clock speed in Hz

```
#!/bin/bash
#SBATCH --nodes 1
#SBATCH --output mlp-cpu.out
#SBATCH --qos janus-compile
export
PYTHONPATH=$PYTHONPATH:/projects/subh6068/python_packages/lib/python2.7/site-packages
export CUDA_ROOT=$CUDA_ROOT:/curc/tools/x86_64/rh6/software/cuda/7.0.28
export
LD_LIBRARY_PATH=$LD_LIBRARY_PATH:/curc/tools/x86_64/rh6/software/cuda/7.0.28/lib
THEANO_FLAGS=mode=FAST_RUN,device=cpu,floatX=float32_python_mlp.py
```

#### Results

#### Quad core ARM Cortex A15 CPU

The logistic regression algorithm has been implemented in this processor, using CPU only flag in Jetson and the results are pretty slow compared to other platforms. It took so long to train the other models. It took 128 Seconds to train the Logistic regression model and it can be able to achieve 92.5% accuracy in validation. Capacity of this CPU - 27 GFLOPs

#### Quad core ARM Cortex A15 CPU + Kepler GPU

This combination is powerful and it can be compared with the super computer nodes. All three algorithms are trained using this combination using GPU flags in Theano. It took 74 seconds to train the Logistic Regression model, 390 minutes for Multi-Layer Perceptron and 183.19 minutes for Convolutional neural net. It can be able to achieve 92.5% accuracy in logistic Regression, 98.3% in Multi-Layer Perceptron and 99.1% accuracy in Convolutional Neural net model. Capacity of this SoC – 300 GFLOPs

#### 12 Core Intel Xeon 5660 CPU

This processor is superfast compared to the ARM processor. All three algorithms are trained using this CPU using CPU flags in Theano. It took 12.2 seconds to train logistic Regression model, 75.21 minutes for Multi-layer perceptron and 148.93 minutes for convolutional neural net. It can be able to achieve 92.5% accuracy in logistic Regression, 98.3% in Multi-Layer Perceptron and 99.1 % accuracy in Convolutional Neural net model. Capacity of this Supercomputer node –134 GFLOPs

#### 12 Core Intel Xeon 5660 CPU + NVIDIA Tesla M2070 GPU

This is the high speed combo among all four. All three algorithms are trained using GPU flags in Theano. It took 10 seconds to train logistic Regression model, 85.7 minutes for Multi-layer perceptron and 38.89 minutes for convolutional neural net. It can be able to achieve 92.5% accuracy in logistic Regression, 98.3% in Multi-Layer Perceptron and 99.1 % accuracy in Convolutional Neural net model. Capacity of this Supercomputer node + GPU – 649 GFLOPs.

## **Analysis**

Comparative results of the entire implementation is tabulated and attached below. The reason for the fast training of CPU in Multi Layer perceptron model is because of not using shared variables, which means it makes the GPU performance poor. Processing time is less than data transferring time. CGMA is poor for that case. From the results it is clear that CPU+GPU Combination can achieve faster goal. Embedded platforms are capable enough and cost efficient.

	ARM® Cortex™- A15 CPU – Quadcore (Jetson SoC)	ARM® A15 + 192 NVIDIA Kepler CUDA Cores (Jetson SoC)	Intel® Xeon® X5660 – 12 core (Janus Node)	Intel® Xeon® X5660 + 448 NVIDIA Tesla CUDA Cores (Janus Node)
Operating Capacity	27 GFLOPS	300 GFLOPS	134 GFLOPS	649 GFLOPS
Cores	4 CPU cores	4 CPU + 192 GPU	12 CPU cores	12 CPU + 448 GPU
Logistic	128 seconds	74 seconds	12.2 seconds	10 seconds
Regression(75 epochs)	92.5% accurate	92.5% accurate	92.5% accurate	92.5%accurate
Multi Layer	No Patience to do	390.22 minutes	75.21 minutes	85.77 minutes
Perceptron(1000	this	98.3% accurate	98.3% accurate	98.3% accurate
Epoch)				
Convolutional	No Patience to do	183.19 minutes	148.93 minutes	38.89 minutes
Neural Net (200 epochs)	this	99.09% accurate	99.09% accurate	99.09% accurate

Table 1: Results

## Future Development

Implementing the same algorithms for different computer vision problem (Saliency) using machine learning, ultimate aim is to contribute for the research I am currently doing under Prof. Sam Siewert. I have taken this course as an opportunity to learn about the computer architecture and machine learning. The objective is achieved. The code has been uploaded in github<sup>15</sup> webpage for future development.

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<sup>&</sup>lt;sup>15</sup> https://github.com/surjithbs17/machinelearning

#### Codes

```
Logistic Regression
This code has been developed using the tutorial from deeplearning.net
Author: Surjith Bhagavath Singh
File Name: convolutional_mlp.py
from future import print function
__docformat__ = 'restructedtext en'
import six.moves.cPickle as pickle
import gzip
import os
import sys
import timeit
import numpy
import theano
import theano.tensor as T
class LogisticRegression(object):
    def init (self, input, n in, n out):
        self.W = theano.shared(
            value=numpy.zeros(
                (n_in, n_out),
                dtype=theano.config.floatX
            ),
            name='W',
            borrow=True
        self.b = theano.shared(
            value=numpy.zeros(
                (n out,),
                dtype=theano.config.floatX
            ),
            name='b',
            borrow=True
        )
        self.p y given x = T.nnet.softmax(T.dot(input, self.W) + self.b)
        self.y pred = T.argmax(self.p y given x, axis=1)
        self.params = [self.W, self.b]
        self.input = input
    def negative log likelihood(self, y):
        return -T.mean(T.log(self.p y given x)[T.arange(y.shape[0]), y])
```

```
def errors(self, y):
        if y.ndim != self.y pred.ndim:
            raise TypeError(
                'y should have the same shape as self.y pred',
                ('y', y.type, 'y pred', self.y pred.type)
        if y.dtype.startswith('int'):
            return T.mean(T.neq(self.y pred, y))
        else:
            raise NotImplementedError()
def load data(dataset):
    data_dir, data_file = os.path.split(dataset)
    if data dir == "" and not os.path.isfile(dataset):
        new path = os.path.join(
            os.path.split( file )[0],
            " . . " ,
            "data"
            dataset
        if os.path.isfile(new path) or data file == 'mnist.pkl.gz':
            dataset = new path
    if (not os.path.isfile(dataset)) and data file == 'mnist.pkl.gz':
        from six.moves import urllib
        origin = (
            'http://www.iro.umontreal.ca/~lisa/deep/data/mnist/mnist.pkl.gz'
        print('Downloading data from %s' % origin)
        urllib.request.urlretrieve(origin, dataset)
   print('... loading data')
    # Load the dataset
    with gzip.open(dataset, 'rb') as f:
            train set, valid set, test set = pickle.load(f,
encoding='latin1')
        except:
            train set, valid set, test set = pickle.load(f)
    def shared dataset(data xy, borrow=True):
        data x, data y = data xy
        shared x =
theano.shared(numpy.asarray(data x,dtype=theano.config.floatX),borrow=borrow)
        shared y =
theano.shared(numpy.asarray(data y,dtype=theano.config.floatX),borrow=borrow)
        return shared x, T.cast(shared y, 'int32')
    test set x, test set y = shared dataset(test set)
    valid set x, valid set y = shared dataset(valid set)
    train set x, train set y = shared dataset(train set)
```

```
rval = [(train set x, train set y), (valid set x, valid set y),
            (test set x, test set y)]
    return rval
def sqd optimization mnist(learning rate=0.13,
n epochs=1000,dataset='mnist.pkl.gz',batch size=600):
    datasets = load data(dataset)
    train set x, train set y = datasets[0]
    valid_set_x, valid_set_y = datasets[1]
    test set x, test set y = datasets[2]
    n train batches = train set x.get value(borrow=True).shape[0] //
batch size
    n valid batches = valid set x.get value(borrow=True).shape[0] //
batch size
    n test batches = test set x.get value(borrow=True).shape[0] // batch size
   print('... building the model')
    index = T.lscalar() # index to a [mini]batch
    x = T.matrix('x') \# data, presented as rasterized images
    y = T.ivector('y') # labels, presented as 1D vector of [int] labels
    classifier = LogisticRegression(input=x, n in=28 * 28, n out=10)
    cost = classifier.negative log likelihood(y)
    test model = theano.function(
        inputs=[index],
        outputs=classifier.errors(y),
        givens={
            x: test set x[index * batch size: (index + 1) * batch size],
            y: test set y[index * batch size: (index + 1) * batch size]
        }
    )
    validate model = theano.function(
        inputs=[index],
        outputs=classifier.errors(y),
        givens={
            x: valid set x[index * batch size: (index + 1) * batch size],
            y: valid set y[index * batch size: (index + 1) * batch size]
        }
    )
    g W = T.grad(cost=cost, wrt=classifier.W)
    g b = T.grad(cost=cost, wrt=classifier.b)
    updates = [(classifier.W, classifier.W - learning rate * g W),
               (classifier.b, classifier.b - learning rate * g b)]
    train model = theano.function(
        inputs=[index],
        outputs=cost,
        updates=updates,
```

```
givens={
        x: train set x[index * batch size: (index + 1) * batch size],
        y: train set y[index * batch size: (index + 1) * batch size]
    }
print('... training the model')
# early-stopping parameters
patience = 5000 # look as this many examples regardless
patience increase = 2 # wait this much longer when a new best is
                              # found
improvement threshold = 0.995 # a relative improvement of this much is
                              # considered significant
validation frequency = min(n train batches, patience // 2)
                              # go through this many
                               # minibatche before checking the network
                              # on the validation set; in this case we
                              # check every epoch
best validation loss = numpy.inf
test score = 0.
start time = timeit.default timer()
done looping = False
epoch = 0
while (epoch < n epochs) and (not done looping):
    epoch = epoch + 1
    for minibatch index in range(n train batches):
        minibatch avg cost = train model(minibatch index)
        iter = (epoch - 1) * n train batches + minibatch index
        if (iter + 1) % validation frequency == 0:
            validation losses = [validate model(i)
                                 for i in range(n valid batches)]
            this validation loss = numpy.mean(validation losses)
            print(
                'epoch %i, minibatch %i/%i, validation error %f %%' %
                    epoch,
                    minibatch index + 1,
                    n train batches,
                    this validation loss * 100.
                )
            )
            if this validation loss < best validation loss:</pre>
                if this validation loss < best validation loss * \</pre>
                   improvement threshold:
                    patience = max(patience, iter * patience increase)
                best validation loss = this validation loss
                test losses = [test model(i)
                               for i in range(n test batches)]
                test score = numpy.mean(test losses)
```

```
print(
                                  epoch %i, minibatch %i/%i, test error of'
                            ' best model %f %%'
                        ) %
                            epoch,
                            minibatch index + 1,
                            n train batches,
                            test score * 100.
                        )
                    )
                    # save the best model
                    with open('best model.pkl', 'wb') as f:
                        pickle.dump(classifier, f)
            if patience <= iter:</pre>
                done looping = True
                break
    end time = timeit.default timer()
   print(
            'Optimization complete with best validation score of %f %%,'
            'with test performance %f %%'
        % (best validation loss * 100., test score * 100.)
   print('The code run for %d epochs, with %f epochs/sec' % (
        epoch, 1. * epoch / (end_time - start_time)))
   print(('The code for file ' +
           os.path.split( file )[1] +
           ' ran for %.1fs' % ((end time - start time))), file=sys.stderr)
def predict():
    # load the saved model
    classifier = pickle.load(open('best model.pkl'))
    # compile a predictor function
    predict model = theano.function(
        inputs=[classifier.input],
        outputs=classifier.y pred)
    # some examples from test test
    dataset='mnist.pkl.gz'
    datasets = load data(dataset)
    test set x, test set y = datasets[2]
    test set x = test set x.get value()
    predicted values = predict model(test set x[:100])
   print("Predicted values for the first 100 examples in test set:")
   print(predicted values)
if name == ' main ':
```

```
sgd optimization mnist()
   predict()
Multi Layer Perceptron
This code has been developed using the tutorial from deeplearning.net
Author: Surjith Bhagavath Singh
0.000
from __future__ import print_function
docformat = 'restructedtext en'
import os
import sys
import timeit
import numpy
import theano
import theano.tensor as T
from logistic sgd import LogisticRegression, load_data
class HiddenLayer(object):
    def __init__(self, rng, input, n_in, n_out, W=None, b=None,
                activation=T.tanh):
        self.input = input
        if W is None:
            W values = numpy.asarray(
                rng.uniform(
                    low=-numpy.sqrt(6. / (n in + n out)),
                    high=numpy.sqrt(6. / (n in + n out)),
                    size=(n in, n out)
                dtype=theano.config.floatX
            if activation == theano.tensor.nnet.sigmoid:
                W values *= 4
            W = theano.shared(value=W values, name='W', borrow=True)
        if b is None:
            b values = numpy.zeros((n out,), dtype=theano.config.floatX)
            b = theano.shared(value=b values, name='b', borrow=True)
        self.W = W
        self.b = b
        lin output = T.dot(input, self.W) + self.b
```

```
self.output = (
            lin output if activation is None
            else activation(lin output)
        )
        self.params = [self.W, self.b]
class MLP(object):
        init (self, rng, input, n in, n hidden, n out):
        self.hiddenLayer = HiddenLayer(
            rng=rng,
            input=input,
            n_in=n_in,
            n out=n hidden,
            activation=T.tanh
        self.logRegressionLayer = LogisticRegression(
            input=self.hiddenLayer.output,
            n in=n hidden,
            n out=n out
        )
        self.L1 = (
            abs(self.hiddenLayer.W).sum()
            + abs(self.logRegressionLayer.W).sum()
        self.L2 sqr = (
            (self.hiddenLayer.W ** 2).sum()
            + (self.logRegressionLayer.W ** 2).sum()
        )
        self.negative log likelihood = (
            self.logRegressionLayer.negative log likelihood
        self.errors = self.logRegressionLayer.errors
        self.params = self.hiddenLayer.params +
self.logRegressionLayer.params
        self.input = input
def test_mlp(learning_rate=0.01, L1_reg=0.00, L2_reg=0.0001, n_epochs=1000,
             dataset='mnist.pkl.gz', batch size=20, n hidden=500):
    datasets = load data(dataset)
    train set x, train set y = datasets[0]
    valid set x, valid set y = datasets[1]
    test set x, test set y = datasets[2]
   n train batches = train set x.get value(borrow=True).shape[0] //
batch size
   n valid batches = valid set x.get value(borrow=True).shape[0] //
batch size
    n test batches = test set x.get value(borrow=True).shape[0] // batch size
```

```
print('... building the model')
index = T.lscalar() # index to a [mini]batch
x = T.matrix('x') # the data is presented as rasterized images
y = T.ivector('y') # the labels are presented as 1D vector of
                    # [int] labels
rng = numpy.random.RandomState(1234)
classifier = MLP(
   rng=rng,
    input=x,
    n in=28 * 28,
    n hidden=n hidden,
    n out=10
cost = (
   classifier.negative log likelihood(y)
    + L1 reg * classifier.L1
    + L2 reg * classifier.L2 sqr
test model = theano.function(
    inputs=[index],
    outputs=classifier.errors(y),
    givens={
        x: test set x[index * batch size:(index + 1) * batch size],
        y: test set y[index * batch size: (index + 1) * batch size]
)
validate model = theano.function(
    inputs=[index],
    outputs=classifier.errors(y),
    givens={
        x: valid set x[index * batch size: (index + 1) * batch size],
        y: valid set y[index * batch size: (index + 1) * batch size]
    }
)
gparams = [T.grad(cost, param) for param in classifier.params]
updates = [
    (param, param - learning rate * gparam)
    for param, gparam in zip(classifier.params, gparams)
]
train model = theano.function(
    inputs=[index],
    outputs=cost,
    updates=updates,
    givens={
        x: train set x[index * batch size: (index + 1) * batch size],
        y: train set y[index * batch size: (index + 1) * batch size]
print('... training')
```

```
patience = 10000 # look as this many examples regardless
patience increase = 2 # wait this much longer when a new best is
                       # found
improvement threshold = 0.995 # a relative improvement of this much is
                               # considered significant
validation frequency = min(n train batches, patience // 2)
                              # go through this many
                              # minibatche before checking the network
                              # on the validation set; in this case we
                              # check every epoch
best validation loss = numpy.inf
best iter = 0
test score = 0.
start time = timeit.default timer()
epoch = 0
done looping = False
while (epoch < n epochs) and (not done looping):
    epoch = epoch + 1
    for minibatch index in range(n train batches):
        minibatch avg cost = train model(minibatch index)
        iter = (epoch - 1) * n train batches + minibatch index
        if (iter + 1) % validation frequency == 0:
            validation losses = [validate model(i) for i
                                 in range(n valid batches)]
            this validation loss = numpy.mean(validation losses)
            print(
                'epoch %i, minibatch %i/%i, validation error %f %%' %
                (
                    epoch,
                    minibatch index + 1,
                    n train batches,
                    this validation loss * 100.
                )
            )
            if this validation loss < best validation loss:</pre>
                    this validation loss < best validation loss *
                    improvement threshold
                ):
                    patience = max(patience, iter * patience increase)
                best validation loss = this validation loss
                best iter = iter
                test losses = [test model(i) for i
                               in range(n test batches)]
                test score = numpy.mean(test losses)
                print((' epoch %i, minibatch %i/%i, test error of '
```

```
'best model %f %%') %
                          (epoch, minibatch index + 1, n train batches,
                           test score * 100.))
            if patience <= iter:</pre>
                done looping = True
                break
    end time = timeit.default timer()
   print(('Optimization complete. Best validation score of %f %% '
           'obtained at iteration %i, with test performance %f %%') \$
          (best validation loss * 100., best iter + 1, test score * 100.))
   print(('The code for file ' +
           os.path.split(__file__)[1] +
           ' ran for %.2fm' % ((end_time - start_time) / 60.)),
file=sys.stderr)
if __name__ == '__main__':
   test mlp()
Convolutional Neural Net
This code has been developed using the tutorial from deeplearning.net
Author: Surjith Bhagavath Singh
File Name: convolutional mlp.py
from __future__ import print_function
import os
import sys
import timeit
import numpy
import theano
import theano.tensor as T
from theano.tensor.signal import downsample
from theano.tensor.nnet import conv2d
from logistic sgd import LogisticRegression, load data
```

```
Surjith Bhagavath Singh
```

2)):

from mlp import HiddenLayer

class LeNetConvPoolLayer(object):

self.input = input

"""Pool Layer of a convolutional network """

assert image shape[1] == filter shape[1]

def init (self, rng, input, filter shape, image shape, poolsize=(2,

```
# there are "num input feature maps * filter height * filter width"
        # inputs to each hidden unit
        fan_in = numpy.prod(filter shape[1:])
        # each unit in the lower layer receives a gradient from:
        # "num output feature maps * filter height * filter width" /
        # pooling size
        fan out = (filter shape[0] * numpy.prod(filter shape[2:]) //
                   numpy.prod(poolsize))
        # initialize weights with random weights
        W bound = numpy.sqrt(6. / (fan in + fan out))
        self.W = theano.shared(
            numpy.asarray(
                rng.uniform(low=-W bound, high=W bound, size=filter shape),
                dtype=theano.config.floatX
            borrow=True
        )
        # the bias is a 1D tensor -- one bias per output feature map
        b values = numpy.zeros((filter shape[0],),
dtype=theano.config.floatX)
        self.b = theano.shared(value=b values, borrow=True)
        # convolve input feature maps with filters
        conv out = conv2d(
            input=input,
            filters=self.W,
            filter shape=filter shape,
            input shape=image shape
        )
        # downsample each feature map individually, using maxpooling
        pooled out = downsample.max pool 2d(
            input=conv out,
            ds=poolsize,
            ignore border=True
        )
        self.output = T.tanh(pooled out + self.b.dimshuffle('x', 0, 'x',
' × ' ) )
        # store parameters of this layer
        self.params = [self.W, self.b]
        # keep track of model input
        self.input = input
def evaluate lenet5(learning rate=0.1, n epochs=200,
                    dataset='mnist.pkl.gz',
                    nkerns=[20, 50], batch size=500):
    rng = numpy.random.RandomState (23455)
    datasets = load data(dataset)
```

```
train set x, train set y = datasets[0]
valid_set_x, valid_set_y = datasets[1]
test set x, test set y = datasets[2]
n train batches = train set x.get value(borrow=True).shape[0]
n valid batches = valid set x.get value(borrow=True).shape[0]
n test batches = test set x.get value(borrow=True).shape[0]
n train batches //= batch size
n valid batches //= batch size
n test batches //= batch size
index = T.lscalar() # index to a [mini]batch
x = T.matrix('x') # the data is presented as rasterized images
y = T.ivector('y') # the labels are presented as 1D vector of
                    # [int] labels
print('... building the model')
layer0 input = x.reshape((batch size, 1, 28, 28))
layer0 = LeNetConvPoolLayer(
    rng,
    input=layer0 input,
    image shape=(batch size, 1, 28, 28),
    filter shape=(nkerns[0], 1, 5, 5),
   poolsize=(2, 2)
layer1 = LeNetConvPoolLayer(
    rng,
    input=layer0.output,
    image shape=(batch size, nkerns[0], 12, 12),
    filter shape=(nkerns[1], nkerns[0], 5, 5),
    poolsize=(2, 2)
layer2 input = layer1.output.flatten(2)
layer2 = HiddenLayer(
   rng,
    input=layer2 input,
    n in=nkerns[1] \star 4 \star 4,
   n out=500,
    activation=T.tanh
)
layer3 = LogisticRegression(input=layer2.output, n in=500, n out=10)
cost = layer3.negative log likelihood(y)
test model = theano.function(
    [index],
    layer3.errors(y),
    givens={
        x: test set x[index * batch size: (index + 1) * batch size],
        y: test set y[index * batch size: (index + 1) * batch size]
```

```
}
validate model = theano.function(
    [index],
    layer3.errors(y),
    givens={
        x: valid set x[index * batch size: (index + 1) * batch size],
        y: valid set y[index * batch size: (index + 1) * batch size]
    }
)
params = layer3.params + layer2.params + layer1.params + layer0.params
grads = T.grad(cost, params)
updates = [
    (param i, param i - learning rate * grad i)
    for param i, grad i in zip(params, grads)
train model = theano.function(
    [index],
    cost,
    updates=updates,
    givens={
        x: train set x[index * batch size: (index + 1) * batch size],
        y: train set y[index * batch size: (index + 1) * batch size]
print('... training')
# early-stopping parameters
patience = 10000 # look as this many examples regardless
patience increase = 2 # wait this much longer when a new best is
                       # found
improvement threshold = 0.995 # a relative improvement of this much is
                               # considered significant
validation frequency = min(n train batches, patience // 2)
                              # go through this many
                              # minibatche before checking the network
                              # on the validation set; in this case we
                              # check every epoch
best validation loss = numpy.inf
best iter = 0
test score = 0.
start time = timeit.default timer()
epoch = 0
done looping = False
while (epoch < n epochs) and (not done looping):
    epoch = epoch + 1
    for minibatch index in range (n train batches):
        iter = (epoch - 1) * n train batches + minibatch index
```

```
if iter % 100 == 0:
                print('training @ iter = ', iter)
            cost ij = train model(minibatch index)
            if (iter + 1) % validation frequency == 0:
                validation losses = [validate model(i) for i
                                     in range(n valid batches)]
                this validation loss = numpy.mean(validation losses)
                print('epoch %i, minibatch %i/%i, validation error %f %%' %
                      (epoch, minibatch index + 1, n train batches,
                       this validation loss * 100.))
                if this validation loss < best validation loss:</pre>
                    if this validation loss < best validation loss * \</pre>
                       improvement_threshold:
                        patience = max(patience, iter * patience increase)
                    best validation loss = this validation loss
                    best iter = iter
                    test losses = [
                        test model(i)
                        for i in range(n test batches)
                    test score = numpy.mean(test losses)
                    print((' epoch %i, minibatch %i/%i, test error of '
                           'best model %f %%') %
                          (epoch, minibatch index + 1, n train batches,
                           test score * 100.))
            if patience <= iter:</pre>
                done looping = True
                break
    end time = timeit.default timer()
   print('Optimization complete.')
   print('Best validation score of %f %% obtained at iteration %i, '
          'with test performance %f %%' %
          (best validation loss * 100., best iter + 1, test score * 100.))
   print(('The code for file ' +
           os.path.split(__file__)[1] +
           ' ran for %.2fm' % ((end_time - start_time) / 60.)),
file=sys.stderr)
if name == ' main ':
    evaluate lenet5()
def experiment(state, channel):
    evaluate lenet5(state.learning rate, dataset=state.dataset)
```