non relativistica:
$$\frac{JP}{JQ} = \frac{e^2}{4\pi c^3} |\dot{v}|^2 \sin^2\theta$$

$$\rightarrow \overline{\nu}$$

Ponendo
$$\bar{\beta} = \frac{\bar{v}}{c} e \hat{n} = \frac{\bar{R}}{R}$$

campi
$$\vec{E} = e \left(\frac{\hat{n} - \overline{\beta}}{8^{2} (1 - \overline{\beta} \cdot \hat{n})^{3}} \right) \frac{1}{R^{2}} + \frac{e}{c} \left(\frac{\hat{n}}{n} \wedge (\hat{n} - \overline{\beta}) \wedge \overline{\beta}}{(1 - \overline{\beta} \cdot \hat{n})^{3}} \right) \frac{1}{R}$$

$$| \vec{B} = \hat{n} \wedge \vec{E}$$

$$| \vec{B} = \hat{n} \wedge \vec{E}$$

$$| \vec{S} = \frac{c}{4\pi} | \vec{E} \wedge \vec{B} | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}) | = \frac{c}{4\pi} | \vec{E} \wedge (\hat{n} \wedge \vec{E}$$

$$\bar{S} = \frac{c}{4\pi} \bar{E}_{\Lambda} \bar{B} = \frac{c}{4\pi} \bar{E}_{\Lambda} (\hat{n}_{\Lambda} \bar{E}) = \frac{cE^{2}}{4\pi} \hat{n} \simeq \frac{e}{4\pi c} \frac{|\hat{n}_{\Lambda}(\hat{n}_{-}\bar{\beta})_{\Lambda} \dot{\bar{\beta}}|^{2}}{(1-\bar{\beta}_{-}\hat{n}_{+})^{6}} |\hat{n}_{R}^{2}$$
(itardant)

$$t'=t-\frac{R}{c}$$
 $\int t_1=T_1+\frac{R}{c}$ $t_i:tempi \ J_i:osservazione$ $\int t_2=T_2+\frac{R}{c}$ $T_i:tempi \ J_i:emissione$

$$\mathcal{E} = \int_{1}^{t_{2}} \overline{S(t')} \cdot \hat{n} dt = \int_{1}^{t_{2}} \overline{S} \cdot \hat{n} \frac{dt}{dt'} dt'$$

$$t_{1}$$

$$t_{2}$$

$$t_{3}$$

$$t_{4}$$

$$t_{5}$$

$$t_{6}$$

$$t_{7}$$

$$t_{7}$$

$$t_{7}$$

$$t_{7}$$

$$t_{7}$$

$$t_{8}$$

$$JP = (\bar{S} \cdot \hat{n})(1 - \bar{\beta} \cdot \hat{n}) R^2 J\Omega$$

$$\frac{JP}{J\Omega} = \frac{e^{2}}{4\pi c} \frac{|\hat{n} \wedge (\hat{n} - \bar{\beta}) \wedge \bar{\beta}|^{2}}{(4 - \bar{\beta} \cdot \hat{n})^{6}} \frac{R^{2}}{R^{2}} \hat{n} \cdot \hat{n} \left(1 - \bar{\beta} \cdot \hat{n}\right) \implies \frac{JP}{J\Omega} = \frac{e}{4\pi c} \frac{|\hat{n} \wedge (\hat{n} - \bar{\beta}) \wedge \bar{\beta}|^{2}}{(4 - \bar{\beta} \cdot \hat{n})^{5}}$$

$$\frac{JP}{J\Omega} = \frac{e}{4\pi c} \frac{\left| \hat{n} \wedge (\hat{n} - \bar{\beta}) \wedge \dot{\bar{\beta}} \right|^{2}}{\left(4 - \bar{\beta} \cdot \hat{n} \right)^{5}}$$

Accelerazione lineare

$$\vec{B} / \vec{B} \implies \vec{A} \cdot \vec{B} = 0$$

$$\theta = \hat{n} \, \hat{B}$$

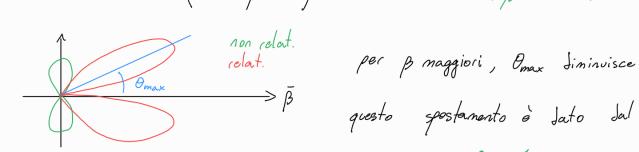
$$\frac{JP}{JQ} = \frac{e^2}{4\pi c} \frac{\left|\hat{n}_{\Lambda}(\hat{n} - \bar{\beta})_{\Lambda}\dot{\bar{\beta}}\right|^2}{\left(4 - \bar{\beta}\cdot\hat{n}\right)^5} = \frac{e}{4\pi c} \frac{\left|\hat{n}_{\Lambda}(\hat{n}_{\Lambda}\dot{\bar{\beta}})\right|^2}{\left(1 - \bar{\beta}\cdot\hat{n}\right)^5} = \frac{e}{4\pi c} \frac{\dot{\beta}^2 \sin^2\theta}{\left(1 - \beta\cos\theta\right)^5}$$

Cerchiamo il massimo angolare di
$$\frac{JP}{J\Omega}$$
:

$$\frac{\sin^{2}\theta}{(1-\beta\cos\theta)^{5}} \stackrel{=}{=} \frac{1-x^{2}}{(1-\beta x)^{5}} \implies \frac{1}{\sqrt{x}} \frac{1-x^{2}}{(1-\beta x)^{5}} = -\frac{2x}{(1-\beta x)^{5}} + \frac{5\beta(1-x^{2})}{(1-\beta x)^{6}} = \frac{-2x(1-\beta x) + 5\beta(1-x^{2})}{(1-\beta x)^{6}} = 0$$

$$=> 2\beta x^{2} - 5\beta x^{2} - 2x + 5\beta = 0 \Rightarrow 3\beta x^{2} + 2x - 5\beta = 0 \Rightarrow x = \frac{-1 \pm \sqrt{1 + 45\beta^{2}}}{3\beta}$$

$$\Rightarrow \theta_{\text{max}} = \cos^{-1}\left(\frac{-1\pm\sqrt{1+15\beta^2}}{3\beta}\right) \simeq \frac{1}{28} \qquad \delta^2 = \frac{1}{1-\beta^2} \Rightarrow \beta \simeq 1-\frac{1}{28^2} \text{ for } 8-8+\infty$$



questo spostamento è Jato Jul termine $(1-\hat{n}\cdot\bar{\beta})^{-5}$

Caso ultra celativistico:
$$\frac{\int P}{\int Q} \simeq \frac{e}{4\pi c} \dot{\beta}^2 \frac{\theta^2}{\left(1-\beta + \frac{\beta \theta^2}{2}\right)^5} \simeq \frac{8e}{\pi c} \dot{\beta}^2 \frac{8^2 \theta^2}{\left(1+8^2 \theta^2\right)^5}$$

