Numerical Solution of Differential Equations Assignment 1

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Acknowledgement:

- ChatGPT was used in the code and makefile for all questions.
- GitHub Copilot was used in the code for all questions.

$$C_{0}[u_{1}^{2} = u_{1}^{2}]$$

$$C_{1}[u_{1-1}^{2} = u_{1}^{2} - u_{1}^{2}] h_{1} + u_{1}^{2}] h_{2}^{2} - u_{1}^{2}] h_{3}^{2} + u_{1}^{2}] h_{2}^{2} + \dots$$

$$C_{2}[u_{1-2}^{2} = u_{1}^{2} - u_{1}^{2}] h_{2} + u_{1}^{2}] h_{2}^{2} - u_{1}^{2}] h_{3}^{2} + u_{1}^{2}] h_{2}^{2} + \dots$$

$$C_{3}[u_{1-3}^{2} = u_{1}^{2} - u_{1}^{2}] h_{3} + u_{1}^{2}] h_{3}^{2} - u_{1}^{2}] h_{3}^{2} + u_{1}^{2}] h_{3}^{2} + \dots$$

$$C_{3}[u_{1-3}^{2} = u_{1}^{2} - u_{1}^{2}] h_{3} + u_{1}^{2}] h_{3}^{2} - u_{1}^{2}] h_{3}^{2} + u_{1}^{2}] h_{3}^{2} + \dots$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & -N_1 & -N_2 & -N_3 \\ 0 & N_1^2/2 & N_2^2/2 & N_3^3/2 \\ 0 & -N_1^3/6 & -N_2^3/6 & -N_3^3/6 \end{bmatrix} \begin{bmatrix} C_0 \\ C_1 \\ C_2 \\ C_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

Using python to generate inverse and solving: $x = A^{-1}b$

→ Inverse is printed in code "91. Py"

$$C_0 = \frac{a(h_1 + h_2 + h_3)}{h_1 h_2 h_3}$$

$$C_1 = \frac{-2(h_2 + h_3)}{h_1^3 - h_1^2 h_2 - h_1^2 h_3 + h_1 h_2 h_3}$$

$$C_2 = \frac{2(h_1 + h_3)}{h_1 h_2^2 - h_1 h_2 h_3 - h_2^3 + h_2^2 h_3}$$

$$C_3 = \frac{-2(h_1 + h_2)}{h_1 h_2 h_3 - h_1 h_3^2 - h_2 h_3^2 + h_3^3}$$

$$\frac{\partial^{2} u}{\partial x^{2}} = C_{0} u_{1}^{2} + C_{1} u_{1-1}^{2} + C_{2} u_{1-2}^{2} + C_{3} u_{1-3}^{2} + O(h_{1}^{2}, h_{2}^{2}, h_{3}^{2})$$

(1) (b)

$$i-1,j+1$$
 $i+1,j+1$

Only cross points as symmetrical nodes will carcel out

Using Taylon's series: $U=U_{1,j}$

Co $U_{1-1,j+1}=U-hu_{x}+hu_{y}+\frac{h^{2}}{2}[u_{xx}+u_{yy}+2u_{xy}]+\frac{h^{3}}{6}[-u_{xx}+3u_{xxy}-3u_{xy}+u_{yyy}]+\cdots]$
 $(u_{1-1,j+1}=u-hu_{x}-hu_{y}+\frac{h^{2}}{2}[u_{xx}+u_{yy}+2u_{xy}]+\cdots]$
 $(u_{1-1,j+1}=u-hu_{x}-hu_{y}+\frac{h^{2}}{2}[u_{xx}+u_{yy}+2u_{xy}]+\cdots]$
 $(u_{1-1,j+1}=u-hu_{x}-hu_{y}+\frac{h^{2}}{2}[u_{xx}+u_{yy}+2u_{xy}]+\cdots]$
 $(u_{1-1,j+1}=u-hu_{x}-hu_{y}+\frac{h^{2}}{2}[u_{xx}+u_{yy}+2u_{xy}]+\cdots]$
 $(u_{1-1,j+1}=u-hu_{x}-hu_{y}+\frac{h^{2}}{2}[u_{xx}+u_{yy}+2u_{xy}]+\cdots]$

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ -h & -h & 0 & h & h \\ h & -h & 0 & -h & h \\ h^{2} & h^{2} & 0 & h^{2} & h^{2} \\ -h^{2} & h^{2} & 0 & -h^{2} & h^{2} \end{bmatrix}$$

$$\mathcal{X} = \begin{bmatrix} C_0 \\ C_1 \\ C_2 \\ C_3 \\ C_4 \end{bmatrix}$$

-> Inverting wing code & solving:

$$C_0 = C_4 = \frac{1}{4h^2}$$
 $C_1 = C_3 = \frac{-1}{4h^2}$

$$\frac{\partial^{2} u}{\partial n^{2}} = \frac{u_{i+1,j+1} - u_{i+1,j-1} + u_{i-1,j-1}}{-u_{i-1,j+1}}$$

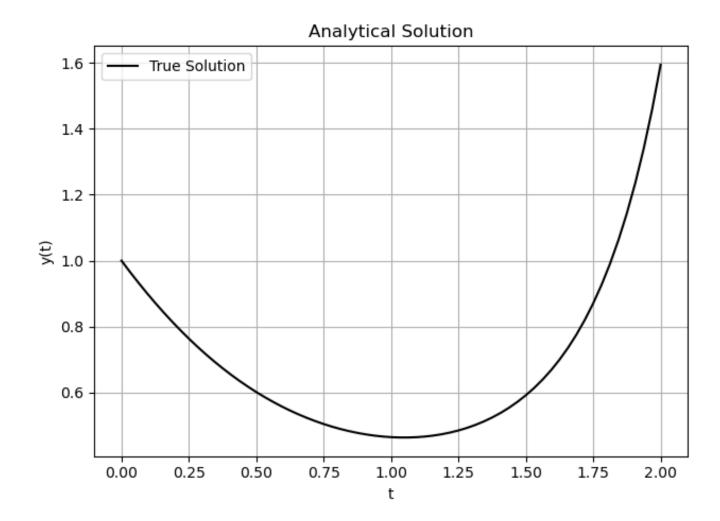
$$\frac{\partial^{2} u}{\partial n^{2}} = \frac{u_{i+1,j+1} - u_{i+1,j-1} + u_{i-1,j-1}}{-u_{i-1,j+1}}$$

The given initial value problem over the interval t=0 to t=20 is:

$$\frac{dy}{dt} = yt^2 - 1.1y$$

where y(0) = 1

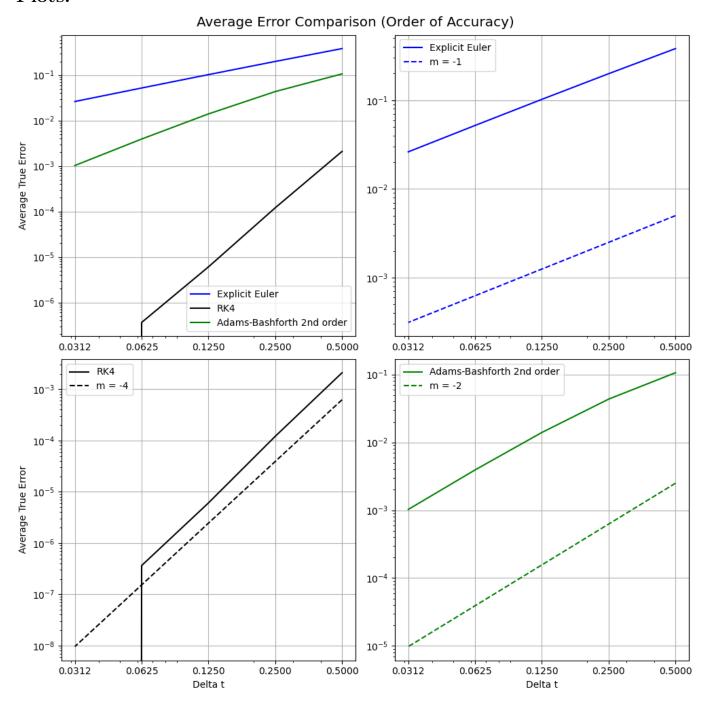
The equation can be solved analytically by variable separable method.

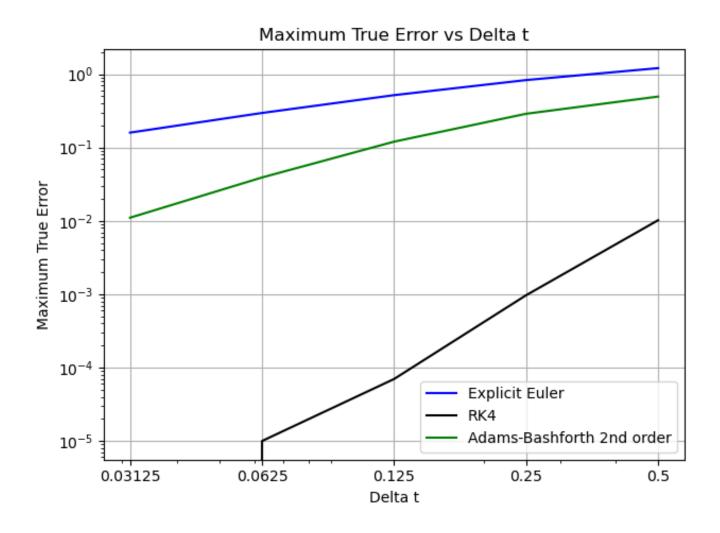


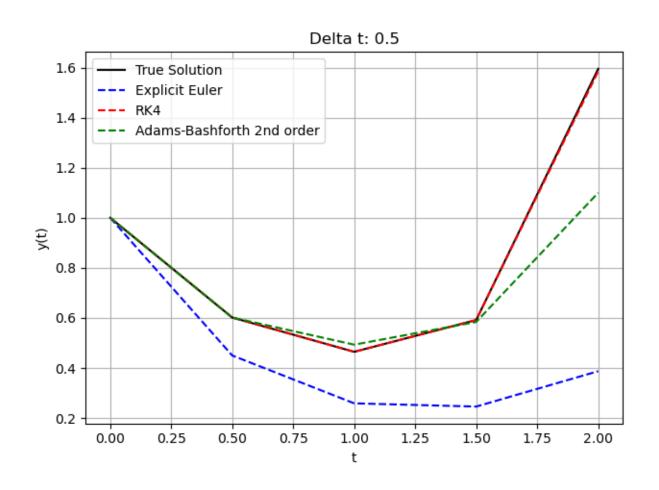
The analytical solution is given below.

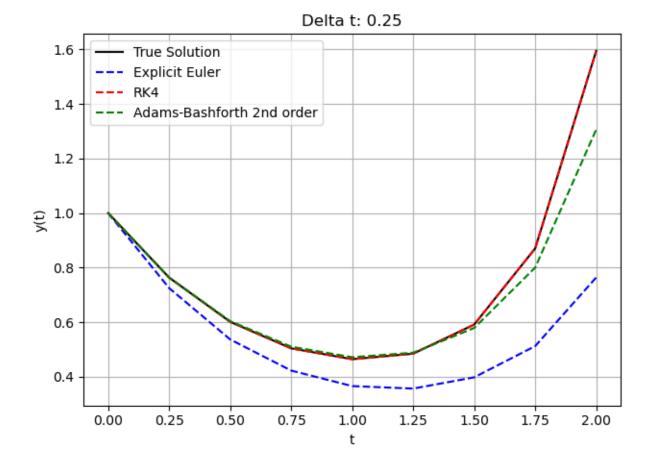
$$ln(y) = \frac{t^3}{3} - 1.1t$$

Plots:



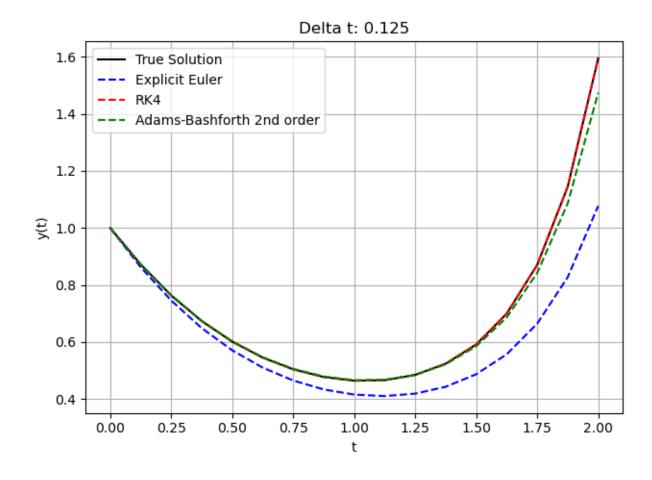


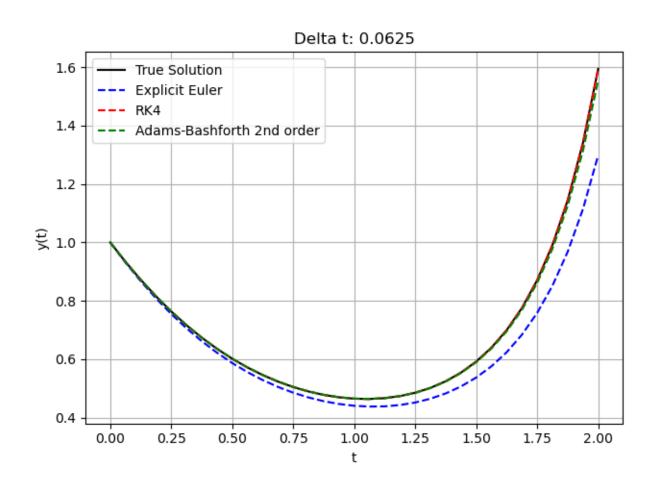


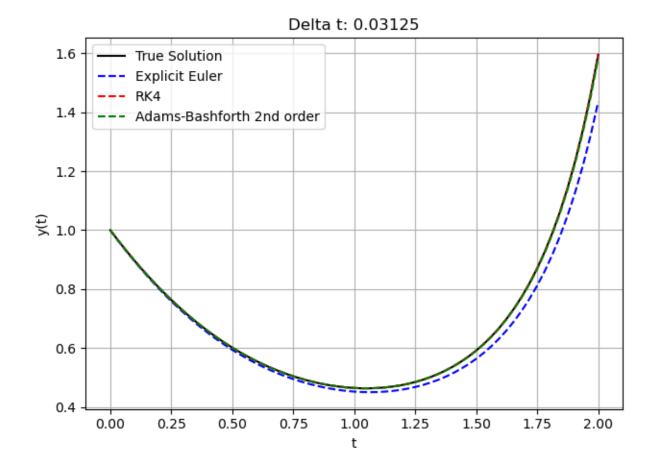


Discussion:

- RK4 depicts the best accuracy irrespective of the step size.
- Of all the methods, Explicit Euler is the least accurate.







The given second order differential equation can be resolved into two first order differential equations and solved using RK4.

Given,

$$m\frac{d^2x}{dt^2} + a\frac{dx}{dt}\frac{dx}{dt} + kx = F_0\sin(\omega t)$$

where, x is the displacement from the equilibrium position in m, t is the time in s. The other constants are m=2 kg, a=5 N/m, k=6 N/m, $F_0=2.5$ N and $\omega=0.5$ rad/s. Given, at t=0 s, $v_0=0$ m/s and x=1 m.

Equation 1:

$$\frac{dx}{dt} = v$$

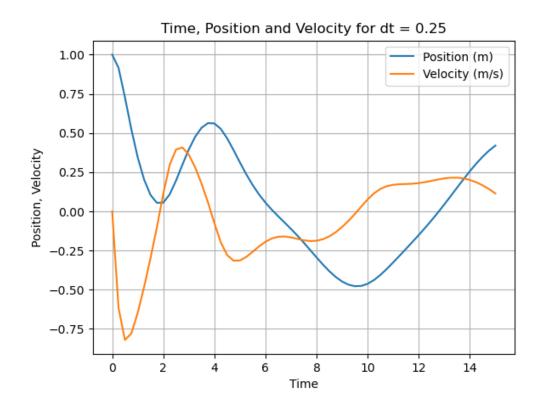
Equation 2:

$$\frac{dv}{dt} = \frac{F_0 sin(\omega t) - a|v|v - kx}{m}$$

Discussion:

• It is concluded that the grid convergence is reached at around 10³ grid points.

Property	Minimum Value	Time (at Minimum)	Maximum Value	Time (at Maximum)
Position	-0.478014	9.58496	1	0
Velocity	-0.827922	0.551758	0.411432	2.66504



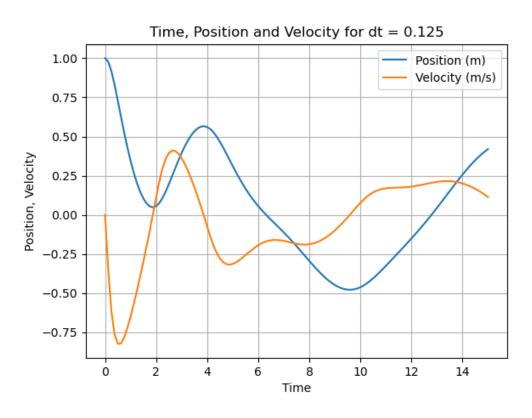
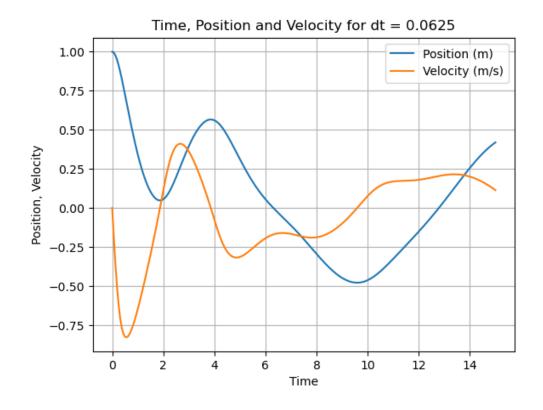
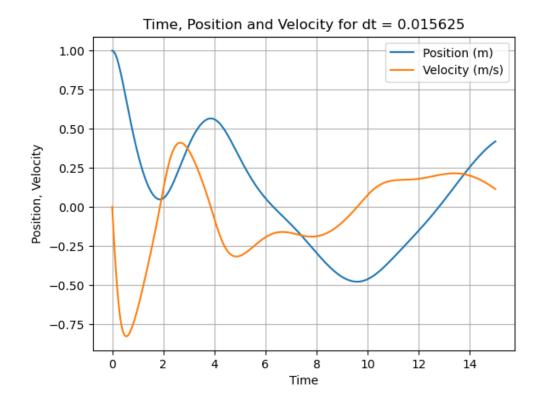


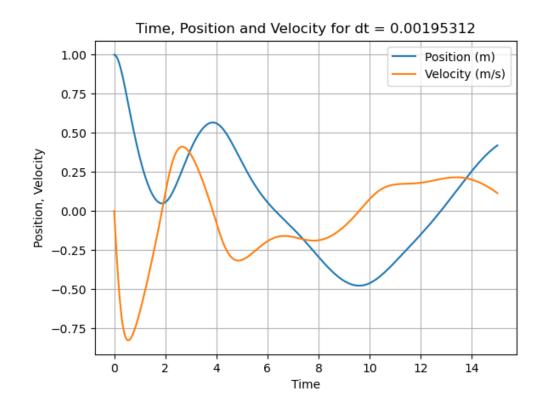
Figure 1: Enter Caption

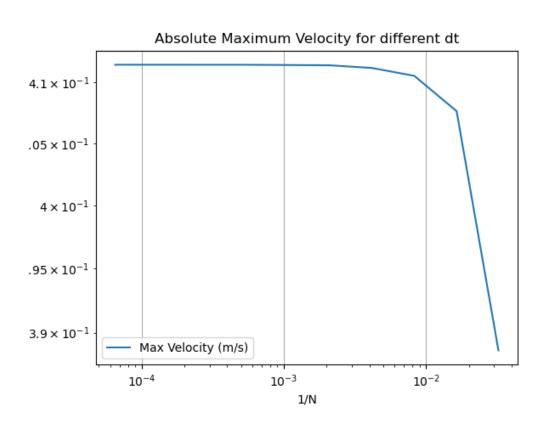


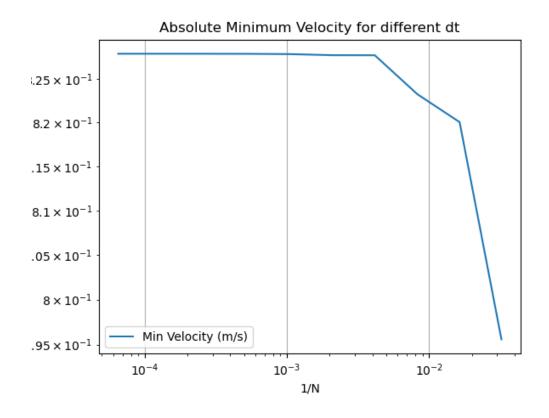


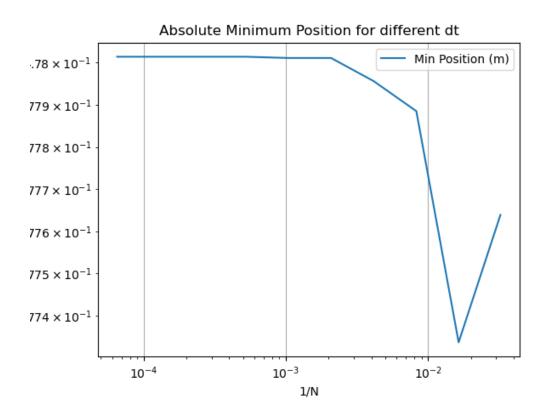






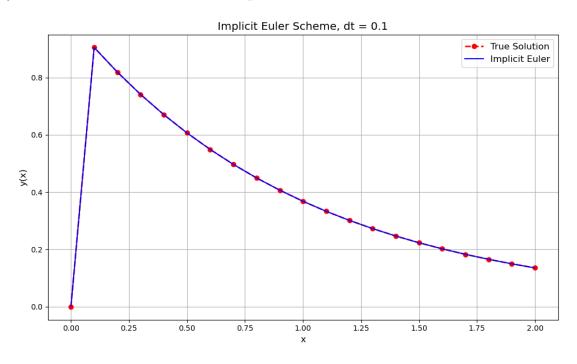






$$\frac{dy}{dx} = -2,00,000y + 2,00,000e^{-x} - e^{-x}$$

with y(0) = 0, from x = 0 to x = 2 with step size of 0.1.



- Implicit is better than explicit as step size is not as restrictive.
- For 10000 times greater step size than required for explicit scheme, we are able to obtain a good approximate solution using implicit scheme.

Explicit Euler:
$$\frac{dy}{dx} = f(x,y) \quad \alpha \leq x \leq b$$

$$(N-1) \text{ sub-intervals} \qquad \qquad y(a) = y_0 \text{ is } y_b = ?$$
with $N-g$ adoptints:
$$V_{i} = h = \frac{b-a}{N-1} \quad \text{true solution}$$

$$V_{i+1} = Y_i + h f(x_i, y_i)$$
Stability:
$$|Y_{i+1}| \leq |Y_i|$$

$$\frac{dy}{dx} = -2 \times 10^5 \left[y - e^{-x} \right] - e^{-x}$$

$$Y_{i+1} = Y_i + h \left[-2 \times 10^5 \left[y_i - e^{-x_i} \right] - e^{-x_i} \right]$$

$$h > 0 \quad \text{de} \quad e^{-x_i} > 0 \quad \text{for } x_i \neq \infty$$
So,
$$|Y_{i+1}| \leq |Y_i| + |$$

$$y' + ay = (a-1) e^{-x}$$

$$A = 2 \times 10^{5}$$

$$IF = e^{\int adx} = e^{ax}$$

$$y e^{ax} = \int e^{(a-1)x} (a-1) dx + C$$

$$y e^{ax} = e^{(a-1)x} + C$$

$$y = e^{-x} + Ce^{-ax}$$

$$y(0) = 0 \Rightarrow 0 = 1 + C \Rightarrow C = -1$$

$$y = e^{-x} - e^{-ax}$$

$$y(0) = 0 \implies 0 = 1 + c \implies c = -1$$

 $y = e^{-x} - e^{-ax}$

Ly Exact Solution

$$\frac{d^2T}{dr^2} + \frac{1}{r}\frac{dT}{dr} + S = 0 \quad \text{over the range } 0 \le r \le 1,$$

with the boundary conditions:
$$T(r=1)=1$$
 and $\left.\frac{dT}{dr}\right|_{r=0}=0$.

The above equation is solved using second order central difference.

Discussion:

- All the plots show the same trend with only scaling due to the source term.
- The peak temperatures always occur at r = 0.
- The peak values are always $0.25 \times S$.
- From this, it can be easily concluded that S = 400 for a peak temperature of 100.

$$\frac{d^{2}T}{dr^{2}} + \frac{1}{r}\frac{dT}{dr} = -S$$

$$\frac{dT}{dr} = T_{\frac{i+1}{r} - 2T_{i}} + T_{i-1}$$

$$\frac{dT}{dr} = T_{i-1$$

