

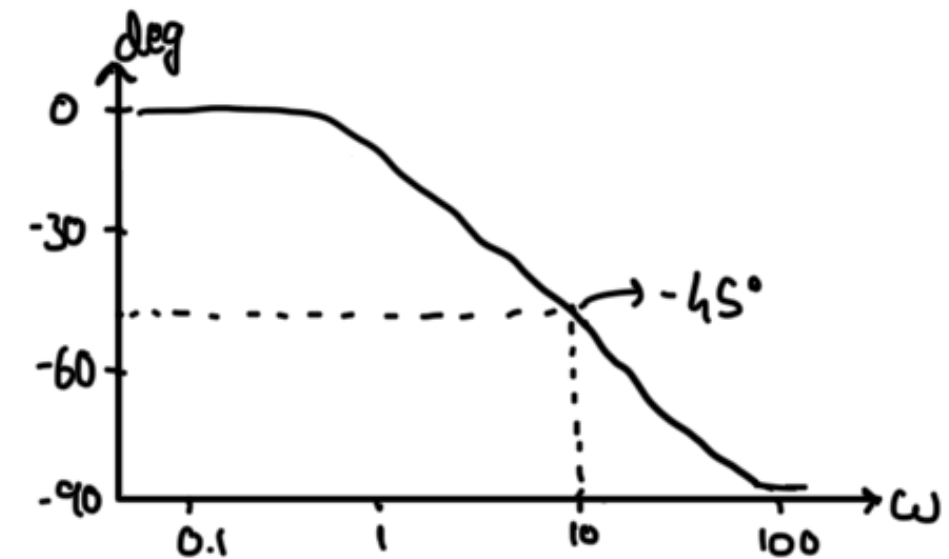
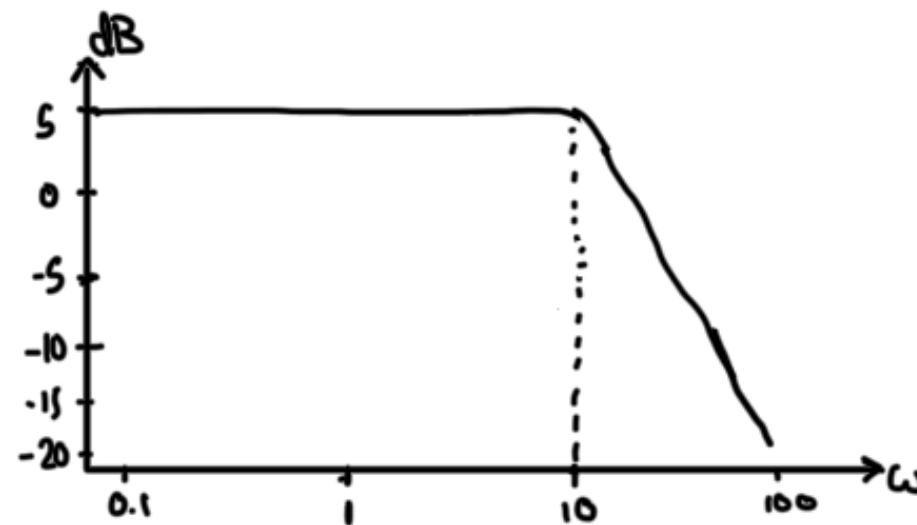


1.1  $G_1(s) = \frac{10}{s+10}$

1. pole  $\Rightarrow |G_1(s)| \rightarrow \infty \Rightarrow s = -10$  is the only pole

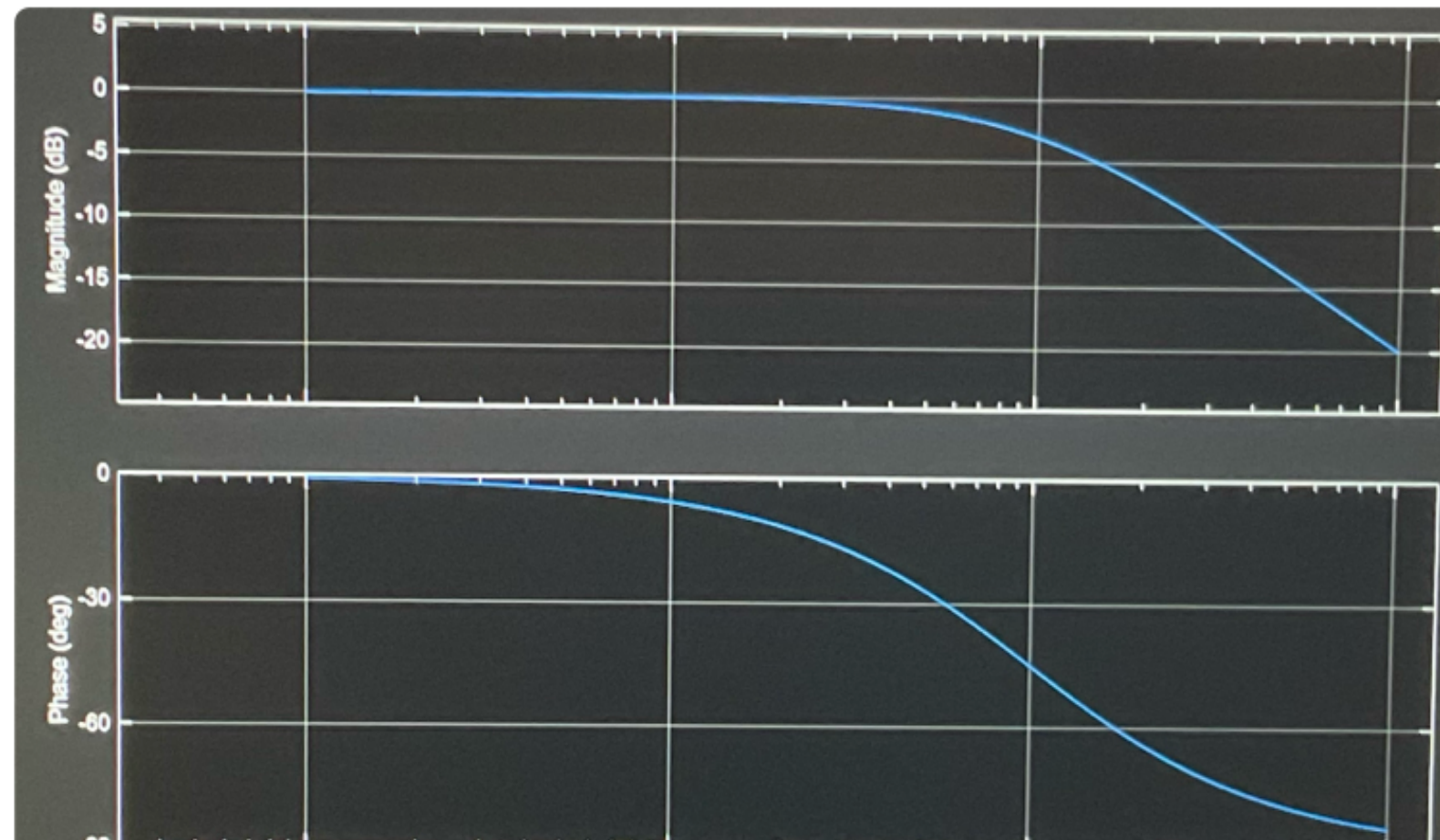
DC gain =  $\lim_{\omega \rightarrow 0} G_1(j\omega) = G_1(0) = 1$

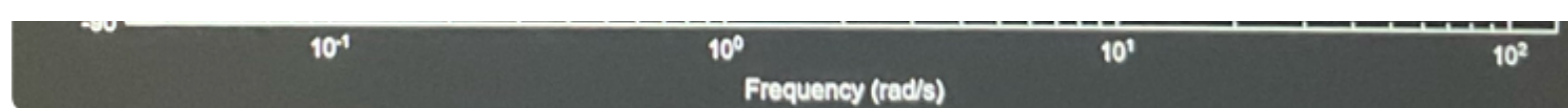
2.



cut of  $\omega \Rightarrow |G_1(j\omega)| = \frac{1}{\sqrt{2}} = \frac{10}{\sqrt{\omega^2+100}} \Rightarrow \omega^2+100 = 200 \Rightarrow \omega_{\text{cutoff}} = 10$

3.



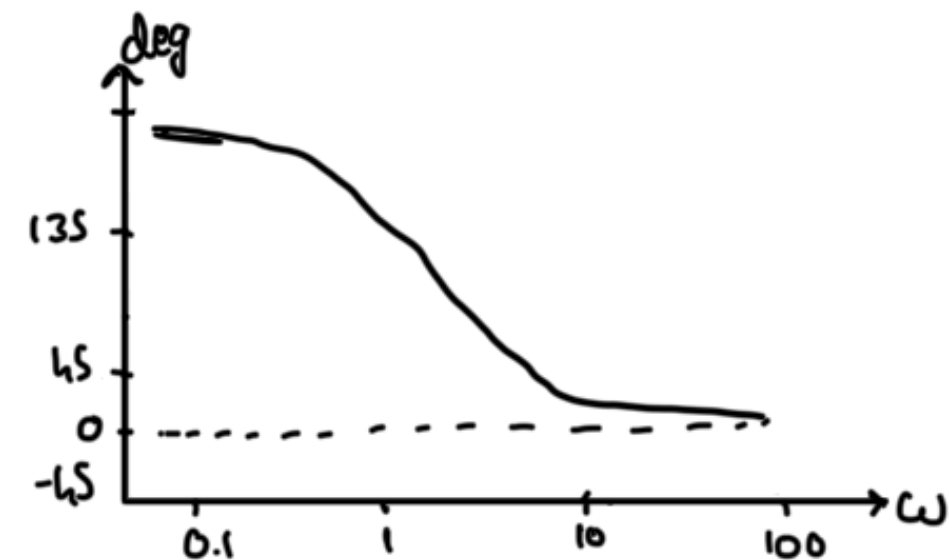
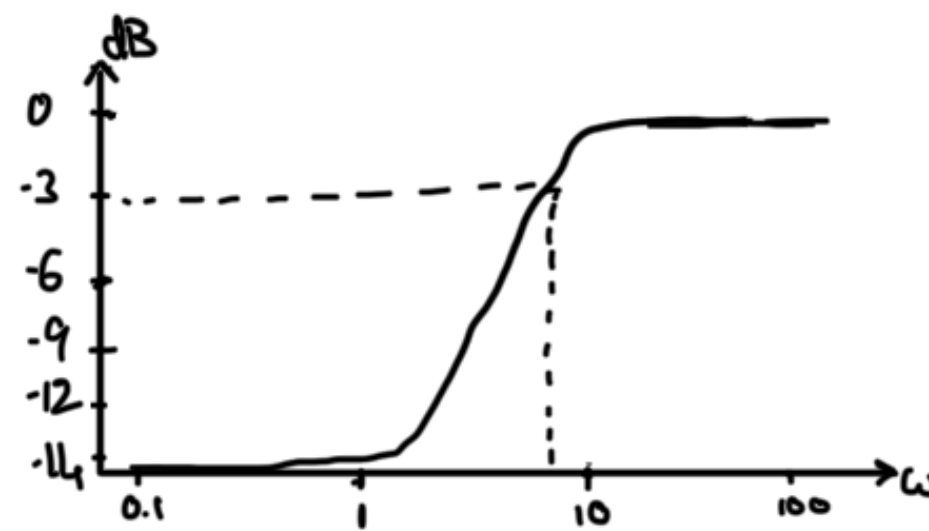


1.2

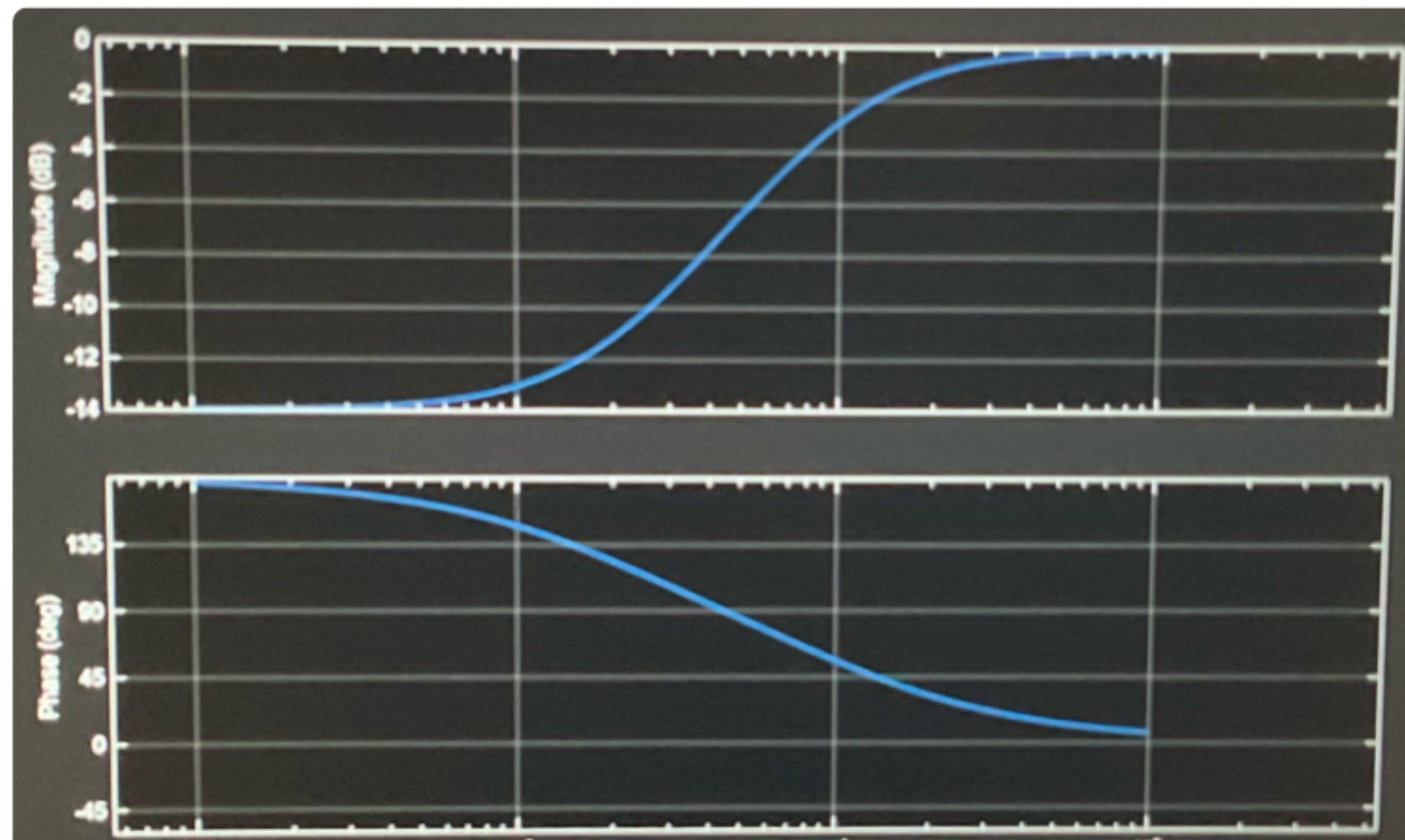
$$G_2(s) = \frac{s-2}{s+10}$$

1. zeros = 2, poles = -10,  $G_2(0) = -1/5$

$$2. |G_2(j\omega)| = \sqrt{\frac{4 + \omega^2}{100 + \omega^2}} = \frac{1}{\sqrt{2}} \Rightarrow 8 + 2\omega^2 = 100 + \omega^2 \Rightarrow \omega_{\text{cutoff}} = \sqrt{92} \quad \frac{12\omega}{\omega^2 - 20}$$



3.



4. let numerator have a  $(s+a)$  term  
right plane root  $\Rightarrow a < 0$   
left plane root  $\Rightarrow a > 0$

$$\text{at } s = j\omega \Rightarrow a + j\omega$$

$$\angle(a + j\omega) = \tan^{-1}(\omega/a)$$

Since  $\omega > 0$ :

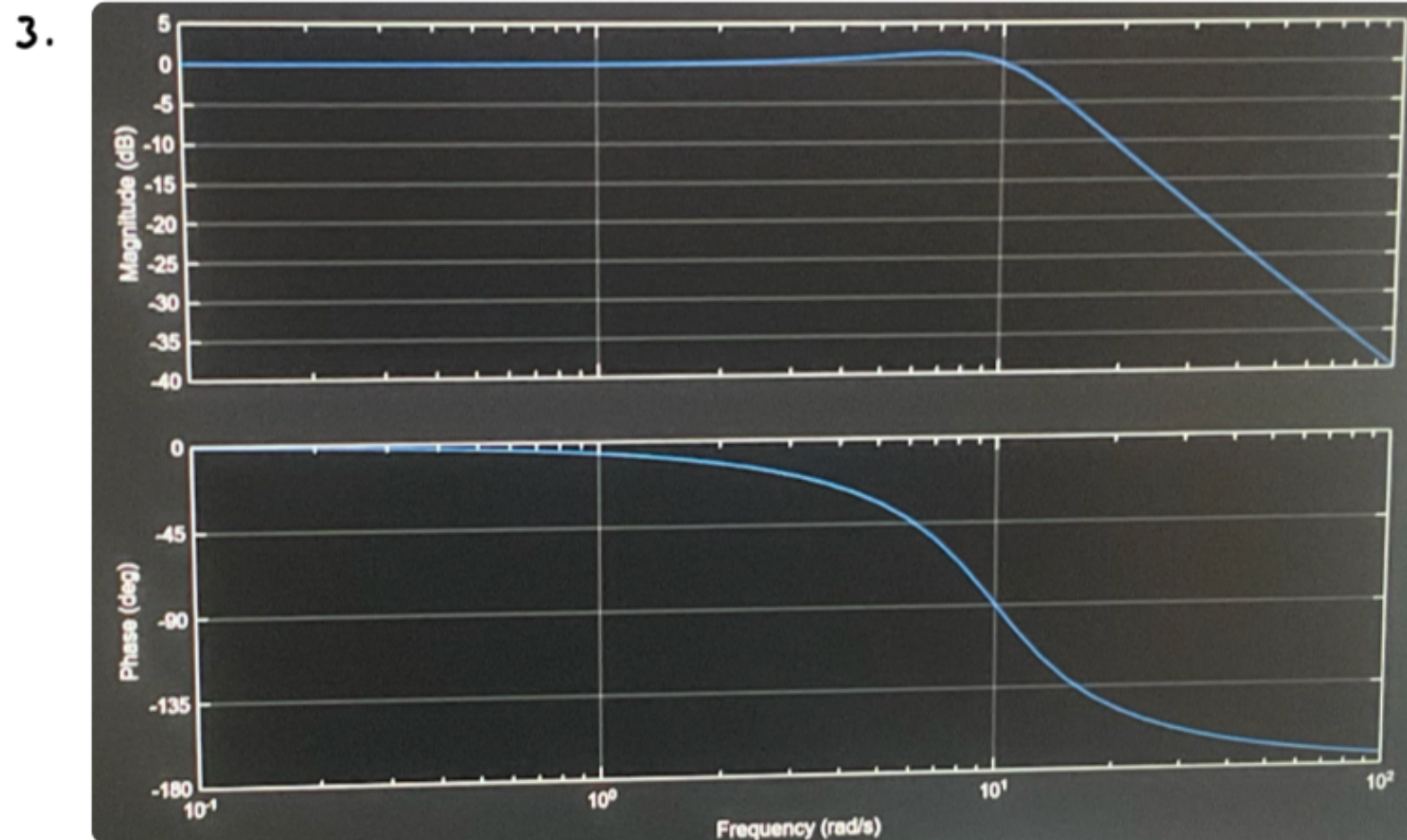
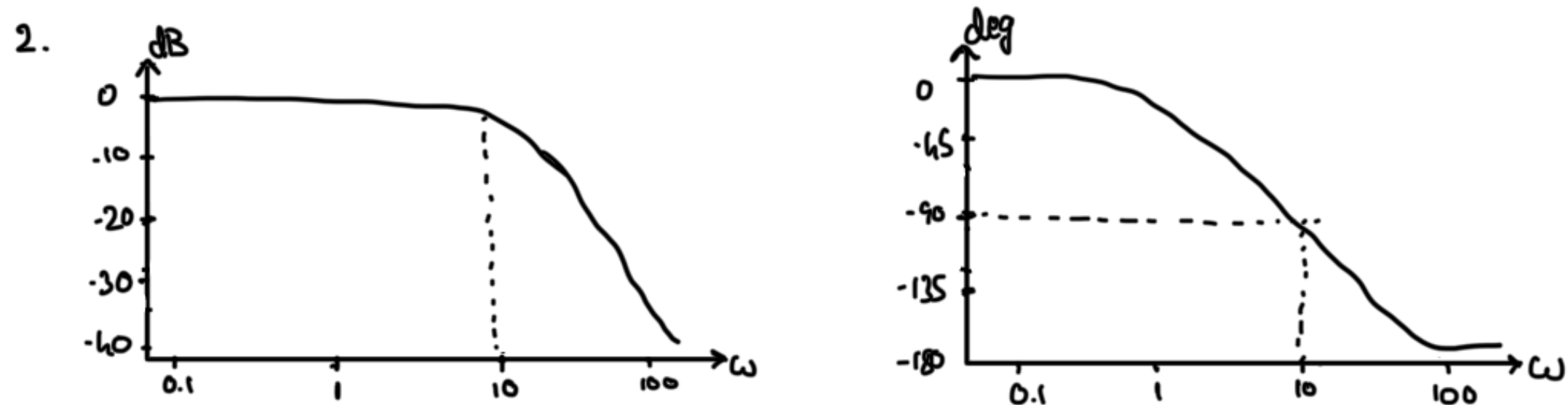
if  $a < 0$ ,  $(a + j\omega)$  will give a negative phase contribution;

else if  $a > 0$  it will



1.3.  $G_3(s) = \frac{100}{s^2 + 10s + 100}$

1.  $s^2 + 10s + 100 = 0 \Rightarrow s = -10 \left( \frac{1}{2} \pm \frac{\sqrt{3}}{2}j \right) = \text{poles}$



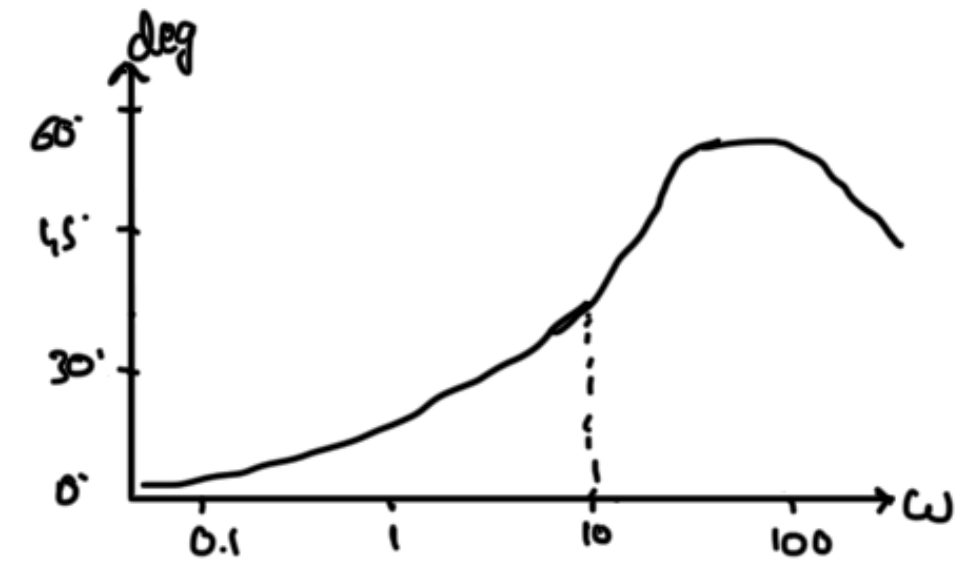
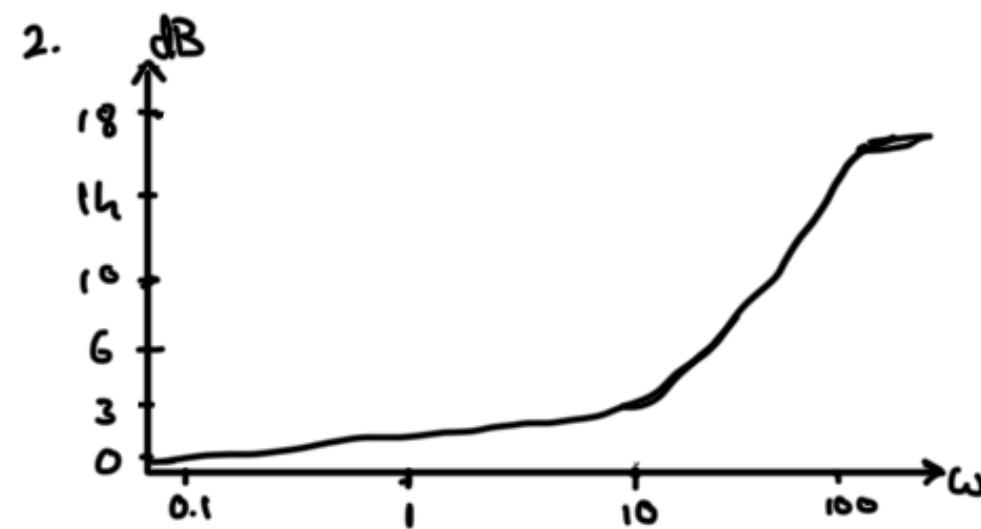
$$G_3(10j) = \frac{1}{j}$$

$$\Rightarrow \angle G_3(10j) = -90^\circ$$

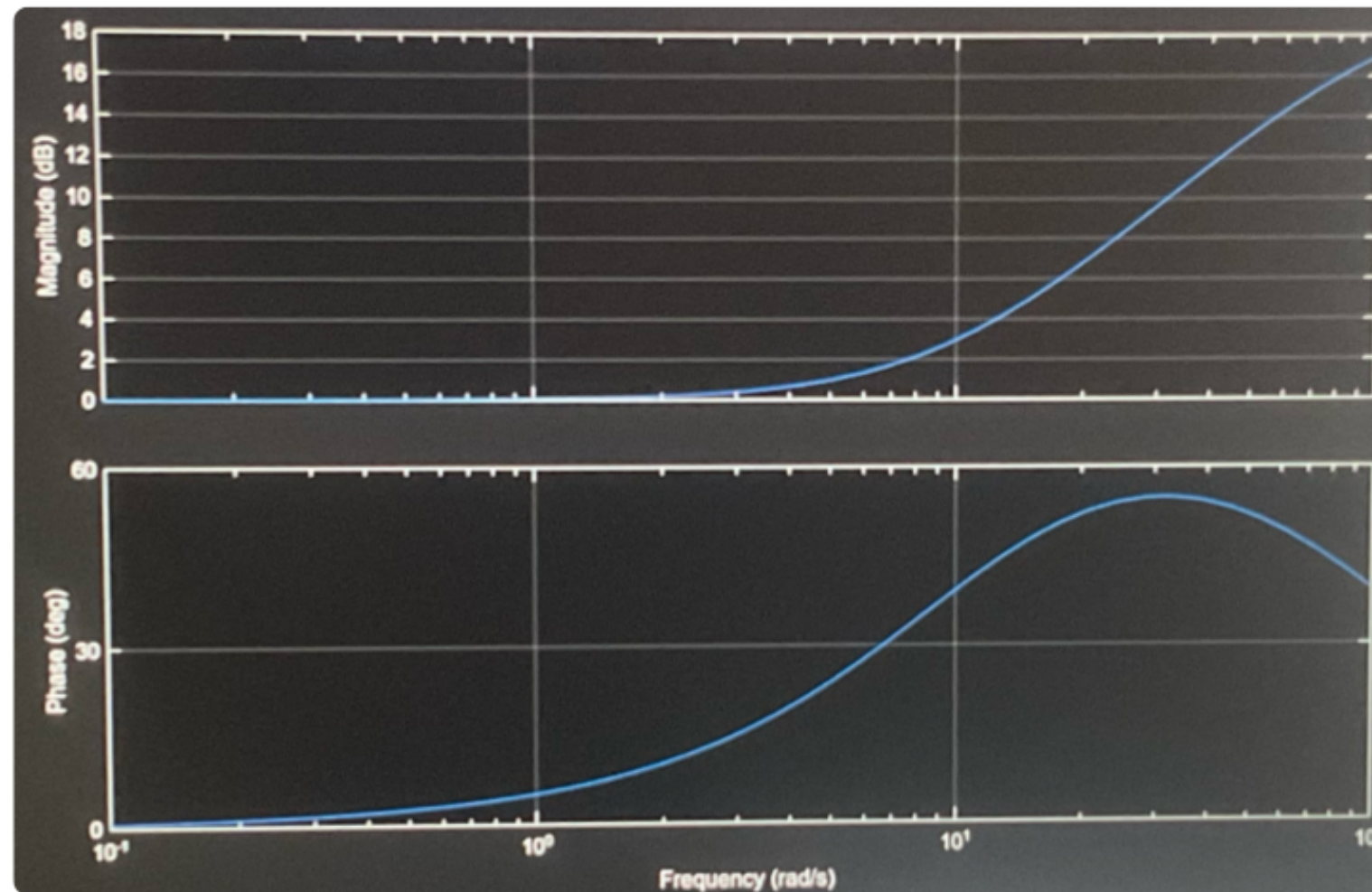
1.4.  $G_2(s) = \frac{0.1s + 1}{0.01s + 1} = \frac{10s + 100}{s + 100}$

else it will give a positive phase contribution;

1. zeros = -10 , poles = -100



3.



$$h. G_h(j\omega) = 10 \frac{j\omega + 10}{j\omega + 100}$$

$$\angle G_h = \tan^{-1} \frac{\omega}{10} - \tan^{-1} \frac{\omega}{100}$$

$$\text{for } 10 < \omega < 100$$

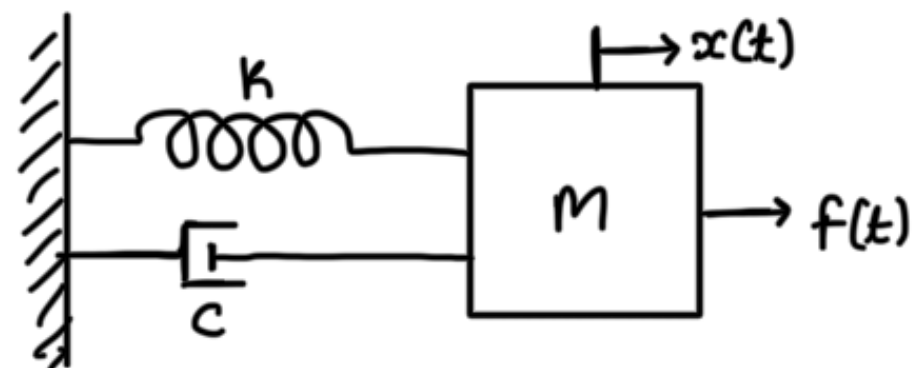
$$0 > \tan^{-1} \frac{\omega}{10} > \frac{\pi}{4}$$

$$0 > \tan^{-1} \frac{\omega}{100} < \frac{\pi}{4}$$

$$\text{hence } \angle G_h > 0$$

$\therefore$  adds positive phase

2.



input force :  $f(t)$

output displacement :  $x(t)$



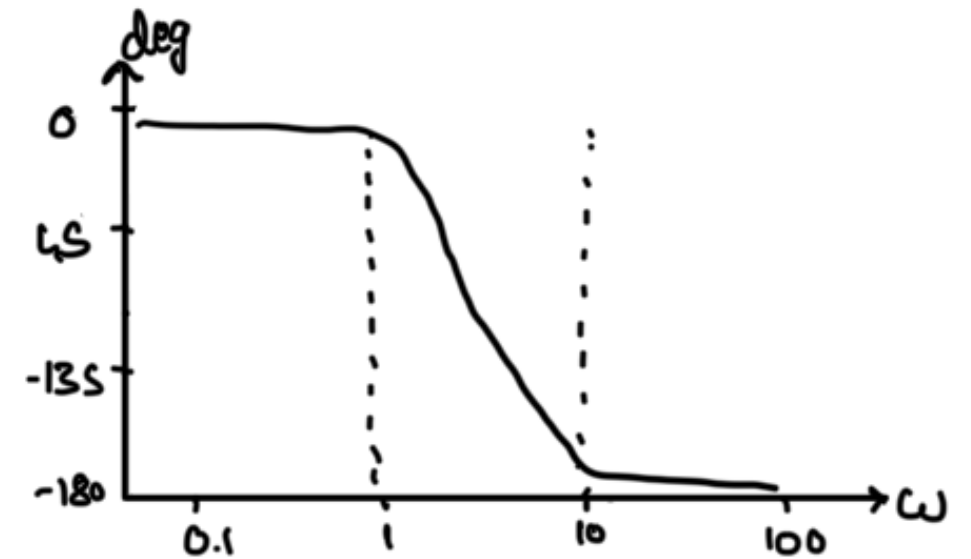
- B.1
1.  $m \frac{d^2 x}{dt^2} = f(t) - b \frac{dx}{dt} - cx(t)$  where  $b$  is damping constant
  2. Taking Laplace :  $(ms^2 + bs + c)X(s) = F(s)$
  3.  $G(s) = \frac{X(s)}{F(s)} = \frac{1}{ms^2 + bs + c}$

- B.2
1.  $m=1$ ,  $b=4$ ,  $c=16$  / all SI units

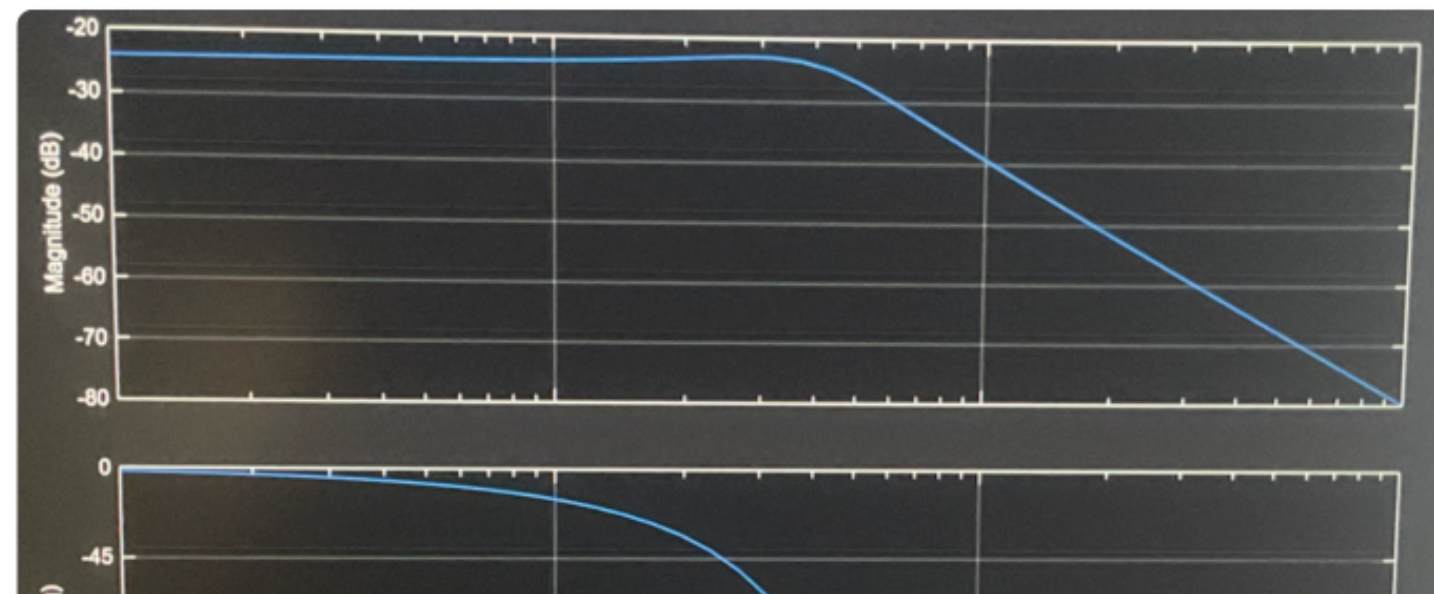
$$G(s) = \frac{1}{s^2 + 4s + 16}$$

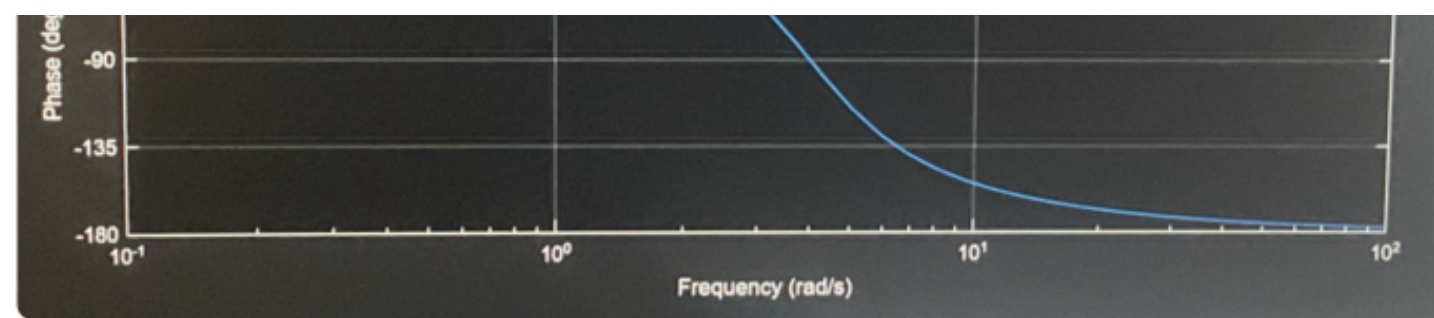
2.  $s^2 + 4s + 16 = 0 \implies s = -2 \pm \sqrt{4 - 16} = -2(1 \pm j\sqrt{3}) = \text{poles}$

3.



4.





PROCEDURE TO PLOT BODE on MATLAB:

for ex:  $G(s) = \frac{as+b}{ps^2+qs+r}$

num = [a b];

den = [p q r];

G = tf(num, den);

bode(g, {0.1, 100}); % angular frequency 0.1 to 100

grid on;

▷ Run