

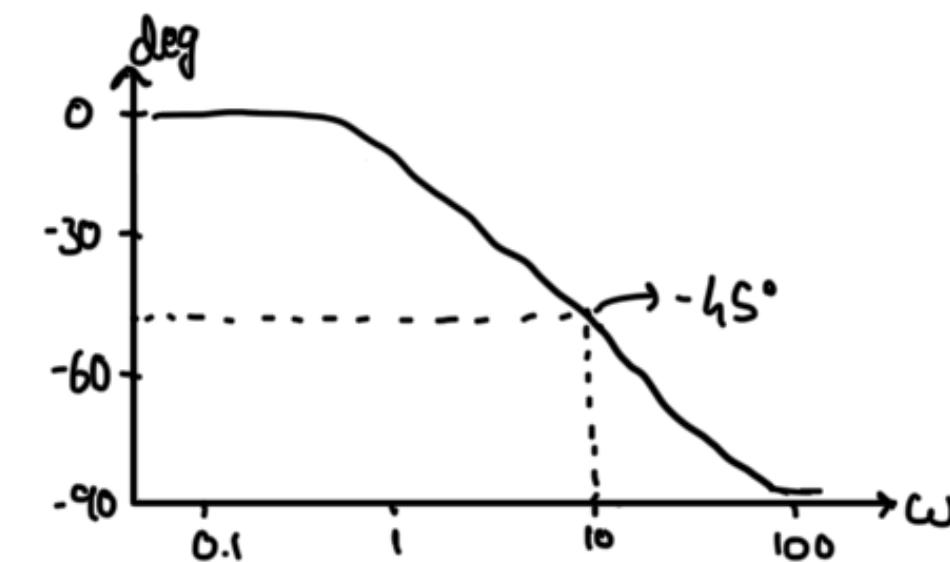
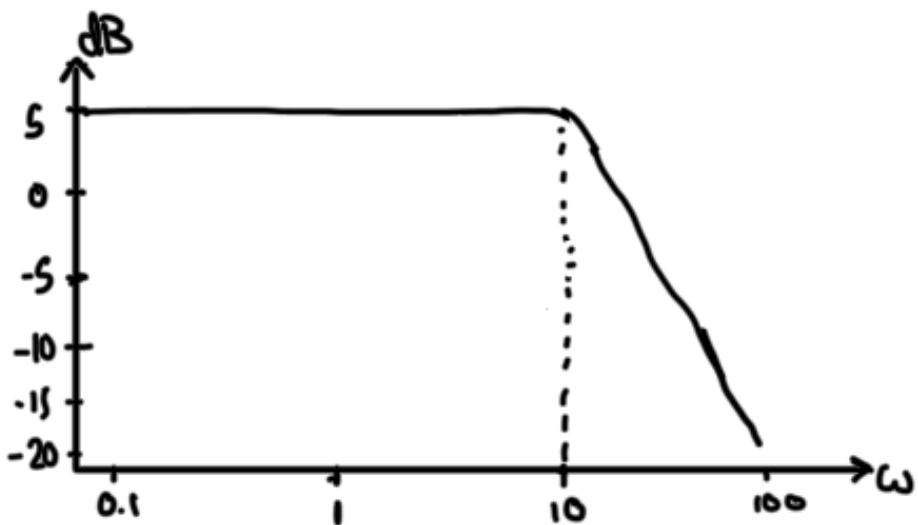
Assignment 1

$$1.1 \quad G_s(s) = \frac{10}{s+10}$$

1. pole $\Rightarrow |G_s(s)| \rightarrow \infty \Rightarrow s = -10$ is the only pole

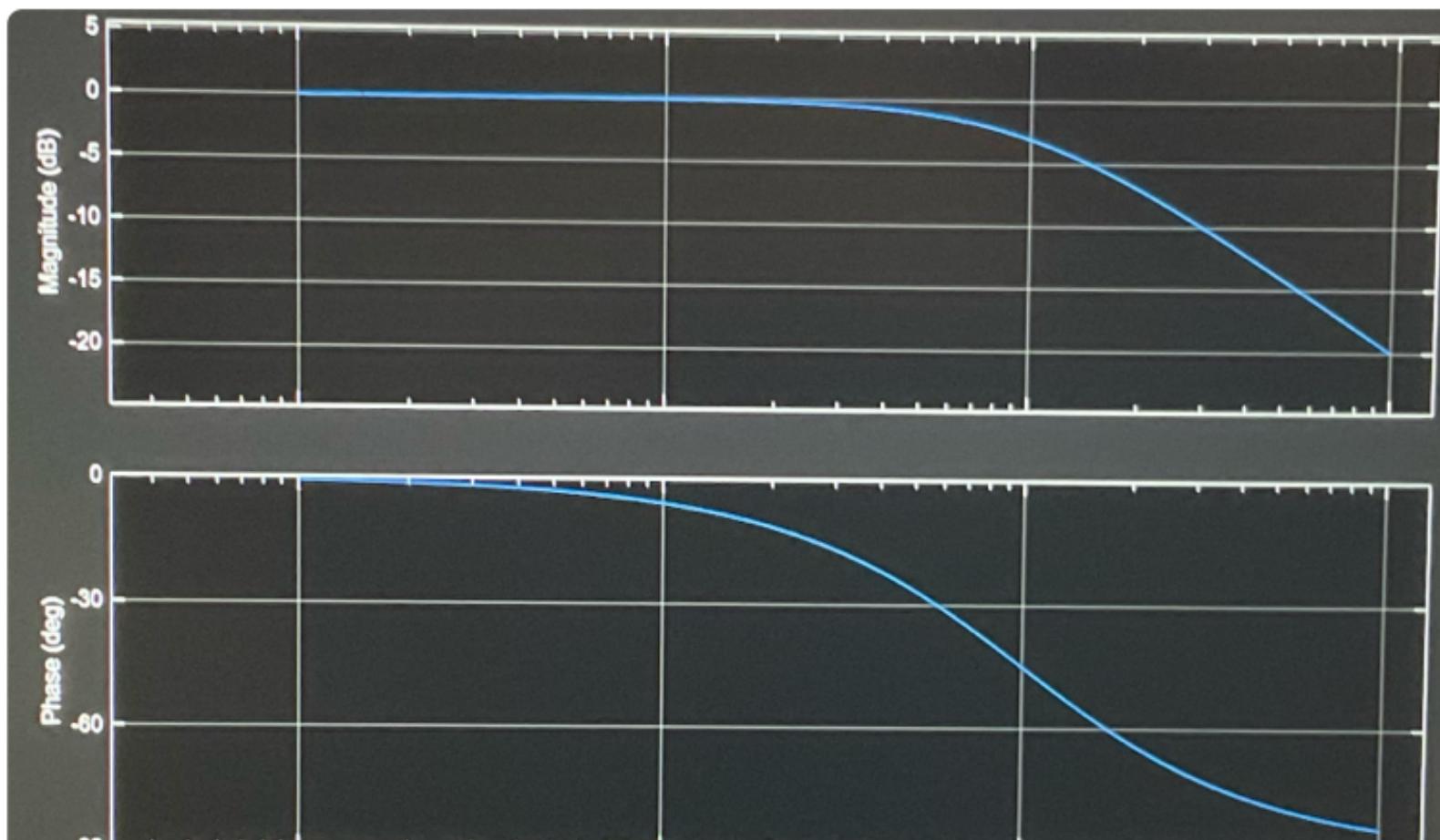
$$\text{DC gain} = \lim_{\omega \rightarrow 0} G_s(j\omega) = G_s(0) = 1$$

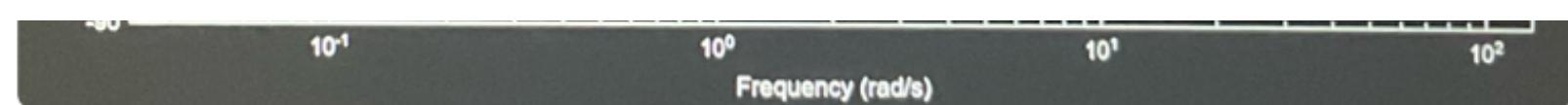
2.



$$\text{Cut off } \omega \Rightarrow |G_s(j\omega)| = \frac{1}{\sqrt{2}} = \frac{10}{\sqrt{\omega^2 + 100}} \Rightarrow \omega^2 + 100 = 200 \Rightarrow \omega_{\text{cutoff}} = 10$$

3.

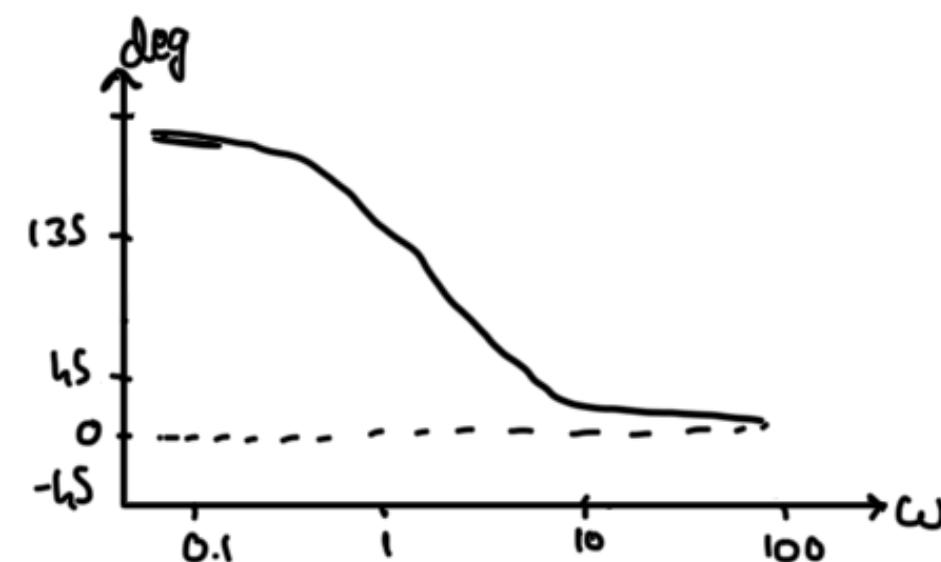
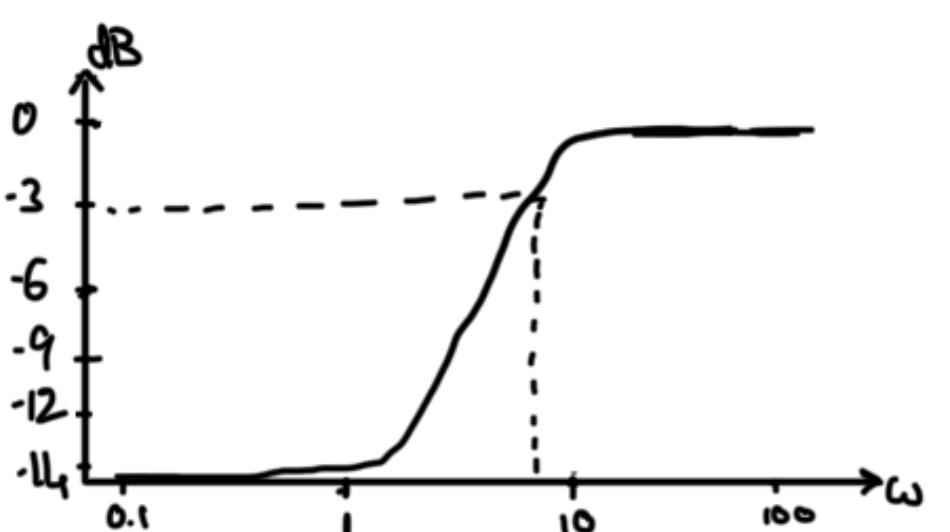




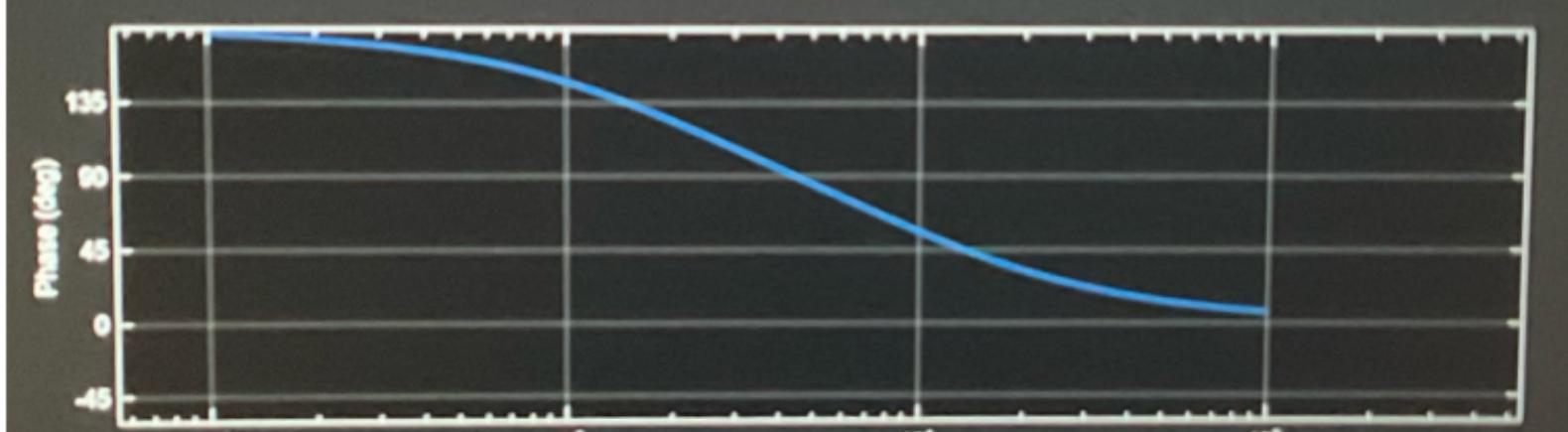
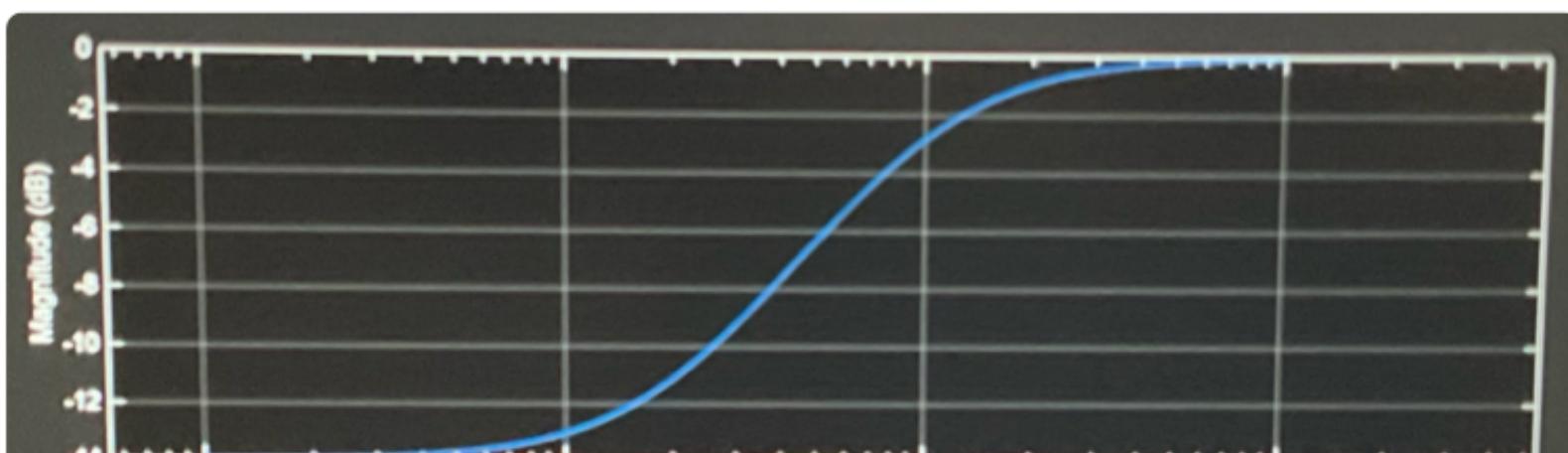
$$1.2 \quad G_2(\omega) = \frac{\omega^2 - 2}{\omega^2 + 10}$$

1. zeros = 2, poles = -10, $G_2(0) = -1/5$

$$2. |G_2(j\omega)| = \sqrt{\frac{1+\omega^2}{100+\omega^2}} = \frac{1}{\sqrt{2}} \Rightarrow 8+2\omega^2 = 100+\omega^2 \Rightarrow \omega_{\text{cutoff}} = \sqrt{92} \quad \frac{12\omega}{\omega^2 - 20}$$



3.



4. let numerator have
a $(\omega + a)$ term
right plane root $\Rightarrow a < 0$
left plane root $\Rightarrow a > 0$
 $\text{at } \omega = j\omega \Rightarrow a + j\omega$
 $L(a+j\omega) = \tan^{-1}(\omega/a)$

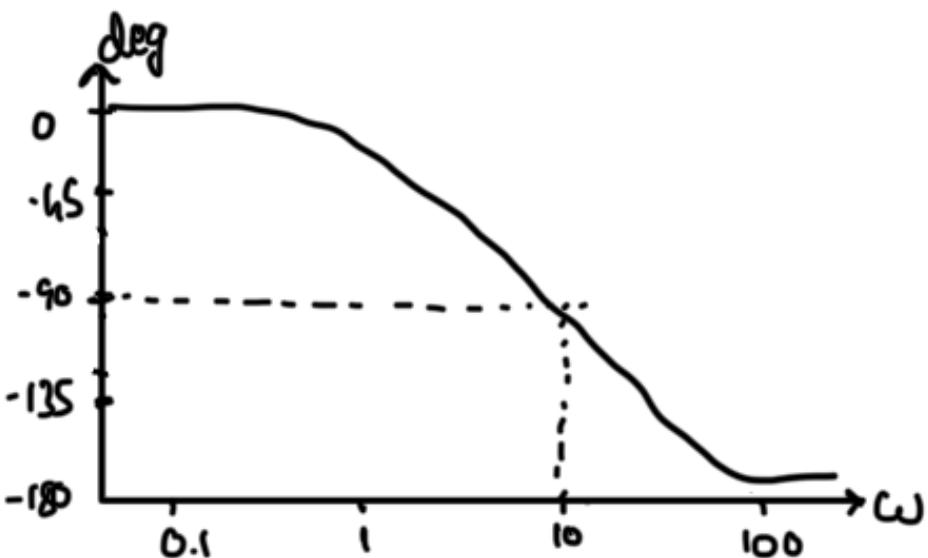
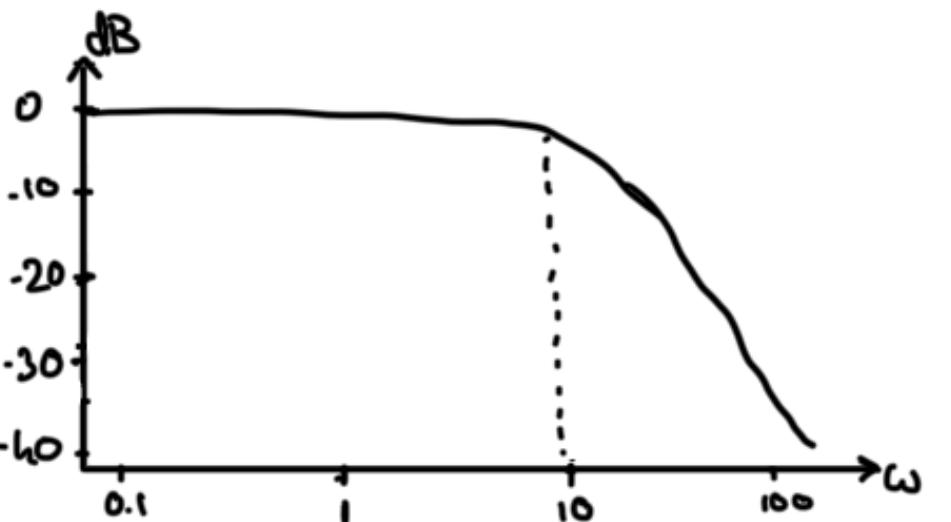
Since $\omega > 0$:
if $a < 0$, $(a+j\omega)$ will
give a negative phase
contribution;
also if $a > 0$ it will

CASE 1: $\omega_n > \zeta \omega$
give a positive phase contribution;

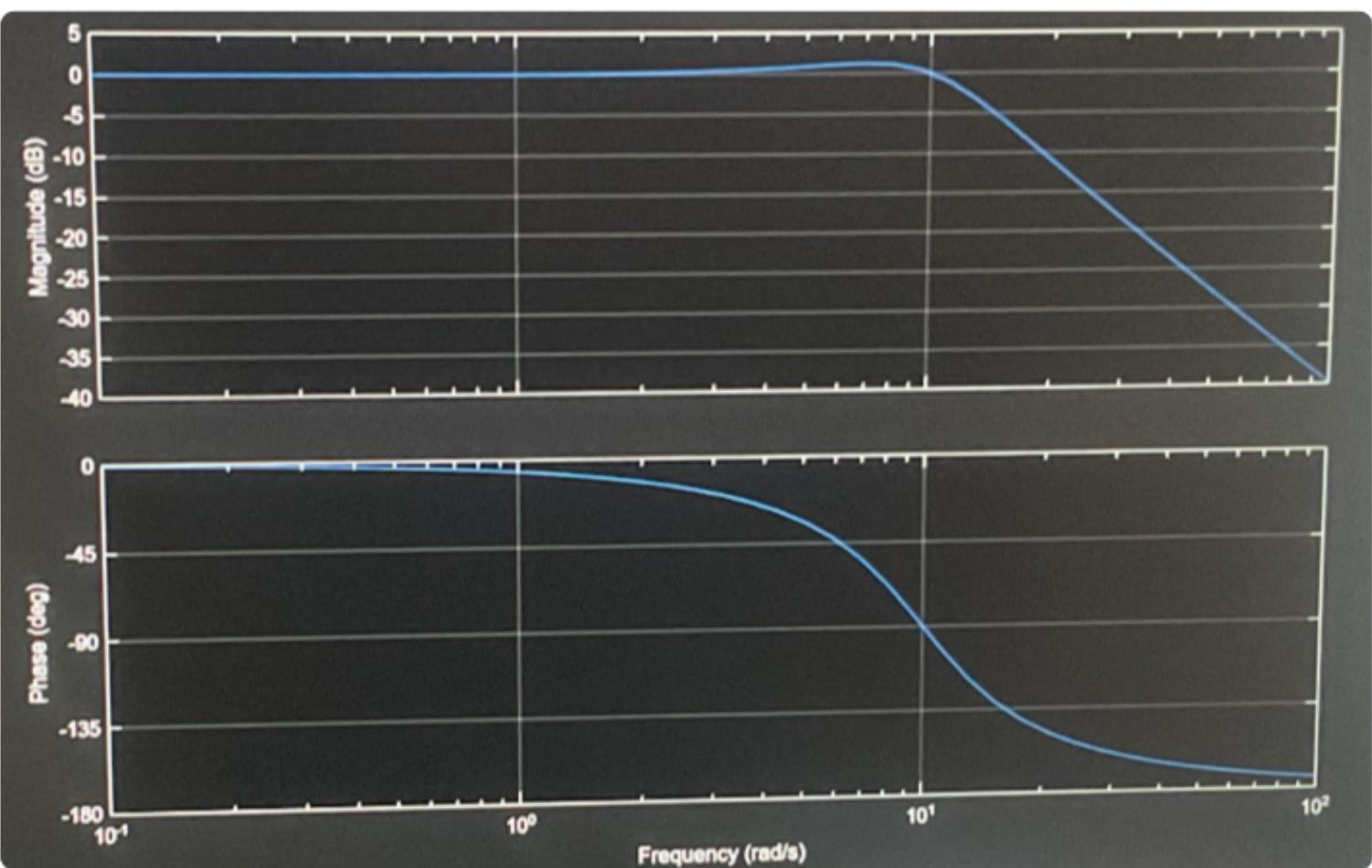
$$1.3. G_3(s) = \frac{100}{\zeta^2 + 10\zeta + 100}$$

$$\text{i. } \zeta^2 + 10\zeta + 100 = 0 \implies \zeta = -10 \left(\frac{1}{2} \pm \frac{\sqrt{3}}{2}j \right) = \text{poles}$$

2.



3.

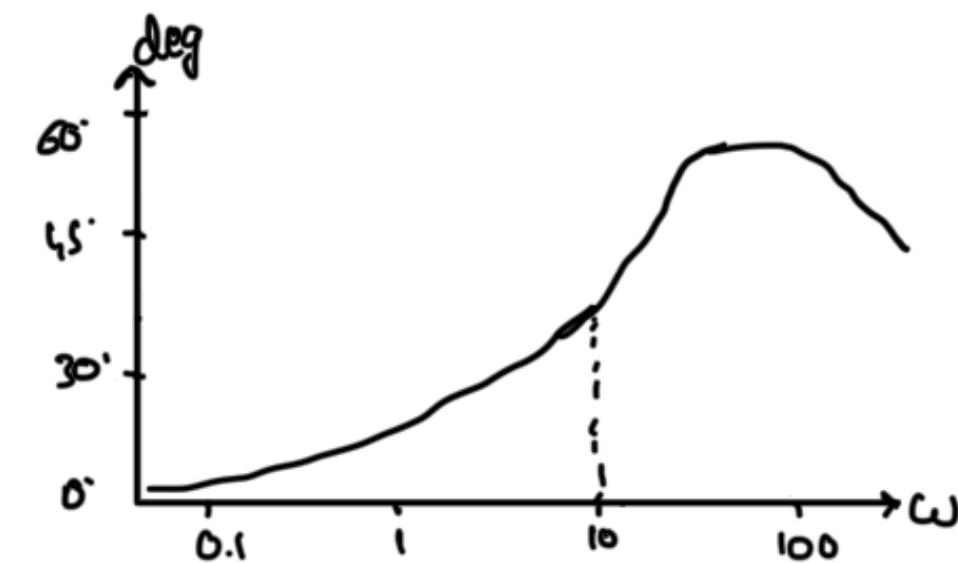
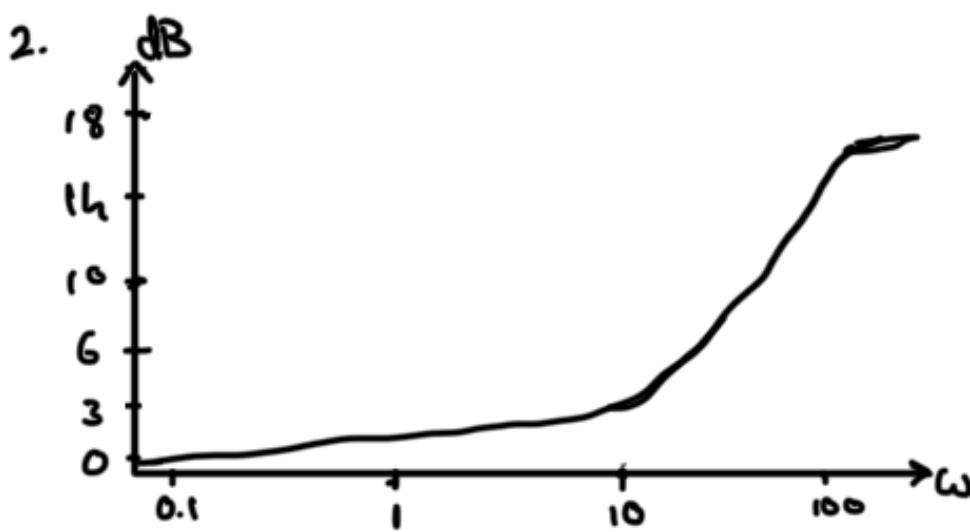


$$G_3(10j) = \frac{1}{j}$$

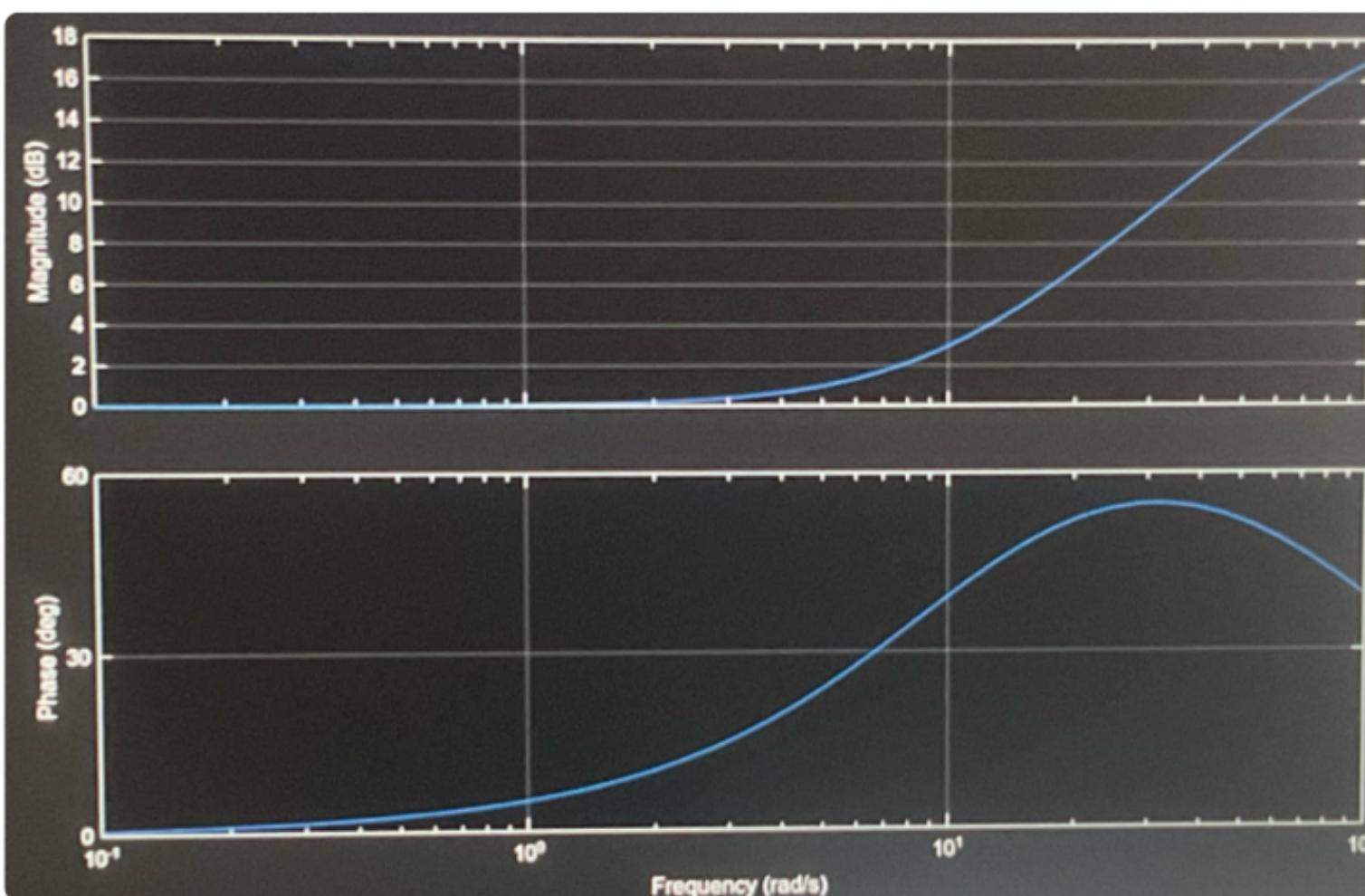
$$\Rightarrow \angle G_3(10j) = -90^\circ$$

$$1.4. G_4(s) = \frac{0.1\zeta s + 1}{0.01\zeta s + 1} = \frac{10\zeta s + 100}{\zeta s + 100}$$

1. zeros = -10 , poles = -100



3.



$$h. G_4(j\omega) = 10 \left(\frac{j\omega + 10}{j\omega + 100} \right)$$

$$\angle G_4 = \tan^{-1} \frac{\omega}{10} - \tan^{-1} \frac{\omega}{100}$$

for $10 < \omega < 100$

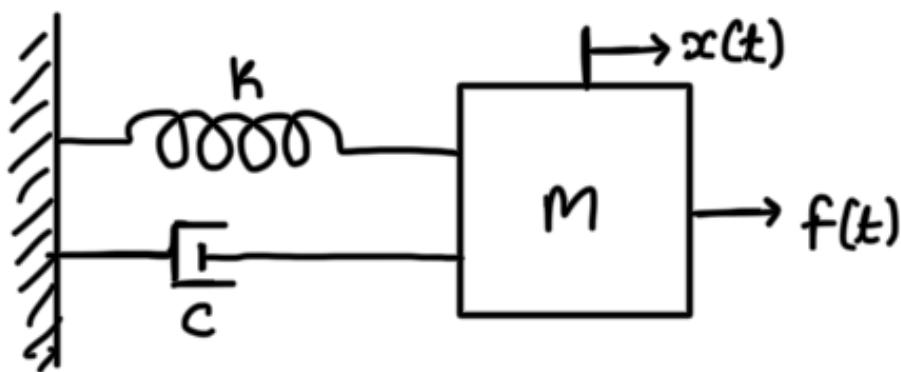
$$0 > \tan^{-1} \frac{\omega}{10} > \frac{\pi}{4}$$

$$0 > \tan^{-1} \frac{\omega}{100} < \frac{\pi}{4}$$

hence $\angle G_4 > 0$

\therefore adds positive phase

2.



input force : $f(t)$

output displacement : $x(t)$

B.1 1. $m \frac{d^2x}{dt^2} = f(t) - b \frac{dx}{dt} - cx(t)$ where b is damping constant

2. Taking Laplace : $(m\omega^2 + b\omega + c)X(s) = F(s)$

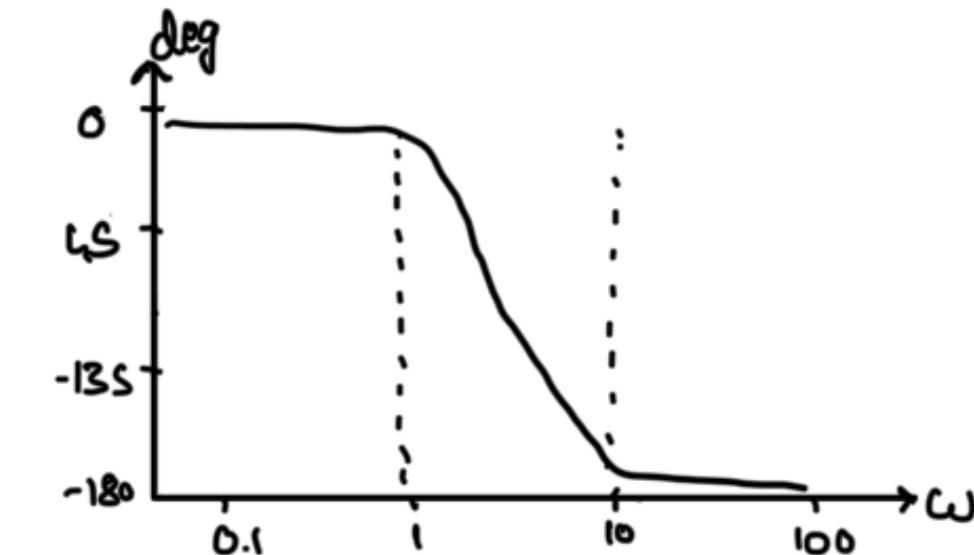
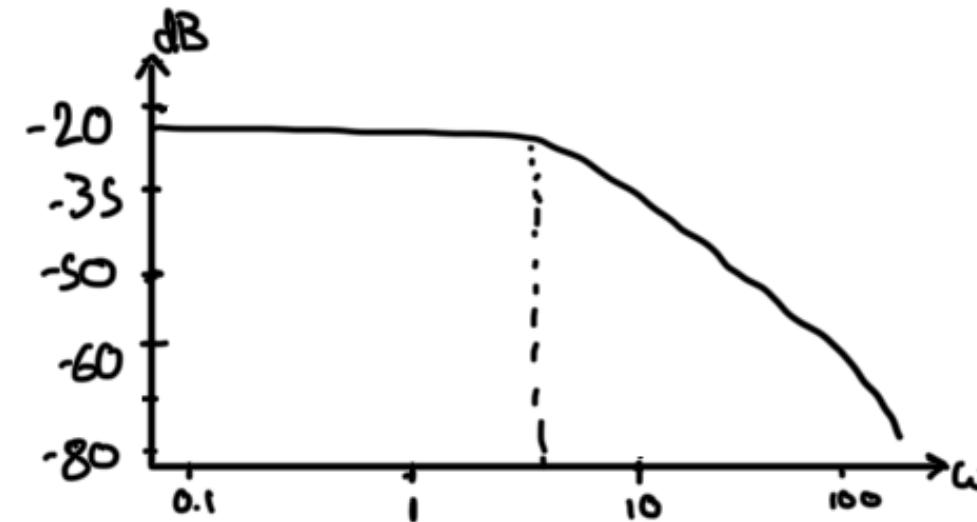
3. $G(s) = \frac{X(s)}{F(s)} = \frac{1}{m\omega^2 + b\omega + C}$

B.2 1. $m=1$, $b=4$, $c=16$ / all SI units

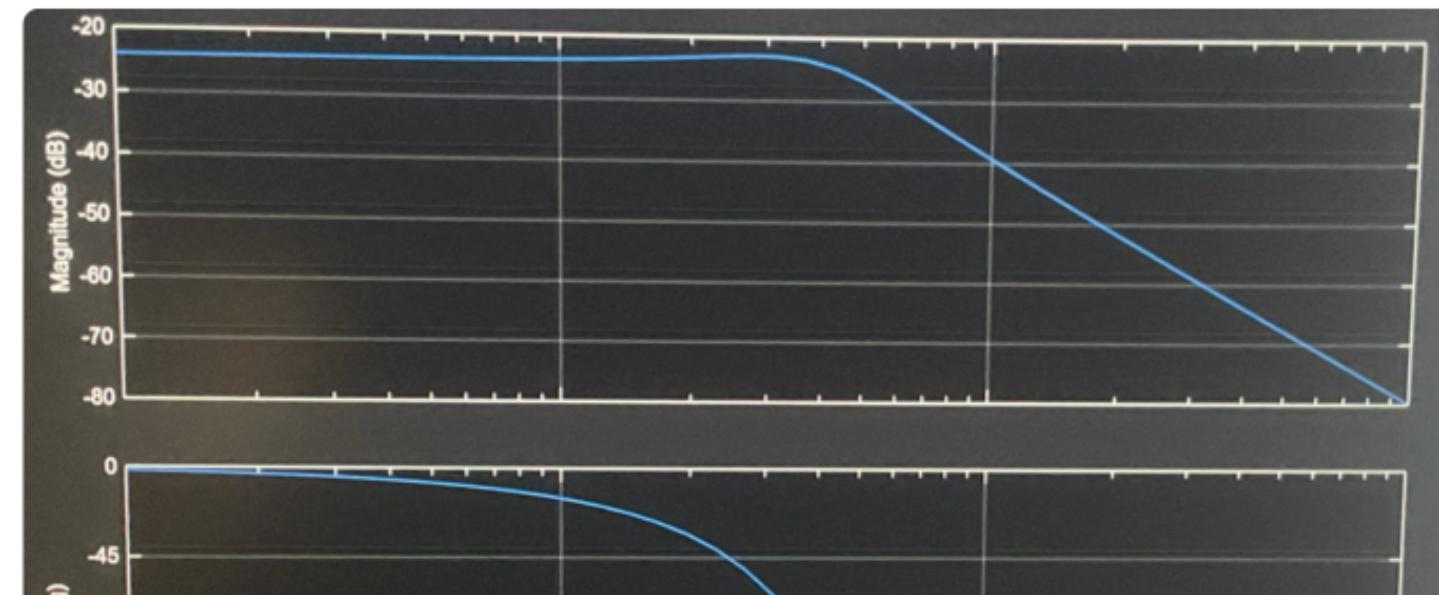
$$G(s) = \frac{1}{s^2 + 4s + 16}$$

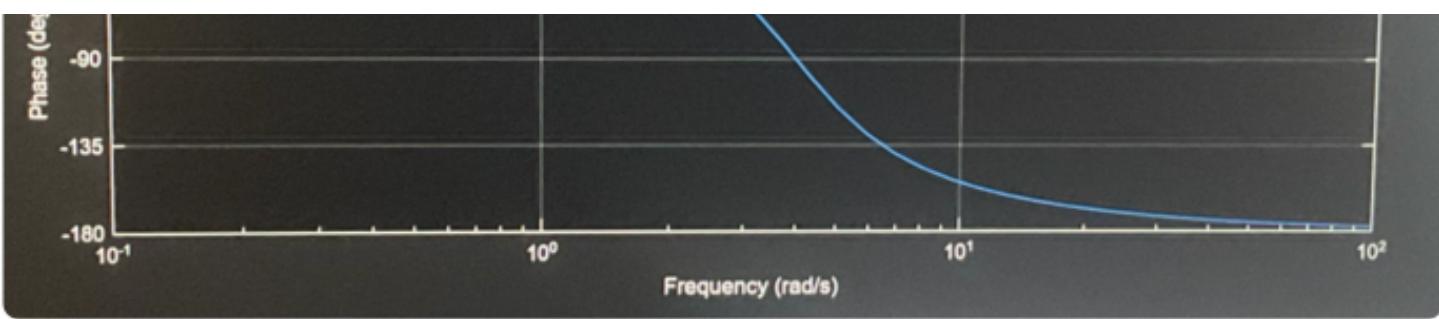
2. $s^2 + 4s + 16 = 0 \implies s = -2 \pm \sqrt{4 - 16} = -2(1 \pm j\sqrt{3}) = \text{poles}$

3.



4.





PROCEDURE TO PLOT BODE on MATLAB:

$$\text{for ex: } G(s) = \frac{as+b}{ps^2+qs+r}$$

num = [a b];

den = [p q r];

G = tf(num, den);

bode(g, [0.1, 100]); % angular frequency 0.1 to 100
grid on;

▷ Run