

# Sign Language Recognition using Machine Learning

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**Abstract**—One of the ways to communicate with deaf and dumb individuals is through sign language. So, in order to speak with deaf and dumb people, one should learn sign language; yet, because not everyone can learn it, communication becomes nearly impossible. The goal of this study is to use machine learning to break through these communication hurdles. The majority of existing technologies rely on external sensors, which are out of reach for most people. We utilize OpenCV to take images and the CNN technique to train the machine, with the output being text. Many previous studies have offered methods for partial sign language identification, however this study intended for the full acceptance of American Sign Language comprises of 26 letters and 10 numbers. The majority of ASL letters are static, however few are dynamic. As a result, the goal of this research was to extract features from finger and hand motions in order to distinguish between static and dynamic gestures.

**Keywords**—Computer vision, imbalanced distribution, ML algorithm, hyperparameters.

## I. INTRODUCTION

Communication is an important component of our day-today lives since it allows us to share information. As speculated Nelson Mandela's quote "Talking to a man in a language he knows goes straight to his head." If you speak to him in his native tongue, you will touch his heart." Language has existed since the birth of civilization and is indisputably fundamental to human communication. It is a medium through which individuals express themselves and comprehend real-world concepts. People with hearing impairments are often overlooked and left out in today's fast-paced culture. They must fight to communicate themselves to those who are different from them, to bring up their thoughts, to speak their opinions, and to express themselves [1]. Even though sign language is a means of communication for deaf and dumb individuals, it has no significance for

nonsign language users. Around 60 million Indians are deaf and dumb. The majority of individuals communicate with normal people through signals, which are extremely difficult to interpret and make communicating information impossible. We are proposing a sign language recognition technology to prevent this from happening. It will be a fantastic tool for persons with Hearing impairments can use sign language to communicate their thoughts, while non-sign language users can understand what the latter is saying. The first three steps of a sign language recognition system are database creation, classification, and prediction [2]. We use the American sign language as a database in our project to allow deaf and dumb people to communicate. We need a sign database with 26 English alphabet signs and 10 numeric signs with proper images for this project. A specific image is assigned to each number or alphabet. These images are in .jpg format, and they were collected as greyscale images during the collection process. These excreted images are fed into the model as input. CNN is used to train the machine, and the output is a text.

Technically, generating descriptors to convey hand forms and motion trajectory is the most difficult aspect of sign language recognition. Hand-shape description, in particular, entails tracking hand regions in a video stream, segmenting hand-shape images from a complicated background in each frame, and problems with gesture detection. The tracking of critical points and curve matching are also related to motion trajectory. Despite the fact that numerous research studies have been undertaken on these two topics to date, SLR remains difficult to achieve satisfactory results due to the variance and occlusion of hands and body joints. Furthermore, integrating the hand-shape and trajectory information together is a difficult task. To overcome these issues, we created a 3D CNN that can organically incorporate hand forms, action trajectory, and facial

expression. Rather than using commonly used color images as input to networks like [1, 2], We use a mixture of color images, depth images, and body skeleton data from the Microsoft Kinect to create our final product. When a person moves, the Kinect motion sensor produces both a color scheme and a depth stream. The locations of the body joints can indeed be procured in realtime by leveraging the public Windows SDK. As a result, we chose Kinect as the capture device for the dataset of sign words. Color and depth changes at the pixel level provide useful information for distinguishing between distinct sign activities. And the trajectory of sign actions can be depicted by the fluctuation of bodily joints in time. CNNs pay attention to changes not only in color, but also in depth and trajectory, when many types of visual sources are used as input. Because CNNs have the ability to learn features automatically from raw data without any prior information, we may bypass the difficulties of tracking hands, segmenting hands from background, and creating descriptors for hands [3]. In recent years, 3D CNNs have been used to classify video streams [2, 4, 5]. CNNs may be concerned about the amount of time it takes to do a task. Training a CNN with a million-scale in million videos takes several weeks or months. Fortunately, using CUDA for parallel processing, it is still possible to attain real-time efficiency.

## II. RELATED WORK

The following is a literature review on the subject, it becomes clear that a variety of strategies have been developed to tackle the issues of gesture identification in video. Hidden Markov Models (HMM) were used in conjunction with Bayesian Network Classifiers and the Gaussian Tree Augmented Naïve Bayes Classifier in [5] to differentiate between different facial expressions captured in video clips.

In particular with regard, Francois et al. [6] presented their work on Human Posture Recognition in an Image Sequences Using 2D and 3D Appearance Methods, on Pattern Recognition. According to the research, PCA is being used to acknowledge silhouettes from a static camera, and then 3D is being used to model posture in order to identify the silhouette. This method has the drawback of necessitating the use of intermediate step gestures, which can lead to ambiguity during training as well as, as a result, decreased prediction accuracy.

The analysis of video segments, which encompasses the extraction of visual information in the form of feature vectors, is a common application of neural networks. Hand tracking, segmentation of people from the background and surroundings, variability in lighting, occlusion, movements, and position are all issues that Neural Networks have to deal with when working with images. According to Nandy et al. [7], they split the dataset into segments and extract features before categorising them using Euclidean Distance and K-Nearest Neighbors, respectively. In a similar vein, Kumud et al. [8] describe Continuous Indian Sign Language Recognition in the same way.

## III. METHODOLOGY

In our model we give our own data as the data set to train the modules and the data set will be pre-processed. We apply the pre-processing approach in MATLAB to normalise the luminance of individual particle pictures and remove low frequency background noise. Firstly, we convert RGB images into grey scale images by eliminating the saturation and hue while retaining the luminance. The Feature extraction takes place, by using CNN to extract information from the frames and forecast hand gestures, a model is utilised. It's a multilayered feed forward neural network used primarily for image identification. The CNN design is made up of numerous convolution layers, each of which has a different function. Has a pooling layer. Our proposed system comprises of the following major steps.

- Creating a Dataset
- Pre-processing
- Feature Extraction
- Applying Model

### 3.1 CREATING A DATASET

We are creating the dataset in this project. Each frame that detects a hand within the ROI (Region of Interest) formed may be saved in a directory that has two folders, train and test, each with 36 files containing recorded images of numerals from 1 to 10 and alphabets from a to z. Now, we'll use OpenCV to collect the live cam stream in order to create the dataset. And create a ROI, which is a We want to detect the hand for the motion in this part of the frame.

### 3.2 PREPROCESSING

After receiving the image from the user, we must

preprocessit. The pre-processing procedure is used to remove low-frequency background noise and normalise the intensity of individual particle pictures. RGB photos are converted to greyscale images. We can execute noise removal and segmentation operations at this step. The basic goal of preprocessing is to reduce input data distortion and development (sign language images). The image preprocessing approach takes advantage of image redundancy. A neighbouring pixel in the actual image that corresponds to one object has been modified to a similar brightness value. The median filter is used to minimise salt and pepper noise in photos during preprocessing.

### 3.3 FEATURE EXTRACTION

Every image contains a vast amount of data, and feature extraction is the process of automatically extracting this data from the images. The input data that will be processed is reduced to a smaller collection of features. Feature extraction is the term for this method. The Feature Extraction stage is required because certain features must be extracted in order for each gesture or sign to be unique.

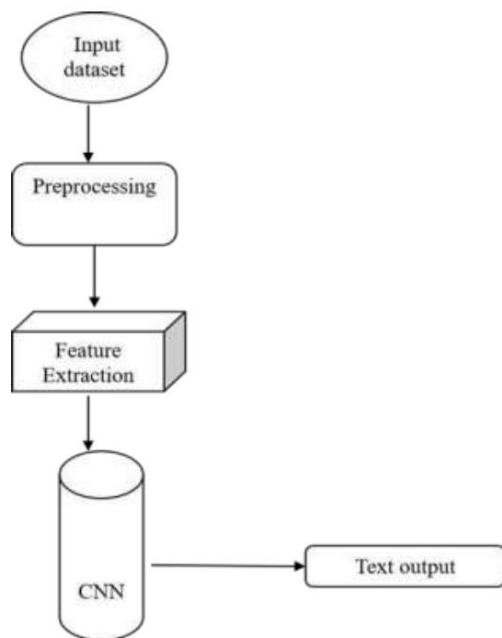


Fig. 1. Proposed System workflow

### 3.4 CONVOLUTIONAL NEURAL NETWORK

The goal of CNN is to understand the technical in the information with higher intelligence using convolution layer in addition to learning the engaging in positive in the data. The Proposed system performs admirably when it comes to object recognition, including image recognition.

They are capable of distinguishing between individual people, continues to face, road signs, and other aspects of visual information. As illustrated in Fig. 2, there are many different CNN variations, but each one is based just on sequence of layers that is present in the system. The Convolution layer is made up of several components, each of which has a different set of two – layer and processing elements to perform. The following section explains the objectives and functionality of some frequently used layers, which are described in greater detail below. The convolutional layer is a type of layer. The convolutional layer is one of the fundamental elements of CNN architecture. It is possible to alter the input data using convolutional layers (Conv), which are made up of a patch of neurons that are connected domestically from the preceding stage. In the output nodes, the dot product will indeed be calculated by the layer that sits between both the area of neurons that are prevalent in the input nodes and the weight training that are prevalent in the output layer to which they would be regionally connected.

A convolution is a mathematical function that characterizes the principle for combining two sets of data into a single larger set of information. According to Fig. 3, the convolution reads the input an extracted feature, appears to apply a convolution filtration or kernel, and gets back an extracted features as an output as has been shown. It is demonstrated in this operation how sliding the kernel from across data input results in the convoluted expected output. At every step, the data input values are magnified by the operating system within its boundaries, and a specific value in the predicted output is created from the result of the multiplication.

The identifying the determinants is the single most important layer. Because this automatic detection problem is a multiclassification problem, the softmax function is being used in the output nodes to classify the results. Finally, the fully -connected layer with 100 neurons is being used to quantify the class scores, which is the fully connected layer. The number 1000 refers to the total number of classes in the dataset in this case. In general, the CNN architecture consists of four main layers: a convolutional layer, a pooling layer, a ReLU layer, and a fully connected or output layer. The convolutional layer is the first of these layers. Testing of the suggested model was carried out on approximately 50 different CNN models by varying hyperparameters such as filter size, stride, and

padding in the manner described in this paper, and the results were encouraging. A number of different combinations of convolutional and pooling layers have been tried out to see how well the system works. In order to improve the effectiveness of the results, an additional layer, referred to as the dropout layer, is included in the proposed approach. The dropout layer is a training algorithm which is used to dismiss randomly chosen neurons during the training process, thereby reducing the likelihood of overfitting.

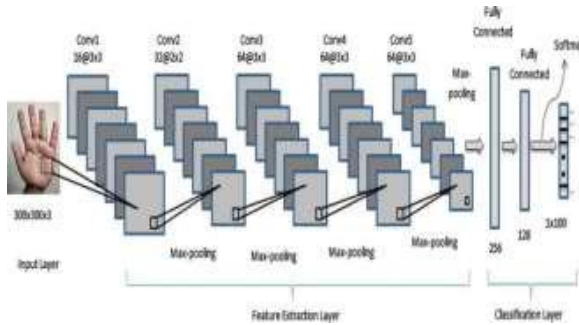


Fig. 2. Schematic representation of CNN

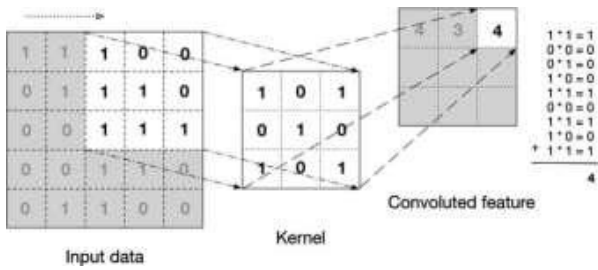


Fig. 3. General Convolutional operation

$$Outcome = \frac{W-G+2P}{T} + 1 \quad \{1\}$$

The outcome with respect to convolutional operation is represented in eqn. 2.

$$b_j^t = g \left( \sum_{j \in b_j} x_j^{t-1} \times m_{ij}^t + c_j^t \right) \quad \{2\}$$

$$g(y) = \max(0, y) \quad \{3\}$$

#### IV. EXPERIMENTATION & RESULT DISCUSSION

Two separate experiments are used to assess the recognition method for Indian Sign Language performed well. To begin, the parameters used to train the model have been fine-tuned, including the layer count, filters, and optimizers. The trained model's performance was tested in the second experiment, which is assessed on both colour and grayscale image datasets. The ISL recognition

system's average precision, recall, F1-score, and accuracy have also been calculated.

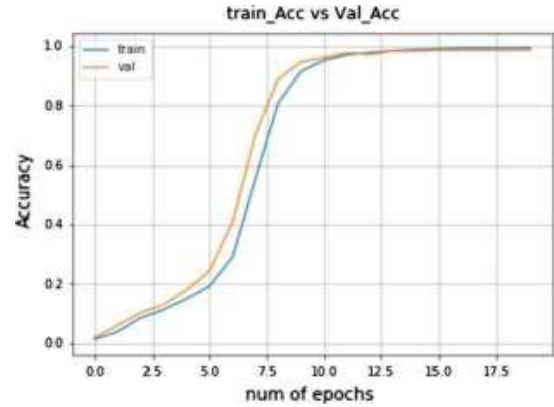


Fig. 4. Training Accuracy of our proposed model

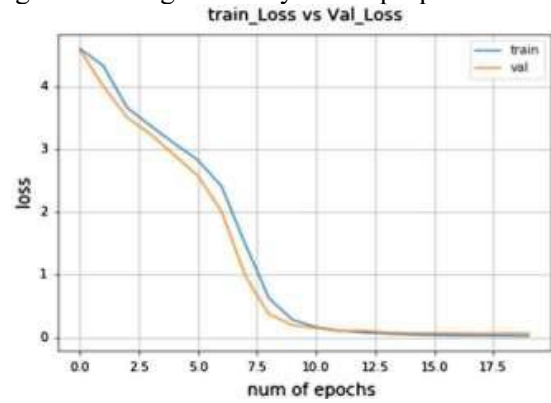
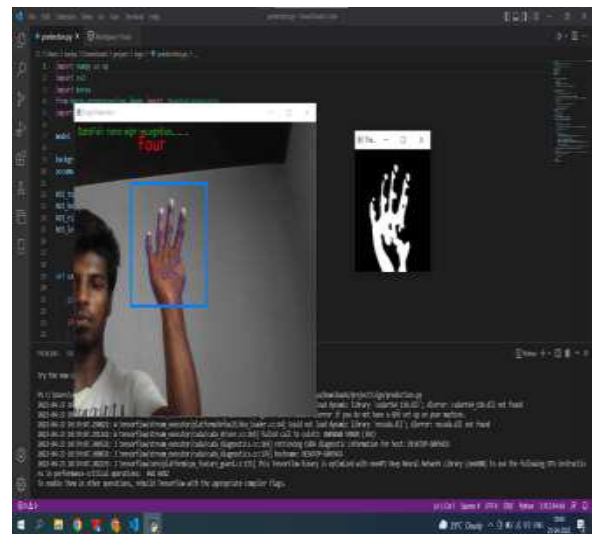


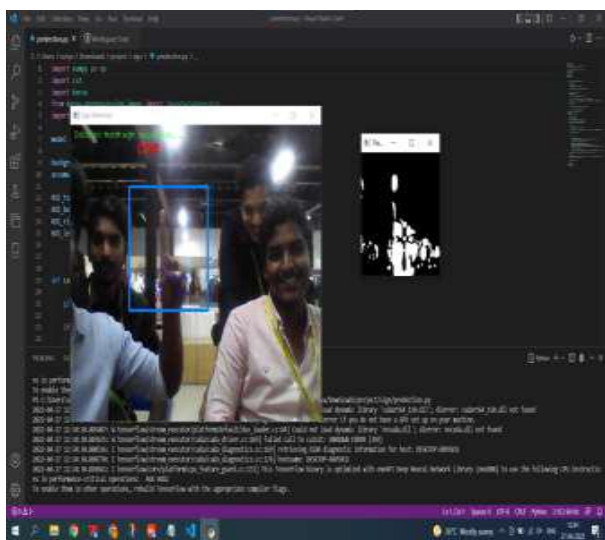
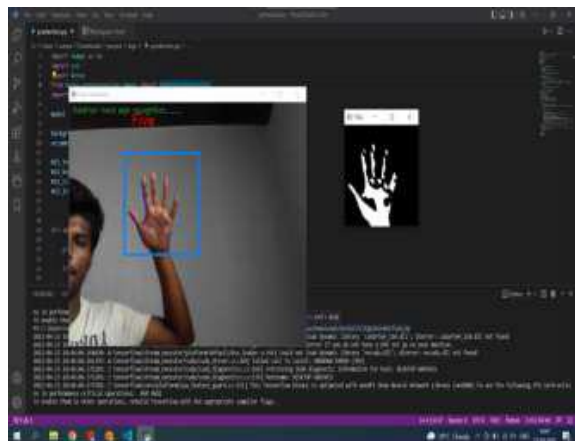
Fig. 5. Training loss of our proposed model

#### Result Screenshot

[Note: The red color text above the bounding box displays the output of the hand sign shown].







## V. CONCLUSION

Number and character images are used to represent the identified hand motions. Ten different numbers and alphabets are used in the experiment. The accuracy of the system described above is more than 90%. For overall performance analysis of suggested Systems, general performance measures such as False Accept Rate and False Reject Rate are chosen.

The rate of false acceptance and rejection is less than 2%. In the dynamic recognition approach, 10 photos are incurred in real time (10 occurrences or 10 for each class). For the database, we receive 3100 photographs. During the testing, all of the photos save the fifth one yielded the proper result. The rate of sign recognition is 95%. The rate of result identification varies depending on the testing sample's Convolutional neural network deep learning model is used in this Recognizing system. The coding is done in real time, using a consistent light source and a plain white background.

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