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KL divergence is defined as, $KL(p||q) = \int_{-\infty}^{\infty} p(x) \log \frac{p(x)}{q(x)} dx$. Let us try with $p(x) = p_{data}(x)$ and $q(x) = p(x|\theta)$. Then,

$$KL(p||q) = \int_{-\infty}^{\infty} p_{data}(x) \log p_{data}(x) dx - \int_{-\infty}^{\infty} p_{data}(x) \log p(x|\theta) dx$$

Minimizing the KL divergence with respect to θ , and ignoring the first term since it doesn't depend on θ , we get,

$$\arg \min_{\theta} KL(p||q) = \arg \min_{\theta} - \int_{-\infty}^{\infty} p_{data}(x) \log p(x|\theta) dx$$

Note that we can approximate the integral (expectation wrt $p_{data}(x)$) on RHS using Monte Carlo approximation. Let us use the N observations $(\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N)$ given. As $N \rightarrow \infty$, Monte-Carlo approximation gets almost equal to the integral.

$$\arg \min_{\theta} KL(p||q) = \arg \max_{\theta} \sum_{n=1}^N \log p(x_n|\theta)$$

The RHS now is precisely the maximum log-likelihood estimate (same as MLE since log is increasing function). Hence, we have shown that minimising KL divergence is equivalent to maximising the MLE.

Note that, had we taken $q(x) = p_{data}(x)$ and $p(x) = p(x|\theta)$, then $KL(p||q)$ wouldn't have given us the solution.

$$KL(p||q) = \int_{-\infty}^{\infty} p(x|\theta) \log p(x|\theta) dx - \int_{-\infty}^{\infty} p(x|\theta) \log p_{data}(x) dx$$

This would require us to compute the expectation wrt $p(x|\theta)$ which is actually an unknown distribution. We can't make use of Monte carlo approximation here.

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Let $\{X_i\}_{i=1}^N$ be N i.i.d Gaussian random variables drawn from $\mathcal{N}(\mu, \sigma^2)$. Let us take an $N \times 1$ matrix $A = \left[\frac{1}{N} \frac{1}{N} \cdots \frac{1}{N}\right]$ and let X be a random vector $X = [X_1 X_2 \cdots X_N]^T$. Let $\bar{X} = AX$. Note that \bar{X} is a Gaussian random variable too. Then,

$$\begin{aligned}\mathbb{E}[\bar{X}] &= A\mathbb{E}[X] = \left[\frac{1}{N} \frac{1}{N} \cdots \frac{1}{N}\right] \times [\mathbb{E}[X_1] \mathbb{E}[X_2] \cdots \mathbb{E}[X_N]]^T \\ &= \left[\frac{1}{N} \frac{1}{N} \cdots \frac{1}{N}\right] \times [\mu \mu \cdots \mu]^T = \mu\end{aligned}$$

$$\begin{aligned}\text{Cov}(\bar{X}) &= A\text{Cov}(X)A^T \\ &= \left[\frac{1}{N} \frac{1}{N} \cdots \frac{1}{N}\right] \text{diag}(\sigma^2, \sigma^2, \dots, \sigma^2) \left[\frac{1}{N} \frac{1}{N} \cdots \frac{1}{N}\right]^T \\ &= \frac{N\sigma^2}{N^2} = \frac{\sigma^2}{N}\end{aligned}$$

Note that we get a diagonal matrix because X_i 's are independent, ie, $\text{cov}(X_i, X_i) = \sigma^2$ and $\text{cov}(X_i, X_j) = 0$ for $i \neq j$. Thus, $\bar{X} \sim \mathcal{N}\left(\mu, \frac{\sigma^2}{N}\right)$

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Proof of a simple trick being used in this problem : replacement of set of observations of Gaussian distribution by its empirical mean, assuming variance is known.

$$\frac{\sum_{i=1}^N (x_i - \mu)^2}{2\sigma^2} = \frac{\sum (x_i - \bar{x} + \bar{x} - \mu)^2}{2\sigma^2} = \frac{N(\bar{x} - \mu)^2}{2\sigma^2} + \frac{S^2}{2\sigma^2}$$

where \bar{x} and S^2 are empirical mean and empirical variance respectively. In the given problem, for the posterior distribution of μ_m , we need to only consider the school m, and we can replace the observations by empirical mean of school m as shown below–

$$\begin{aligned} p(\mu_m | x^{(m)}, \mu_0 \sigma^2, \sigma_0^2) &= \frac{p(x^{(m)} | \mu_m, \sigma^2) p(\mu_m | \mu_0, \sigma_0^2)}{\int p(x^{(m)} | \mu_m, \sigma^2) p(\mu_m | \mu_0, \sigma_0^2) d\mu_m} \\ &\propto \exp\left(-\frac{\sum_{i=1}^{N_m} (x_i^{(m)} - \mu_m)^2}{2\sigma^2}\right) \exp\left(-\frac{(\mu_m - \mu_0)^2}{2\sigma_0^2}\right) \\ &\propto \exp\left(-\frac{N(\bar{x}^{(m)} - \mu)^2}{2\sigma^2}\right) \exp\left(-\frac{(\mu_m - \mu_0)^2}{2\sigma_0^2}\right) \end{aligned}$$

Using completing the squares trick, we readily get the posterior mean μ_{mp} and variance σ_{mp}^2 as

$$\begin{aligned} \mu_{mp} &= \frac{\sigma_0}{N_m \sigma_0^2 + \sigma^2} \mu_0 + \frac{N_m \sigma_0^2}{N_m \sigma_0^2 + \sigma^2} \bar{x}^{(m)} \\ \frac{1}{\sigma_{mp}^2} &= \frac{1}{\sigma_0^2} + \frac{N_m}{\sigma^2} \end{aligned}$$

Thus, the posterior distribution is $\mu_m \sim \mathcal{N}(\mu_{mp}, \sigma_{mp}^2)$ The marginal likelihood is given by,

$$\begin{aligned} p(x | \mu_0, \sigma^2, \sigma_0^2) &= \prod_{m=1}^M \int p(x^{(m)} | \mu_m, \mu_0, \sigma^2, \sigma_0^2) p(\mu_m | \mu_0, \sigma_0^2) d\mu_m \\ &= \prod_{m=1}^M \frac{p(x^{(m)} | \mu_m, \sigma^2) p(\mu_m | \mu_0, \sigma_0^2)}{p(\mu_m | x^{(m)}, \mu_{mp}, \sigma_{mp}^2)} \end{aligned}$$

The above is the exact value. We can use the same trick of replacing with $\bar{x}^{(m)}$ to get,

$$p(x | \mu_0, \sigma^2, \sigma_0^2) = \prod_{m=1}^M \mathcal{N}\left(\bar{x}^{(m)}, \mu_m, \frac{\sigma^2}{N_m}\right) \mathcal{N}(\mu_m | \mu_0, \sigma_0^2) = \prod_{m=1}^M \mathcal{N}\left(\bar{x}^{(m)} | \mu_0, \sigma_0^2 + \sigma^2/N_m\right)$$

We have used $\bar{x}^{(m)} = \mu_m + \epsilon$, and took expectation and variance. $\mathbb{E}[\bar{x}^{(m)}] = \mu_0$ and $\text{Var}[\bar{x}^{(m)}] = \sigma_0^2 + \sigma^2/N_m$ Computation of MLE-II involves taking maximum wrt μ_0 of the marginal log

likelihood. Doing so with the empirical mean replaced version of marginal likelihood, and taking derivative wrt μ_0 we get,

$$\begin{aligned}\sum_{m=1}^M \frac{\bar{x}^{(m)} - \mu_0}{\sigma_0^2 + \sigma^2/N_m} &= 0 \\ \Rightarrow \mu_0 &= \frac{\sum_{m=1}^M \frac{\bar{x}^{(m)}}{\sigma_0^2 + \sigma^2/N_m}}{\sum_{m=1}^M \frac{1}{\sigma_0^2 + \sigma^2/N_m}}\end{aligned}$$

The above is the MLE-II estimate of μ_0 .

Substituting the obtained MLE-II estimate of μ_0 in μ_{mp} , we get

$$\mu_{mp} = \frac{\sigma_0}{N_m \sigma_0^2 + \sigma^2} \frac{\sum_{m=1}^M \frac{\bar{x}^{(m)}}{\sigma_0^2 + \sigma^2/N_m}}{\sum_{m=1}^M \frac{1}{\sigma_0^2 + \sigma^2/N_m}} + \frac{N_m \sigma_0^2}{N_m \sigma_0^2 + \sigma^2} \bar{x}^{(m)}$$

This increases the probability of marginal likelihood of X given the hyperparameters. There is no change in the form of the solution. The posterior is still a normal distribution with a different mean. Instead of taking any random μ_0 , we took a specific μ_0 .

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We have $p(Z|\alpha) = \int p(Z|\pi, \alpha) p(\pi|\alpha) d\pi$. Since the entries are generated independently, we have

$$\begin{aligned} p(Z|\alpha) &= \int \int \cdots \int_K \prod_{n=1}^N \left(\prod_{k=1}^K p(Z_{nk}|\pi_k, \alpha) \right) \prod_{k'=1}^K p(\pi_{k'}|\alpha) d\pi_1 d\pi_2 \cdots d\pi_K \\ &= \prod_{k=1}^K \int \prod_{n=1}^N (\pi_k)^{z_{nk}} (1 - \pi_k)^{1-z_{nk}} p(\pi_k|\alpha) d\pi_k \\ &= \prod_{k=1}^K \int (\pi_k)^{\sum z_{nk}} (1 - \pi_k)^{N - \sum z_{nk}} \frac{\pi_k^{\frac{\alpha}{K} - 1}}{B\left(\frac{\alpha}{K}, 1\right)} \\ &= \prod_{k=1}^K \frac{B\left(\sum_{n=1}^N z_{nk} + \frac{\alpha}{K}, N + 1 - \sum_{n=1}^N z_{nk}\right)}{B\left(\frac{\alpha}{K}, 1\right)} \end{aligned}$$

where $B(a, b) = \frac{\Gamma(a)\Gamma(b)}{\Gamma(a+b)}$. So, we see that it can be written in the form of product of ratios of beta functions.

For the next part, note that $p(Z_{nk} = 1|Z_{-nk}) = \int_0^1 \pi_k p(\pi_k|Z_{-nk}) d\pi_k = \mathbb{E}[\pi_k]$ wrt the posterior distribution of $p(\pi_k|Z_{-nk})$

$$p(\pi_k|Z_{-nk}) = \frac{p(Z_{-nk}|\pi_k) p(\pi_k)}{\int_0^1 p(Z_{-nk}|\pi_k) p(\pi_k) d\pi_k}$$

The posterior distribution can be easily obtained by seeing the column as tossing a coin $N-1$ times, getting $\sum_{i=1, i \neq n}^N z_{ik} = t_{-nk}$ heads. We readily get the posterior distribution as,

$$\begin{aligned} p(\pi_k|Z_{-nk}) &= \text{Beta}\left(\frac{\alpha}{K} + t_{-nk}, N - t_{-nk}\right) \\ \implies \mathbb{E}[\pi_k] &= \frac{\frac{\alpha}{K} + t_{-nk}}{\frac{\alpha}{K} + N} \end{aligned}$$

This form of result makes intuitive sense. Before observing Z_{-nk} , $p(Z_{nk} = 1) = \mathbb{E}[\pi_k]$ wrt $p(\pi_k)$, the prior distribution, which is $\frac{\frac{\alpha}{K}}{\frac{\alpha}{K} + 1}$. This is supported by $\frac{\alpha}{K} + 1$ datapoints. Considering only the observations Z_{nk} , the value is $\frac{t_{-nk}}{N-1}$ which is supported by $N-1$ datapoints. So,

$$\mathbb{E}[\pi_k] = \frac{\left(\frac{\alpha}{K} + 1\right) \left(\frac{\frac{\alpha}{K}}{\frac{\alpha}{K} + 1}\right) + (N - 1) \left(\frac{t_{-nk}}{N-1}\right)}{\frac{\alpha}{K} + 1 + N - 1}$$

It is like a weighted average of our prior and posterior beliefs. Also note that, as $K \rightarrow \infty$, the value becomes $\frac{t_{-nk}}{N}$. This is like replacing a missing value in a column with the column average.

Finally, to get the expected number of 1s in a column and in the entire matrix,

$$\begin{aligned}\mathbb{E}[z_{nk}] &= 1 \times p(z_{nk} = 1|\alpha) + 0 \times p(z_{nk} = 0|\alpha) = \int_0^1 p(z_{nk} = 1|\pi_k, \alpha) p(\pi_k|\alpha) d\pi_k \\ &= \mathbb{E}[\pi_k] = \frac{\frac{\alpha}{K}}{\frac{\alpha}{K} + 1}\end{aligned}$$

By linearity of expectations, (and given that z_{nk} 's independently generated), we get the expected number of ones in a column as $N\mathbb{E}[z_{nk}]$ and number of ones in the entire matrix as $NK\mathbb{E}[z_{nk}]$. Thus, number of 1s in a column is $\frac{N\alpha}{\frac{\alpha}{K} + 1}$ and number of 1s in the entire matrix is $\frac{N\alpha}{\frac{\alpha}{K} + 1}$.

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The marginal prior on w , after integrating out b is given by,

$$\begin{aligned} p(w|\sigma_{spike}^2, \sigma_{slab}^2) &= p(w|b=1, \sigma_{spike}^2, \sigma_{slab}^2) \times p(b=1) + p(w|b=0, \sigma_{spike}^2, \sigma_{slab}^2) \times p(b=0) \\ &= \frac{1}{2} \mathcal{N}(w|0, \sigma_{slab}^2) + \frac{1}{2} \mathcal{N}(w|0, \sigma_{spike}^2) \end{aligned}$$

The plot of marginal prior with $(\sigma_{spike}^2, \sigma_{slab}^2) = (1, 100)$ is shown in Figure 1. Comparing with $\mathcal{N}(0, 1)$ distribution, we see that the marginal prior is a bit fat tailed, and the probability that a sample will be close to mean 0 is also less. This marginal prior doesn't force w to take the value of 0 as aggressively as a standard Normal distribution.

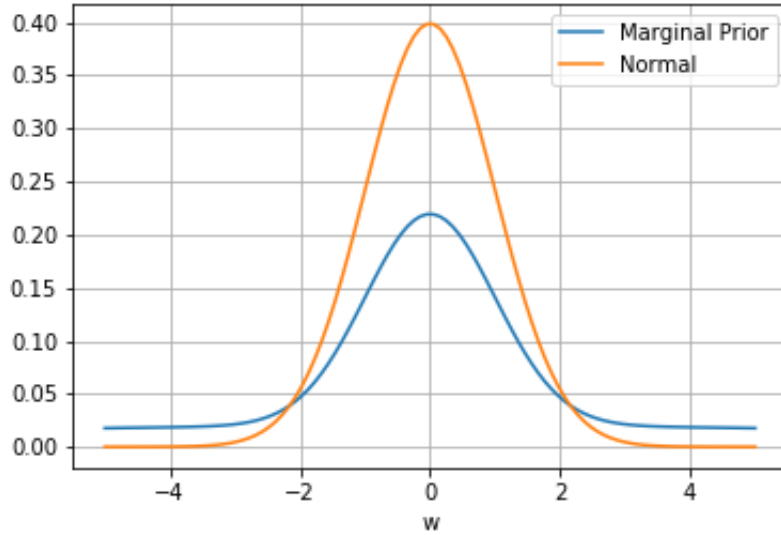


Figure 1: Marginal prior on w

$$\begin{aligned} p(b=1|w, \sigma_{spike}^2, \sigma_{slab}^2) &= \frac{p(w|b=1, \sigma_{spike}^2, \sigma_{slab}^2) \times p(b=1)}{p(w|b=1, \sigma_{spike}^2, \sigma_{slab}^2) \times p(b=1) + p(w|b=0, \sigma_{spike}^2, \sigma_{slab}^2) \times p(b=0)} \\ &= \frac{\mathcal{N}(w|0, \sigma_{slab}^2)}{\mathcal{N}(w|0, \sigma_{slab}^2) + \mathcal{N}(w|0, \sigma_{spike}^2)} \end{aligned}$$

$$\begin{aligned} p(b=1|x, \sigma_{spike}^2, \sigma_{slab}^2, \rho^2) &= \int p(b=1|w, x, \sigma_{spike}^2, \sigma_{slab}^2, \rho^2) p(w|x, \sigma_{spike}^2, \sigma_{slab}^2, \rho^2) dw \\ &= \int p(b=1|w, \sigma_{spike}^2, \sigma_{slab}^2) p(w|x, \sigma_{spike}^2, \sigma_{slab}^2, \rho^2) dw \end{aligned}$$

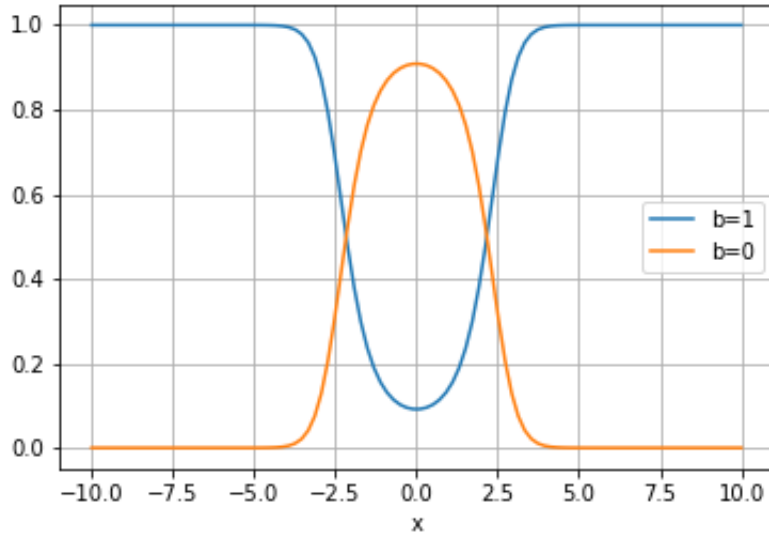
The above simplification stems from the fact that x in turn depends on w .

$$\begin{aligned}
p(w|x, \sigma_{spike}^2, \sigma_{slab}^2, \rho^2) &= \frac{p(x|w, \sigma_{spike}^2, \sigma_{slab}^2, \rho^2) p(w|\sigma_{spike}^2, \sigma_{slab}^2, \rho^2)}{\int p(x|w, \sigma_{spike}^2, \sigma_{slab}^2, \rho^2) p(w|\sigma_{spike}^2, \sigma_{slab}^2, \rho^2) dw} \\
&= \frac{\mathcal{N}(x|w, \rho^2) (\mathcal{N}(w|0, \sigma_{slab}^2) + \mathcal{N}(w|0, \sigma_{spike}^2))}{\int \mathcal{N}(x|w, \rho^2) (\mathcal{N}(w|0, \sigma_{slab}^2) + \mathcal{N}(w|0, \sigma_{spike}^2)) dw} \\
&= \frac{\mathcal{N}(x|w, \rho^2) (\mathcal{N}(w|0, \sigma_{slab}^2) + \mathcal{N}(w|0, \sigma_{spike}^2))}{\mathcal{N}(x|0, \rho^2 + \sigma_{slab}^2) + \mathcal{N}(x|0, \rho^2 + \sigma_{spike}^2)}
\end{aligned}$$

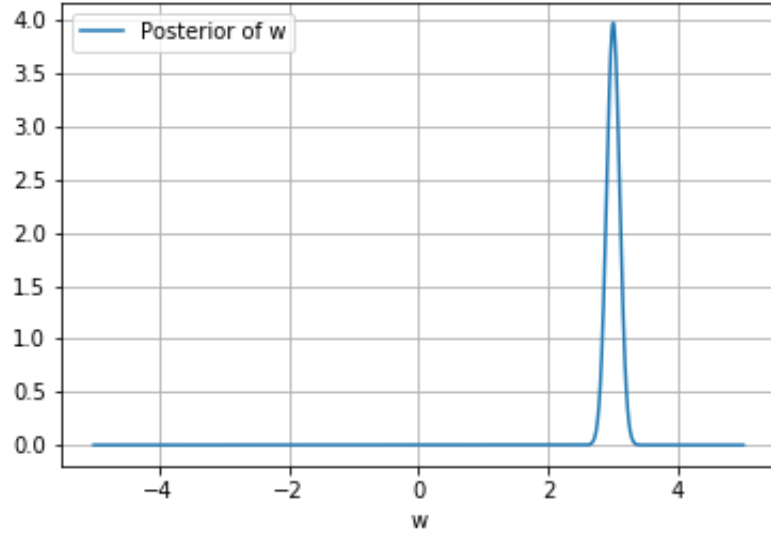
The denominator computation is easy, because $x = w + \epsilon \implies \mathbb{E}[x] = \mathbb{E}[w]$ and $\text{Var}[x] = \text{Var}[w] + \rho^2$. When we take $w \sim \mathcal{N}(w|0, \sigma_{slab}^2)$, we get $x \sim \mathcal{N}(x|0, \rho^2 + \sigma_{slab}^2)$. Similarly, we get $x \sim \mathcal{N}(x|0, \rho^2 + \sigma_{spike}^2)$ for $w \sim \mathcal{N}(w|0, \sigma_{spike}^2)$. Note that x is sum of two independent Gaussian random variables and hence Gaussian. So, we have

$$\begin{aligned}
p(b=1|x, \sigma_{spike}^2, \sigma_{slab}^2, \rho^2) &= \int \frac{\mathcal{N}(w|0, \sigma_{slab}^2)}{\mathcal{N}(w|0, \sigma_{slab}^2) + \mathcal{N}(w|0, \sigma_{spike}^2)} \times \frac{\mathcal{N}(x|w, \rho^2) (\mathcal{N}(w|0, \sigma_{slab}^2) + \mathcal{N}(w|0, \sigma_{spike}^2))}{\mathcal{N}(x|0, \rho^2 + \sigma_{slab}^2) + \mathcal{N}(x|0, \rho^2 + \sigma_{spike}^2)} dw \\
&= \frac{\mathcal{N}(x|0, \rho^2 + \sigma_{slab}^2)}{\mathcal{N}(x|0, \rho^2 + \sigma_{slab}^2) + \mathcal{N}(x|0, \rho^2 + \sigma_{spike}^2)}
\end{aligned}$$

The following plot shows $p(b=1|x, \sigma_{spike}^2, \sigma_{slab}^2, \rho^2)$ for $(\sigma_{spike}^2, \sigma_{slab}^2, \rho^2) = (1, 100, 0.01)$. Graph of $(b=0|x, \sigma_{spike}^2, \sigma_{slab}^2, \rho^2)$ is shown for comparison. If a value of x close to 0 is observed, this means that there is a very high chance of b being 0, ie, an irrelevant feature. If a value of x greater than 4 is observed, then it is almost certain that b is 1, ie, a relevant feature.



The plot of $p\left(w|x, \sigma_{spike}^2, \sigma_{slab}^2, \rho^2\right)$ is shown next. The value of x is taken to be 3, and other hyperparameters are same as before. As is evident from the figure, we see that there is a huge spike at $w = 3$. This is obvious because the noisy observation was at $x=3$, so w is also expected to be very close to 3.

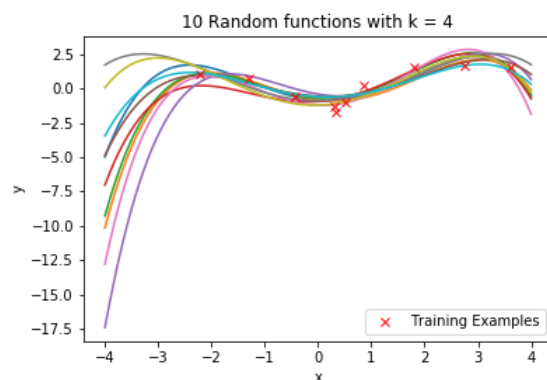
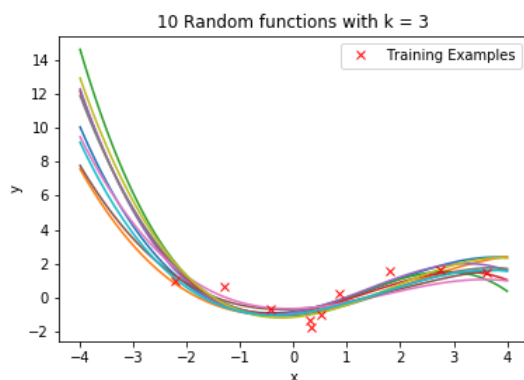
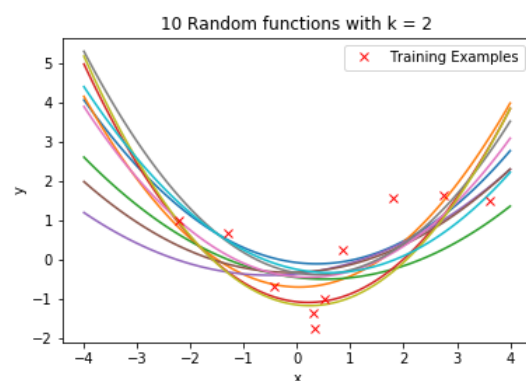
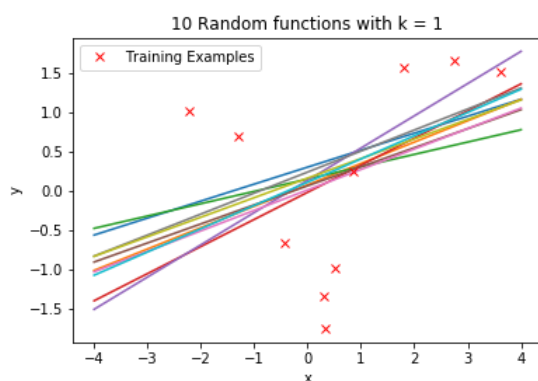


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The plot of 10 random functions inferred from the posterior are shown below. $k = 1$ clearly doesn't fit the data that well. We can only judge which model fits well looking at the marginal log likelihood (model comparison). The model with $k = 3$ seems to explain data the best since it has the highest marginal log likelihood value.



k	Marginal Log likelihood
1	-32.35
2	-22.78
3	-22.08
4	-22.39

Table 1: Marginal log likelihood for various values of k

The log likelihood values taking w_{map} are shown below. From the table, model with $k = 4$ has the highest log likelihood value. This is different from the marginal log likelihood case where we found model with $k = 3$ to be the best. We should consider marginal log likelihood over log likelihood to be the model indicator because we are considering the uncertainty in w in marginal LL computation. We integrate over all possible values of w to get marginal LL. However, for w_{map} LL, we ignore the uncertainty in w by taking a specific value of $w = w_{map}$. We can't put our faith in a model by looking at just a single value of w .

k	w_{map} Log likelihood
1	-28.09
2	-15.36
3	-10.9
4	-7.23

Table 2: Marginal log likelihood for various values of k

The plots of posterior predictive mean along with ± 2 times the standard deviation is shown next. Since $k = 3$ is our best model, from the figure it is obvious that we'd want an (x, y) pair in the region of $[-4, -2.5]$ to improve our learned model, as the variance / standard deviation is pretty high in this region. More specifically, the standard deviation is maximum at $x = -4$, so I'd prefer to get the y value for $x = -4$.

