

# SURYANSH KUMAR

B332, Brain Anderson Building, CECS, ANU, ACT 2601, Canberra. https://suryanshkumar.github.io



#### **EDUCATION**

· Australian National University.

Ph.D. in Engineering and Computer Science.

Research Area: Computer Vision.

Supervisory Panel: Yuchao Dai, Hongdong Li, Richard Hartley.

• IIIT-HYDERABAD.

M.S. in Computer Science and Engineering.

Research Area: Robot Vision. Supervisor: K Madhava Krishna. July 2011 - July 2013.

Sept. 2015 - Till date.

Expt. Graduation March 2019

#### AWARDS AND ACHIEVEMENTS

- · Awarded ANU Vice-Chancellor Grant.
- · Winner of NRSfM Challenge at CVPR 2017, Prize awarded by Disney Research.
- · Student funding to attend ICML 2017, Sydney Australia and ICCV 2017, Venice Italy.
- · Student funding to attend Robot Vision Summer School 2016, Kiola, Australia.
- · Recipient of "Australian National University Higher Degree Research" Merit Scholarship Award.
- · Recipient of "Best Innovative Group 2014", by Uurmi Systems Private Limited, India.
- Fully funded by Campus France to do research at INRIA, Grenoble-France.
- · Full-Time Scholarship Student for MS program at IIIT-Hyderabad, India.
- · Winner of "8085 Programming" and "Project Demonstration" contest at TITIKSHA 2008.

#### **Publications**

- [1] Suryansh Kumar, Yuchao Dai, Hongdong Li. Superpixel Soup: Monocular Dense 3D Reconstruction of a Complex Dynamic Scene. Transactions on Pattern and Machine Intelligence, 2018 (**T-PAMI**), IEEE, (Under Review).
- [2] Suryansh Kumar, Anoop Cherian, Yuchao Dai, Hongdong Li. Scalable Dense Non-rigid Structure from Motion: A Grassmannian Perspective. Conference on Computer Vision and Pattern Recognition (CVPR), IEEE, 2018, Utah, USA.
- [3] Suryansh Kumar, Yuchao Dai, Hongdong Li. Monocular Dense 3D Reconstruction of a Complex Dynamic Scene from Two Perspective Images. International Conference on Computer Vision (ICCV), IEEE, 2017, Venice, Italy.
- [4] Suryansh Kumar, Yuchao Dai, Hongdong Li. Spatio-Temporal Union of Subspaces for Multi-body Non-rigid Structure-from-Motion. Pattern Recognition Journal (PR), Elsevier, 2017. (Received Best Algorithm Award in NRSFM Challenge at CVPR 2017)
- [5] Suryansh Kumar, Yuchao Dai, Hongdong Li.
   Multi-body Non-rigid Structure from Motion.
   International Conference on 3D Vision (3DV), IEEE, 2016, Stanford University, USA.
- [6] Suryansh Kumar, Siva Karthik M, K. Madhava Krishna.
  Markov Random Field based Small Obstacle discovery over Images.
  International Conference on Robotics and Automation (ICRA), IEEE, 2014, Hong Kong, China.
- [7] Suryansh Kumar, Ayush Dewan, K. Madhava Krishna. A Bayes filter based adaptive floor segmentation with homography and appearance cues. ICVGIP, ACM, 2012, IIT-Bombay, India. (Oral Presentation)

[8] Sarthak Upadhyay, Suryansh Kumar, K. Madhava Krishna. CRF Based Frontier Detection using Monocular Camera. ICVGIP, ACM, 2014, IISc Bangalore, India. (Oral Presentation)

#### RESEARCH INTERESTS

- · Computer Vision: 3D Reconstruction, Depth Estimation and Motion Segmentation.
- ROBOTICS: Camera Calibration, SLAM and Visual SLAM.
- · MATHEMATICS: Mathematical Optimisation, Compressed Sensing, Topological Manifolds.
- · Machine Learning: Deep Learning, Support Vector Machine, Probabilistic Graphical Models.
- OTHERS: Discrete Differential Geometry.

#### Professional Service

• REVIEWER: 3DV 2017, ICRA 2018, CVPR 2018, 3DV 2018, IEEE C.I Magazine 2018.

• TA, COMPUTER VISION COURSE. (ENGN4528/6528) Feb. 2018 - July 2018. Course Instructor: Hongdong Li.

• TA, Individual Engineering Project Course. (ENGN4200) Feb. 2017 - July 2017. Course Instructor: Yuchao Dai.

• TA, COMPUTER VISION COURSE. (ENGN4528/6528) Feb. 2017 - July 2017. Course Instructor: Jonghyuk Kim.

• Consultant-Engineer, Algorithm Developer. July 2014 - July 2015. Company: Uurmi Systems, Hyderabad, India.

#### RESEARCH EXPERIENCE

• INRIA, e-Motion, Grenoble-France. Sept. 2013 - Feb. 2014.

Visiting Scientist.

Topic: Autonomous Driving

Advisors: Dizan Vasquez, Christian Laugier.

• IIIT-Hyderabad, India. Jan. 2011 - Aug. 2013.

Research Assistant.
Topic: Robot Vision

Supervisor: K Madhava Krishna.

• IIT-HYDERABAD, INDIA. Aug. 2010 - Dec. 2010.

Project Associate.

Topic: Pervasive Sensor Networks Supervisor: P. Rajalakshmi.

## Online Course Certification

• Machine Learning

Coursera, License No: FBXH2KPEU44M, Course Instructor: Andrew Ng.

· Neural Networks and Deep Learning

Coursera, License No: UJWL63E4KPB2, Course Instructor: Andrew Ng.

• Improving Deep Neural Networks: Hyperparameter tuning, Regularization and Optimization Coursera, License No: PDVY9DCXEA7H, Course Instructor: Andrew Ng.

# TECHNICAL SKILL SET

- Programming Language: C/C++, Python.
- · Scripting Language: Matlab, Octave, Unix Shell Programming.
- · Libraries and APIs: OpenCV, OpenGL, ROS, Eigen, STL, Numpy, Scipy, Pangolin.
- Deep Neural Network Frameworks: PyTorch, TensorFlow.
- Web and Documentation: HTML, CSS,  $\LaTeX$  .
- · Others: Embedded C, Unix System Programming.

### LANGUAGES

English, Hindi.

References are available on request