# Sushmita Bhattacharya

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## RESEARCH INTERESTS

Reinforcement Learning, Autonomous Multiagent Systems, and Robotics.

#### **EDUCATION**

• Ph.D. in Computer Science Harvard University, MA, USA

Present

Advisor: Dr. Stephanie Gil

• M.Tech. in Computer Science Indian Institute of Technology Bombay

2015

Advisor: Dr. N. L. Sarda

• B.E. in Computer Science Indian Institute of Engineering Science and Technology Shibpur

2011

Advisor: Dr. Prasun Ghosal.

#### RESEARCH PROJECTS

## • Multiagent RL for autonomous taxicab pickup problems in urban environments

- Derived an online optimization framework using GNN-based offline policy approximation for coordinated taxi routing/pickup schedules with stochastic requests in downtown San Francisco.
- Proposed a Wasserstein distance-based switching framework that adapts to fluctuating demand distributions.
- Extended to a large urban map using map partition and a two-phased rollout-based online optimization framework that closely approximates a near-optimal policy. Presented associated theoretical bounds on the number of taxis.
- o Published a conference paper [4] at ICRA 2023 and a conference paper [3] at ICRA 2024.

# · RL for large POMDP with realistic computation and communication constraints

- Developed scalable multiagent rollout and approximate policy iteration algorithms for finding cooperative policies in large Partially Observable Markov Decision Processes with large control space and robust approaches to deal with imperfect agent communication.
- Proposed feature-based partitioning of the state-space and partitioned approximate policy iteration for problems with large state space to deal with exploration-exploitation issues with parallel computation.
- Published a journal paper [2] at IEEE T-RO, a journal paper [6] at IEEE RA-L, and a conference paper [5] at CoRL.

#### RESEARCH EXPERIENCE

• Interactive AI Personalization Research Intern at Apple Inc.

June 2022 - August 2022

• Graduate Research Assistant at Arizona State University

August 2018 - June 2020

## TEACHING EXPERIENCE

• Teaching Assistant at Arizona State University

o Topics in Reinforcement Learning, Instructor: Dr. D. P. Bertsekas

Spring 2020, Spring 2019

o Coordination of Multi-Robot Systems, Instructor: Dr. S Gil

Fall 2019

o Introduction to Artificial Intelligence, Instructor: Dr. S Gil

Spring 2019

o Planning and Learning Methods in AI, Instructor: Dr. S Gil

Fall 2018

• Teaching Assistant at Indian Institute of Technology Bombay

o Embedded Systems Lab, Instructor: Dr. Kavi Arya

Spring 2014

o Database and Information Systems Lab, Instructor: Dr. N. L. Sarda

Fall 2014

## TALKS AND PRESENTATIONS

- Sequential Decision-making with Reinforcement Learning Invited talk at Apple Inc, February, 2023.
- Multiagent Rollout and Policy Iteration for POMDP with Application to Multi-Robot Repair Problems Sushmita Bhattacharya, Siva Kailas, Sahil Badyal, Stephanie Gil, and Dimitri Bertsekas Presentation at Conference on Robot Learning (CoRL), 2020
- Reinforcement Learning for POMDP: Rollout and Policy Iteration with Application to Sequential Repair Sushmita Bhattacharya, Thomas Wheeler, Stephanie Gil, Dimitri Bertsekas Poster presentation at Learning for Dynamics and Control (L4DC), 2019

## **REVIEWER**

- Conference on Robotics and Automation (ICRA)
- International Conference on Intelligent Robots and Systems (IROS)

# OTHER WORK EXPERIENCE

• Software Developer in Microsoft India Development Center.

December 2016 - July 2018

• Data Scientist in Honeywell Technology Solution Labs.

July 2015 - December 2016

#### AWARDS AND ACHIEVEMENT

• 2022 Apple Scholars in AI/ML PhD Fellowship in Fundamentals of Machine Learning.

- Engineering Graduate Fellowship from Ira A. Fulton Schools of Engineering (Spring 2020) for extraordinary academic achievements.
- Secured All India Rank 57 among 2,24,160 candidates appeared in Graduate Aptitude Test in Engineering, 2013 in Computer Science.

## **PUBLICATIONS**

[1] Multiagent Reinforcement Learning: Rollout and Policy Iteration for POMDP with Application to Multi-Robot Problems,

**Sushmita Bhattacharya**, Siva Kailas, Sahil Badyal, Stephanie Gil, Dimitri Bertsekas, IEEE Transactions on Robotics, 2024.

- [2] Approximate Multiagent Reinforcement Learning for On-Demand Urban Mobility Problem on a Large Map, Daniel Garces, Sushmita Bhattacharya, Dimitri Bertsekas, Stephanie Gil, International Conference on Robotics and Automation (ICRA), 2024.
- [3] Multiagent Reinforcement Learning for Autonomous Routing and Pickup Problem with Adaptation to Variable Demand,

Daniel Garces, **Sushmita Bhattacharya**, Stephanie Gil, Dimitri Bertsekas, International Conference on Robotics and Automation (ICRA), 2023.

- [4] Multiagent Rollout and Policy Iteration for POMDP with Application to Multi-Robot Repair Problems, Sushmita Bhattacharya, Siva Kailas, Sahil Badyal, Stephanie Gil, and Dimitri Bertsekas, Conference on Robot Learning (CoRL), 2020.
- [5] Reinforcement Learning for POMDP: Rollout and Policy Iteration with Application to Autonomous Sequential Repair Problems,

**Sushmita Bhattacharya**, Sahil Badyal, Thomas Wheeler, Stephanie Gil, and Dimitri Bertsekas, IEEE Robotics and Automation Letters (RA-L), 2020.