BVA2 – Advanced Image Processing OVERVIEW

GERALD ZWETTLER

Topics

Overview Lecture, Labs

Labs and Grading

Science Landscape Computer Vision

Outlook: Exercises

Labs

Exercises to all topics/chapters are handed out to be completed within 2 weeks (~3 weeks for larger exercises). From a total of 200 points, exercises for 100 points can be selected as 100%. Some exercises can be achieved in groups of 2 students.

During the labs, exercises are partially started and discussed together and can be worked on under guidance of the lecturer.

After grading of the exercises, one student/group will be selected to present and discuss the solution. This way one can gain insight into topics too, where the exercises were left out.

As toolset ImageJ/IntelliJ is used for Java solutions from scratch and OpenCV via Python wrappers and Spider IDE for comprehensive exercises where a given code basis is inevitable.

Labs cont'd

expected deliverables:

- 1 zip file per exercise, naming: ex_(1|2|3|4|5|6|...|n)_name1.zip), e.g. ex_47_zwettler.zip
- all source files (no projects or binaries), well documented
- utilized testing images (if space permits, otherwise some relevant ones)
- documentation as PDF:
 - Theoretical background and literature if appropriate
 - Statement of the problem
 - Description of solution and implementation (if applicable)
 - Results, extensive test-runs (if applicable)
 - Discussion

Grading

both, labs and exam must be positive. Overall grade with 50% labs and 50% exam. Exam: 15min oral exam at the end of the term.

>87.5%: 1, >75%: 2, >62.5%: 3, >50%: 4, else 5.

Definition

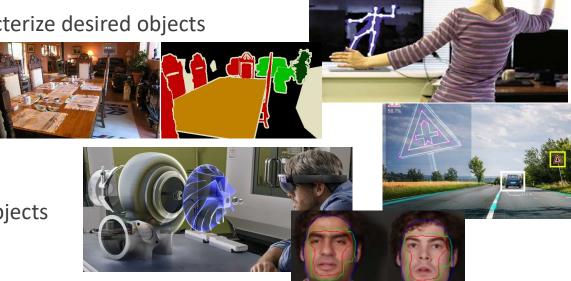
- Computer Vision as extension of Image Processing refers to complex and advanced image analysis, detecting/segmenting desired structures as basis for full image and scene understanding.
 - input data:
 - single monocular images
 - video streams
 - 3D images, additional sensor data, 3D Surface Models
 - more often huge amount of input data (tagged or untagged) in the sense of big data images, i.e. big visual data as
 dominant information available from the internet
 - some of the involved disciplines are:
 - Image Processing (filtering, image reconstruction, color transformations, simple segmentation tasks,...)
 - Optics and Imaging Systems (camera calibration, distortion, 3D reconstruction,...)
 - Computer Graphics (geometric modelling, shape models, reflections, lightening models, test data generation, 3D reconstruction, result representation,...)
 - Pattern Recognition (Texture, SIFT, VSLAM,...)
 - Robotics (VSLAM, autonomous driving, production inspection)
 - Artificial Intelligence and Heuristics (feature based classification, registration, symbolic representation,...)
 - Mathematics, Numerics (projective geometry, probabilities, statistics, signal processing,...)

Fields of Application

- 3D Reconstruction from planar images
- recognition
 - marker, objects
 - face detection / recognition, iris, fingerprint, gesture, handwriting, human pose and activity recognition
 - optical character recognition
- classification/segmentation
 - object contour segmentation extract and characterize desired objects
 - semantic visual classification of entire images
 - complex reasoning from image data utilizing AI
- navigation
 - autonomous driving land, underwater, space
- mixed reality
 - synthesizing real-world and computer-graphics objects
- synthetic images
 - morphing, computer generated imagery (movies)





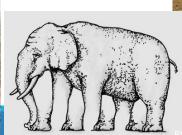


How do Humans Recognize and Interpret Images?

- up-to-now human outperformed AI in image recognition tasks with complex semantic interpretation – meanwhile changing due to incorporation of Deep Learning cNN for Computer Vision Tasks. The bastions of human superiority are on the decline (chess \rightarrow AlphaZero, GO \rightarrow AlphaGo,...)
 - human visual recognition neural network input [Bramao et al. 2011; DiCarlo et al. 2012; Fleming 2014]:
 - (surface) color
 - 3D vision due to parallax of human eyes
 - lighting / shading for 3D shape and distance approximation
 - image texture
 - shape and surface properties
 - a priori knowledge of learned objects, size and their 3D structure
 - stereotype reasoning as short-circuit for human recognition system









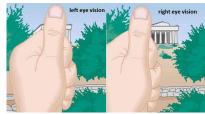








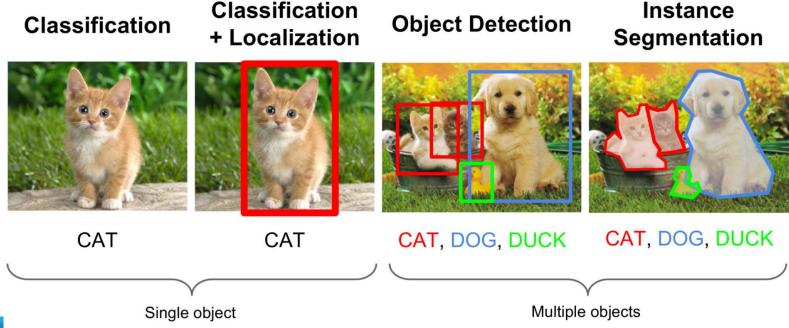






Basic Terminology

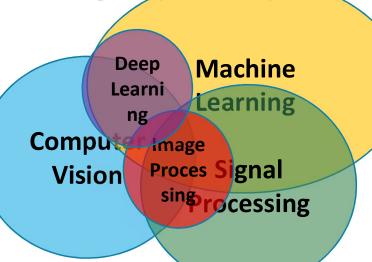
- semantic interpretation of images often a prerequisite
 - tagging of the entire image by one "word" → Classification
 - additionally detecting the ROI around the potentially occluded key object → Object detection with Classification and Localization for images with 1 or more objects involved
 - marking the precise visible or occluded pixel region referring to the classified object → Instance segmentation



Computer Vision and image processing algorithms knowledge map and comparison

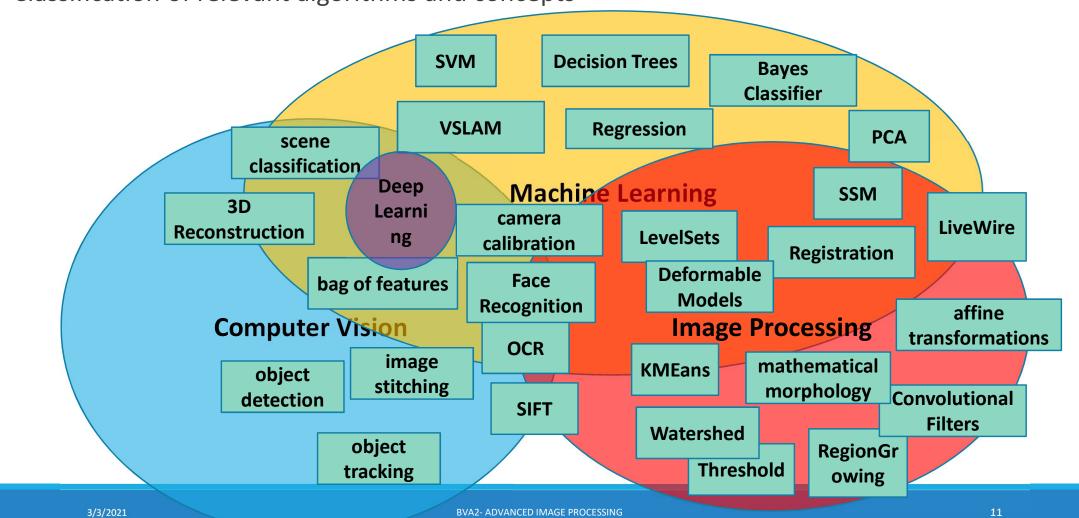
- machine learning, deep learning, computer vision, signal processing and image processing domains closely related
 - image processing thereby a specialization of common signal processing.
 - image processing and computer vision to be differentiated according to the level of semantic perception
 - computer vision and deep learning as specialization od CV necessitate image processing pre-processing steps

knowledge map and comparison



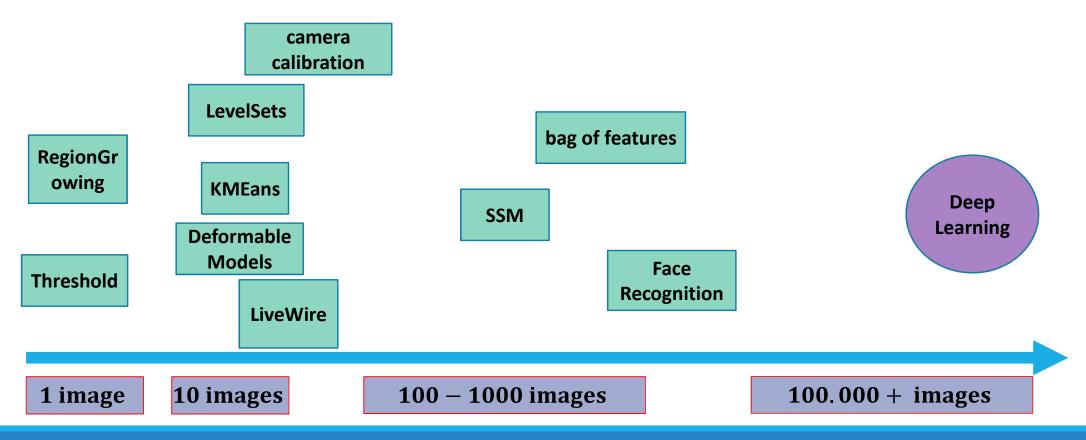
domain	input data	output data
image processing	image	modified image
signal processing	signal (EKG, image, EEG,)	derived information, signal
computer vision	image / images / video	semantic classification
machine learning	features of signal from any domain	classification, model parameters, numeric solution

Classification of relevant algorithms and concepts



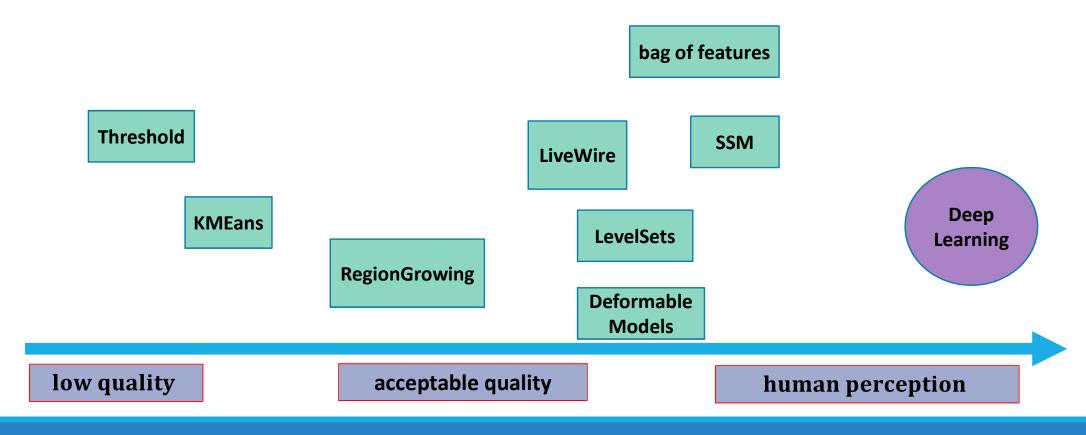
Computer Vision and image processing algorithms – qualitative comparison

required training data for segmentation approaches



Computer Vision and image processing algorithms – qualitative comparison cont'd

achievable segmentation/classification accuracy



References

- [DiCarlo et al. 2012] DiCarlo, J.J., Zoccolan, D., and Rust, N.C., 2012. "How does the brain solve visual object recognition?" . In: *NEURON 73(3)*.
- [Bramao et al. 2011] Bramao, I., Faisca, L., Petersson, K.M., and Reis, A. 2011. The Contribution of Color to Object Recognition. In: Tech, Rijeka, Croatia, available from: http://pubman.mpdl.mpg.de/pubman/item/escidoc:1468179/component/escidoc:1468180/Bramao-InTech-12.pdf
- [Fleming 2014] Fleming, R.W., 2014. "Visual perception of materials and their properties". In *Vision Reserach* 94, pp. 62-75.

1. Linear Imaging Systems : camera calibration, video segmentation (heat map)



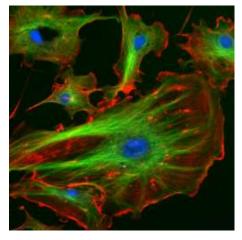


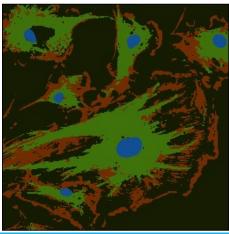






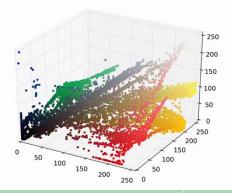
2. Segmentation and Classification: KMeans Clustering, MeanShift



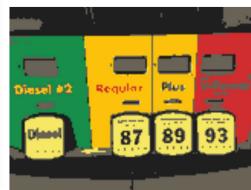




input image showing solid colors of similar chromaticity and luminosity



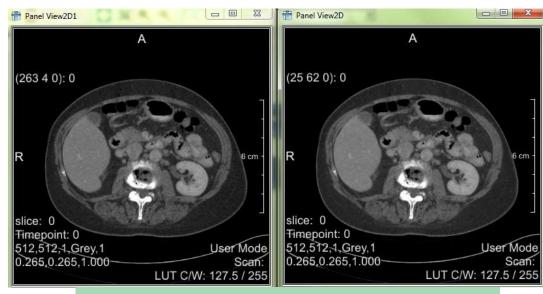
pixels as 3D particles in 3D color space



final classification with n=7 clusters with kernel radius k=25 leading to fragmentation into 7 color segments

3. Image Restauration and Nonlinear Filtering: Anisotropic Diffusion, Richardson-Lucy Deconvolution

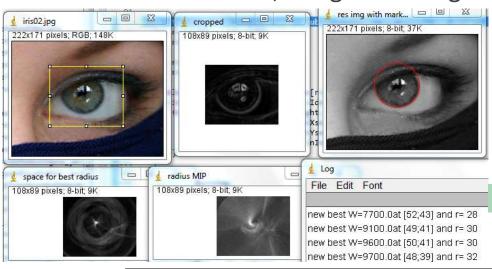


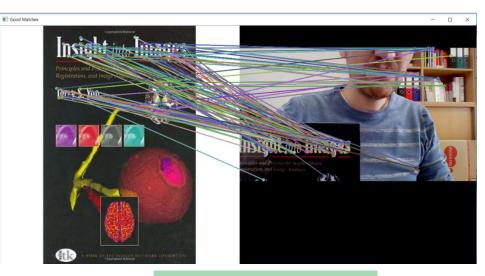


anisotropic diffusion – edge conserving low-pass filtering

RLD: before and after

4. Localization: Hough Circles for Iris Detection, SIFT Feature Detection, Image Stitching





SIFT Feature Matching

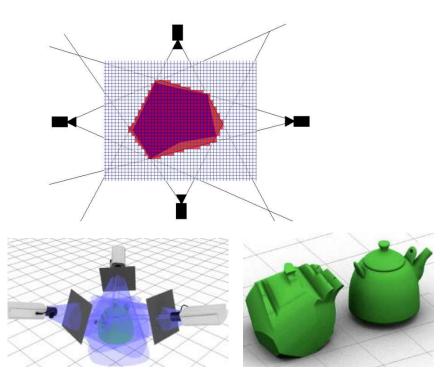
Hough Circles

http://matthewalunbrown.com/autostitch/autostitch.html



Image Stitching

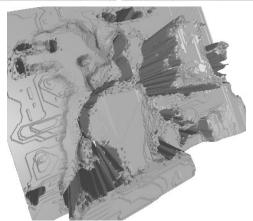
5. 3D Reconstruction: Stereo Matching and Visual Hull from Silhouette Reconstruction







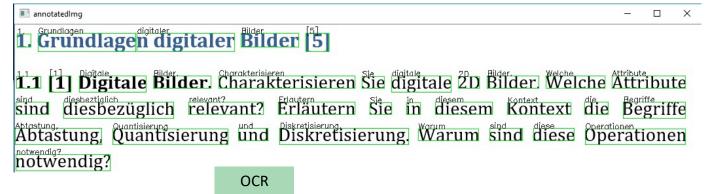


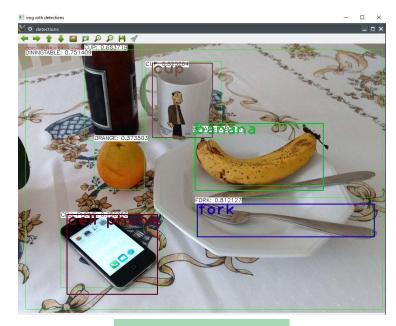


https://docs.opencv.org/3.4/dd/d53/tutorial_py_depthmap.html, https://imagetostl.com/

6. Computer Vision and Machine Learning: OCR from scratch and using Tesseract, Object Detection & Classification







Yolo Object Detection