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SUBJECT : BEEE.

NO OF PAGES WRITTEN :- 7



1) Draw and explain full wave rectifier, ⑤

This rectifier circuit consists of the voltage source, two diodes and a resistive load connected as shown in fig.

During +ve half cycle.

During -ve half cycle.

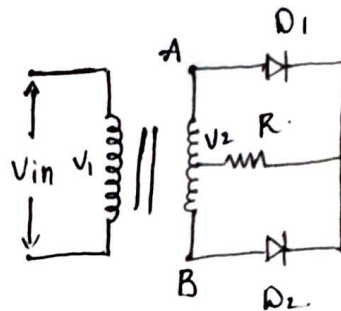
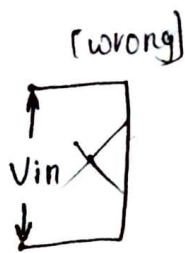
$D_1 \rightarrow$ Forward bias (closed switch)

$D_1 \rightarrow$ Reverse bias (open switch)

$D_2 \rightarrow$ Reverse bias (open switch)

$D_2 \rightarrow$ Forward bias (closed switch)

Figure:



2) Define slip, synchronous speed of Induction motor,

Slip: The difference between the synchronous speed ' N_s ' of the rotating stator field and the actual rotor speed ' N_r ' is called 'slip'.

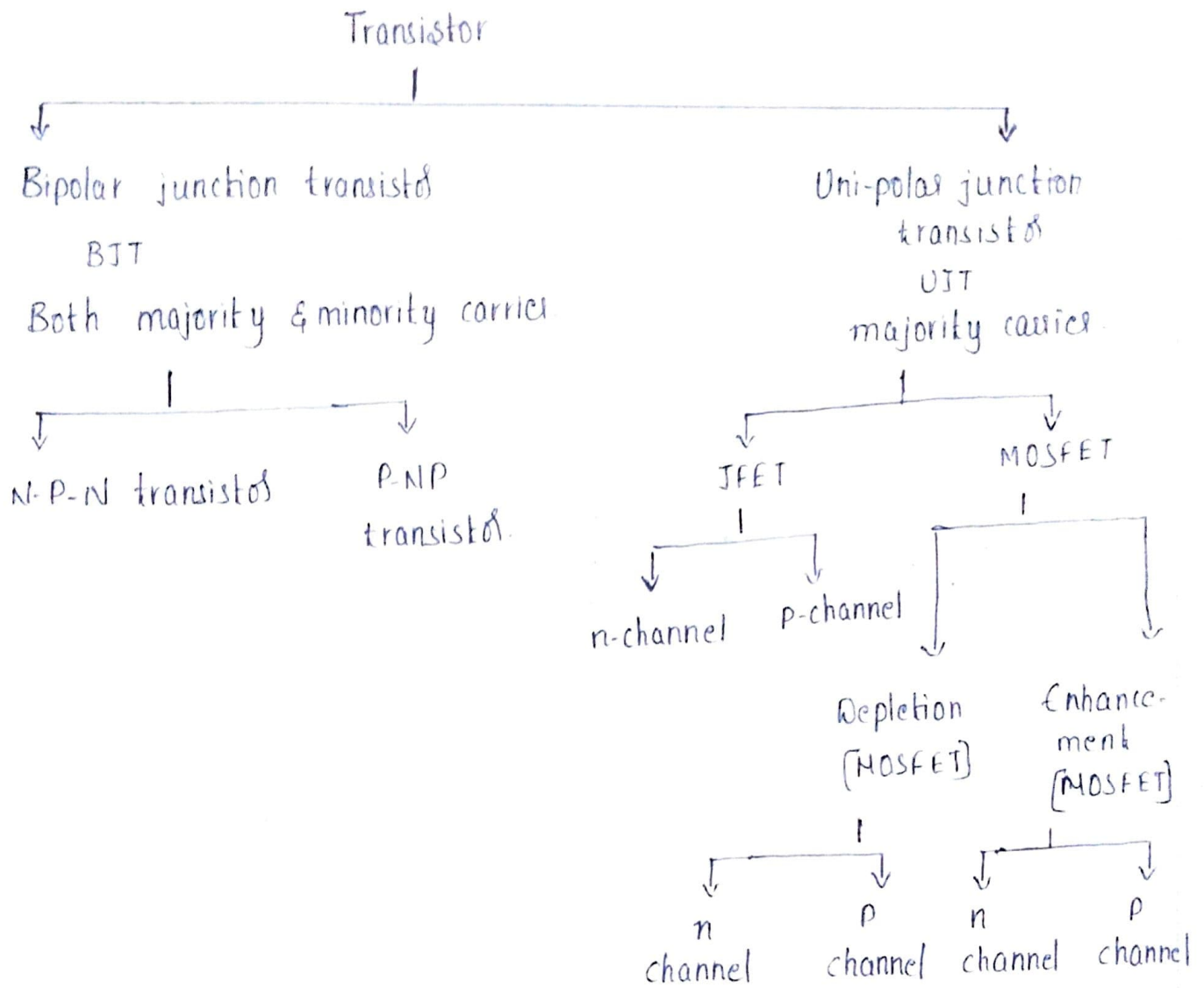
$$\% \text{ of slip} = \frac{N_s - N_r}{N_s} \times 100$$

The synchronous speed is the speed of the revolution of the magnetic Φ field in the stator winding of the motor. It is the speed at which the electromotive force is produced by the alternating machine.

The synchronous speed is given by the relation shown below.

$$N_s = \frac{120 f}{p}$$

3] Explain classification of transistors?

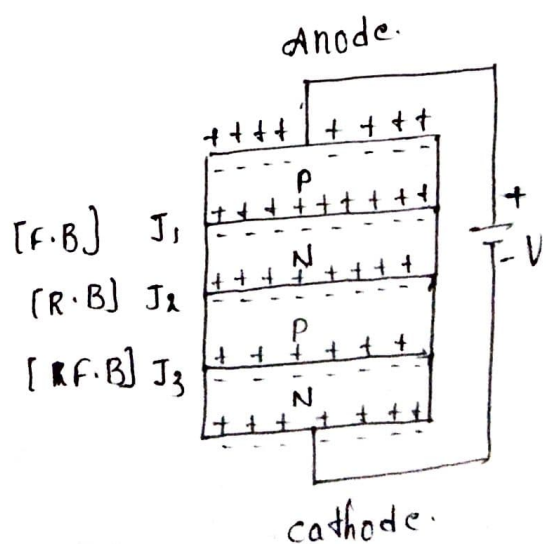


4] Explain operating regions of SCR?

SCR operates mainly in these modes:

- 1) Forward Blocking mode.
- 2) Forward conducting mode.
- 3) Reverse Blocking mode.

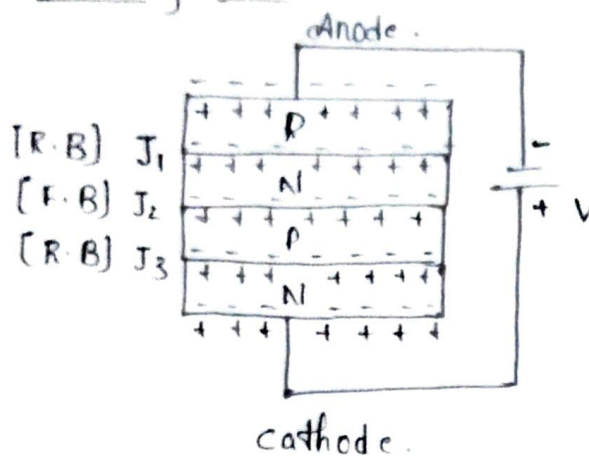
* forward Blocking Mode:



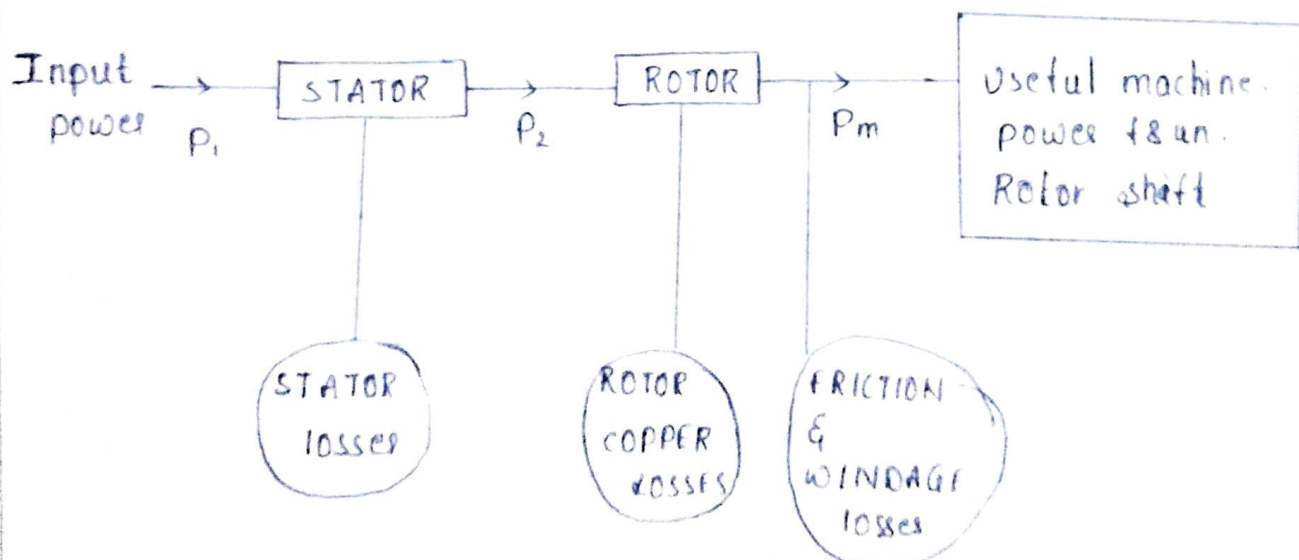
* Forward conducting mode:

When the anode to cathode forward voltage is \uparrow with the angle gate circuit open available avalanche breakdown occurs in junction J_2 and the large amount of currents starts flowing through the device.

* Reverse blocking mode:



5) Explain the power flow stages in I.M and give the relation between $P_a : P_c : P_m$?



$$P_2 - P_1 = \text{stator losses}$$

$$P_r = P_2 - \text{rotor copper losses}$$

$$P_m = P_r - \text{friction \& windage losses}$$

$$\frac{P_2 - P_m}{P_2} = \frac{\text{Rotor copper losses}}{\text{Rotor input}} = \frac{N_s - N_r}{N_s} = s$$