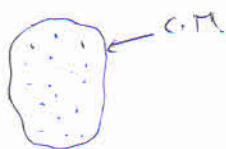


Review of Fluid Mechanics

① Control Volume (C.V) and Control Mass analysis (System)

Control Mass or System Approach



The mass particles remains the ~~same~~ same as the system moves.

→ Since the fluid is ~~same~~ ^{moving}, to contain the same mass particles, the system boundaries will change in time.

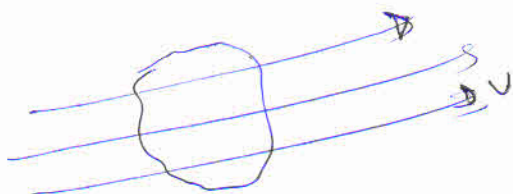


→ The analysis becomes complex, since the system boundary changes with time.

→ However all Newtonian Laws are written for a system.

→ Mass conservation is naturally satisfied $\frac{dM}{dt} = 0$ for the system

Control Volume (C.V)

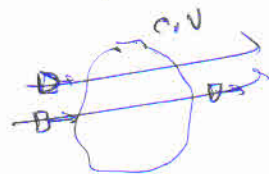


→ Fixed volume in space through which fluid crosses.

→ Easy for fluid flow analysis since C.V shape is fixed in space.

→ However Newtonian laws are defined for control mass (system) and not for C.V

→ For eg: Mass conservation for system is $\frac{dM}{dt} = 0$ (2)
 However for C.V. $\frac{dM}{dt} \neq 0$



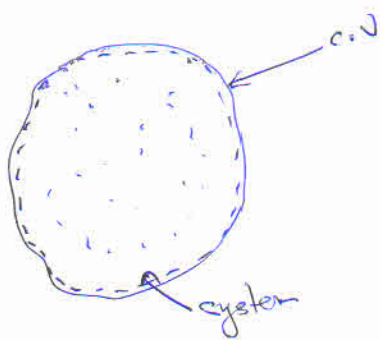
→ There can be fluid crossing the C.V. boundary with out any uniform flux, leading to mass accumulation.

→ Therefore the conservation laws for C.V. approach takes different forms than that of the system approach.

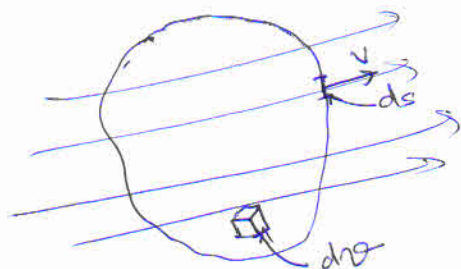
Reynolds Transport Theorem

→ Relates the conservation laws for system to C.V.

→ Consider a C.V. fixed in space. At $t=0$, ~~assume a~~
 consider a system which exactly matches with the C.V.



→ Consider any property N whose variation is sought with in the C.V., in a time interval of Δt .



→ Since there is inflow and outflow of mass with in the C.V., the property will be transported through the C.V. boundary with the net ~~flux~~ ^{mass} flux of fluid ~~matter~~, crossing the boundary.

(3)

Let η be the specific quantity of N

$$\text{i.e. } \eta = \frac{N}{m}$$

→ The net flux of property η crossing the boundary

$$\int_{cs} \rho \mathbf{v} \cdot d\mathbf{s} \eta$$

→ Similarly, the time rate of change of property η within the C.V. is,

$$\frac{\partial}{\partial t} \int_{cv} \rho \eta d\tau$$

The ~~net~~ total change of property within C.V. in a time interval Δt

$$\Rightarrow \frac{\partial}{\partial t} \int_{cv} \rho \eta d\tau + \int_{cs} \rho \eta \mathbf{v} \cdot d\mathbf{s}$$

Similarly the time rate of change of property 'N' in the system ~~is~~ ^{as it moves} is $\frac{dN}{dt}$

→ If we consider a very small time interval,

$\Delta t \rightarrow 0$, then the movement of the system is infinitesimally small and the system and C.V. can be assumed to occupy the same region.

⇒ In this limit $\Delta t \rightarrow 0$, the changes happening in system can be equated to the changes happening in C.V.

i.e. Reynold's Transport theorem.

$$\left(\frac{d}{dt} \int_{\text{system}} \rho \eta dV \right) = \frac{d}{dt} \int_{\text{CV}} \rho \eta dV + \int_{\text{CS}} \rho \eta \mathbf{v} \cdot \mathbf{n} dS.$$

The equivalent form in differential approach is called the Material derivative / substantial derivative or Total derivative.

$$\frac{D\phi}{Dt} = \frac{\partial \phi}{\partial t} + \vec{V} \cdot \nabla \phi$$

Mass Conservation.

$$N = M \quad ; \quad \eta = 1.$$

$$\left(\frac{DM}{Dt} \right)_{\text{system}} = 0 = \frac{\partial}{\partial t} \int_{\text{CV}} \rho dV + \int_{\text{CS}} \rho \mathbf{v} \cdot \mathbf{n} dS.$$

$$\text{i.e.} \quad \left[\frac{\partial}{\partial t} \int_{\text{CV}} \rho dV + \int_{\text{CS}} \rho \mathbf{v} \cdot \mathbf{n} dS = 0 \right]$$

$$\frac{\partial}{\partial t} \int_{\text{CV}} \rho dV + \int_{\text{CV}} \nabla \cdot (\rho \vec{V}) dV = 0$$

$$\int_{\text{CV}} \left[\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{V}) \right] dV = 0$$

$$\Rightarrow \left[\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{V}) = 0 \right] \Rightarrow \text{Mass conservation in differential form / Continuity equation}$$

$$\left(\frac{\partial \rho}{\partial t} + \rho (\nabla \cdot \vec{V}) + \vec{V} \cdot \nabla \rho \right) \Rightarrow \left[\frac{D\rho}{Dt} + \rho (\nabla \cdot \vec{V}) = 0 \right] \text{ Another form.}$$

$$\nabla \cdot \vec{V} = \frac{1}{r^2} \frac{D(r^2 \vec{V})}{Dt}$$

$$\text{For Incompressible Flows } \frac{D\rho}{Dt} = 0 \text{ or } \nabla \cdot \vec{V} = 0$$

$$\text{Incompressible C.E.} \Rightarrow \frac{D\rho}{Dt} = 0 \text{ or } \nabla \cdot \vec{V} = 0$$

Conservation of Momentum

$\Sigma F =$ rate of change of momentum.

$$N = m\vec{v}$$

$$\eta = \vec{v}$$



~~$$\frac{dm\vec{v}}{dt}$$~~

$$\left[\frac{d(m\vec{v})}{dt} \right]_{\text{system}} = \Sigma F$$

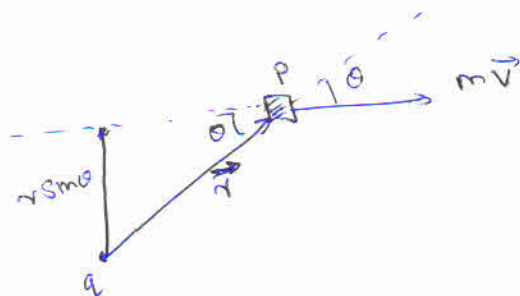
$$\frac{\partial}{\partial t} \int_V \rho \vec{v} dV + \int_S \rho \vec{v} \vec{v} \cdot \vec{n} dS = \Sigma F = - \int_V \nabla P dV + \int_V \rho \vec{f} dV$$

$$\boxed{\frac{\partial(\rho \vec{v})}{\partial t} + \nabla \cdot (\rho \vec{v} \vec{v}) = -\nabla P + \rho \vec{f}}$$

$$\text{or } \boxed{\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} = \frac{-\nabla P + \rho \vec{f}}{\rho}}$$

Conservation of Angular Momentum

Rate of change of angular momentum = ΣT_{ext} .



Angular momentum is defined as the cross product of the position vector of a mass particle with to a datum point Q, to the linear momentum of the mass particle.

$$\vec{L} = (\vec{r} \times m\vec{v}) \Rightarrow (\vec{r} \times \vec{v}) m$$

$$\frac{D(\vec{L})}{Dt} = \Sigma \tau$$

$$N = \vec{L} = (\vec{r} \times \vec{v}) m$$

$$\eta = (\vec{r} \times \vec{v})$$

$$\frac{D(\vec{r} \times \vec{v}) m}{Dt} = \frac{\partial}{\partial t} \int_V \rho (\vec{r} \times \vec{v}) dV + \int_S \rho (\vec{r} \times \vec{v}) \vec{v} \cdot \vec{n} dS = \Sigma \tau$$

Conservation of Energy

⑥

$$\boxed{\delta Q = \delta E + \delta W} \rightarrow \text{first law of thermodynamics}$$

$\delta Q \Rightarrow$ Heat supplied into the system

$\delta W \Rightarrow$ Work done by the system.

$$\boxed{\frac{d(\delta E)}{dt} = \frac{\delta Q}{\delta t} - \frac{\delta W}{\delta t}}$$

$$\frac{dE}{dt} = \dot{Q} - \dot{W}$$

$E \rightarrow$ ~~internal~~ energy.

$\dot{Q} \Rightarrow$ rate of heat given to system

$\dot{W} \Rightarrow$ rate of work done by the system.

$$E \Rightarrow \left(e + gz + \frac{v^2}{2} \right) m$$

$$\left(\frac{dE}{dt} \right)_{\text{system}} = \frac{\partial}{\partial t} \int_{\omega} \rho \left(e + gz + \frac{v^2}{2} \right) d\omega + \int_{cs} \rho \left(e + gz + \frac{v^2}{2} \right) \vec{v} \cdot d\vec{s}$$

$$= \dot{Q} - \dot{W}$$

$\dot{W} \Rightarrow$ Work done due to pressure force, \dot{W}_p shaft work etc.

$$\dot{W}_p = (\Delta P) A (\Delta s)$$

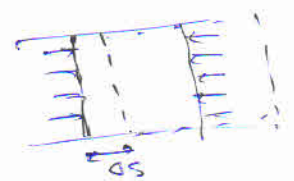
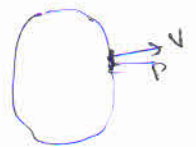
$$\dot{W}_p = \Delta P A \left(\frac{\partial s}{\partial t} \right)$$

$$= \Delta P A \vec{V}$$

In vector form $\dot{W}_p = \int_{cs} P dA \cdot \vec{V}$

$$\dot{W} = \dot{W}_p + \dot{W}_s$$

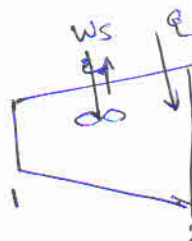
$$\frac{\partial}{\partial t} \int_{\omega} \rho \left(e + gz + \frac{v^2}{2} \right) d\omega + \int_{cs} \rho (\vec{V} \cdot d\vec{s}) \left[e + \frac{P}{\rho} + gz + \frac{v^2}{2} \right] = \dot{Q} - \dot{W}_s$$



$$\boxed{h = e + Pv = \text{specific enthalpy}}$$

$$\therefore \left[\frac{\partial}{\partial t} \int_{\omega} \rho \left(e + gz + \frac{v^2}{2} \right) d\omega + \int_{cs} \rho \vec{V} \cdot d\vec{s} \left[h + gz + \frac{v^2}{2} \right] = \dot{Q} - \dot{W}_s \right]$$

One dimensional steady flow energy equation.



$$\dot{Q} - \dot{W}_s = \rho_2 V_2 A_2 \left[h + gz + \frac{V^2}{2} \right]_2 - \rho_1 V_1 A_1 \left[h + gz + \frac{V^2}{2} \right]_1$$

From C.E $\rho_1 A_1 V_1 = \rho_2 A_2 V_2 = \dot{m}$

$$\dot{Q} - \dot{W}_s = \dot{m} \left[\left[h_2 + gz_2 + \frac{V_2^2}{2} \right] - \left[h_1 + gz_1 + \frac{V_1^2}{2} \right] \right]$$

Let $q = \frac{\dot{Q}}{\dot{m}}$ and $w = \frac{\dot{W}_s}{\dot{m}}$

$$\therefore q - w = \left[h_2 + gz_2 + \frac{V_2^2}{2} \right] - \left[h_1 + gz_1 + \frac{V_1^2}{2} \right]$$

The term ~~$h + \frac{V^2}{2}$~~ $h + \frac{V^2}{2} + gz$ is equal to the total energy and the term

$h + \frac{V^2}{2}$ is called the total or stagnation enthalpy

$$\therefore h_0 = h + \frac{V^2}{2}$$

$$\therefore h_{01} - h_{02} = w$$

\Rightarrow If there is no heat transfer.

From thermodynamics $h = c_p T$ and $u = c_v T$

$$\therefore h_0 = h + \frac{V^2}{2}$$

$$c_p T_0 = c_p T + \frac{V^2}{2} \Rightarrow$$

$$T_0 = T + \frac{V^2}{2c_p}$$

→ In the absence of heat and work transfer, ($\dot{Q} = \dot{W} = 0$), the internal energy change across the inlet and outlet of a constant density fluid ($\rho = \frac{1}{v} = \text{const}$) is $U_1 - U_2 = 0$

∴ The energy equation reduces to.

$$\boxed{\frac{P_1}{\rho} + \frac{V_1^2}{2} + gz_1 = \frac{P_2}{\rho} + \frac{V_2^2}{2} + gz_2}$$

→ which is the Bernoulli's eqn.

→ The Bernoulli's eqn can also be derived from Euler equation. (Inviscid flow)

$$\begin{aligned} m \frac{d\vec{V}}{dt} &= \rho \vec{F} \\ \frac{\partial u}{\partial t} + \vec{V} \cdot \nabla \vec{V} &= -\frac{\nabla P}{\rho} + \vec{F} \end{aligned} \quad \left| \begin{array}{l} \text{Assumptions} \\ \textcircled{1} \text{ Steady} \\ \vec{F} \rightarrow \text{body force} \\ \vec{F} = -g\hat{k} \end{array} \right.$$

$$\vec{V} \cdot \nabla \vec{V} = \nabla \left(\frac{V^2}{2} \right) - \vec{V} \times \text{curl } \vec{V}$$

$$\nabla \left(\frac{V^2}{2} \right) - \vec{V} \times \text{curl } \vec{V} = -\frac{\nabla P}{\rho} + g\hat{k}$$

$$\nabla \left(\frac{V^2}{2} \right) + \frac{\nabla P}{\rho} + g\hat{k} = \vec{V} \times \text{curl } \vec{V}$$

$$\vec{ds} = dx\hat{i} + dy\hat{j} + dz\hat{k}$$

Take dot product with respect to a position vector \vec{ds}

$$\nabla \left(\frac{V^2}{2} \right) \cdot \vec{ds} + \frac{\nabla P}{\rho} \cdot \vec{ds} + g\hat{k} \cdot \vec{ds}$$

$$\frac{\partial}{\partial x} \left(\frac{v^2}{2} \right) dx + \frac{\partial}{\partial y} \left(\frac{v^2}{2} \right) dy + \frac{\partial}{\partial z} \left(\frac{v^2}{2} \right) dz$$

$$\Rightarrow d \left(\frac{v^2}{2} \right)$$

$$\therefore \int d \frac{v^2}{2} + \int d \frac{p}{\rho} + \int g dz = \int \vec{r} \times \text{curl } \vec{v} \cdot d\vec{s} \rightarrow \textcircled{1}$$

This is a differential form of eq. which can be integrated b/w two points. However evaluating

$\int \vec{r} \times \text{curl } \vec{v} \cdot d\vec{s}$ is a problem

The integral $\int \vec{r} \times \text{curl } \vec{v} \cdot d\vec{s}$ vanishes under two cases

→ ① if ~~curl~~ $\text{curl } \vec{v} = 0$ i.e. flow is irrotational

→ ② if $d\vec{s}$ is a streamline.

$\therefore \int d \left(\frac{v^2}{2} \right) + \int \frac{dp}{\rho} + \int g dz = 0$ } If flow is irrotational
or
if integration is taken along a streamline.

$$\therefore \boxed{\frac{v^2}{2} + \frac{p}{\rho} + gz = C} \rightarrow \textcircled{1}$$

→ The equation is valid between any two points in the flow, if the flow is irrotational and incompressible

→ If the flow is rotational, the equation is valid only along a streamline

~~Reynolds Transport Theorem~~ ①

~~Review of Fluid Mechanics~~

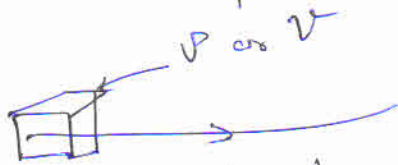
~~Lecture 2 (8-Jan-2020)~~

Compressibility of Compressible flows

$$\text{Compressibility} = \frac{1}{\text{Bulk Modulus}} \approx \frac{1}{\rho} \frac{\Delta \rho}{\Delta P}$$

Large Compressibility \Rightarrow very easy to get compressed
eg. air.

\rightarrow However large compressibility does not ensure that flow is compressible or not.



If the density of the fluid element does not change as it moves, flow is called incompressible. $\frac{D\rho}{Dt} = 0$

If density changes, flow is called compressible. $\frac{D\rho}{Dt} \neq 0$

\rightarrow We try to estimate the percentage change in density with the flow speed (Inertial forces)

$$\Delta \rho \Rightarrow \frac{\Delta \rho}{\rho} \times \rho \Rightarrow \left(\frac{\Delta \rho}{\Delta V} \right) \Delta V$$

$$\Delta \rho \Rightarrow \frac{\rho V^2}{\left(\frac{\Delta \rho}{\Delta V} \right)} \Rightarrow \frac{\Delta \rho}{\rho} = \frac{V^2}{a^2} ; \frac{\Delta \rho}{\Delta V} = a^2$$

$$\text{ie } \boxed{\frac{\Delta \rho}{\rho} \approx M^2}$$

If we limit the incompressible flows as those with density change with in 10%.

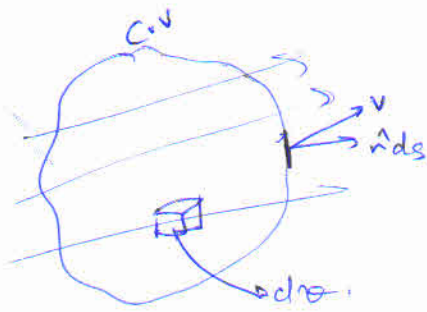
$$\text{the } \frac{\Delta \rho}{\rho} = 0.1 \approx M^2$$

$$\therefore \boxed{M \approx 0.33}$$

\rightarrow This corresponds to roughly 100 m/s

Linear Momentum Equation

Consider a c.v as shown in fig.



$$N = m\vec{v}$$

$$\eta = \vec{v}$$

\vec{f} = body force per unit mass

$$\frac{Dm\vec{v}}{Dt} = \sum \vec{f}, \quad \text{No shear stress.}$$

$$\frac{DN}{Dt} = \frac{Dm\vec{v}}{Dt} = \int_{cv} \frac{\partial}{\partial t} \rho \vec{v} d\tau + \int_{cs} \rho \vec{v} \vec{v} \cdot \vec{n} ds = - \int_{cs} p ds + \int_{cv} \rho \vec{f} d\tau$$

$$\int_{cv} \left[\frac{\partial}{\partial t} \rho \vec{v} \right] + \int_{cs} \rho \vec{v} \vec{v} \cdot \vec{n} ds + \int_{cs} p ds - \int_{cv} [\rho \vec{f}] d\tau = 0$$

$\Rightarrow \nabla \cdot \rho \vec{v} \vec{v} \Rightarrow \nabla p d\tau$

$$\Rightarrow \int_{cv} \left[\frac{\partial}{\partial t} (\rho \vec{v}) + \nabla \cdot \rho \vec{v} \vec{v} + \nabla p - \rho \vec{f} \right] d\tau = 0$$

$$\Rightarrow \boxed{\frac{\partial}{\partial t} (\rho \vec{v}) + \nabla \cdot \rho \vec{v} \vec{v} = -\nabla p + \rho \vec{f}} \quad \text{Euler Equation}$$

$$\rho \frac{\partial \vec{v}}{\partial t} + \underbrace{\vec{v} \frac{\partial \rho}{\partial t} + \vec{v} (\nabla \cdot \rho \vec{v})}_{\text{C.E}} + (\rho \vec{v} \cdot \nabla \vec{v}) = -\nabla p + \rho \vec{f}$$

$$\therefore \rho \frac{\partial \vec{v}}{\partial t} + \rho \vec{v} \cdot \nabla \vec{v} = -\nabla p + \rho \vec{f}$$

$$\text{or } \boxed{\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} = -\frac{\nabla p}{\rho} + \vec{f}} \quad \text{Another form of Euler equation.}$$