LONGITUDINAL MULTIPLE SCLEROSIS LESION SEGMENTATION USING 3D CONVOLUTIONAL NEURAL NETWORKS

Suthirth Vaidya, Abhijith Chunduru, Ramanathan Muthuganapathy, Ganapathy Krishnamurthi

Biomedical Imaging Lab, Department of Engineering Design Indian Institute of Technology Madras, India

ABSTRACT

We present our entry for the Longitudinal Multiple Sclerosis Challenge 2015 using 3D convolutional neural networks (CNN). We model a voxel-wise classifier using multi-channel 3D patches of MRI volumes as input. For each ground truth, a CNN is trained and the final segmentation is obtained by combining the probability outputs of these CNNs. Efficient training is achieved by using sub-sampling methods and sparse convolutions. We obtain accurate results with dice scores comparable to the inter-rater variability.

Index Terms— Multiple Sclerosis, 3D Convolutional Neural Networks, Deep Learning, Neuroimaging

1. INTRODUCTION

Multiple Sclerosis (MS) is a chronic demyelinating disease and affects over 2 million patients globally. The condition is typically diagnosed based on hyperintense or hypointense appearance on Magnetic Resonance (MR) Images. However, the complex appearance and visually vague edges of lesions make segmentation by specialists a difficult and time-consuming task. Methods such as Gaussian Mixture Models[1] have been proposed for the automated segmentation of MS lesions. Motivated by the performance of Convolutional Neural Networks(CNN) for visual recognition from 2D images[2], we decided to apply a 3D version of CNN for this challenge.

2. MATERIAL AND METHODS

2.1. Pre-Processing

We use the data provided by the Longitudinal Multiple Sclerosis Challenge 2015. The data provided is skull-stripped and corrected for bias. Further to this, we employ a normalization technique similar to one described by G. Urban et al.[3]

The data is histogram matched to an arbitrary data point (patient 1, time point 1) and normalized using the mean CSF value. We also added an additional step of truncating the intensity values to the quartile range of [0.01, 0.99]. The nor-

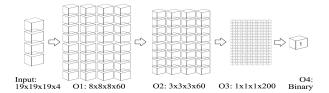


Fig. 1. Architecture of the 3D CNN: L1 - 60 filters of 4x4x4 with average pooling of 2x2x2, L2 - 60 filters of 3x3x3 with average pooling of 2x2x2, L3 - Multi-layer Perceptron, L4 - Softmax. O1, O2, O3 and O4 are respective outputs of L1, L2, L3 and L4.

malization step was carried out using Advanced Normalization Tools (ANTs)[4] and Atropos[5].

2.2. Convolutional Neural Network

We employ a voxel-wise classifier to perform the segmentation task. Three dimensional patches from each channel - T1, T2, FLAIR and PD centered around the voxel of interest is fed to the classifier. Thus, the classifier effectively analyzes 4 dimensions for each voxel.

2.2.1. Data Sampling

Since MS Lesions only constitute a very small percentage of the MRI volume, we performed a data sampling method to reduce the class imbalance in our training data. In this method, each image volume is divided into subvolumes of equal size. Three dimensional patches for training are selected only from those subvolumes that contain lesion voxels greater than a set threshold.

In addition, this sampling technique allows the use of sparse convolution method as described in [6] which has proven to speed up the training of convolutional neural networks for segmentation.

2.2.2. Architecture

We developed a 3D Convolutional Neural Network which performs 3D spatial convolutions as opposed to 2D convolu-

tion used in image classification tasks. The architecture has been represented in Fig.1.

All convolutional layers use softplus activation function. The model is trained using logarithmic likelihood as cost function and optimization is carried out using mini-batch gradient descent with a momentum. We gain a speed up of several orders by processing 25³ voxels in one gradient optimization using the earlier mentioned sparse convolution method. We were able to train our model within one day and prediction took around 2 minutes per brain image on an Nvidia Tesla K20 GPU.

We trained two Convolutional Neural Networks, one for each radiologist mask with the same architecture and specifications. We used the posterior probability maps of the lesion class from the CNNs to generate our final prediction.

2.3. Post-Processing

We add posterior probability values from both CNNs with equal confidence and use it to arrive at our final segmentation. Since Multiple Sclerosis is only seen in white matter, we apply a white matter mask on the prediction by registering the test images with pre-built brain templates [7] and perform grayscale dilation on the corresponding WM priors for each patient.

3. RESULTS AND DISCUSSION

Table 1 shows the results on the dataset using mask1 as the ground truth. Fig 2 shows an example prediction.

	01	IRV	02	IRV	03	IRV
Dice	81.63	86.34	78.62	80.37	80.61	83.39
Jaccard	68.97	75.96	64.78	67.18	67.52	71.51
PPV	87.82	81.73	81.89	85.63	86.93	79.51
Sensitivity	76.26	91.50	75.61	75.71	75.15	87.66
LTPR	46.34	95.12	40.63	68.75	35.29	73.53
LFPR	41.67	59.14	74.14	45.65	63.16	43.48
VD	13.16	11.96	7.67	11.58	13.56	10.24
SD	57.29	63.57	129.32	83.98	84.24	65.83
SV	23354	30108	28995	2770	27224	34719
MV	26892	26892	31405	31405	31494	31494
VCC	99.04	-79.30	99.04	-79.30	99.04	-79.30
NLTPR	10.00	52.86	0.00	33.33	0.00	75.00
NLFPR	73.53	84.17	92.89	86.36	73.90	86.93

Table 1. Results obtained from 'training02' time points. IRV refers to the inter-rater metrics for the corresponding time points. The metrics dice score, jaccard score, positive prediction value (PPV), true positive rate (TPR), lesion true positive rate based on lesion count (LTPR), lesion false positive rate based on lesion count (LFPR), volume difference (VD), surface difference (SD), segmentation volume (SV), volume change correlation (VCC), new lesion TPR (NLTPR) and new lesion FPR (NLFPR) are used to evaluate the algorithm.

We demonstrate that our Convolutional Neural Network (CNN) is able to classify MS lesions with dice score that

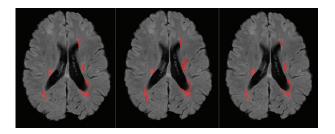


Fig. 2. Mask1, Mask2 and Prediction from training01_01

is comparable to inter-rater variability. The proposed subsampling method reduced class imbalance and allowed us to use sparse convolution method to gain a speed up of several orders and train our model in one day.

The current model does not consider longitudinal correlations among data and a model capable of incorporating this information to predict future lesion voxels is under development. We were also not successful in training deeper networks and intend to improve our performance for the final submission along these lines.

4. REFERENCES

- [1] J. Souplet, C. Lebrun, N. Ayache, and G. Malandain, "An automatic segmentation of t2-flair multiple sclerosis lesions," 07 2008.
- [2] Christian Szegedy, Wei Liu, Yangqing Jia, Pierre Sermanet, Scott Reed, Dragomir Anguelov, Dumitru Erhan, Vincent Vanhoucke, and Andrew Rabinovich, "Going deeper with convolutions," *CoRR*, vol. abs/1409.4842, 2014.
- [3] G. Urban, M. Bendszus, F. A. Hamprecht, and J. Kleesiek, "Multi-modal brain tumor segmentation using deep convolutional neural networks," in MICCAI BraTS (Brain Tumor Segmentation) Challenge. Proceedings, winning contribution, 2014, pp. 31–35.
- [4] Brian B Avants, Nick Tustison, and Gang Song, "Advanced normalization tools (ants)," *Insight J*, 2009.
- [5] Brian B Avants, Nicholas J Tustison, Jue Wu, Philip A Cook, and James C Gee, "An open source multivariate framework for n-tissue segmentation with evaluation on public data," *Neuroinformatics*, vol. 9, no. 4, pp. 381– 400, 2011.
- [6] Hongsheng Li, Rui Zhao, and Xiaogang Wang, "Highly efficient forward and backward propagation of convolutional neural networks for pixelwise classification," *CoRR*, vol. abs/1412.4526, 2014.
- [7] Brian Avants and Nick Tustison, "ANTs/ANTsR Brain Templates," 01 2014.