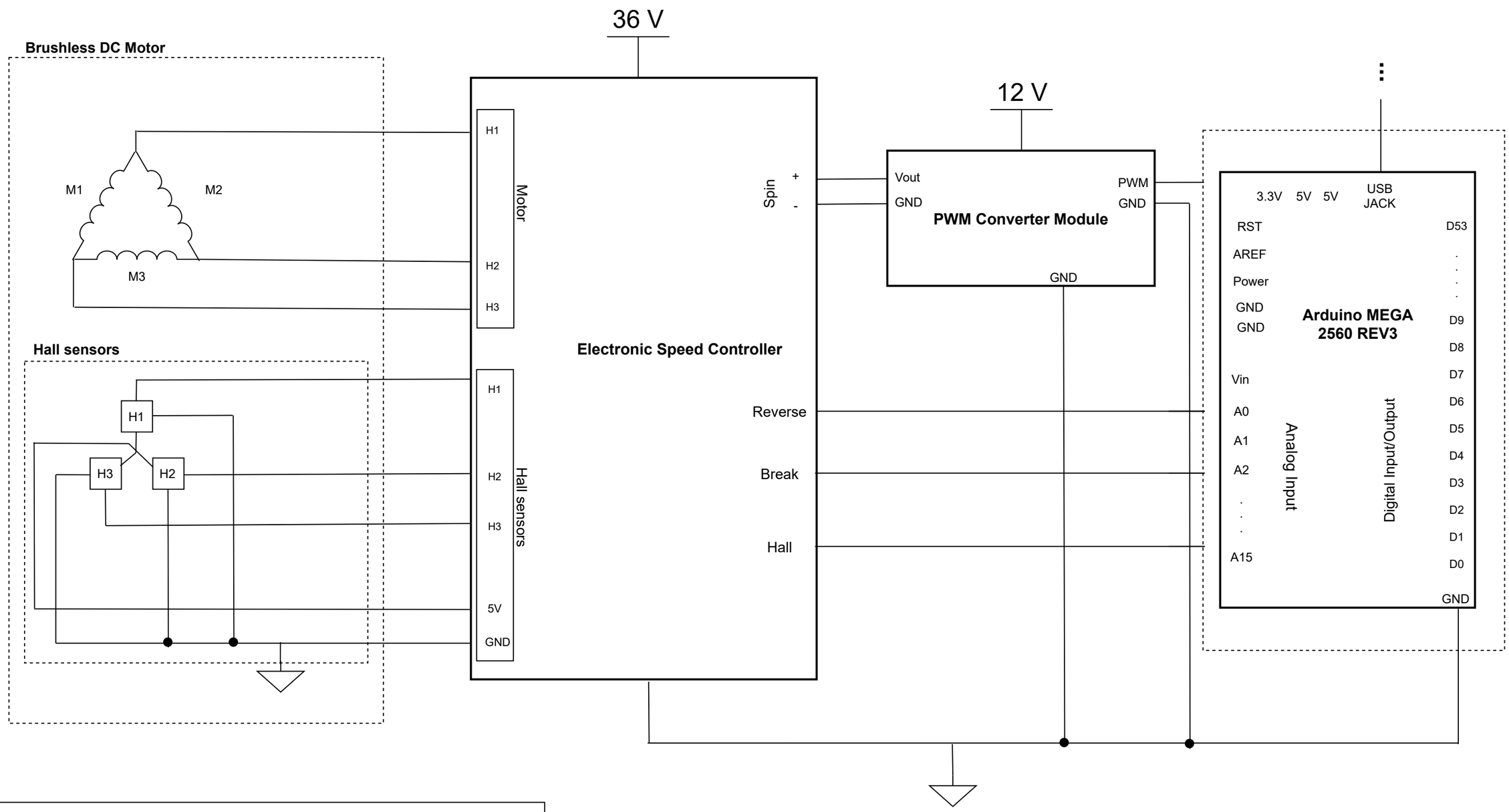

Arduino pin no. configuration

Wheel	Spin	Break	Reverse	Hall
Front Left	7	25	29	21
Front Right	6	24	28	20
Back Left	5	23	27	19
Back Right	4	22	26	18

- Yellow - Break wire
- Blue - Reverse wire
- Green - Spin wire

mu SPACE CORP	Title **Delivery robot Motor Control System Schematic**	Approved by **Suthiwat Y., Natnaree S.**	Date **21-Apr-21**	Revision **R1**
	Project **Delivery Robot**	Drawer **Natnaree S.**	Page **1/2**	