view_frames Result Recorded at time: 7861.755 world Broadcaster: /odom_to_map Broadcaster: /ground_truth_to_tf Average rate: 100.202 Hz Average rate: 10.204 Hz Most recent transform: 7861.802 (-0.047 sec old) Most recent transform: 7861.717 (0.038 sec old) Buffer length: 4.960 sec Buffer length: 4.900 sec base_footprint odom Broadcaster: /ground_truth_to_tf Average rate: 100.202 Hz Most recent transform: 7861.717 (0.038 sec old) Buffer length: 4.960 sec base_stabilized Broadcaster: /ground_truth_to_tf Average rate: 100.202 Hz Most recent transform: 7861.717 (0.038 sec old) Buffer length: 4.960 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (7861.755 sec old) Most recent transform: 0.000 (7861.755 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec downward_cam_link sonar_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (7861.755 sec old) Buffer length: 0.000 sec downward_cam_optical_frame