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Finite MDPs

Please use [this link](#) to peruse the available environments in OpenAI Gym.

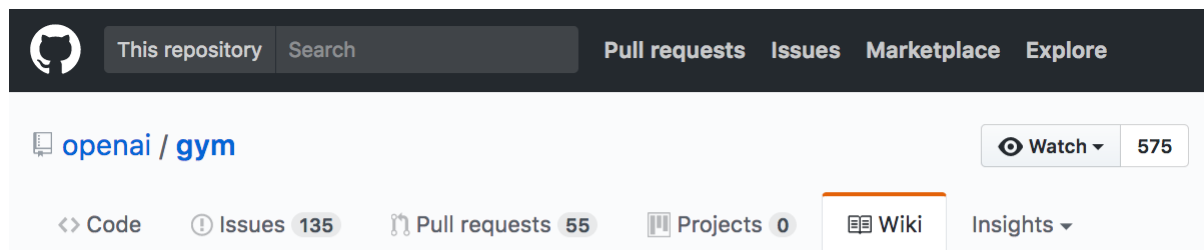


Table of environments

Marco Birck edited this page 6 days ago · 6 revisions

Here is a synopsis of the environments as of 2016-06-20, in order by space dimensionality. See discussion and code in [Write more documentation about environments: Issue #106](#).

Environment Id	Observation Space	Action Space	Reward Range
TimePilot-ram-v0	Box(128,)	Discrete(10)	(-inf, inf)
Amidar-ram-v0	Box(128,)	Discrete(10)	(-inf, inf)

The environments are indexed by **Environment Id**, and each environment has corresponding **Observation Space**, **Action Space**, **Reward Range**, **tStepL**, **Trials**, and **rThresh**.

CartPole-v0

Find the line in the table that corresponds to the **CartPole-v0** environment. Take note of the corresponding **Observation Space** (`Box(4,)`) and **Action Space** (`Discrete(2)`).