



## Notes

In general, the state space  $\mathcal{S}$  is the set of **all nonterminal states**.

In continuing tasks (like the recycling task detailed in the video), this is equivalent to the set of **all states**.

In episodic tasks, we use  $\mathcal{S}^+$  to refer to the set of **all states, including terminal states**.

The action space  $\mathcal{A}$  is the set of possible actions available to the agent.

In the event that there are some states where only a subset of the actions are available, we can also use  $\mathcal{A}(s)$  to refer to the set of actions available in state  $s \in \mathcal{S}$ .

Search or ask questions in  
[Knowledge](#).

Ask peers or mentors for help in  
[Student Hub](#).

NEXT