



## 2. Model Based Approaches

You can think of model based solutions to the prediction problem as also having  $\epsilon$  component. In that view, this approach requires:

- 1. Defining process models (offline).
- 2. Using process models to compare driver behavior to what would be expected
- 3. *Probabilistically classifying* driver intent by comparing the likelihoods of variou multiple-model algorithm.
- 4. Extrapolating process models to generate trajectories.

## 2.1 Defining Process Models

You saw how process models can vary in complexity from very simple...

 $\Gamma \cdot \gamma = \Gamma$