

```
print(x.shape)
```

```
torch.Size([34, 1])
```

```
class GNN(torch.nn.Module):
    def __init__(self, hidden_channels):
        super(GNN, self).__init__()
        torch.manual_seed(12345)
        self.conv1 = nn.Conv1d(34, hidden_channels, 1)
        self.conv2 = nn.Conv1d(hidden_channels, hidden_channels, 1)

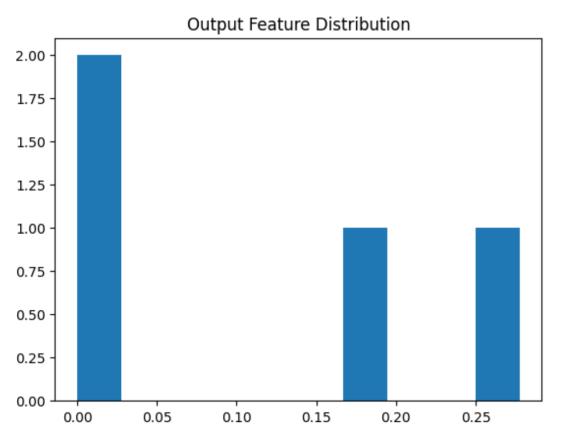
def forward(self, x, edge_index):
        x = self.conv1(x)
        x = x.relu()
        x = r.relu(self.conv2(x))
        return x
```

model = GNN(hidden_channels=4)
output = model(x, edge_index)

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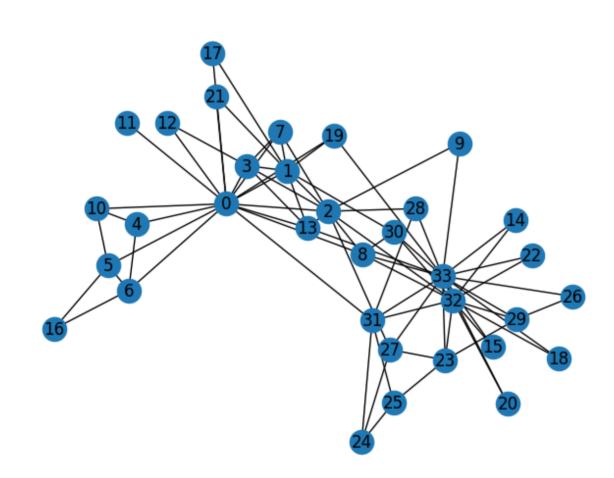
plt.hist(output.detach().numpy())
plt.title('Output Feature Distribution')

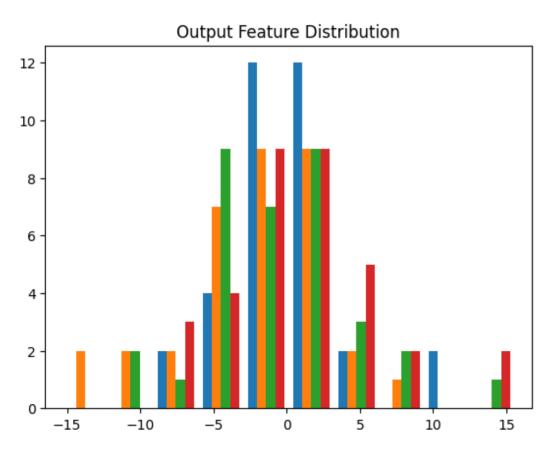
plt.show()



```
## This code first creates a sample graph using the karate club network from NetworkX.
# It then converts the graph to PyTorch tensors — edge_index contains the connectivity information
# and x contains the initial feature for each node.
# A simple 2-layer GNN model is defined using PyTorch nn.Conv1d layers.
# The model takes the node features x and connectivity edge_index as input.
# It passes x through two convolutional layers with ReLU activations to output node embeddings.
# The model is initialized and run on the sample graph.
# The output is plotted as a histogram to visualize the distribution of learned node embeddings.
## The key steps are:
# Represent graph as tensors
# Define convolution layers
# Pass node features through conv layers
# Output is node embeddings
# This shows the basic working of a graph neural network in PyTorch in a simple way.
# More complex implementations can have deeper models, residual connections, batch normalization etc.
# The same principle of passing features through convolutional layers on graph topology applies.
```

```
import networkx as nx
import matplotlib.pyplot as plt
import torch
import torch.nn as nn
import torch.nn.functional as F
# Create sample graph
G = nx.karate_club_graph()
# Plot graph
nx.draw(G, with_labels=True)
plt.show() # Use plt.show() instead of plt.savefig()
# Features and adjacency matrix
x = torch.eye(G.number_of_nodes(), dtype=torch.float) # Set data type to float
A = torch.tensor(nx.to_numpy_array(G), dtype=torch.float) # Convert to tensor and set data type to float
# GNN Layer
class GNNLayer(nn.Module):
   def __init__(self, in_channels, out_channels):
       super().__init__()
        self.linear = nn.Linear(in_channels, out_channels)
   def forward(self, x, A):
       x = torch.matmul(A, x)
       x = self.linear(x)
        return x
# Create GNN
class GNN(nn.Module):
   def __init__(self, in_channels, out_channels, num_layers):
       super().__init__()
       self.layers = nn.ModuleList()
       self.layers.append(GNNLayer(in_channels, 8))
        self.layers.append(GNNLayer(8, out_channels))
   def forward(self, x, A):
        for layer in self.layers:
           x = layer(x, A)
        return x
# Train
model = GNN(34, 4, 2)
output = model(x, A)
# Plot output
plt.hist(output.detach().numpy())
plt.title('Output Feature Distribution')
plt.show() # Use plt.show() instead of plt.savefig()
```





```
# This implements a 2-layer GNN using PyTorch modules and graph convolution.

## The key steps are:

# Create graph and get adjacency matrix

# Define GNN layer to do graph convolution

# Build model with input and output channels

# Train model on graph

# Plot output node embeddings

# The GNNLayer does message passing - multiplying the adjacency matrix with input features.

# The GNN stacks two such layers and trains it end-to-end on the graph.
```