

# ACM-ICPC Self-Study Plan with C++ Code

## Overview

This 16-week comprehensive study plan covers all essential topics for ACM-ICPC preparation with complete C++ implementations.

## Week 1-2: Foundation & Basic Data Structures

### Topics Covered:

- Time & Space Complexity
- Arrays, Vectors, Strings
- Basic I/O optimization
- STL containers

### Key Problems & Solutions:

#### 1. Fast I/O Template

```
cpp

#include <bits/stdc++.h>
using namespace std;

int main() {
    ios_base::sync_with_stdio(false);
    cin.tie(NULL);

    int n;
    cin >> n;
    vector<int> arr(n);

    for(int i = 0; i < n; i++) {
        cin >> arr[i];
    }

    // Your solution here

    return 0;
}
```

#### 2. Two Pointers Technique

```
cpp
```

*// Find pair with sum equal to target*

```
vector<int> twoSum(vector<int>& nums, int target) {  
    int left = 0, right = nums.size() - 1;  
  
    while(left < right) {  
        int sum = nums[left] + nums[right];  
        if(sum == target) {  
            return {left, right};  
        }  
        else if(sum < target) {  
            left++;  
        }  
        else {  
            right--;  
        }  
    }  
    return {-1, -1};  
}
```

### 3. Sliding Window Maximum

cpp

```

vector<int> maxSlidingWindow(vector<int>& nums, int k) {
    deque<int> dq;
    vector<int> result;

    for(int i = 0; i < nums.size(); i++) {
        // Remove elements outside window
        while(!dq.empty() && dq.front() <= i - k) {
            dq.pop_front();
        }

        // Remove smaller elements
        while(!dq.empty() && nums[dq.back()] <= nums[i]) {
            dq.pop_back();
        }

        dq.push_back(i);

        if(i >= k - 1) {
            result.push_back(nums[dq.front()]);
        }
    }

    return result;
}

```

## Week 3-4: Advanced Data Structures

### Topics Covered:

- Stack, Queue, Priority Queue
- Disjoint Set Union (DSU)
- Segment Trees
- Binary Indexed Trees (BIT/Fenwick Tree)

### 1. Disjoint Set Union with Path Compression

cpp

```

class DSU {
private:
    vector<int> parent, rank;

public:
    DSU(int n) {
        parent.resize(n);
        rank.resize(n, 0);
        for(int i = 0; i < n; i++) {
            parent[i] = i;
        }
    }

    int find(int x) {
        if(parent[x] != x) {
            parent[x] = find(parent[x]);
        }
        return parent[x];
    }

    void unite(int x, int y) {
        int px = find(x), py = find(y);
        if(px == py) return;

        if(rank[px] < rank[py]) {
            parent[px] = py;
        }
        else if(rank[px] > rank[py]) {
            parent[py] = px;
        }
        else {
            parent[py] = px;
            rank[px]++;
        }
    }

    bool connected(int x, int y) {
        return find(x) == find(y);
    }
};

```

## 2. Segment Tree (Range Sum Queries)

cpp

```

class SegmentTree {
private:
    vector<long long> tree;
    int n;

    void build(vector<int>& arr, int node, int start, int end) {
        if(start == end) {
            tree[node] = arr[start];
        }
        else {
            int mid = (start + end) / 2;
            build(arr, 2*node, start, mid);
            build(arr, 2*node+1, mid+1, end);
            tree[node] = tree[2*node] + tree[2*node+1];
        }
    }

    void updateHelper(int node, int start, int end, int idx, int val) {
        if(start == end) {
            tree[node] = val;
        }
        else {
            int mid = (start + end) / 2;
            if(idx <= mid) {
                updateHelper(2*node, start, mid, idx, val);
            }
            else {
                updateHelper(2*node+1, mid+1, end, idx, val);
            }
            tree[node] = tree[2*node] + tree[2*node+1];
        }
    }

    long long queryHelper(int node, int start, int end, int l, int r) {
        if(r < start || end < l) {
            return 0;
        }
        if(l <= start && end <= r) {
            return tree[node];
        }
        int mid = (start + end) / 2;
        return queryHelper(2*node, start, mid, l, r) +
            queryHelper(2*node+1, mid+1, end, l, r);
    }

public:

```

```
SegmentTree(vector<int>& arr) {  
    n = arr.size();  
    tree.resize(4 * n);  
    build(arr, 1, 0, n-1);  
}  
  
void update(int idx, int val) {  
    updateHelper(1, 0, n-1, idx, val);  
}  
  
long long query(int l, int r) {  
    return queryHelper(1, 0, n-1, l, r);  
}  
};
```

### 3. Binary Indexed Tree (Fenwick Tree)

cpp

```

class BIT {
private:
    vector<int> tree;
    int n;

public:
    BIT(int size) {
        n = size;
        tree.assign(n + 1, 0);
    }

    void update(int idx, int val) {
        for(++idx; idx <= n; idx += idx & -idx) {
            tree[idx] += val;
        }
    }

    int query(int idx) {
        int sum = 0;
        for(++idx; idx > 0; idx -= idx & -idx) {
            sum += tree[idx];
        }
        return sum;
    }

    int rangeQuery(int l, int r) {
        return query(r) - query(l - 1);
    }
};

```

## Week 5-6: Graph Algorithms - Traversal & Shortest Paths

### Topics Covered:

- DFS, BFS
- Dijkstra's Algorithm
- Bellman-Ford Algorithm
- Floyd-Warshall Algorithm

### 1. DFS Implementation

cpp

```
vector<vector<int>>> adj;
vector<bool> visited;

void dfs(int node) {
    visited[node] = true;

    for(int neighbor : adj[node]) {
        if(!visited[neighbor]) {
            dfs(neighbor);
        }
    }
}
```

*// Usage*

```
int main() {
    int n, m;
    cin >> n >> m;

    adj.resize(n);
    visited.assign(n, false);

    for(int i = 0; i < m; i++) {
        int u, v;
        cin >> u >> v;
        adj[u].push_back(v);
        adj[v].push_back(u);
    }

    dfs(0);
    return 0;
}
```

## 2. BFS Implementation

cpp



```
vector<int> bfs(int start, int n) {  
    vector<int> distance(n, -1);  
    queue<int> q;  
  
    distance[start] = 0;  
    q.push(start);  
  
    while(!q.empty()) {  
        int node = q.front();  
        q.pop();  
  
        for(int neighbor : adj[node]) {  
            if(distance[neighbor] == -1) {  
                distance[neighbor] = distance[node] + 1;  
                q.push(neighbor);  
            }  
        }  
    }  
  
    return distance;  
}
```

### 3. Dijkstra's Algorithm

cpp

```

vector<int> dijkstra(int start, int n) {
    vector<int> dist(n, INT_MAX);
    priority_queue<pair<int, int>, vector<pair<int, int>>, greater<pair<int, int>>> pq;

    dist[start] = 0;
    pq.push({0, start});

    while(!pq.empty()) {
        int d = pq.top().first;
        int u = pq.top().second;
        pq.pop();

        if(d > dist[u]) continue;

        for(auto& edge : adj[u]) {
            int v = edge.first;
            int w = edge.second;

            if(dist[u] + w < dist[v]) {
                dist[v] = dist[u] + w;
                pq.push({dist[v], v});
            }
        }
    }

    return dist;
}

```

## 4. Bellman-Ford Algorithm

cpp

```

bool bellmanFord(int start, int n, vector<tuple<int, int, int>>& edges) {
    vector<int> dist(n, INT_MAX);
    dist[start] = 0;

    // Relax edges n-1 times
    for(int i = 0; i < n - 1; i++) {
        for(auto& edge : edges) {
            int u, v, w;
            tie(u, v, w) = edge;

            if(dist[u] != INT_MAX && dist[u] + w < dist[v]) {
                dist[v] = dist[u] + w;
            }
        }
    }

    // Check for negative cycles
    for(auto& edge : edges) {
        int u, v, w;
        tie(u, v, w) = edge;

        if(dist[u] != INT_MAX && dist[u] + w < dist[v]) {
            return false; // Negative cycle found
        }
    }

    return true;
}

```

## Week 7-8: Graph Algorithms - Advanced

### Topics Covered:

- Minimum Spanning Tree (Kruskal's & Prim's)
- Topological Sort
- Strongly Connected Components
- Bridges and Articulation Points

### 1. Kruskal's MST Algorithm

cpp

```

struct Edge {
    int u, v, weight;
    bool operator<(const Edge& other) const {
        return weight < other.weight;
    }
};

int kruskalMST(int n, vector<Edge>& edges) {
    sort(edges.begin(), edges.end());
    DSU dsu(n);

    int mstWeight = 0;
    int edgesUsed = 0;

    for(Edge& e : edges) {
        if(!dsu.connected(e.u, e.v)) {
            dsu.unite(e.u, e.v);
            mstWeight += e.weight;
            edgesUsed++;

            if(edgesUsed == n - 1) break;
        }
    }

    return mstWeight;
}

```

## 2. Topological Sort (DFS-based)

cpp

```

vector<int> topologicalSort(int n) {
    vector<int> result;
    vector<bool> visited(n, false);

    function<void(int)> dfs = [&](int node) {
        visited[node] = true;

        for(int neighbor : adj[node]) {
            if(!visited[neighbor]) {
                dfs(neighbor);
            }
        }

        result.push_back(node);
    };

    for(int i = 0; i < n; i++) {
        if(!visited[i]) {
            dfs(i);
        }
    }

    reverse(result.begin(), result.end());
    return result;
}

```

### 3. Tarjan's Algorithm for Strongly Connected Components

cpp

```

class TarjanSCC {
private:
    vector<vector<int>>> adj;
    vector<int> disc, low, stackMember;
    stack<int> st;
    vector<vector<int>>> sccs;
    int timer;

    void SCCUtil(int u) {
        disc[u] = low[u] = ++timer;
        st.push(u);
        stackMember[u] = true;

        for(int v : adj[u]) {
            if(disc[v] == -1) {
                SCCUtil(v);
                low[u] = min(low[u], low[v]);
            }
            else if(stackMember[v]) {
                low[u] = min(low[u], disc[v]);
            }
        }

        if(low[u] == disc[u]) {
            vector<int> component;
            int w;
            do {
                w = st.top();
                st.pop();
                stackMember[w] = false;
                component.push_back(w);
            } while(w != u);

            sccs.push_back(component);
        }
    }

public:
    TarjanSCC(int n) {
        adj.resize(n);
        disc.assign(n, -1);
        low.assign(n, -1);
        stackMember.assign(n, false);
        timer = 0;
    }
}

```

```

void addEdge(int u, int v) {
    adj[u].push_back(v);
}

vector<vector<int>> findSCCs() {
    for(int i = 0; i < adj.size(); i++) {
        if(disc[i] == -1) {
            SCCUtil(i);
        }
    }
    return sccs;
}
};

```

## Week 9-10: Dynamic Programming

### Topics Covered:

- Basic DP concepts
- Classic DP problems
- Optimization techniques
- State space reduction

### 1. Longest Common Subsequence

```

cpp

int longestCommonSubsequence(string text1, string text2) {
    int m = text1.length(), n = text2.length();
    vector<vector<int>> dp(m + 1, vector<int>(n + 1, 0));

    for(int i = 1; i <= m; i++) {
        for(int j = 1; j <= n; j++) {
            if(text1[i-1] == text2[j-1]) {
                dp[i][j] = dp[i-1][j-1] + 1;
            }
            else {
                dp[i][j] = max(dp[i-1][j], dp[i][j-1]);
            }
        }
    }

    return dp[m][n];
}

```

## 2. 0/1 Knapsack Problem

cpp

```
int knapsack(vector<int>& weights, vector<int>& values, int W) {
    int n = weights.size();
    vector<vector<int>> dp(n + 1, vector<int>(W + 1, 0));

    for(int i = 1; i <= n; i++) {
        for(int w = 1; w <= W; w++) {
            if(weights[i-1] <= w) {
                dp[i][w] = max(dp[i-1][w],
                               dp[i-1][w - weights[i-1]] + values[i-1]);
            }
            else {
                dp[i][w] = dp[i-1][w];
            }
        }
    }

    return dp[n][W];
}
```

## 3. Edit Distance

cpp



```

int editDistance(string word1, string word2) {
    int m = word1.length(), n = word2.length();
    vector<vector<int>> dp(m + 1, vector<int>(n + 1));

    for(int i = 0; i <= m; i++) dp[i][0] = i;
    for(int j = 0; j <= n; j++) dp[0][j] = j;

    for(int i = 1; i <= m; i++) {
        for(int j = 1; j <= n; j++) {
            if(word1[i-1] == word2[j-1]) {
                dp[i][j] = dp[i-1][j-1];
            }
            else {
                dp[i][j] = 1 + min({dp[i-1][j], // Delete
                                   dp[i][j-1], // Insert
                                   dp[i-1][j-1]}); // Replace
            }
        }
    }

    return dp[m][n];
}

```

## 4. Matrix Chain Multiplication

cpp

```

int matrixChainMultiplication(vector<int>& dimensions) {
    int n = dimensions.size() - 1;
    vector<vector<int>> dp(n, vector<int>(n, 0));

    for(int len = 2; len <= n; len++) {
        for(int i = 0; i < n - len + 1; i++) {
            int j = i + len - 1;
            dp[i][j] = INT_MAX;

            for(int k = i; k < j; k++) {
                int cost = dp[i][k] + dp[k+1][j] +
                    dimensions[i] * dimensions[k+1] * dimensions[j+1];
                dp[i][j] = min(dp[i][j], cost);
            }
        }
    }

    return dp[0][n-1];
}

```

## Week 11-12: Number Theory & Mathematics

### Topics Covered:

- GCD, LCM, Extended Euclidean Algorithm
- Modular Arithmetic
- Prime Numbers, Sieve of Eratosthenes
- Fast Exponentiation

### 1. Extended Euclidean Algorithm

cpp

```

int extgcd(int a, int b, int& x, int& y) {
    if(b == 0) {
        x = 1;
        y = 0;
        return a;
    }

    int x1, y1;
    int gcd = extgcd(b, a % b, x1, y1);

    x = y1;
    y = x1 - (a / b) * y1;

    return gcd;
}

int modInverse(int a, int m) {
    int x, y;
    int gcd = extgcd(a, m, x, y);

    if(gcd != 1) return -1; // Inverse doesn't exist

    return (x % m + m) % m;
}

```

## 2. Sieve of Eratosthenes

cpp

```
vector<bool> sieve(int n) {  
    vector<bool> isPrime(n + 1, true);  
    isPrime[0] = isPrime[1] = false;  
  
    for(int i = 2; i * i <= n; i++) {  
        if(isPrime[i]) {  
            for(int j = i * i; j <= n; j += i) {  
                isPrime[j] = false;  
            }  
        }  
    }  
  
    return isPrime;  
}  
  
vector<int> getPrimes(int n) {  
    vector<bool> isPrime = sieve(n);  
    vector<int> primes;  
  
    for(int i = 2; i <= n; i++) {  
        if(isPrime[i]) {  
            primes.push_back(i);  
        }  
    }  
  
    return primes;  
}
```

### 3. Fast Exponentiation

cpp

```

long long fastPow(long long base, long long exp, long long mod) {
    long long result = 1;
    base %= mod;

    while(exp > 0) {
        if(exp & 1) {
            result = (result * base) % mod;
        }
        base = (base * base) % mod;
        exp >>= 1;
    }

    return result;
}

```

#### 4. Chinese Remainder Theorem

```

cpp

long long chineseRemainder(vector<long long>& remainders, vector<long long>& moduli) {
    long long prod = 1;
    for(long long m : moduli) prod *= m;

    long long result = 0;
    for(int i = 0; i < remainders.size(); i++) {
        long long pp = prod / moduli[i];
        int x, y;
        extgcd(pp, moduli[i], x, y);
        result += remainders[i] * pp * x;
    }

    return ((result % prod) + prod) % prod;
}

```

## Week 13-14: Strings & Advanced Algorithms

### Topics Covered:

- String matching algorithms
- Suffix arrays and LCP arrays
- Trie data structure
- Advanced techniques

### 1. KMP Algorithm



```

vector<int> computeLPS(string pattern) {
    int m = pattern.length();
    vector<int> lps(m, 0);
    int len = 0, i = 1;

    while(i < m) {
        if(pattern[i] == pattern[len]) {
            len++;
            lps[i] = len;
            i++;
        }
        else {
            if(len != 0) {
                len = lps[len - 1];
            }
            else {
                lps[i] = 0;
                i++;
            }
        }
    }

    return lps;
}

```

```

vector<int> KMPSearch(string text, string pattern) {
    vector<int> result;
    vector<int> lps = computeLPS(pattern);
    int n = text.length(), m = pattern.length();
    int i = 0, j = 0;

    while(i < n) {
        if(pattern[j] == text[i]) {
            i++; j++;
        }

        if(j == m) {
            result.push_back(i - j);
            j = lps[j - 1];
        }
        else if(i < n && pattern[j] != text[i]) {
            if(j != 0) {
                j = lps[j - 1];
            }
            else {
                i++;
            }
        }
    }
}

```

```
    }  
    }  
}  
  
return result;  
}
```

## 2. Trie Implementation

cpp



```
class TrieNode {
public:
    unordered_map<char, TrieNode*> children;
    bool isEndOfWord;

    TrieNode() {
        isEndOfWord = false;
    }
};

class Trie {
private:
    TrieNode* root;

public:
    Trie() {
        root = new TrieNode();
    }

    void insert(string word) {
        TrieNode* current = root;
        for(char c : word) {
            if(current->children.find(c) == current->children.end()) {
                current->children[c] = new TrieNode();
            }
            current = current->children[c];
        }
        current->isEndOfWord = true;
    }

    bool search(string word) {
        TrieNode* current = root;
        for(char c : word) {
            if(current->children.find(c) == current->children.end()) {
                return false;
            }
            current = current->children[c];
        }
        return current->isEndOfWord;
    }

    bool startsWith(string prefix) {
        TrieNode* current = root;
        for(char c : prefix) {
            if(current->children.find(c) == current->children.end()) {
                return false;
            }
        }
    }
}
```

```

    }
    current = current->children[c];
}
return true;
}
};

```

### 3. Z Algorithm

```

cpp
vector<int> zAlgorithm(string s) {
    int n = s.length();
    vector<int> z(n, 0);
    int l = 0, r = 0;

    for(int i = 1; i < n; i++) {
        if(i <= r) {
            z[i] = min(r - i + 1, z[i - l]);
        }

        while(i + z[i] < n && s[z[i]] == s[i + z[i]]) {
            z[i]++;
        }

        if(i + z[i] - 1 > r) {
            l = i;
            r = i + z[i] - 1;
        }
    }

    return z;
}

```

## Week 15-16: Geometry & Final Practice

### Topics Covered:

- Basic geometry algorithms
- Convex hull
- Line intersection
- Contest strategies and optimization

### 1. Point and Line Structures

cpp

```
struct Point {
    double x, y;

    Point(double x = 0, double y = 0) : x(x), y(y) {}

    Point operator+(const Point& p) const { return Point(x + p.x, y + p.y); }
    Point operator-(const Point& p) const { return Point(x - p.x, y - p.y); }
    Point operator*(double t) const { return Point(x * t, y * t); }

    double dot(const Point& p) const { return x * p.x + y * p.y; }
    double cross(const Point& p) const { return x * p.y - y * p.x; }

    double length() const { return sqrt(x * x + y * y); }
    double distance(const Point& p) const { return (p - *this).length(); }
};

struct Line {
    Point a, b;

    Line(Point a, Point b) : a(a), b(b) {}

    bool intersect(const Line& other, Point& intersection) const {
        Point dir1 = b - a;
        Point dir2 = other.b - other.a;

        double det = dir1.cross(dir2);
        if(abs(det) < 1e-9) return false; // Parallel lines

        double t = (other.a - a).cross(dir2) / det;
        intersection = a + dir1 * t;
        return true;
    }
};
```

## 2. Convex Hull (Graham Scan)

cpp

```

int orientation(Point p, Point q, Point r) {
    double val = (q.y - p.y) * (r.x - q.x) - (q.x - p.x) * (r.y - q.y);
    if(abs(val) < 1e-9) return 0;
    return (val > 0) ? 1 : 2; // 1 = Clockwise, 2 = Counterclockwise
}

vector<Point> convexHull(vector<Point> points) {
    int n = points.size();
    if(n < 3) return {};

    // Find bottom-most point
    int l = 0;
    for(int i = 1; i < n; i++) {
        if(points[i].y < points[l].y) l = i;
        else if(points[i].y == points[l].y && points[i].x < points[l].x) l = i;
    }

    swap(points[0], points[l]);

    // Sort points by polar angle
    sort(points.begin() + 1, points.end(), [&](Point a, Point b) {
        int o = orientation(points[0], a, b);
        if(o == 0) {
            return points[0].distance(a) < points[0].distance(b);
        }
        return o == 2;
    });

    vector<Point> hull;
    for(int i = 0; i < n; i++) {
        while(hull.size() > 1 &&
            orientation(hull[hull.size()-2], hull[hull.size()-1], points[i]) != 2) {
            hull.pop_back();
        }
        hull.push_back(points[i]);
    }

    return hull;
}

```

## Contest Tips & Template

### Complete Contest Template

cpp

```

#include <bits/stdc++.h>
using namespace std;

typedef long long ll;
typedef pair<int, int> pii;
typedef vector<int> vi;
typedef vector<ll> vll;

#define FOR(i, a, b) for(int i = (a); i < (b); i++)
#define RFOR(i, a, b) for(int i = (a); i >= (b); i--)
#define REP(i, n) FOR(i, 0, n)
#define ALL(v) v.begin(), v.end()
#define SZ(v) (int)v.size()
#define PB push_back
#define MP make_pair

const int INF = 1e9;
const ll LINF = 1e18;
const int MOD = 1e9 + 7;

void solve() {
    // Your solution here
}

int main() {
    ios_base::sync_with_stdio(false);
    cin.tie(NULL);

    int t = 1;
    // cin >> t;

    while(t--) {
        solve();
    }

    return 0;
}

```

## Practice Schedule

### Daily Practice (2-3 hours):

1. **Week 1-8:** 5 easy + 3 medium problems daily
2. **Week 9-12:** 3 medium + 2 hard problems daily
3. **Week 13-16:** Virtual contests + upsolving

## Weekly Contests:

- Participate in Codeforces rounds
- AtCoder Beginner/Regular contests
- Practice old ICPC regionals

## Recommended Problem Sets:

- **Codeforces:** Div 2 A-D problems
- **AtCoder:** ABC problems
- **CSES Problem Set:** Complete all sections
- **UVa Online Judge:** Classic problems
- **Kattis:** ICPC-style problems

## Study Resources

### Books:

1. "Competitive Programming" by Steven Halim
2. "Introduction to Algorithms" by CLRS
3. "Guide to Competitive Programming" by Antti Laaksonen

### Online Resources:

1. CP-Algorithms (<https://cp-algorithms.com/>)
2. USACO Guide (<https://usaco.guide/>)
3. Codeforces EDU section
4. YouTube: Errichto, SecondThread, William Lin

### Practice Platforms:

- Codeforces
- AtCoder
- CodeChef
- SPOJ
- HackerRank
- LeetCode (for DP and data structures)

# Advanced Topics & Implementations

## Network Flows

### 1. Maximum Flow (Dinic's Algorithm)

cpp

```

struct Edge {
    int to, rev, cap;
};

class MaxFlow {
private:
    vector<vector<Edge>> graph;
    vector<int> level, iter;

    void bfs(int s) {
        fill(level.begin(), level.end(), -1);
        queue<int> q;
        level[s] = 0;
        q.push(s);

        while(!q.empty()) {
            int v = q.front();
            q.pop();
            for(auto& e : graph[v]) {
                if(e.cap > 0 && level[e.to] < 0) {
                    level[e.to] = level[v] + 1;
                    q.push(e.to);
                }
            }
        }
    }

    int dfs(int v, int t, int f) {
        if(v == t) return f;

        for(int& i = iter[v]; i < graph[v].size(); i++) {
            Edge& e = graph[v][i];
            if(e.cap > 0 && level[v] < level[e.to]) {
                int d = dfs(e.to, t, min(f, e.cap));
                if(d > 0) {
                    e.cap -= d;
                    graph[e.to][e.rev].cap += d;
                    return d;
                }
            }
        }
        return 0;
    }

public:
    MaxFlow(int n) {

```



```

graph.resize(n);
level.resize(n);
iter.resize(n);
}

void addEdge(int from, int to, int cap) {
    graph[from].push_back({to, (int)graph[to].size(), cap});
    graph[to].push_back({from, (int)graph[from].size() - 1, 0});
}

int maxflow(int s, int t) {
    int flow = 0;
    while(true) {
        bfs(s);
        if(level[t] < 0) return flow;
        fill(iter.begin(), iter.end(), 0);
        int f;
        while((f = dfs(s, t, INT_MAX)) > 0) {
            flow += f;
        }
    }
}
};

```

## 2. Minimum Cost Maximum Flow

cpp

```

struct Edge {
    int to, rev, flow, cap, cost;
};

class MinCostMaxFlow {
private:
    vector<vector<Edge>> graph;
    vector<int> dist, parent, parent_edge;

    bool spfa(int s, int t) {
        fill(dist.begin(), dist.end(), INT_MAX);
        vector<bool> inQueue(graph.size(), false);
        queue<int> q;

        dist[s] = 0;
        q.push(s);
        inQueue[s] = true;

        while(!q.empty()) {
            int v = q.front();
            q.pop();
            inQueue[v] = false;

            for(int i = 0; i < graph[v].size(); i++) {
                Edge& e = graph[v][i];
                if(e.cap > e.flow && dist[v] + e.cost < dist[e.to]) {
                    dist[e.to] = dist[v] + e.cost;
                    parent[e.to] = v;
                    parent_edge[e.to] = i;
                    if(!inQueue[e.to]) {
                        q.push(e.to);
                        inQueue[e.to] = true;
                    }
                }
            }
        }
    }

    return dist[t] != INT_MAX;
}

public:
    MinCostMaxFlow(int n) {
        graph.resize(n);
        dist.resize(n);
        parent.resize(n);
        parent_edge.resize(n);
    }

```

```

}

void addEdge(int from, int to, int cap, int cost) {
    graph[from].push_back({to, (int)graph[to].size(), 0, cap, cost});
    graph[to].push_back({from, (int)graph[from].size() - 1, 0, 0, -cost});
}

pair<int, int> minCostMaxFlow(int s, int t) {
    int flow = 0, cost = 0;

    while(spfa(s, t)) {
        int pushFlow = INT_MAX;
        for(int v = t; v != s; v = parent[v]) {
            Edge& e = graph[parent[v]][parent_edge[v]];
            pushFlow = min(pushFlow, e.cap - e.flow);
        }

        for(int v = t; v != s; v = parent[v]) {
            Edge& e = graph[parent[v]][parent_edge[v]];
            e.flow += pushFlow;
            graph[v][e.rev].flow -= pushFlow;
            cost += pushFlow * e.cost;
        }

        flow += pushFlow;
    }

    return {flow, cost};
}
};

```

## Matrix Operations

### 1. Matrix Multiplication and Exponentiation

cpp

```
typedef vector<vector<ll>> Matrix;
```

```
Matrix multiply(const Matrix& A, const Matrix& B, int mod = MOD) {
```

```
    int n = A.size(), m = B[0].size(), p = B.size();
```

```
    Matrix C(n, vector<ll>(m, 0));
```

```
    for(int i = 0; i < n; i++) {
```

```
        for(int j = 0; j < m; j++) {
```

```
            for(int k = 0; k < p; k++) {
```

```
                C[i][j] = (C[i][j] + A[i][k] * B[k][j]) % mod;
```

```
            }
```

```
        }
```

```
    }
```

```
    return C;
```

```
}
```

```
Matrix matrixPower(Matrix A, ll n, int mod = MOD) {
```

```
    int size = A.size();
```

```
    Matrix result(size, vector<ll>(size, 0));
```

```
    // Initialize identity matrix
```

```
    for(int i = 0; i < size; i++) {
```

```
        result[i][i] = 1;
```

```
    }
```

```
    while(n > 0) {
```

```
        if(n & 1) {
```

```
            result = multiply(result, A, mod);
```

```
        }
```

```
        A = multiply(A, A, mod);
```

```
        n >>= 1;
```

```
    }
```

```
    return result;
```

```
}
```

```
// Example: Fibonacci using matrix exponentiation
```

```
ll fibonacci(ll n) {
```

```
    if(n <= 1) return n;
```

```
    Matrix fib = {{1, 1}, {1, 0}};
```

```
    Matrix result = matrixPower(fib, n - 1);
```

```
return result[0][0];
```

```
}
```

## Heavy-Light Decomposition

### HLD Implementation

```
cpp
```

```

class HeavyLightDecomposition {
private:
    vector<vector<int>>> adj;
    vector<int> parent, depth, heavy, head, pos;
    SegmentTree segTree;
    int currentPos;

    int dfs(int v) {
        int size = 1, maxChildSize = 0;

        for(int u : adj[v]) {
            if(u != parent[v]) {
                parent[u] = v;
                depth[u] = depth[v] + 1;
                int childSize = dfs(u);

                if(childSize > maxChildSize) {
                    maxChildSize = childSize;
                    heavy[v] = u;
                }
                size += childSize;
            }
        }

        return size;
    }

    void decompose(int v, int h) {
        head[v] = h;
        pos[v] = currentPos++;

        if(heavy[v] != -1) {
            decompose(heavy[v], h);
        }

        for(int u : adj[v]) {
            if(u != parent[v] && u != heavy[v]) {
                decompose(u, u);
            }
        }
    }

public:
    HeavyLightDecomposition(vector<vector<int>>> &graph, vector<int> &values)
        : adj(graph), segTree(values) {
        int n = adj.size();
    }

```

```

parent.assign(n, -1);
depth.assign(n, 0);
heavy.assign(n, -1);
head.resize(n);
pos.resize(n);
currentPos = 0;

dfs(0);
decompose(0, 0);
}

void update(int v, int val) {
    segTree.update(pos[v], val);
}

ll query(int u, int v) {
    ll result = 0;

    while(head[u] != head[v]) {
        if(depth[head[u]] > depth[head[v]]) {
            result += segTree.query(pos[head[u]], pos[u]);
            u = parent[head[u]];
        }
        else {
            result += segTree.query(pos[head[v]], pos[v]);
            v = parent[head[v]];
        }
    }

    if(depth[u] > depth[v]) swap(u, v);
    result += segTree.query(pos[u], pos[v]);

    return result;
}
};

```

## Advanced String Algorithms

### 1. Suffix Array with LCP

cpp

```

class SuffixArray {
private:
    string s;
    vector<int> sa, rank, lcp;

public:
    SuffixArray(string str) : s(str + "$") {
        int n = s.length();
        sa.resize(n);
        rank.resize(n);
        lcp.resize(n);

        buildSuffixArray();
        buildLCP();
    }

    void buildSuffixArray() {
        int n = s.length();
        vector<int> cnt(max(256, n), 0);

        // Initial sort by first character
        for(int i = 0; i < n; i++) cnt[s[i]]++;
        for(int i = 1; i < 256; i++) cnt[i] += cnt[i-1];
        for(int i = n-1; i >= 0; i--) sa[--cnt[s[i]]] = i;

        rank[sa[0]] = 0;
        for(int i = 1; i < n; i++) {
            rank[sa[i]] = rank[sa[i-1]] + (s[sa[i]] != s[sa[i-1]]);
        }

        for(int k = 1; k < n; k <= 1) {
            vector<int> newSa(n), newRank(n);

            // Sort by second key
            int pos = 0;
            for(int i = n - k; i < n; i++) newSa[pos++] = i;
            for(int i = 0; i < n; i++) {
                if(sa[i] >= k) newSa[pos++] = sa[i] - k;
            }

            // Sort by first key
            fill(cnt.begin(), cnt.end(), 0);
            for(int i = 0; i < n; i++) cnt[rank[i]]++;
            for(int i = 1; i < n; i++) cnt[i] += cnt[i-1];
            for(int i = n-1; i >= 0; i--) sa[--cnt[rank[newSa[i]]]] = newSa[i];
        }
    }
}

```



```

// Update ranks
newRank[sa[0]] = 0;
for(int i = 1; i < n; i++) {
    newRank[sa[i]] = newRank[sa[i-1]] +
    (rank[sa[i]] != rank[sa[i-1]] ||
    sa[i] + k >= n || sa[i-1] + k >= n ||
    rank[sa[i] + k] != rank[sa[i-1] + k]);
}

rank = newRank;
if(rank[sa[n-1]] == n-1) break;
}
}

void buildLCP() {
    int n = s.length();
    vector<int> invSa(n);

    for(int i = 0; i < n; i++) invSa[sa[i]] = i;

    int k = 0;
    for(int i = 0; i < n; i++) {
        if(invSa[i] == n-1) {
            k = 0;
            continue;
        }

        int j = sa[invSa[i] + 1];
        while(i + k < n && j + k < n && s[i + k] == s[j + k]) k++;

        lcp[invSa[i]] = k;
        if(k) k--;
    }
}

vector<int> getSuffixArray() { return sa; }
vector<int> getLCP() { return lcp; }
};

```

## 2. Manacher's Algorithm (Palindromes)

cpp

```

vector<int> manacher(string s) {
    string modified = "#";
    for(char c : s) {
        modified += c;
        modified += "#";
    }

    int n = modified.length();
    vector<int> p(n, 0);
    int center = 0, right = 0;

    for(int i = 0; i < n; i++) {
        if(i < right) {
            p[i] = min(right - i, p[2 * center - i]);
        }

        while(i + p[i] + 1 < n && i - p[i] - 1 >= 0 &&
            modified[i + p[i] + 1] == modified[i - p[i] - 1]) {
            p[i]++;
        }

        if(i + p[i] > right) {
            center = i;
            right = i + p[i];
        }
    }

    return p;
}

```

*// Find longest palindromic substring*

```

string longestPalindrome(string s) {
    vector<int> p = manacher(s);
    int maxLen = 0, centerIndex = 0;

    for(int i = 0; i < p.size(); i++) {
        if(p[i] > maxLen) {
            maxLen = p[i];
            centerIndex = i;
        }
    }

    int start = (centerIndex - maxLen) / 2;
    return s.substr(start, maxLen);
}

```

# Mo's Algorithm

## Mo's Algorithm Implementation

cpp

```

struct Query {
    int l, r, idx;
    int blockIdx;

    bool operator<(const Query& other) const {
        if(blockIdx != other.blockIdx) {
            return blockIdx < other.blockIdx;
        }
        return (blockIdx & 1) ? (r < other.r) : (r > other.r);
    }
};

class MoAlgorithm {
private:
    vector<int> arr;
    vector<int> freq;
    int currentAnswer;
    int blockSize;

    void add(int pos) {
        freq[arr[pos]]++;
        if(freq[arr[pos]] == 1) {
            currentAnswer++;
        }
    }

    void remove(int pos) {
        freq[arr[pos]]--;
        if(freq[arr[pos]] == 0) {
            currentAnswer--;
        }
    }

public:
    MoAlgorithm(vector<int>& array) : arr(array) {
        int n = arr.size();
        blockSize = sqrt(n) + 1;
        freq.resize(1000001, 0);
        currentAnswer = 0;
    }

    vector<int> processQueries(vector<pair<int, int>>& queries) {
        vector<Query> q;
        for(int i = 0; i < queries.size(); i++) {
            q.push_back({queries[i].first, queries[i].second, i,
                queries[i].first / blockSize});
        }
    }
}

```

```

}

sort(q.begin(), q.end());

vector<int> answers(queries.size());
int currentL = 0, currentR = -1;

for(Query& query : q) {
    while(currentL > query.l) {
        currentL--;
        add(currentL);
    }
    while(currentR < query.r) {
        currentR++;
        add(currentR);
    }
    while(currentL < query.l) {
        remove(currentL);
        currentL++;
    }
    while(currentR > query.r) {
        remove(currentR);
        currentR--;
    }

    answers[query.idx] = currentAnswer;
}

return answers;
}
};

```

## Square Root Decomposition

### SQRT Decomposition for Range Updates

cpp

```

class SqrtDecomposition {
private:
    vector<ll> arr, lazy;
    int blockSize, numBlocks;

public:
    SqrtDecomposition(vector<int>& array) {
        arr.assign(array.begin(), array.end());
        int n = arr.size();
        blockSize = sqrt(n) + 1;
        numBlocks = (n + blockSize - 1) / blockSize;
        lazy.assign(numBlocks, 0);
    }

    void update(int l, int r, ll val) {
        int startBlock = l / blockSize;
        int endBlock = r / blockSize;

        if(startBlock == endBlock) {
            for(int i = l; i <= r; i++) {
                arr[i] += val;
            }
        }
        else {
            // Update partial first block
            for(int i = l; i < (startBlock + 1) * blockSize; i++) {
                arr[i] += val;
            }

            // Update complete middle blocks
            for(int i = startBlock + 1; i < endBlock; i++) {
                lazy[i] += val;
            }

            // Update partial last block
            for(int i = endBlock * blockSize; i <= r; i++) {
                arr[i] += val;
            }
        }
    }

    ll query(int pos) {
        int block = pos / blockSize;
        return arr[pos] + lazy[block];
    }
}

```

```
ll rangeSum(int l, int r) {  
    ll sum = 0;  
    for(int i = l; i <= r; i++) {  
        sum += query(i);  
    }  
    return sum;  
}  
};
```

## Contest Strategy & Tips

### Time Management

1. **First 15 minutes:** Read all problems, identify easy ones
2. **Next 2 hours:** Solve problems in order of difficulty
3. **Last hour:** Debug, optimize, attempt harder problems

### Problem-Solving Approach

1. **Understand:** Read problem 2-3 times
2. **Examples:** Work through sample cases manually
3. **Algorithm:** Choose appropriate algorithm/data structure
4. **Edge cases:** Consider boundary conditions
5. **Implementation:** Code carefully with good variable names
6. **Testing:** Test with samples and edge cases

### Common Mistakes to Avoid

- Integer overflow (use long long when needed)
- Array bounds (0-indexed vs 1-indexed)
- Infinite loops in graph algorithms
- Not handling empty input
- Wrong time complexity analysis

### Debugging Techniques

cpp

```

#ifdef LOCAL
#define debug(x) cout << #x << " = " << x << endl
#else
#define debug(x)
#endif

// Print arrays
template<typename T>
void printArray(vector<T>& arr) {
    for(int i = 0; i < arr.size(); i++) {
        cout << arr[i] << (i == arr.size()-1 ? "\n" : " ");
    }
}

```

## Final Recommendations

### Last Month Before Contest:

1. **Virtual contests:** 3-4 per week
2. **Team practice:** Coordinate with teammates
3. **Upsolving:** Spend equal time on upsolving
4. **Weak areas:** Focus on your weakest topics
5. **Template:** Finalize your contest template

### Contest Day:

1. **Sleep well:** 7-8 hours of sleep
2. **Eat properly:** Light meal before contest
3. **Arrive early:** Set up your workspace
4. **Stay calm:** Don't panic on hard problems
5. **Communicate:** Work effectively with teammates

Remember: Consistent practice is key. Solve at least 5-10 problems daily and participate in regular contests. The combination of theoretical knowledge and practical problem-solving experience will prepare you well for ACM-ICPC success.

Good luck with your preparation!