



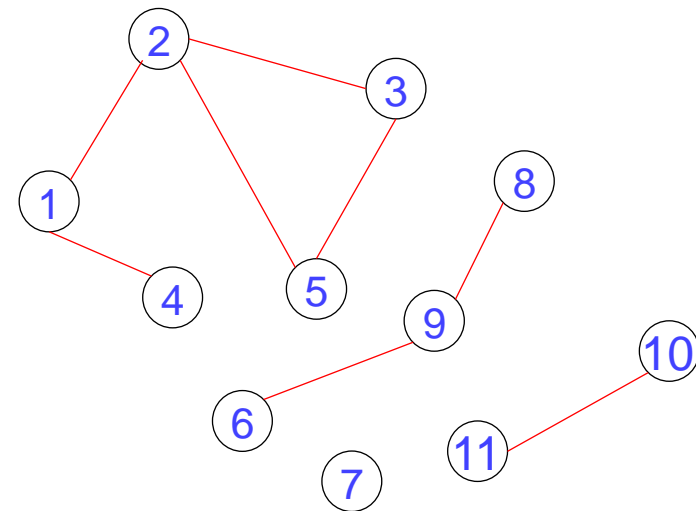
Graph Algorithms: Breadth-First Search (BFS)

Graph Searching

- A vertex v is reachable from vertex u iff there is a path from u to v
- A search method starts at a given vertex u and visits/labels/marks every vertex that is reachable from u

Graph Search Methods

- Many graph problems solved using a search method
 - Path from one vertex to another
 - Is the graph connected?
 - Find a spanning tree
 - etc.
- Commonly used search methods:
 - Breadth-first search
 - Depth-first search

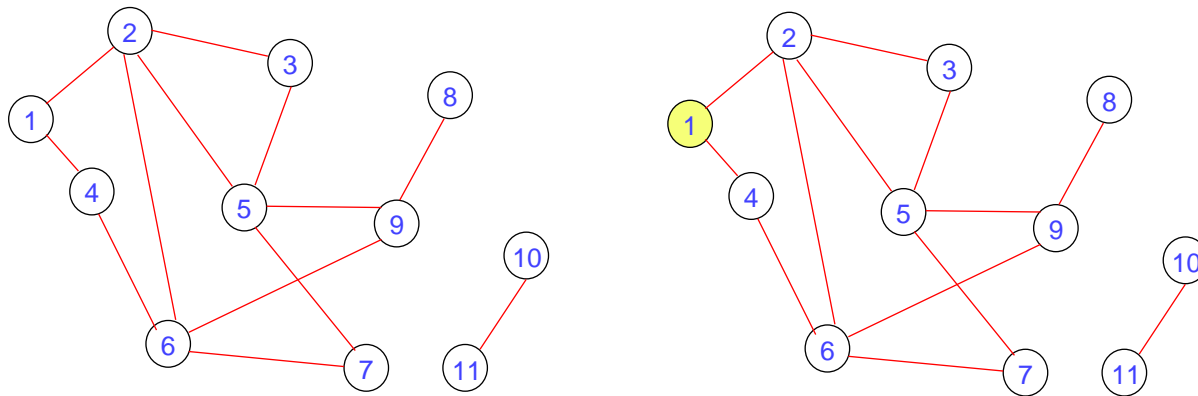


Dispensers

- Graph searches require a data structure that temporarily holds vertices that are neighbors of previously visited vertices, or edges that leave previously visited vertices
- The data structures that are used form a family of abstract data types called ***dispensers***
- A ***dispenser*** is an abstract data type that supports insert, delete, and retrieve operations
- The ***dispenser*** family is characterized by the fact that whenever it is not empty, only one of its data items is accessible for delete or retrieve operations
- Stacks, queues, and priority queues are the best-known abstract data types in the ***dispenser*** family
- They determine the accessible item in a different ways:
 - In a stack, it is the item that was inserted last
 - In a queue, it is the item that was inserted first
 - In a priority queue, it is the item that has the highest priority
 - the priority of an item in a priority queue may be specified as a parameter when the item is inserted, or it may be determined from the item's data contents

Breadth-first Search (BFS)

- Visit start vertex and put into a **FIFO queue**
- Repeatedly remove a vertex from the queue, visit its unvisited adjacent vertices, put newly visited vertices into the queue
- Start search at vertex **1**



Visit/mark/label start vertex and put in a FIFO queue **Q**



BFS(G, root)

let **Q** be a queue

label root as discovered

Q.enqueue(root)

while **Q** is not empty **do**

v := **Q.dequeue()**

if **v** is the goal **then**

return v

for all edges from **v** to **w** in **G.adjacentEdges(v)** **do**

if **w** is not labeled as discovered **then**

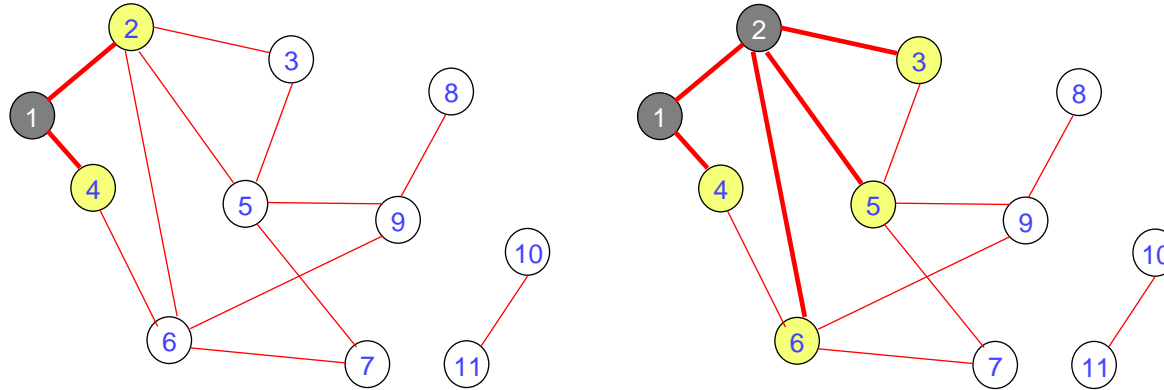
 label **w** as discovered

Q.enqueue(w)

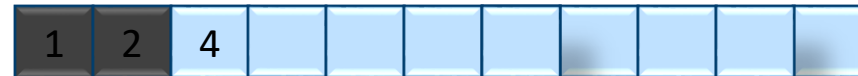
Output: Goal state. The parent links trace the shortest path back to **root**

Breadth-first Search (BFS)

- Remove **1** from **Q**, visit adjacent unvisited vertices, put in **Q**
- Remove **2** from **Q**, visit adjacent unvisited vertices, put in **Q**

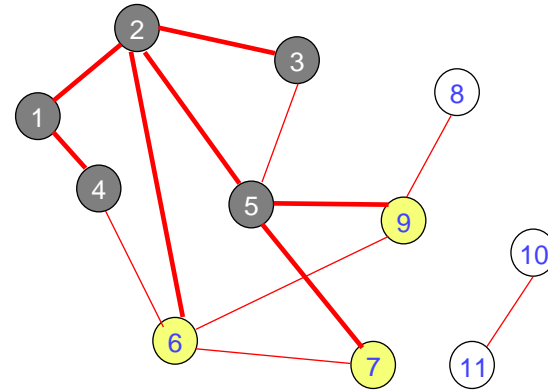
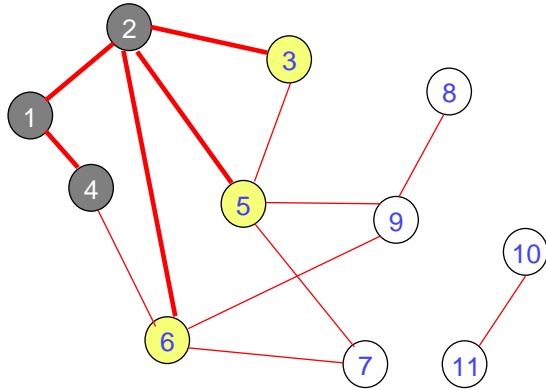


Visit/mark/label start vertex and put in a FIFO queue

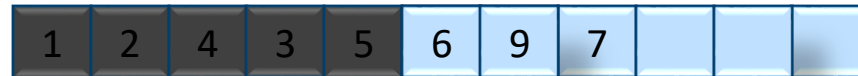


Breadth-first Search (BFS)

- Remove **4** from **Q**, visit adjacent unvisited vertices, put in **Q**
- Remove **3** from **Q**, visit adjacent unvisited vertices, put in **Q**
- Remove **5** from **Q**, visit adjacent unvisited vertices, put in **Q**

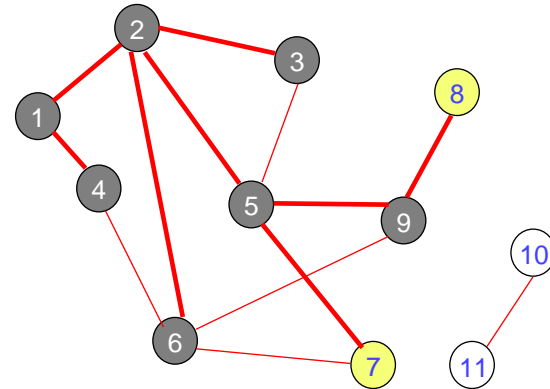
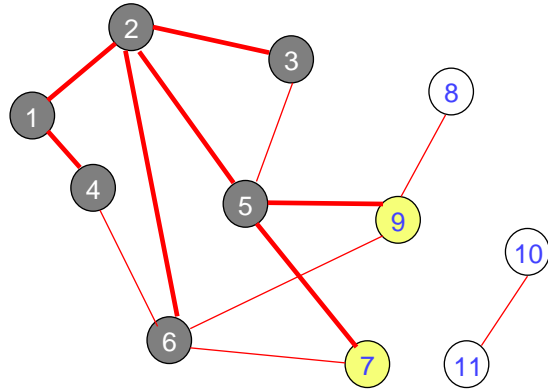


Visit/mark/label start vertex and put in a FIFO queue



Breadth-first Search (BFS)

- Remove **6** from **Q**, visit adjacent unvisited vertices, put in **Q**
- Remove **9** from **Q**, visit adjacent unvisited vertices, put in **Q**
- Remove **7** from **Q**, visit adjacent unvisited vertices, put in **Q**

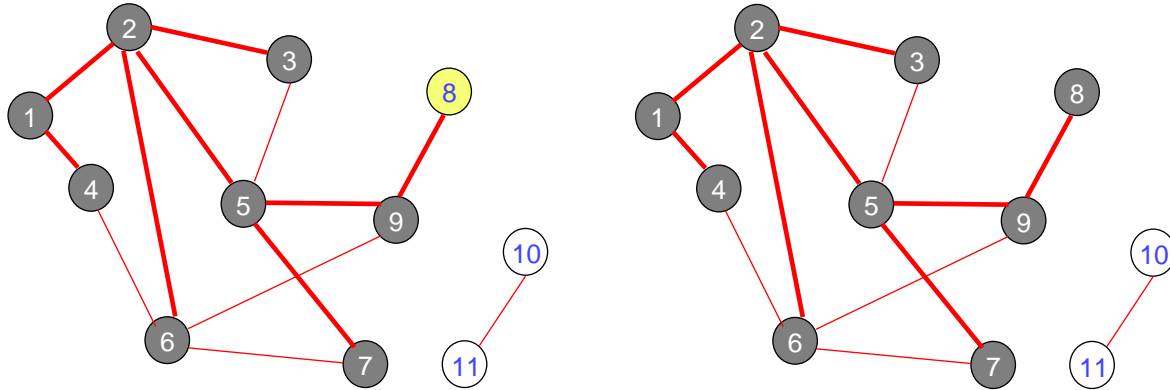


Visit/mark/label start vertex and put in a FIFO queue



Breadth-first Search (BFS)

- Remove **8** from **Q**, visit adjacent unvisited vertices, put in **Q**
- Return to the invoking method

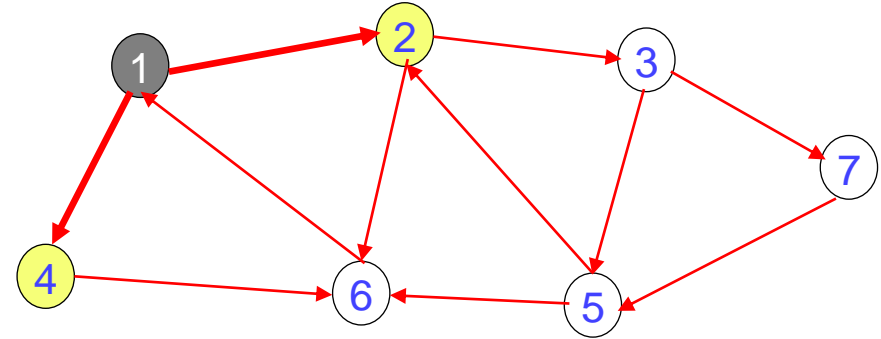
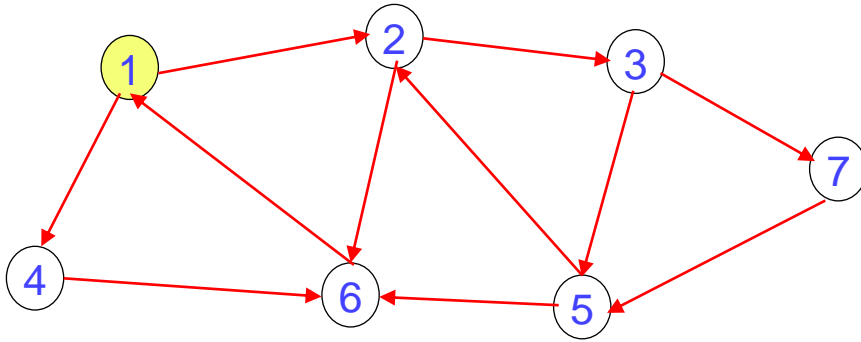


Visit/mark/label start vertex and put in a FIFO queue



Breadth-first Search (BFS)

- Start search at vertex **1**
- Remove **1** from **Q**, visit adjacent unvisited vertices, put in **Q**

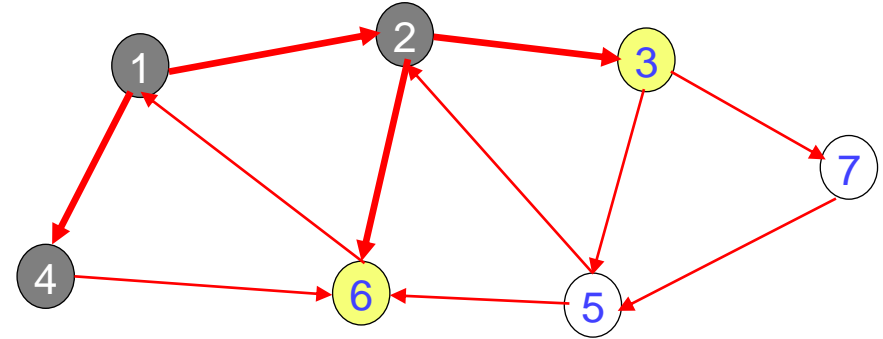
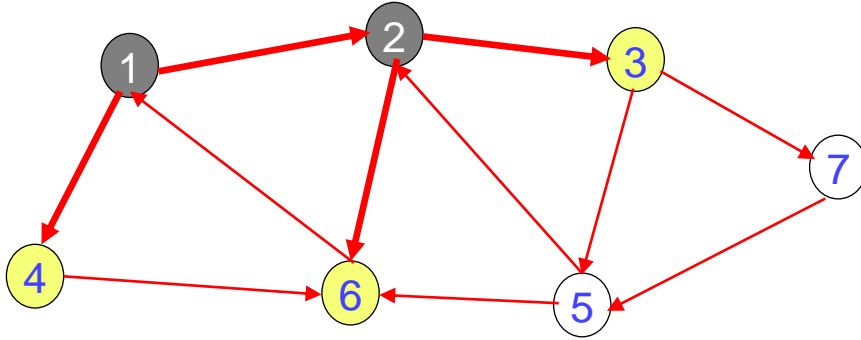


Visit/mark/label start vertex and put in a FIFO queue



Breadth-first Search (BFS)

- Remove **2** from **Q**, visit adjacent unvisited vertices, put in **Q**
- Remove **4** from **Q**, visit adjacent unvisited vertices, put in **Q**

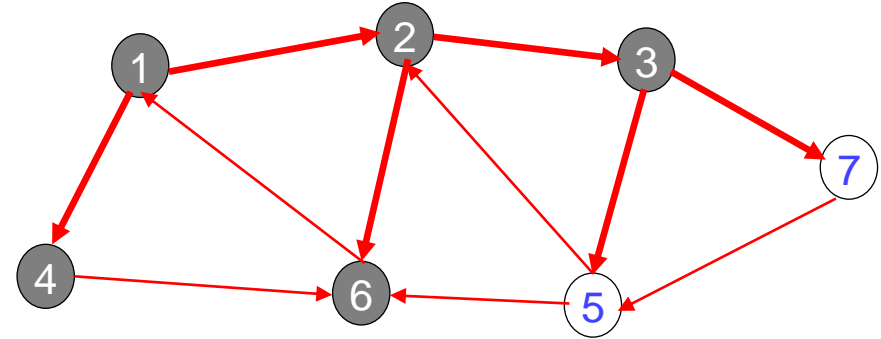
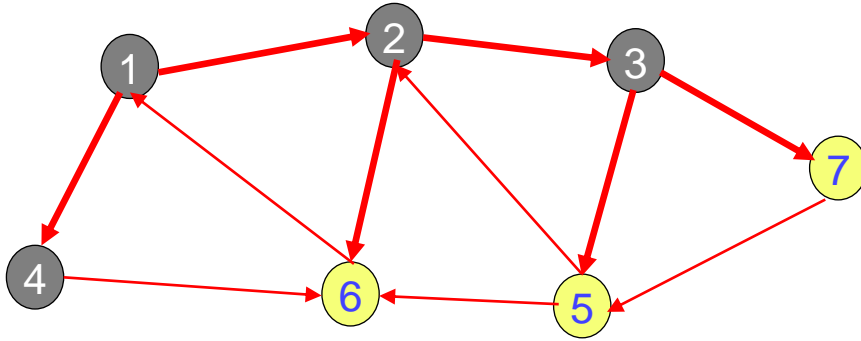


Visit/mark/label start vertex and put in a FIFO queue



Breadth-first Search (BFS)

- Remove **3** from **Q**, visit adjacent unvisited vertices, put in **Q**
- Remove **6** from **Q**, visit adjacent unvisited vertices, put in **Q**

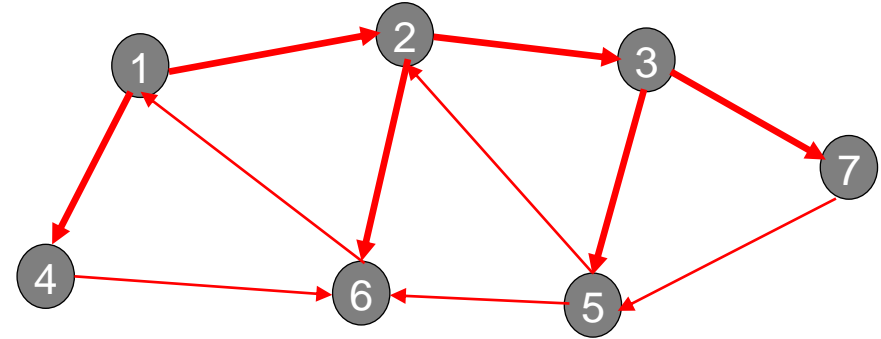
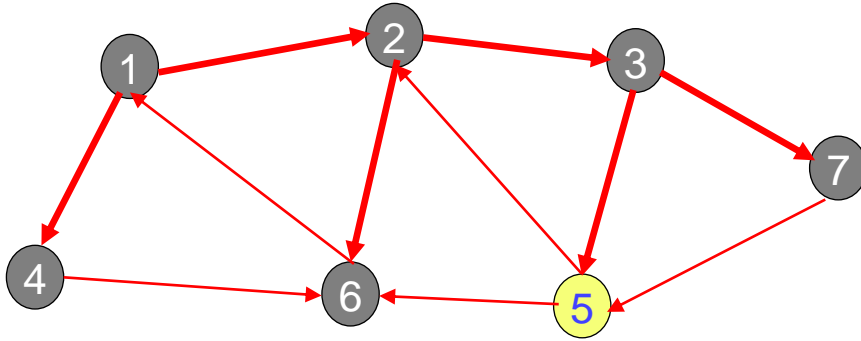


Visit/mark/label start vertex and put in a FIFO queue



Breadth-first Search (BFS)

- Remove **7** from **Q**, visit adjacent unvisited vertices, put in **Q**
- Remove **5** from **Q**, visit adjacent unvisited vertices, put in **Q**



Visit/mark/label start vertex and put in a FIFO queue



BFS Properties and Complexity

- All vertices reachable from the start vertex (including the start vertex) are visited

Time Complexity

- Each visited vertex is put on (and so removed from) the queue exactly once
- When a vertex is removed from the queue, we examine its adjacent vertices
 - **$O(N)$** if adjacency matrix used
 - **$O(\text{vertex degree})$** if adjacency lists used
- Total time
 - **$O(MN)$** , where **M** is number of vertices in the component that is searched (adjacency matrix)
 - **$O(N + \text{sum of component vertex degrees})$** (adj. lists) = **$O(N + \text{number of edges in component})$**

Applications of BFS

- Shortest Path and Minimum Spanning Tree for unweighted graph
- Peer to Peer Networks
- Crawlers in Search Engines
- Social Networking Websites
- GPS Navigation systems
- Broadcasting in Network
- In Garbage Collection
- Cycle detection in undirected graph
- Ford–Fulkerson algorithm
- To test if a graph is Bipartite
- Path Finding
- Finding all nodes within one connected component

Application: Path from Vertex u to Vertex v

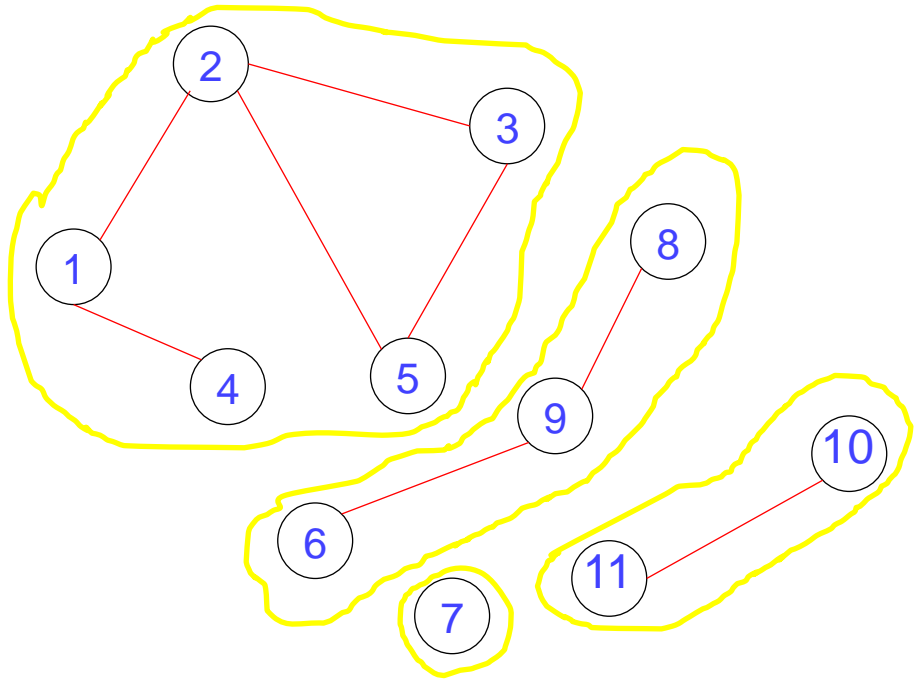
- Start a breadth-first search at vertex u
- Terminate when vertex v is visited or when Q becomes empty (whichever occurs first)
- Time
 - $O(N^2)$ when adjacency matrix used
 - $O(N + E)$ when adjacency lists used (E is number of edges)

Application: Is The Graph Connected?

- Start a breadth-first search at any vertex of the graph
- Graph is connected iff all N vertices get visited
- Time
 - $O(N^2)$ when adjacency matrix used
 - $O(N + E)$ when adjacency lists used (E is number of edges)

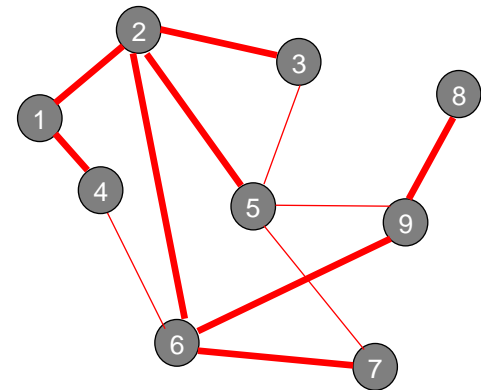
Connected Components

- Start a breadth-first search at any as yet unvisited vertex of the graph
- Newly visited vertices (plus edges between them) define a component
- Repeat until all vertices are visited
- Time complexity
 - $O(N^2)$ when adjacency matrix used
 - $O(N + E)$ when adjacency lists used (E is number of edges)



Spanning Tree

- Start a breadth-first search at any vertex of the graph
- If graph is connected, the $N - 1$ edges used to get to unvisited vertices define a spanning tree (breadth-first spanning tree)
- Time complexity
 - $O(N^2)$ when adjacency matrix used
 - $O(N + E)$ when adjacency lists used (E is number of edges)



Breadth-first search from vertex **1**
Breadth-first spanning tree

Next Lecture

Graph Algorithms: Depth-First Search (DFS)

Thank you for your attention...

Any question?

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