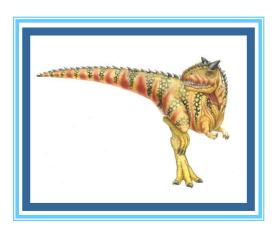
Chapter 5: Process Synchronization





Chapter 5: Process Synchronization

- Background
- ☐ The Critical-Section Problem
- Peterson's Solution
- Synchronization Hardware
- Mutex Locks
- Semaphores
- Classic Problems of Synchronization
- Monitors
- Synchronization Examples
- Alternative Approaches





Objectives

- □ To present the concept of process synchronization.
- ☐ To introduce the critical-section problem, whose solutions can be used to ensure the consistency of shared data
- To present both software and hardware solutions of the critical-section problem
- To examine several classical process-synchronization problems
- To explore several tools that are used to solve process synchronization problems





Background

- Processes can execute concurrently
 - May be interrupted at any time, partially completing execution
- Concurrent access to shared data may result in data inconsistency
- Maintaining data consistency requires mechanisms to ensure the orderly execution of cooperating processes
- Illustration of the problem:
 Suppose that we wanted to provide a solution to the consumer-producer problem that fills **all** the buffers. We can do so by having an integer **counter** that keeps track of the number of full buffers. Initially, **counter** is set to 0. It is incremented by the producer after it produces a new buffer and is decremented by the consumer after it consumes a buffer.





Producer





Consumer





Race Condition

☐ counter++ could be implemented as

```
register1 = counter
register1 = register1 + 1
counter = register1
```

□ counter-- could be implemented as

```
register2 = counter
register2 = register2 - 1
counter = register2
```

□ Consider this execution interleaving with "count = 5" initially:

```
S0: producer execute register1 = counter {register1 = 5}
S1: producer execute register1 = register1 + 1 {register1 = 6}
S2: consumer execute register2 = counter {register2 = 5}
S3: consumer execute register2 = register2 - 1 {register2 = 4}
S4: producer execute counter = register1 {counter = 6}
S5: consumer execute counter = register2
```





Critical Section Problem

- □ Consider system of n processes $\{p_0, p_1, ..., p_{n-1}\}$
- Each process has critical section segment of code
 - Process may be changing common variables, updating table, writing file, etc
 - When one process in critical section, no other may be in its critical section
- Critical section problem is to design protocol to solve this
- Each process must ask permission to enter critical section in entry section, may follow critical section with exit section, then remainder section





Critical Section

☐ General structure of process **P**_i

```
do {
     entry section
     critical section

     exit section

remainder section
} while (true);
```





Algorithm for Process P_i

```
do {
    while (turn == j);
        critical section
    turn = j;
        remainder section
} while (true);
```

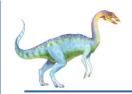




Solution to Critical-Section Problem

- 1. Mutual Exclusion If process P_i is executing in its critical section, then no other processes can be executing in their critical sections
- 2. Progress If no process is executing in its critical section and there exist some processes that wish to enter their critical section, then the selection of the processes that will enter the critical section next cannot be postponed indefinitely
- 3. **Bounded Waiting** A bound must exist on the number of times that other processes are allowed to enter their critical sections after a process has made a request to enter its critical section and before that request is granted
 - Assume that each process executes at a nonzero speed
 - No assumption concerning relative speed of the n processes





Critical-Section Handling in OS

Two approaches depending on if kernel is preemptive or nonpreemptive

- Preemptive allows preemption of process when running in kernel mode
- Non-preemptive runs until exits kernel mode, blocks, or voluntarily yields CPU
 - Essentially free of race conditions in kernel mode





Peterson's Solution

- Good algorithmic description of solving the problem
- Two process solution
- Assume that the **load** and **store** machine-language instructions are atomic; that is, cannot be interrupted
- ☐ The two processes share two variables:
 - int turn;
 - Boolean flag[2]
- The variable turn indicates whose turn it is to enter the critical section
- The flag array is used to indicate if a process is ready to enter the critical section. flag[i] = true implies that process P_i is ready!





Algorithm for Process Pi

```
do {
    flag[i] = true;
    turn = j;
    while (flag[j] && turn = = j);
        critical section

    flag[i] = false;
    remainder section
} while (true);
```





Peterson's Solution (Cont.)

- Provable that the three CS requirement are met:
 - 1. Mutual exclusion is preserved

```
P<sub>i</sub> enters CS only if:
   either flag[j] = false or turn = i
```

- 2. Progress requirement is satisfied
- 3. Bounded-waiting requirement is met





Synchronization Hardware

- Many systems provide hardware support for implementing the critical section code.
- All solutions below based on idea of locking
 - Protecting critical regions via locks
- □ Uniprocessors could disable interrupts
 - Currently running code would execute without preemption
 - Generally too inefficient on multiprocessor systems
 - Operating systems using this not broadly scalable
- Modern machines provide special atomic hardware instructions
 - ▶ Atomic = non-interruptible
 - Either test memory word and set value
 - Or swap contents of two memory words

