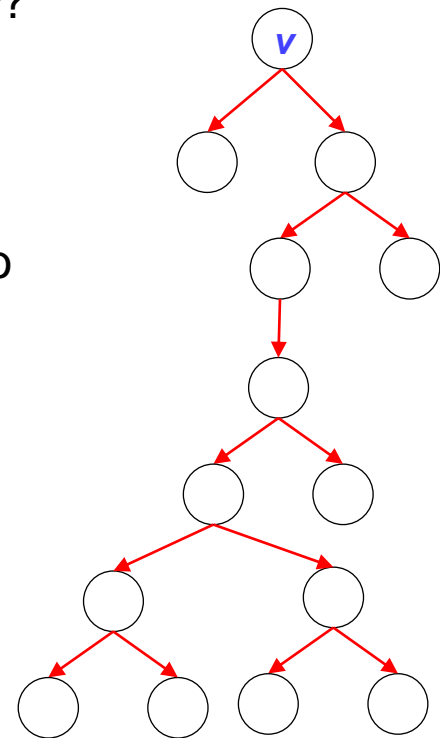




Applications of DFS in Directed Graphs

Application: Graph is Strongly Connected using DFS

- How to check if there exists a path from every vertex in G to v ?
 - Lets get G^R by reversing the edges in G
 - Then do DFS(v)
 - If all vertices are visited in G^R , then there is a path from v to every vertex in G^R
 - That implies, in the original graph G , there is a path from every vertex to v
 - If in second DFS, if any vertex x is not visited by v , that implies in the original graph G , there is no path from x to v
 - Time complexity: **$2 \cdot \text{DFS}$**



Application: Graph is Strongly Connected using DFS

Pick an arbitrary vertex v

do DFS(v)

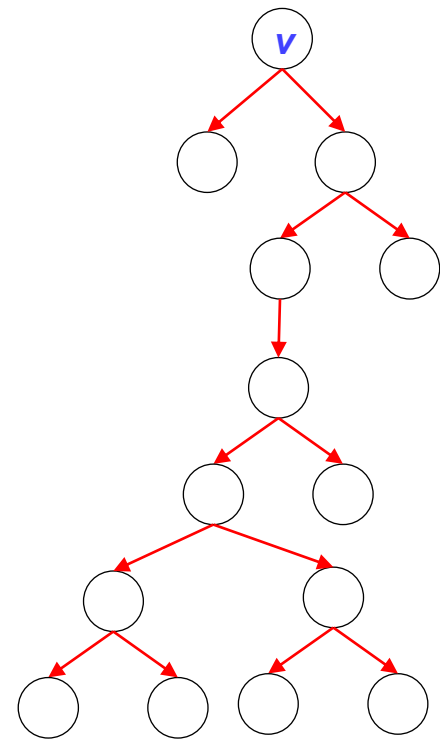
Reverse G , do DFS(v) on G^R

if all vertices are visited in both DFS's **then**

G is strongly connected

else

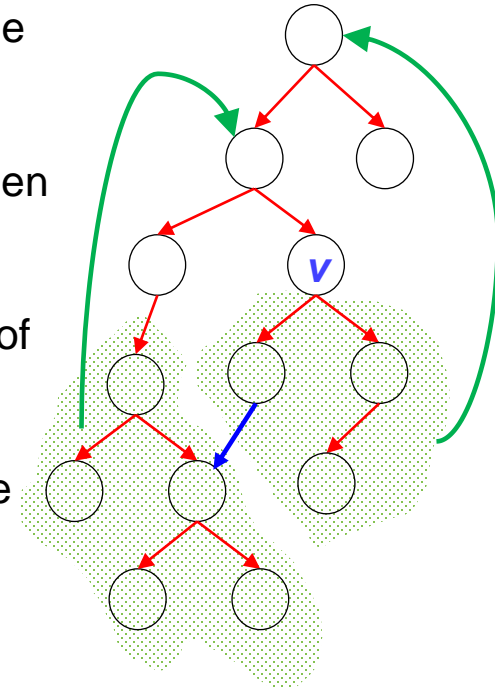
G is not strongly connected




- Can we do better? Can we do it with one DFS?

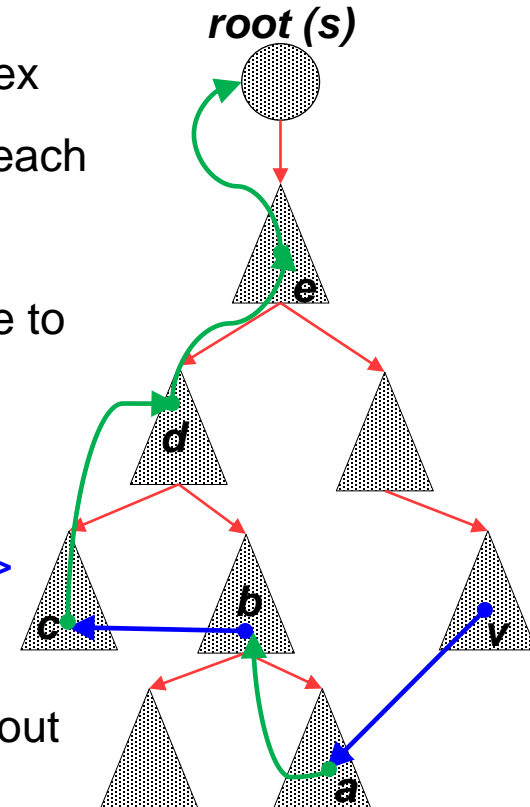
Application: Graph is Strongly Connected using DFS

- Suppose my DFS tree looks like this:
- Now we want to ensure, while processing a vertex v , there are some edges going out from either v or from the subtree rooted at v
- If from a subtree rooted at v there is no edge going out from this, then the graph is not strongly connected
 - Because then we can only enter the subtree, we can not go out of this set of vertices
 - Therefore, it is necessary that an edge goes out of every subtree
 - Back edge
 - Cross edge
 - Is it a sufficient condition?



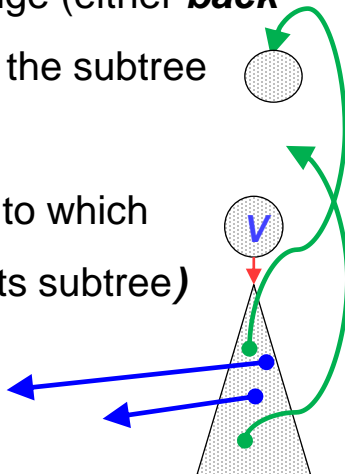
Application: Graph is Strongly Connected using DFS

- To check for sufficiency:
 - Given the DFS tree, from the root we can reach every vertex
 - Now, it is enough to show that from every vertex, we can reach the root as well
 - With both a **cross edge** and a **back edge**, we can traverse to a vertex which is having arrival time strictly less than v
 - Every time with DFS, we will get to the vertex with smaller arrival time: $arr[v] > arr[a] > arr[b] > arr[c] > arr[d] > arr[e] > arr[s]$ 
 - Therefore, it is also **sufficient** to check that an edge goes out of every subtree



Application: Graph is Strongly Connected using DFS

- To modify DFS to check if there is an edge going out of every sub tree?
 - Subtree**: The part of the tree which is composed of the descendants of any vertex
 - DFS(v) should return the smallest arrival time to which there is an edge (either **back edge** or **cross edge**) from the subtree rooted at v
 - i.e., **min**(all the arrival time to which there is an edge from v or its subtree)
 - Algorithm?
 - Any special case?



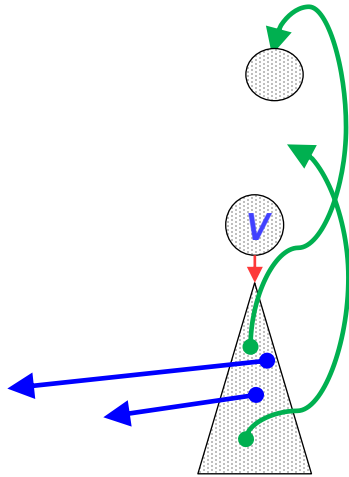
```

time = 0;
SC(v)
{
    visited[v] = 1;
    arr[v] = time++;
    SEdge = arr[v];
    for all vertex u out-adjacent from v do
        if !visited[u] then
            SEdge = min(SEdge, SC(u));
        else
            SEdge = min(SEdge, arr[u]);
    if SEdge = arr[v] then
        return SEdge;
}

```

Application: Graph is Strongly Connected using DFS

- To modify DFS to check if there is an edge going out of every sub tree?
 - Any special case?
 - What is the time complexity?



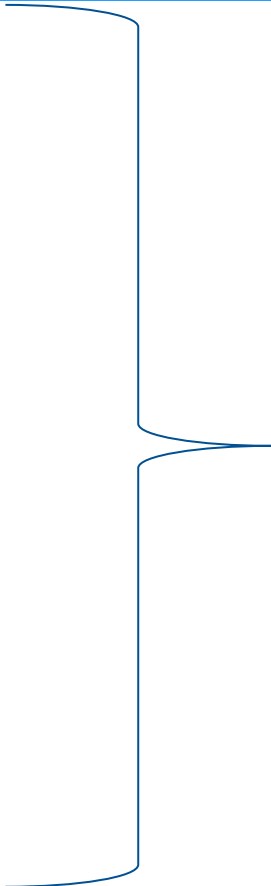
```

time = 0;
SC(v)
{
    visited[v] = 1;
    arr[v] = time++;
    SEdge = arr[v];
    for (for all vertex u out-adjacent from v) do
        if !visited[u] then
            SEdge = min(SEdge, SC(u));
        else
            SEdge = min(SEdge, arr[u]);
    if SEdge = arr[v] && v != starting vertex then
        return SEdge;
}

```

Summary of BFS and DFS Applications

- **Applications of BFS in undirected graphs:**
 - Connected components
 - Bipartite
 - Shortest distance of the vertices to the start vertex
- **Applications of DFS in undirected graphs:**
 - 2-Edge connectivity
 - Planer (only pointer)
 - 2-Vertex connectivity (only pointer)
- **Applications of DFS in directed graphs:**
 - Acyclic
 - Topological sort
 - Strongly connected



What is the time complexity for each of them?

Next Lecture

Dijkstra's Shortest Path Algorithm

Thank you for your attention...

Any question?

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