view_frames Result Recorded at time: 19.420 odom Broadcaster: /gazebo Average rate: 100.201 Hz Most recent transform: 19.410 (0.010 sec old) Buffer length: 4.980 sec base_footprint Broadcaster: /robot_state_publisher Broadcaster: /gazebo Broadcaster: /gazebo Average rate: 10000.000 Hz Average rate: 150.402 Hz Average rate: 150.402 Hz Most recent transform: 0.000 (19.420 sec old) Most recent transform: 19.410 (0.010 sec old) Most recent transform: 19.410 (0.010 sec old) Buffer length: 0.000 sec Buffer length: 4.980 sec Buffer length: 4.980 sec base_link right_wheel_link left_wheel_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 0.000 (19.420 sec old) Most recent transform: 19.400 (0.020 sec old) Most recent transform: 19.400 (0.020 sec old) Buffer length: 0.000 sec Buffer length: 4.900 sec Buffer length: 4.900 sec laser_link left_caster_link right_caster_link