ALGORITHMS AND DATA STRUCTURES II

Lecture 2

Heaps,

Heapsort Algorithm,

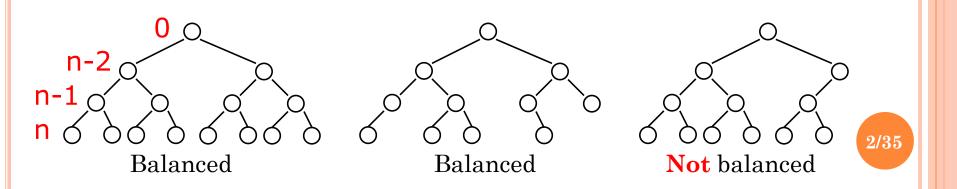
Priority Queues

1/35

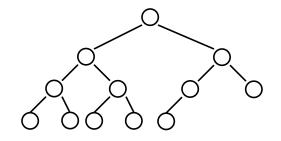
Lecturer: K. Markov

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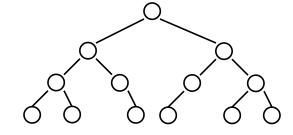
- Binary trees
 - The depth of a node is its distance from the root.
 - The depth of a tree is the depth of the deepest node.
- A binary tree of depth n is balanced if all the nodes at depths 0 through n-2 have two children



- •A balanced binary tree is left-justified if:
 - all the leaves are at the same depth, or
 - all the leaves at depth n+1 are to the left of all the nodes at depth n.

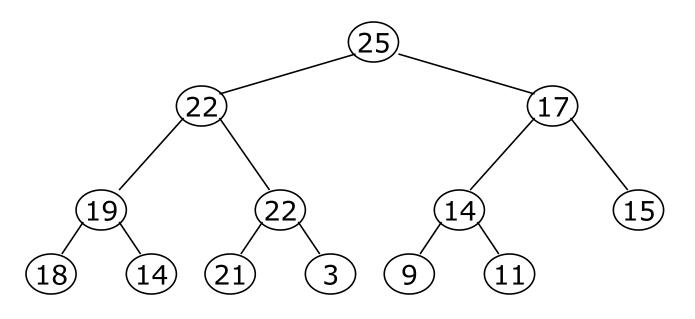


Left-justified

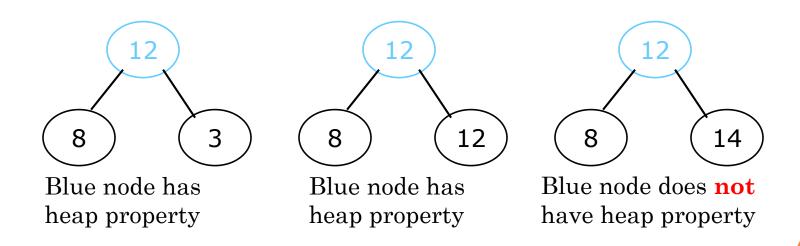


Not left-justified

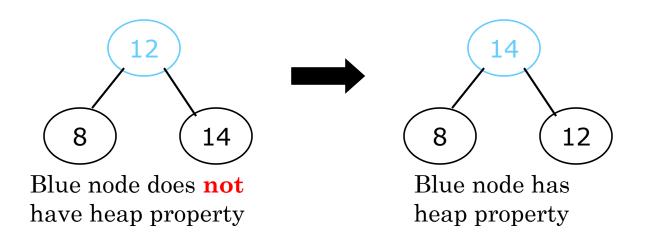
- •What is a heap?
 - A balanced, left-justified binary tree in which no node has a value greater than the value in its parent.



- Heap property
 - A node has the heap property if the value in the node is as large as or larger than the values in its children.

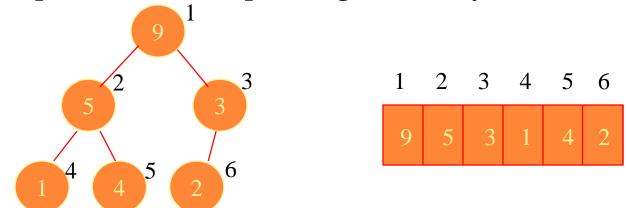


- "Heapify"
 - Given a node that does not have the heap property, you can give it the heap property by exchanging its value with the value of the larger child



Array representation

• In practice, it is easier and more efficient to implement a heap using an array.



• Relationships between indexes of parents and children.

 $\begin{aligned} & PARENT(i) \\ & \{return \lfloor i/2 \rfloor \} \end{aligned}$

LEFT(i) {return 2i}

RIGHT(i) {return 2i+1}

- Maintaining heap property
 - Input: array A and index i.
 - **Output**: sub-tree rooted at *i* with heap property.

```
def MaxHeapify (A, i)
    l = LEFT(i)
    r = RIGHT (i)
    if l <= A.heap_size and A[l] > A[i]: // if L child exists and is > A[i]
         largest = 1
    else:
         largest = i
    if r \le A.heap\_size and A[r] > A[largest]:
         largest = r
    if largest ≠ i:
         swap (A[i], A[largest])
         MaxHeapify (A, largest)
                                            // heapify the subtree
```

8/35

- Constructing a heap
 - <u>Bottom-up:</u> Put everything in an array and then heapify the trees in a bottom-up way.
 - Given a heap of n nodes, what's the index of the last parent? $(\lfloor n/2 \rfloor)$

```
def HeapBottomUp (A)

//Constructs a heap from the elements

//of a given array by the bottom-up algorithm

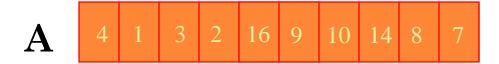
//Input: An array A[1..n] of orderable items

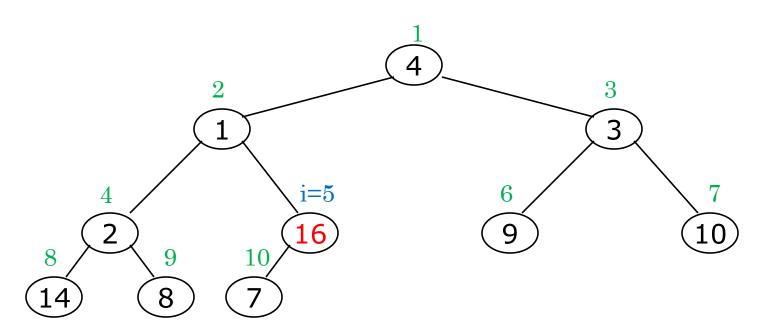
//Output: A heap A[1..n]

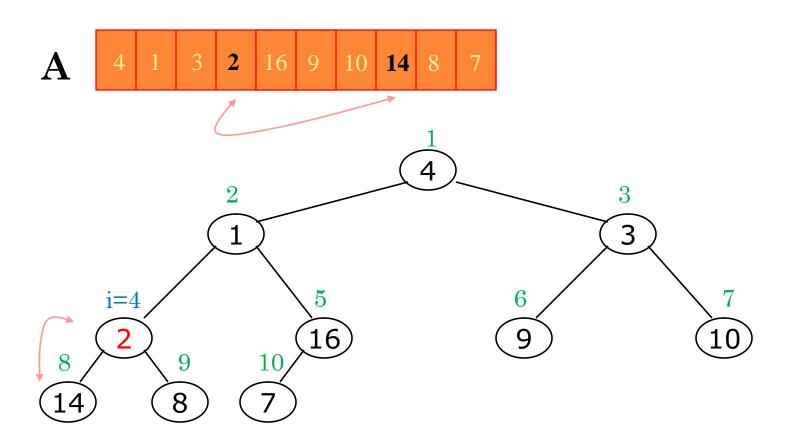
A.heap_size = A.length

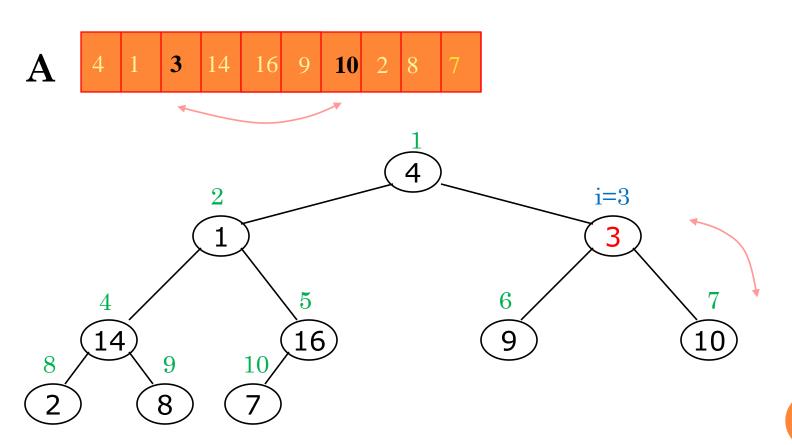
for i = [A.length / 2] to 1

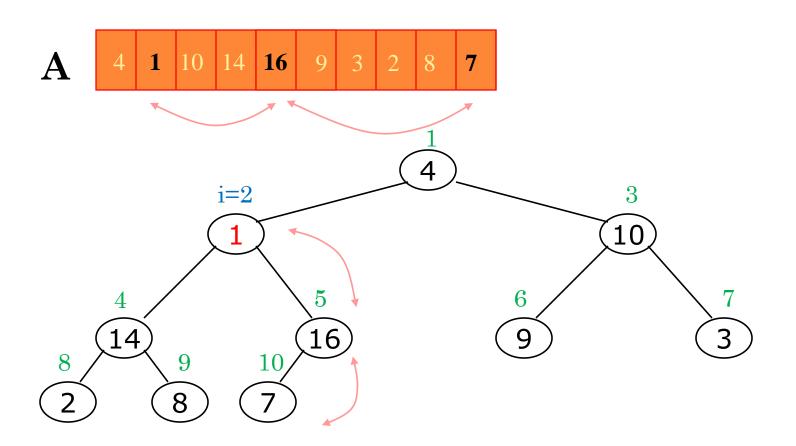
MaxHeapify (A, i)
```

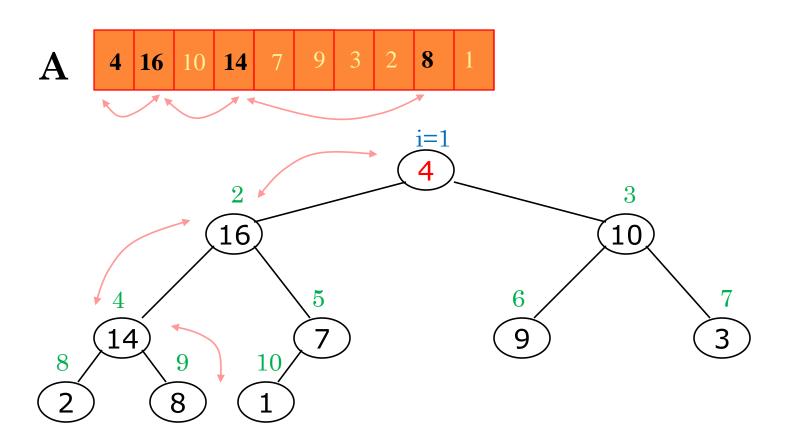




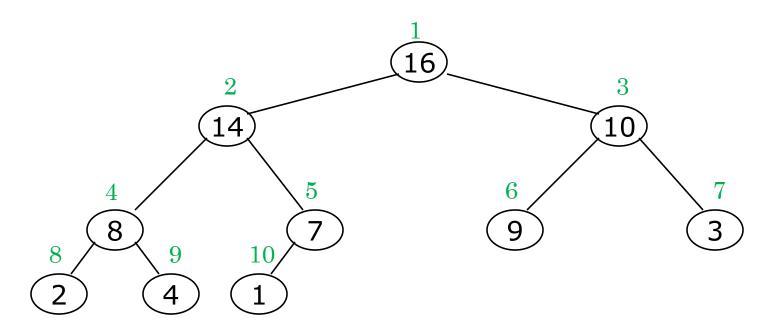










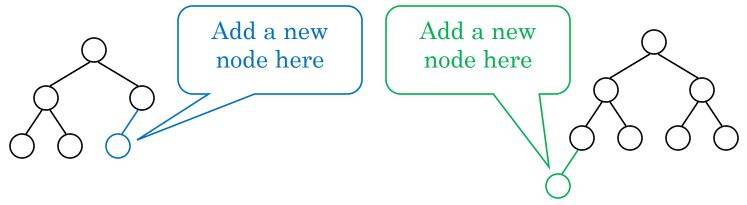


- Time complexity of heap construction
 - An n node heap has height $h = \lfloor \log n \rfloor$.
 - There are at most $\lceil n/2^{h+1} \rceil$ nodes at any height h.
 - MaxHeapify complexity is $O(\log n) = O(h)$
 - The time complexity of **HeapBottomUp** is then bounded from above by

$$\sum_{h=0}^{\lfloor \log n \rfloor} \left\lceil \frac{n}{2^{h+1}} \right\rceil O(h) = O\left(n \sum_{h=0}^{\lfloor \log n \rfloor} \frac{h}{2^h}\right) = O\left(n \sum_{h=0}^{\infty} \frac{h}{2^h}\right) = O(n)$$

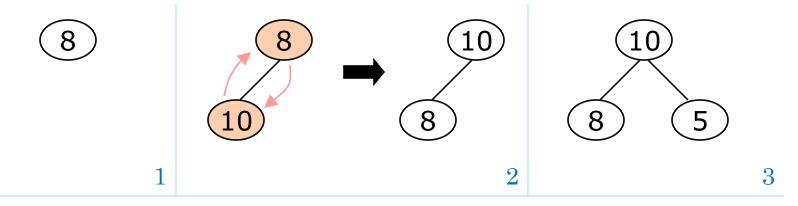
since
$$\sum_{h=0}^{\infty} \frac{h}{2^h} = 2$$

- New element insertion.
 - Insert element at the last position in heap.
 - Add the node just to the right of the rightmost node in the deepest level
 - If the deepest level is full, start a new level.

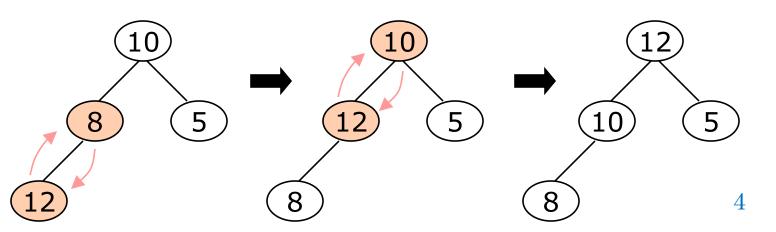


- Compare with its parent, and exchange them if it violates the heap property.
- Continue comparing the new element with nodes 17/35 up the tree until the heap property condition is satisfied.

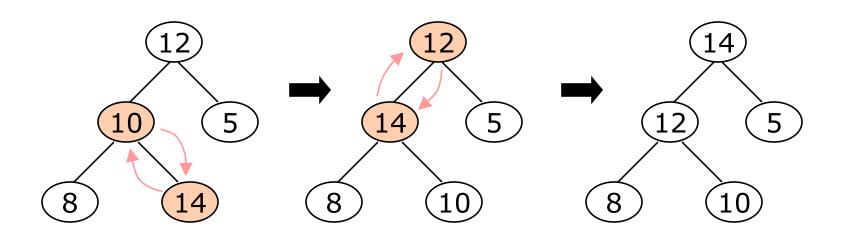
- Top down heap construction.
 - Start with empty heap.
 - Insert all nodes one at a time.



18/35



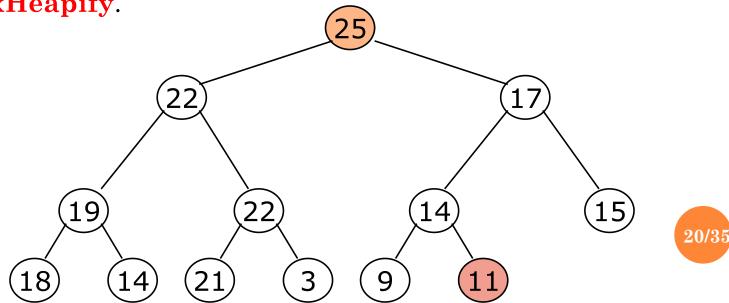
- Top down heap construction.
 - Start with empty heap.
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Root deletion

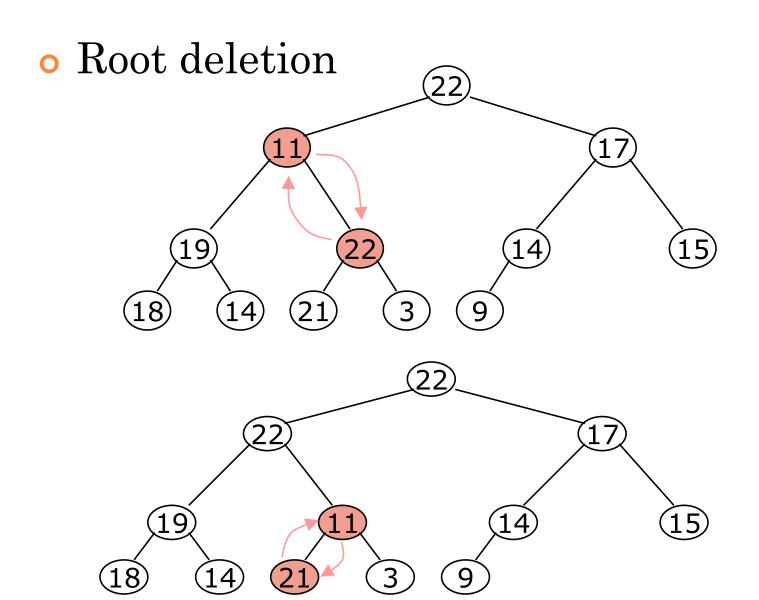
- The root of a heap can be deleted and the heap fixed up as follows:
 - Exchange the root with the last leaf.
 - Decrease the heap's size by 1.

- Heapify the smaller tree in exactly the same way we did it in **MaxHeapify**.



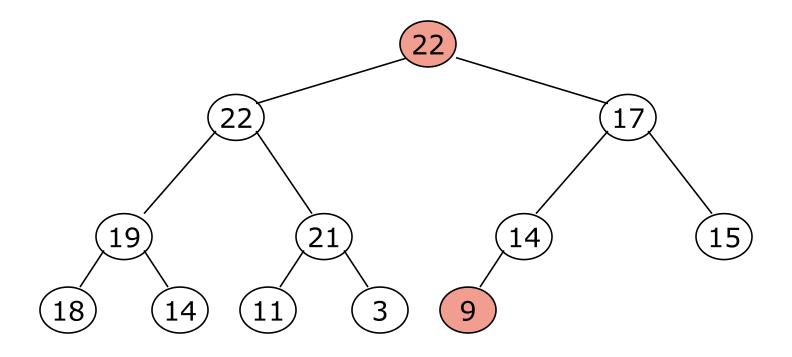
• Root deletion [19]





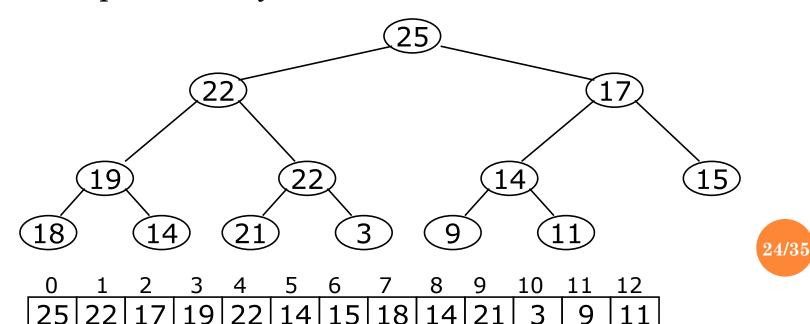


- Root deletion
 - Removing next root



• Heapsort algorithm:

- (Heap construction) Build heap for a given array (either bottom-up or top-down)
- (Maximum deletion) Apply the root-deletion operation n-1 times to the remaining heap until heap contains just one node.



- The "root" is the first element in the array
- The "rightmost node at the deepest level" is the last element
- Swap them...

```
    0
    1
    2
    3
    4
    5
    6
    7
    8
    9
    10
    11
    12

    25
    22
    17
    19
    22
    14
    15
    18
    14
    21
    3
    9
    11
```

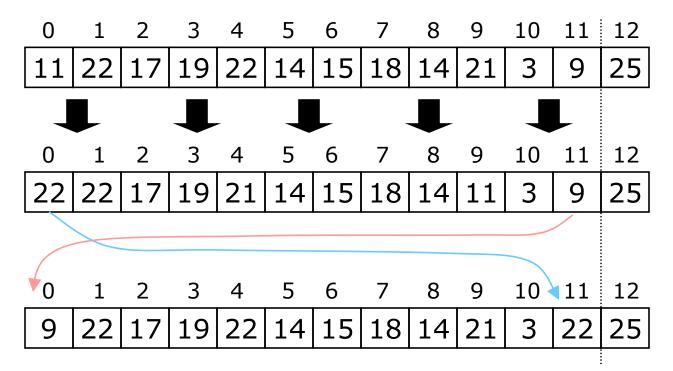
```
    0
    1
    2
    3
    4
    5
    6
    7
    8
    9
    10
    11
    12

    11
    22
    17
    19
    22
    14
    15
    18
    14
    21
    3
    9
    25
```

• ...And pretend that the last element in the array no longer exists—that is, the "last index" is 11 (9)



• Reheap the root node (index 0, containing 11)



- o...And again, remove and replace the root node
- Repeat until the last becomes first, and the array is sorted!



• Animated example

6 5 3 1 8 7 2 4

• Pseudo-code of the Heapsort algorithm.

```
def Heapsort (A)
  //Constructs a heap from the elements
  //Sorts elements of the array.
  //Input: An array A[1..n] of orderable items
  //Output: A sorted A[1..n]
  HeapBottomUp (A)
  for i = A.length to 2: // n-1 times
    swap (A[1], A[i])
    A.heap_size = A.heap_size - 1
    MaxHeapify (A, 1)
```

- Analysis of the Heapsort
- Heapsort consists of two parts:
 - Heap construction which has O(n) time complexity.
 - For loop (repeated n-1 times) which has time complexity $O(\log n)$.

Total:

$$O(n) + (n-1) * O(\log n) = O(n \log n)$$



- Priority queue is an abstract data type which is like a regular queue or stack data structure, but additionally, each element is associated with a "priority".
 - **stack** elements are pulled in last-in first-out-order (e.g. a stack of papers)
 - **queue** elements are pulled in first-in first-out-order (e.g. a line in a cafeteria)
 - **priority queue** elements are pulled highest-priority-first (e.g. cutting in line, or VIP service).



- Operations on priority queues
 - Insert (S, x) insert element x into queue S.
 - Maximum (S) return the element of S with the largest key.
 - *Extract-Max* (S) removes and returns the element of S with the largest key.
 - *Increase-Key* (*S*, *x*, *k*) increases the value of *x*'s key to the new value *k* which should be at least as large as *x*'s current key value.

- Priority queue is implemented as heap.
- Operations on priority queues:
 - Extract-Max (S) operation

```
def Extract-Max (A)
  // Input: heap A[1..n]
  // Removes and returns the root element
  max = A[1]
  A[1] = A[A.heap_size]
  A.heap_size = A.heap_size - 1
  MaxHeapify (A, 1)
  return max
```

• Time complexity: $O(\log n)$



- Operations on priority queues
 - *Increase-Key (S)* operation

```
def Heap-Increase-Key (A, i, k)

// Input: heap A[1..n], element index i, and its new key k.

// Output: heap A[1..n] conforming to heap property.

A[i] = k

while i > 1 and A[Parent(i)] < A[i]:
    swap (A[Parent(i)], A[i])
    i = Parent (i)</pre>
```

• Time complexity: $O(\log n)$



- Operations on priority queues
 - *Insert (S, x)* operation

```
def Max-Heap-Insert (A, k)
  // Input: heap A[1..n] and new key k.
  // Output: heap A[1..n+1].
  A.heap_size = A.heap_size + 1
  A[A.heap_size] = MAX_NEGATIVE
  Heap-Increase-Key (A, A.heap_size, k)
```

• Time complexity: $O(\log n)$



THAT'S ALL FOR TODAY!

