# ALGORITHMS AND DATA STRUCTURES II



1/26

Lecture 4
Spanning Tree,
Weighted Graphs,
Prim's and Kruskal's algorithms.

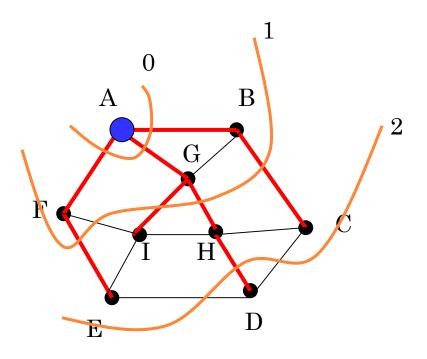
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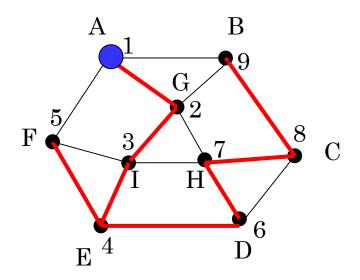
#### **SPANNING TREE**

- Assume you have an undirected graph
   G = (V,E)
- Spanning tree of graph G is tree  $T = (V, E_T \subseteq E, R)$ 
  - Tree has same set of nodes.
  - All tree edges are graph edges.
  - Root of tree is R.
- **Think:** "smallest set of edges needed to connect everything together".

### **SPANNING TREE**



Breadth-first Spanning Tree

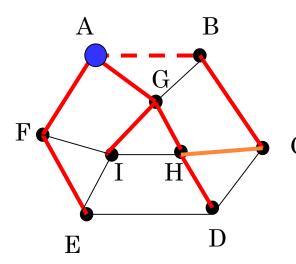


Depth-first spanning tree

#### **SPANNING TREE**

# • Properties:

- In any tree T = (V, E), |E| = |V| 1
- For any edge e in G but not in T, there is a simple cycle Y containing only edge e and edges in spanning tree.
- Moreover, inserting edge *e* into **T** and deleting any edge in **Y** gives another spanning tree **T**'.



#### **EXAMPLE:**

edge **(H,C)**:

simple cycle is (H,C,B,A,G,H)

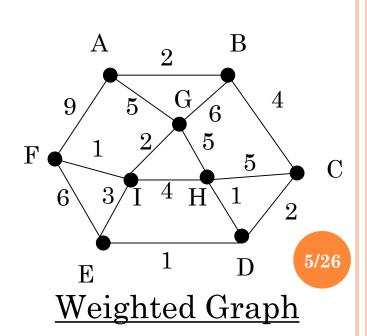
adding (H,C) to T and deleting (A,B)

gives another spanning tree

#### WEIGHTED GRAPHS

### Openition:

- A weighted graph is a graph G(V,E) with real valued weights assigned to each edge.
- Equivalently, a weighted graph is a triple G(V,E,W), where V is the set of vertices,  $\boldsymbol{E}$  is the set of edges, and W is the set of weights. The weights on edges are also called distances or costs.



#### WEIGHTED GRAPHS

## • Representation:

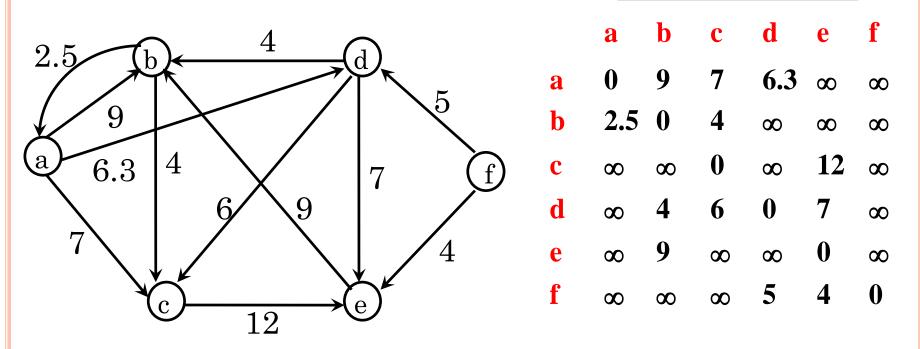
• A weighted graph G(V,E,W) can be represented by a **distance matrix** 

$$D_{n \times n} = \begin{bmatrix} d(1,1) & \dots & d(1,n) \\ \dots & \dots & \dots \\ d(n,1) & \dots & d(n,n) \end{bmatrix} \quad n = |V|$$

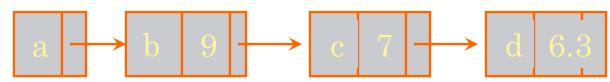
where d(i,i) = 0, and for  $1 \le i \ne j \le n$ , if edge  $(i,j) \in E$  then d(i,j) is the weight of (i,j), otherwise d(i,j) is infinite  $\infty$  (a sufficiently large number in practice).

#### WEIGHTED GRAPHS

# • Representation:







7/26

Distance Matrix

 $\circ$  Let T(V', E') be a spanning tree of a weighted graph G and

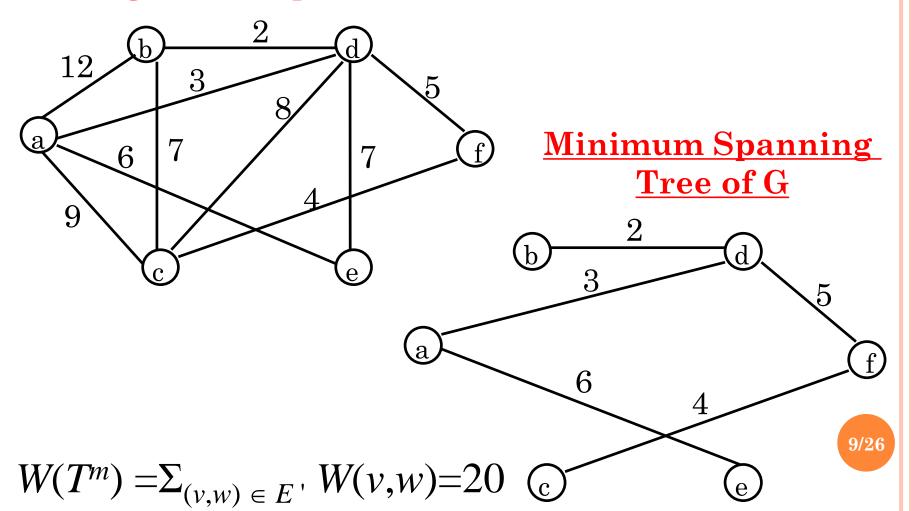
$$W(T) = \sum_{(v,w) \in E'} W(v,w)$$

be the sum of weights of edges in T, where W(v,w) denotes the weight of edge (v,w).

o A minimum spanning tree of G is a spanning tree  $T^m$  of G such that

$$W(T^m) = \min_{\mathbf{T}} \{W(T)\}.$$

#### Weighted Graph G

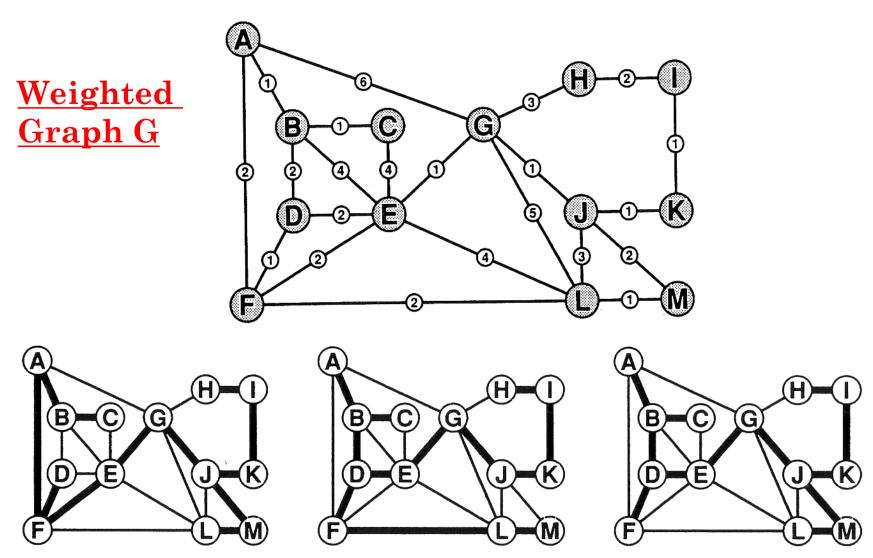


• Minimum spanning tree is useful when we attempt to minimize the cost of connecting all the nodes.

# • Applications:

- Constructing electric power networks or telephone networks.
- Making printed circuit boards (PCBs).
- Etc.
- Note: Minimum spanning tree need not to be unique. (simple examples)

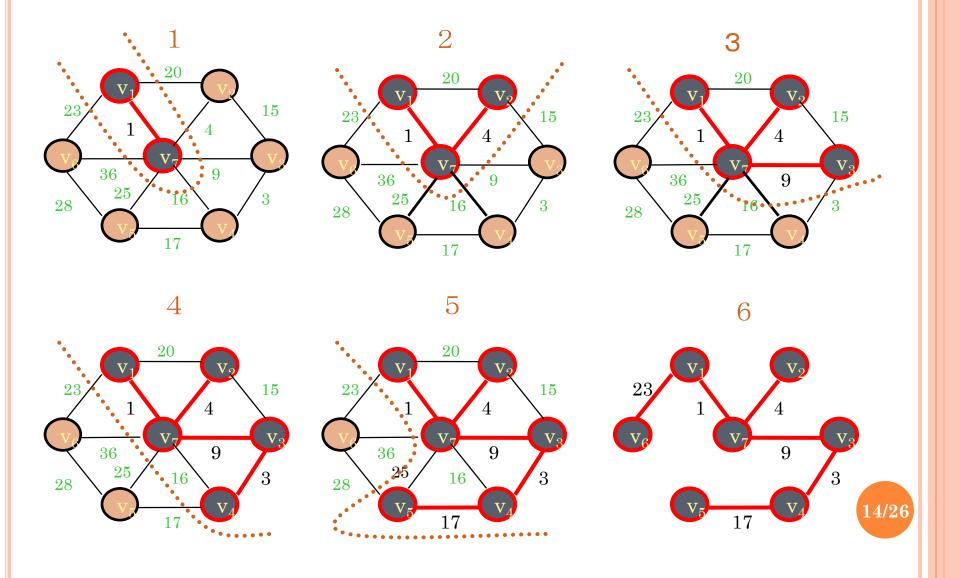




Multiple Minimum Spanning Trees of G

- Building MST two strategies:
  - **Prim's algorithm** start with a root node *s* and try to grow a tree from *s* outward. At each step, add the node that can be attached as cheaply as possible to the partial tree we already have.
  - **Kruskal's algorithm** start with no edges and successively insert edges from *E* in order of increasing cost. If an edge makes cycle when added, skip this edge.

- 1) Pick an arbitrary vertex r of G(V,E) as the root of the minimum spanning tree of G. Assume a partial solution (spanning tree) T has been obtained (initially,  $T = \{r\}$ ).
- 2) Choose an edge (v,w) such that  $v \in T$ ,  $w \in V-T$ , and the weight of edge (v,w) is the minimum among that of edges from the nodes of T to nodes of V-T.
- 3) Add the node w into T.
- 4) Repeat the above 2) and 3) until T = V.



• If the graph is represented by an **adjacency** (**distance**) matrix, the time complexity of Prim's algorithm is  $O(|V|^2)$ .

o Prim's algorithm can be made more efficient by maintaining the graph using **adjacency lists** and keeping a **priority queue** of the nodes not in T. Under this implementation, the time complexity of Prim's algorithm is  $O((|V|+|E|)\log|V|)$ .

# • Implementation:

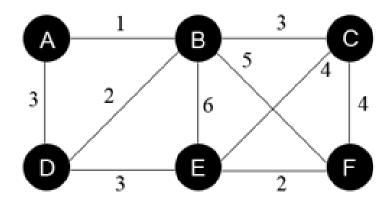
```
\operatorname{def} \operatorname{MST-PRIM} (G, w, r)
// Graph G with set of nodes G.V, weight matrix w and
// root node r. MST is the edges set A = \{(v, v, \pi), v \in V - r\}.
   for each u \in G.V:
     u.key = \infty
     u.\pi = NIL
   r.key = 0
   Q = Min-Priority-Queue (G.V)
   while Q \neq \emptyset:
     u = \text{Extract-Min}(Q)
      for each v \in G.Adj[u]:
         if v \in Q and w(u,v) < v.key:
           v.\pi = u
           v.key = w(u,v)
```

16/26

- Implementation notes:
  - During execution of the algorithm, all nodes that are **NOT** in the **MST**, reside in the **minimum priority queue** based on the *key* attribute.
  - For each node v, the attribute v.key is the minimum weight of any edge connecting v to a node in the MST.
  - If there is no edge  $v.key = \infty$ .
  - The attribute  $v.\pi$  names the parent of v in 17/26 the MST.

• Animated example:

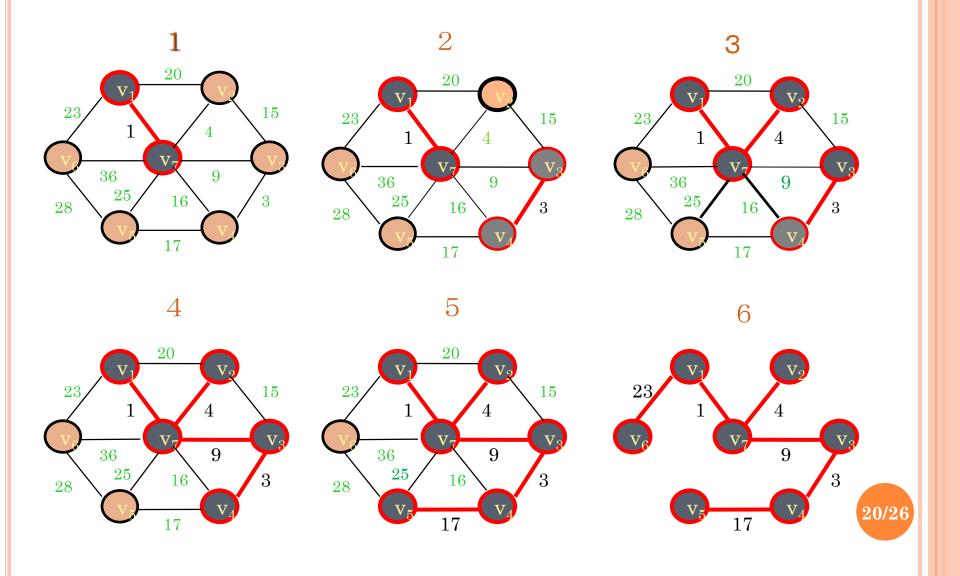
SET: { }



1) Pick the cheapest edge available and add it to the MST

$$e_0 = \min_{\mathbf{v},\mathbf{u}} w(\mathbf{v},\mathbf{u}), \qquad A = \{e_0\}$$

- 2) Choose next cheapest edge e=(v,w)
- 3) If adding *e* to the *A* makes a cycle, do not add it.
- 4) Repeat the above 2) and 3) until all edges are chosen.

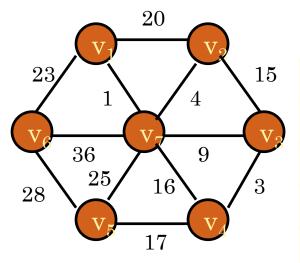


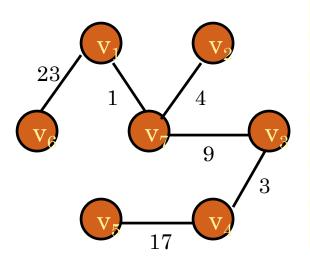
# • Implementation:

return A

```
def MST-KRUSKAL (G, w)
// Graph G with set of nodes G.V, weight matrix w.
// MST is the edges set A=\{\}.
   A = \emptyset
  for each v \in G.V:
    MAKE-SET(v)
  Sort edges of G.E into non-decreasing order by weight w
  for each edge (u, v) \in G.E, taken in non-decreasing order of w:
     if FIND-SET (u) \neq FIND-SET (v):
       A = A \cup \{(u, v)\}
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       UNION (u, v)
```

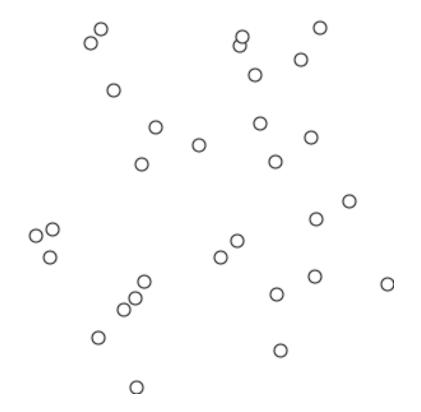
- Implementation notes.
  - UNION-FIND data structure:
    - Given a node u the operation FIND-SET (u) will return the name of the set containing u.
    - To test if two nodes u and v are in the same set, we simply check if FIND-SET(u) = FIND-SET(v)
    - The operation **UNION** ( $\mathbf{u}$ ,  $\mathbf{v}$ ) will take two sets containing  $\mathbf{u}$  and  $\mathbf{v}$  respectively and will merge them into a single set.
    - To make a set from one or several nodes, we use the **MAKE-SET** () operation.





Edge	Action	Sets
		$\{v_1\}, \{v_2\}, \{v_3\}, \{v_4\}, \{v_5\}, \{v_6\}, \{v_7\}$
$(v_1, v_7)$	Add	$\{\mathbf{v}_1, \mathbf{v}_7\}, \{\mathbf{v}_2\}, \{\mathbf{v}_3\}, \{\mathbf{v}_4\}, \{\mathbf{v}_5\}, \{\mathbf{v}_6\}$
$(v_3, v_4)$	Add	$\{\mathbf{v}_1, \mathbf{v}_7\}, \{\mathbf{v}_2\}, \{\mathbf{v}_3, \mathbf{v}_4\}, \{\mathbf{v}_5\}, \{\mathbf{v}_6\}$
$(v_2, v_7)$	Add	$\{v_1, v_2, v_7\}, \{v_3, v_4\}, \{v_5\}, \{v_6\}$
$(v_3, v_7)$		$\{v_1, v_2, v_3, v_4, v_7\}, \{v_5\}, \{v_6\}$
$(v_2, v_3)$	Reject	
$(v_4, v_7)$	Reject	
$(v_4, v_5)$		$\{v_1, v_2, v_3, v_4, v_5, v_7\}, \{v_6\}$
$(v_1, v_2)$	Reject	
$(v_1, v_6)$	Add	$\{v_1, v_2, v_3, v_4, v_5, v_6, v_7\}$

Animated example based on Euclidean distance:



- Complexity.
  - Initializing set A takes O(1).
  - Making |V| sets takes O(V) time.
  - Time to sort the edges by weight is O(Elog E).
  - There are  $|\mathbf{E}|$  FIND-SET and UNION operations taking O(E) time.
  - Since the graph is connected,  $|E| \ge |V|$ -1 and  $|E| < |V|^2$ ,  $\log |V|^2 = 2\log |V|$  which is  $O(\log V)$ .

25/26

• Total running time is O(ElogV).

# THAT'S ALL FOR TODAY!

