

Resampling in Sequential Monte Carlo

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Resampling Schemes

Definition

We will take valid resampling schemes to be those satisfying

- ▶ The total number of particles N remains fixed
- ▶ The particles after resampling are equally weighted
- ▶ The scheme is unbiased: the expected number of offspring of particle i is equal to Nw_i for each i

Multinomial Resampling¹

Definition

Parental indices $a_i \in \{1, \dots, N\}$:

$$(a_i \mid w_{1:N}) \stackrel{iid}{\sim} \text{Categorical}(N, w_{1:N})$$

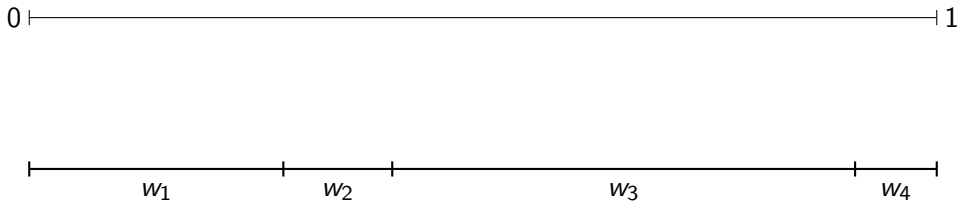
Offspring numbers $v_i \in \{0, \dots, N\}$ such that $\sum v_i = N$:

$$(v_{1:N} \mid w_{1:N}) \sim \text{Multinomial}(1 : N, w_{1:N})$$

¹Efron & Tibshirani (1994) 'An introduction to the bootstrap'

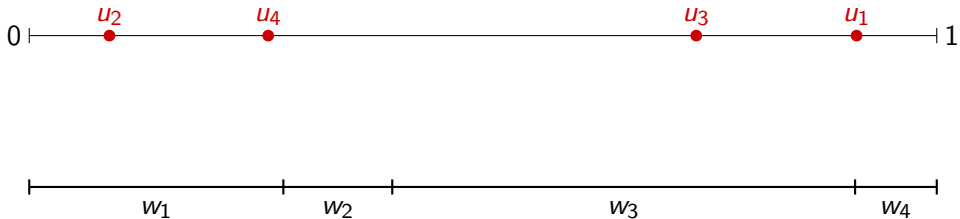
Multinomial Resampling

Inversion Sampling



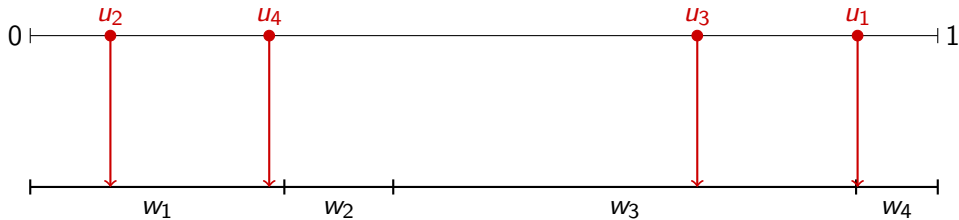
Multinomial Resampling

Inversion Sampling



Multinomial Resampling

Inversion Sampling



Residual Resampling^{2,3}

Definition

1. Deterministically assign $\lfloor Nw_i \rfloor$ offspring to particle i ; $i=1, \dots, N$
2. There are $R := N - \sum_{i=1}^N \lfloor Nw_i \rfloor$ offspring still to be assigned
3. Assign these randomly according to the residual weights $r_i := \frac{1}{R}(Nw_i - \lfloor Nw_i \rfloor)$

²Liu & Chen (1998) 'Sequential Monte Carlo methods for dynamic systems'

³Whitley (1994) 'A genetic algorithm tutorial'

Residual Resampling

Definition


If residuals are assigned using multinomial resampling, offspring counts are distributed

$$v_{1:N} \stackrel{d}{=} \lfloor Nw_{1:N} \rfloor + \text{Multinomial}(R, r_{1:N})$$


Residual Resampling

Illustration

$w_1 = 0.28$ 

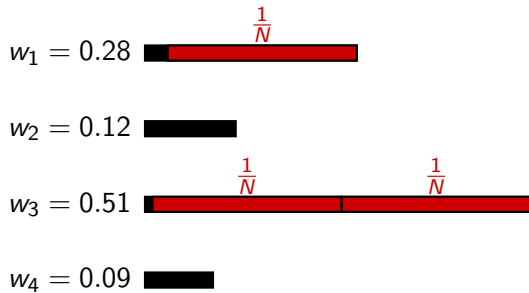
$w_2 = 0.12$ 

$w_3 = 0.51$ 

$w_4 = 0.09$ 

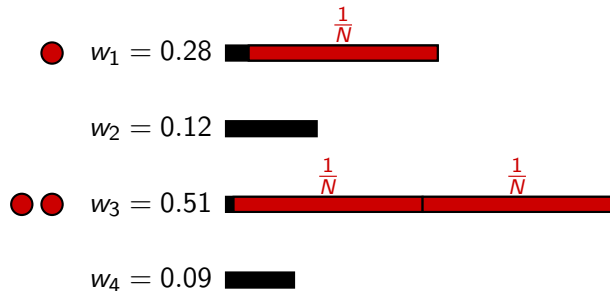
Residual Resampling

Illustration



Residual Resampling

Illustration



Residual Resampling

Illustration

● $r_1 \propto 0.03$ ■


$r_2 \propto 0.12$ ■■■

●● $r_3 \propto 0.01$ ■


$r_4 \propto 0.09$ ■■■

Residual Resampling

Illustration

● $r_1 = 0.12$ 

$r_2 = 0.48$ 

● ● $r_3 = 0.04$ 

$r_4 = 0.36$ 

Stratified Resampling⁴

Definition

Draw uniformly from each stratified interval

$$U_i \sim \text{Uniform} \left(\frac{i-1}{N}, \frac{i}{N} \right); \quad i = 1, \dots, N$$

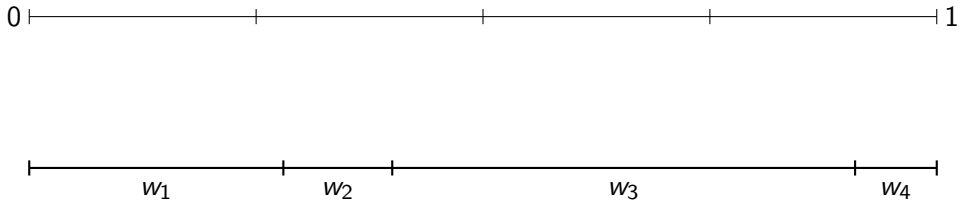
and determine the parental indices by inversion

$$a_i = \inf \left\{ k : \sum_{j=1}^k w_j \geq U_i \right\}$$

⁴Kitagawa (1996) 'Monte Carlo filter and smoother for non-Gaussian nonlinear state space models'

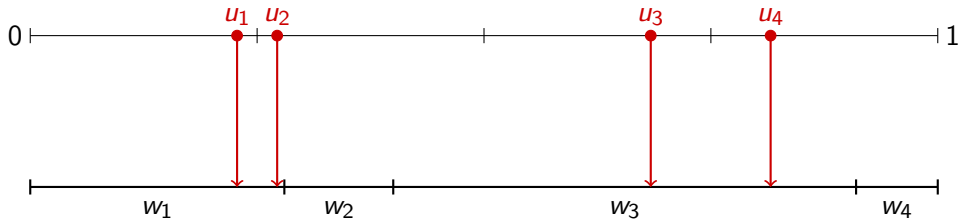
Stratified Resampling

Inversion Sampling



Stratified Resampling

Inversion Sampling



Systematic Resampling^{5,6}

Definition

Draw uniformly from $[0, \frac{1}{N}]$, and add multiples of $\frac{1}{N}$

$$U_1 \sim \text{Uniform} \left(0, \frac{1}{N} \right)$$

$$U_i = U_1 + \frac{i-1}{N}; \quad i = 2, \dots, N$$

and determine the parental indices by inversion

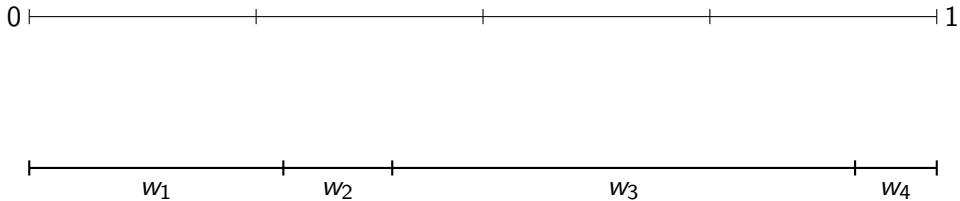
$$a_i = \inf \left\{ k : \sum_{j=1}^k w_j \geq U_i \right\}$$

⁵Carpenter, Clifford & Fearnhead (1999) 'Improved particle filter for nonlinear problems'

⁶Whitley (1994) 'A genetic algorithm tutorial'

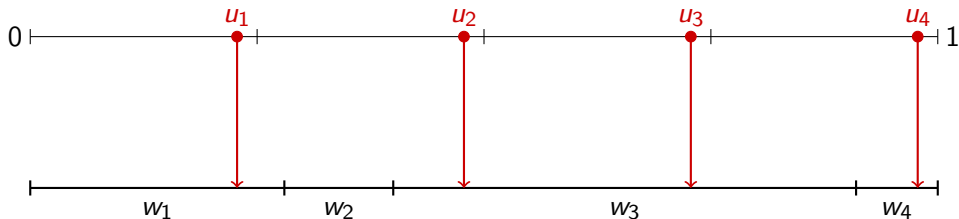
Systematic Resampling

Inversion Sampling



Systematic Resampling

Inversion Sampling



References I