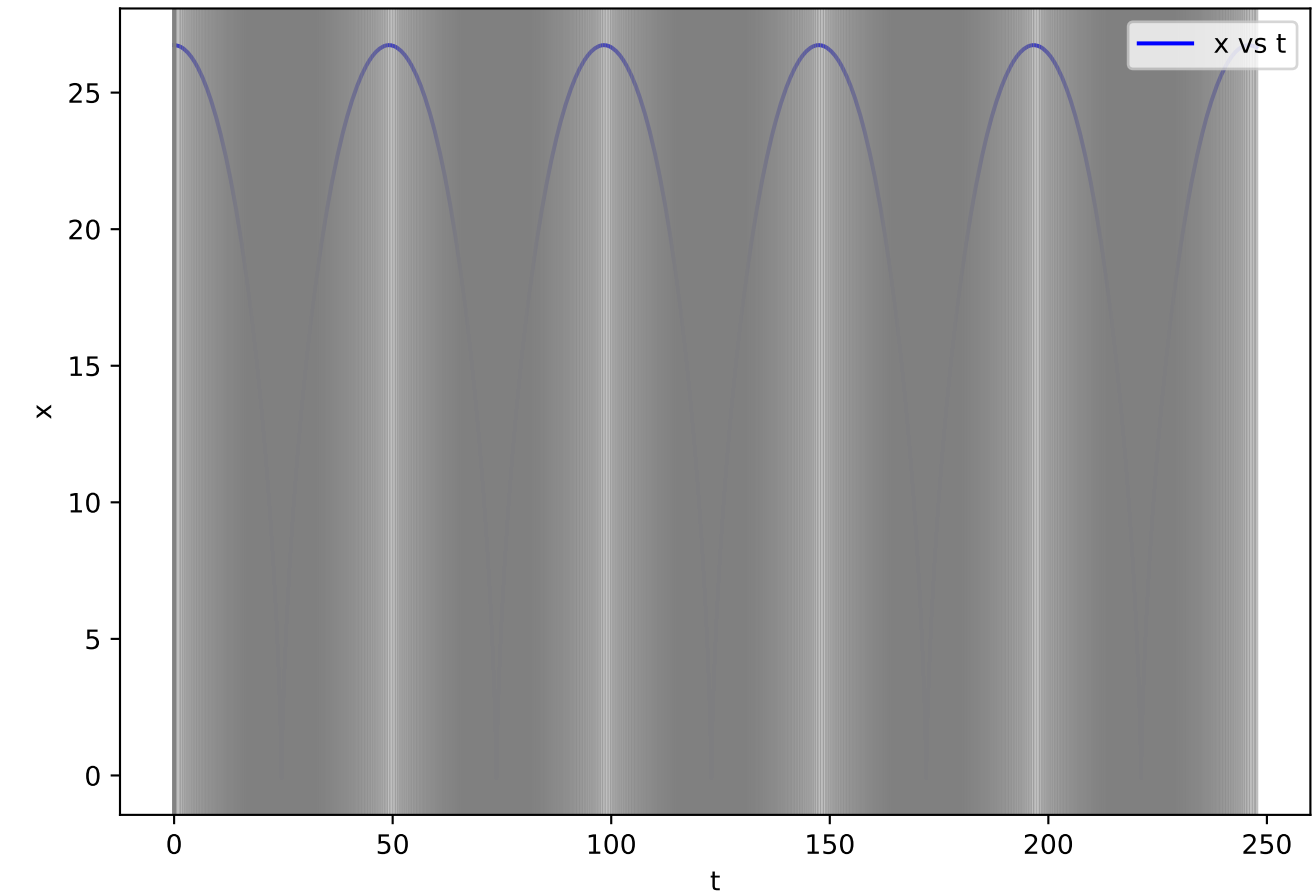


x vs t. Comportamiento paso Δt



y vs t. Comportamiento paso Δt

