



Introduction to Chipmunk

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What's Chipmunk?



What's Chipmunk?

- 2D physics engine written in C
- Cross platform
- Two main editions:
 - ▶ Chipmunk (vanilla C version, free)
 - ▶ **Chipmunk Pro (C, Obj-C, more features, not free)**
- Hundreds of games shipped
- Written by Scott Lembcke, a very smart guy

We will use Chipmunk Pro Trial in this course.



Lots of cool features!

Sleeping objects

Fast collision
detection

Fast impulse
solver

Flexible collision
filtering system

Many language
bindings (Obj-
C, Python,
Ruby, C++, ...)

Circle, convex
polygon, beveled line
segment collision
primitives

Lightweight and
no
dependencies

Well
documented

Raycasting

Optimized for
mobile devices

Joints



Chipmunk Basics

Four basic object types:

- **Rigid bodies**
 - ▶ Hold physical properties (mass, position, rotation, etc...)
 - ▶ Don't have a shape until one is attached to them
 - ▶ Better if 1:1 pixel/unit correlation with sprites
- **Collision shapes**
 - ▶ Circles, polygons, lines
 - ▶ One body can have many shapes
 - ▶ Hold surface properties (friction, elasticity, etc...)
- **Constraints/joints**
- **Spaces**
 - ▶ Containers for simulated objects
 - ▶ Bodies, shapes and joints must be added to a space
 - ▶ Control the whole simulation

Rigid bodies

ChipmunkBody / cpBody

- Static and non-static
- Properties:
 - ▶ Mass
 - ▶ Moment of inertia
 - ▶ Center of gravity
 - ▶ Linear velocity
 - ▶ Applied force
 - ▶ Rotation
 - ▶ Angular velocity
 - ▶ Applied torque
 - ▶ Data pointer
- Forces and impulses
- Bodies can sleep
- Don't modify a body's position directly!



Shapes

ChipmunkShape / cpShape

- Three types:
 - ▶ Circle (fastest and simplest)
 - ▶ Line segment (mainly for static bodies)
 - ▶ Convex polygon (slowest, most flexible)
- Properties:
 - ▶ Body it is attached to
 - ▶ Space it is contained in
 - ▶ Sensor
 - ▶ Elasticity
 - ▶ Friction
 - ▶ Group
 - ▶ Layer
 - ▶ Data pointer
- Need to be attached to a body
- Need to be added to a space
- Shapes on the same body don't generate collisions



Spaces

ChipmunkSpace / cpSpace

- Must be “stepped”
- **Always step by a CONSTANT DELTA**
- Accuracy can be tweaked by setting the number of iterations
- Properties:
 - ▶ Iterations
 - ▶ Global gravity
 - ▶ Global damping
 - ▶ Data pointer
 - ▶ Other advanced properties
- Offers API to add/remove bodies/shapes/constraints
- Uses delegation pattern for handling collisions



Collision detection

- Collisions are detected and resolved during a step
- Application provides collision handlers
- Four handlers:
 - ▶ “begin” - called when two shapes just started touching for the first time in this step; collision can be marked as ignored by returning false
 - ▶ “preSolve” - called while two shapes are touching; collision values can be modified on the fly
 - ▶ “postSolve” - called after a collision response has been processed; good to retrieve resulting forces
 - ▶ “separate” - called when two shapes just stopped touching



Tying it all together

- Use a 1:1 conversion between pixels and Chipmunk's units
- Step with a constant delta; step multiple times within a single frame if the frame delta is too big
- Use the CCPhysicsSprite class from Cocos2D for physics based sprites
- Be careful when removing bodies and shapes from a space:
 - ▶ Don't do it in a collision handler
 - ▶ Always remove a body and its shapes at the same time



Autogeometry

- Fantastic feature only available in Chipmunk Pro
- Extracts collision shapes from images (!)
- Extremely fast, it can be done every frame to create deformable/destructable terrain
- Image data can come from a file or in-memory texture



Part I

GOAL:

Make the mountain and the tanks part of the physics simulation

Steps needed:

- Initialize Chipmunk
- Use the Autogeometry feature on the mountain
- Add an invisible floor
- Refactor the Tank class to use Chipmunk
- Implement the “update” method

Part 2

GOAL:

The tanks can shoot!

Steps needed:

- Design and create a Projectile class
- Make the Tank shoot a Projectile
- Implement collision handlers