FII out the hazard snalykis and fisk assessment below. HA-001 should be for the lane depairine varining function as discussed in the lecture. HA-002 should be for the lane keeping assistance function as discussed in the lecture. Then come up with your own situations and hazards for the lane solsteams system. FII in the AH-003 and HA-004 rows.

| Hazard | ID Situa | tional Analysis | | | | | | | Hazard Identification | | | | | Hazardous Event Classification | | | | | | | Determination of ASIL and Safety Goals | | |
|--------|----------|--------------------|-------------------------|-------------------------------|-------------------|-----------------------------|----------------------------|--|---|----------------------------------|---|--|---|---|----------------------------|--|--|-----------------------------|---|--|--|---|--|
| | Opera | ational Mode | Operational Scenario | Environmental Details | Situation Details | Other Details (ontional) | Item Usage (function) | Situation Description | Function | Deviation | Deviation Details | Hazardous Event (resulting effect) | Event Details | Hazardous Event Description | Exposure (of situation) | Rationale (for exposure) | Severity (of notential harm) | Rationale (for severity) | Controllability (of hazardous event) | Rationale (for controllability) | ASIL Determination | Safety Goal | |
| HA-001 | | 3 - Normal driving | | y EN06 - Rain (slippery road) | | | | high speed and correctly used system. | apply an oscillating steering torque to provide the driver with haptic feedback | | The LDW function applies an oscillating torque with very high torque(above limit). | with other vehicle | High haptic feedback can affect driver's ability to steer as intended. The driver could lose control of the vehicle and collide with another vehicle or with road infrastructure. | The LDW function applies too high an oscillating torque to th steering wheel (above limit). | e probability | roads occur quite frequcently but not daily. | S3 - Life-threatening or fatal injuries | | | This hazard is basicly a loss of steering capabilities and thus very difficult to control. No hards on the | | The oscillating steering torque from the lane departure warning function shall be limited. | |
| | | • | Road | EN01 - Normal conditions | | | IU02 - Incorrectly used | druing normal conditions with high speed and an incorrectly used system. | | activated | The LKA is always on an might therefor be treated as a fully autonomous vehicle. | | Usages outside of the intended capabilities of the LKA could lead to vehicle collision as situations it can not handle might occur. | limitation. | probability | function is deemed to be uncommon. | S3 - Life-threatening or fatal injuries | | or uncontrollable | steering wheels makes this situation difficult to control. | | The lane keeping assistance function shall be time limited and additional steering torque shall end after a given time interval so that the driver cannot misuse the system for autonomous driving | |
| HA-003 | | | | y EN01 - Normal conditions | | | | speed and correctly used system. | apply an oscillating steering torque to provide the driver with haptic feedback. | DV19 - Sensor detection is wrong | Incommect time detection - the LDW gives happic feedback in the middle of the time. | | Suprising / amnoying haptic feedback can affect driver's ability to steme as intended. Focus might be placed on deactivating the function. The driver could lose control of the whichis and collide sitth another vehicle or with road infrastructure. | t incorrect lane dection. | probability | highway during normal conditions happers more or less daily for many drivers. | | | | The function is annoying and takes focus from the driving task, but changing the radio station or arswering a call should be of similar difficulty and more than 99% of the drivers can handle that. | В | The LDW shall not active on incorrect lane detections. | |
| HA-004 | OMOS | 3 - Normal driving | OS04 - Highway | y EN01 - Normal conditions | SD02 - High spee | 1 | IU02 - Incorrectly used | Normal driving on a highway during normal conditions with high speed and incorrectly used system. | Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane | | Incorrect lane detection - the LKA starts steering out of the lane. | EV00 - Collision with other vehicle | The LKA steers the vehicle into another lane. | The LKA function makes an incorrect lane dection. | E2 - Low probability | | S3 - Life-threatening or fatal injuries | High speeds | | No hands on the steering wheels makes this situation difficult to control. | В | The LKA shall not active on incorrect lane detections. | |