

$$1) m \ddot{r} = \sum_i F_i$$

$$\Rightarrow m \begin{bmatrix} \ddot{x} \\ \ddot{y} \\ \ddot{z} \end{bmatrix} = \sum_i \begin{bmatrix} F_x \\ F_y \\ F_z \end{bmatrix}$$

$$m \ddot{x} = \sum_i F_{x,i}$$

Einzel part. Wheel:

$$\Rightarrow \begin{bmatrix} \dot{x} \\ \dot{y} \\ 0 \end{bmatrix} \times \begin{bmatrix} 0 \\ 0 \\ B_0 \end{bmatrix} = \begin{bmatrix} B_0 \dot{y} \\ -B_0 \dot{x} \\ 0 \end{bmatrix}$$

$$m \ddot{x} = F_x = q E_x + (q \mathbf{v} \times \mathbf{B})_x$$

$$= -q \frac{\partial V}{\partial x} + q \begin{bmatrix} \dot{x} \\ \dot{y} \\ 0 \end{bmatrix} \times \begin{bmatrix} 0 \\ 0 \\ B_0 \end{bmatrix} \Big|_x$$

$$= -q \left( -\frac{V_0}{d^2} x \right) + q B_0 \dot{y}$$

$$\Rightarrow \ddot{x} - \frac{q B_0}{m} \dot{y} - \frac{q V_0}{m d^2} x = 0$$

$$= \ddot{x} - \omega_0 \dot{y} - \frac{1}{2} \omega_z^2 x = 0$$

$$m \ddot{y} = F_y = q \tilde{E}_y + (q \mathbf{V} \times \mathbf{B})_y$$

$$= -q \frac{\partial V}{\partial y} - q B_0 \dot{x}$$

$$= \frac{q V_0}{d^2} x - q B_0 \dot{x}$$

$$\Rightarrow \ddot{y} + \frac{q B_0}{m} \dot{x} - \frac{q V_0}{m d^2} x = 0$$

$$m \ddot{z} = q \tilde{E}_z = -q \frac{\partial V}{\partial z} = -\frac{4 q V_0}{2 d^2} z$$

$$\Rightarrow \ddot{z} + \omega_z^2 z = 0$$

$$\Rightarrow z = A \cos(\omega_z z) + B \sin(\omega_z z)$$





$$2) \ddot{x} - \omega_0 \dot{y} - \frac{1}{2} \omega_z^2 x +$$

$$i(\ddot{y} + \omega_0 \dot{x} - \frac{1}{2} \omega_z^2 y) = 0$$

$$\Rightarrow \ddot{x} + i \dot{x} + i \omega_0 \dot{x} - \omega_0 \dot{y} -$$

$$\frac{1}{2} \omega_z^2 (x + i y) = 0$$

$$\Rightarrow \ddot{f} + i \omega_0 (\dot{x} + i \dot{y}) - \frac{1}{2} \omega_z^2 f = 0$$

$$\Rightarrow \ddot{f} + i \omega_0 \dot{f} - \frac{1}{2} \omega_z^2 f = 0 \quad \blacksquare$$

$$3) \text{ however } \omega_{\pm} \in \mathbb{R} :$$

$$\Rightarrow \omega_0^2 - 2\omega_z^2 > 0$$

$$\Rightarrow \omega_0^2 > 2\omega_z^2$$

$$\left( \frac{q B_0}{m} \right)^2 > \left( \frac{2q V_0}{m d^2} \right)$$

$$\Rightarrow \frac{q}{m} B_0^2 > \frac{4 V_0}{d^2} \quad \blacksquare$$

$$4) f(t) = A_+ (\cos \omega_+ t + i \sin \omega_+ t) \\ + A_- (\cos \omega_- t + i \sin \omega_- t)$$

$$x(t) = \operatorname{Re}(f(t)) \\ = A_+ \cos \omega_+ t + A_- \cos \omega_- t$$

$$y(t) = \operatorname{Im}(f(t)) \\ = A_+ \sin \omega_+ t + A_- \sin \omega_- t$$

vi får altså max når  
disse er i samme fase:

$$R_+ = A_+ + A_-$$

og min når disse er i  
mot fase:

$$R_- = |A_+ + A_-|$$

$$5) x(0) = \operatorname{Re}(f(0)) = A_+ + A_- = x_0$$



$$y(0) = \text{Im}(f(0)) = 0$$

$$\begin{aligned} \dot{f} &= \frac{d}{dt} \left[ A_+ e^{-i\omega_+ t} + A_- e^{-i\omega_- t} \right] \\ &= -A_+ i\omega_+ e^{-i\omega_+ t} - A_- i\omega_- e^{-i\omega_- t} \end{aligned}$$

$$\begin{aligned} \dot{y} = \text{Im}(\dot{f}) &= -A_+ \omega_+ \cos \omega_+ t \\ &\quad - A_- \omega_- \cos \omega_- t \end{aligned}$$

$$\dot{y}(0) = V_0$$

$$\Rightarrow A_+ \omega_+ - A_- \omega_- = V_0$$

$$\begin{aligned} \dot{x} = \text{Re}(\dot{f}) &= A_+ \omega_+ \sin \omega_+ t \\ &\quad + A_- \omega_- \sin \omega_- t \\ &= 0 \end{aligned}$$

$$X(0) = X_0$$

$$\Rightarrow A_+ + A_- = X_0 \quad (i)$$

$$Y(0) = V_0$$

$$\Rightarrow -A_+ \omega_+ - A_- \omega_- = V_0 \quad (ii)$$

$$(i) \text{ gives } A_- = X_0 - A_+ \quad (iii)$$

Setze (iii) in (ii)

$$\Rightarrow -A_+ \omega_+ - X_0 \omega_- + A_+ \omega_- = V_0$$

$$\Rightarrow A_+ (\omega_- - \omega_+) = V_0 + X_0 \omega_-$$

$$\Rightarrow A_+ = \frac{V_0 + X_0 \omega_-}{\omega_- - \omega_+} \quad (iv)$$

Setze (iv) in (iii)

$$\Rightarrow A_- = X_0 - \frac{V_0 + X_0 \omega_-}{\omega_- - \omega_+}$$



$$= \frac{X_0(\omega_- - \omega_+) - V_0 - X_0 \omega_-}{\omega_- - \omega_+}$$

$$= \frac{-X_0 \omega_+ - V_0}{\omega_- - \omega_+}$$

$$= - \frac{V_0 + X_0 \omega_+}{\omega_- - \omega_+}$$

$$z(0) = z_0$$

$$\Rightarrow A \cos \omega_z \theta + B \sin \omega_z \theta$$

$$= z_0$$

$$\Rightarrow A = z_0$$

$$\dot{z} = \omega_z (-z_0 \sin \omega_z t + B \cos \omega_z t)$$

$$\dot{z}(0) = \omega_z (-z_0 \sin \omega_z \cdot 0 + B \cos \omega_z \theta)$$

$$= \omega_z B = 0$$

$$\Rightarrow \beta = 0$$

$$\Rightarrow \underline{\underline{z(t) = z_0 \cos(\omega_z t)}}$$