Problem 5

October 22, 2019

1 Problem 5: Universal Approximators: Depth Vs. Width

Computational Hardware details: 4 vCPUs, 15 GB RAM, NVIDIA Tesla P100 x 2 GPUs.

```
[1]: import numpy as np
from math import sin,sqrt
from sklearn.model_selection import train_test_split
import time

from keras.models import Sequential
from keras.layers import Dense, BatchNormalization
from keras.optimizers import SGD as SGD
from keras import regularizers

import matplotlib.pyplot as plt
```

```
Using TensorFlow backend.
/usr/local/lib/python3.5/dist-
packages/tensorflow/python/framework/dtypes.py:516: FutureWarning: Passing
(type, 1) or '1type' as a synonym of type is deprecated; in a future version of
numpy, it will be understood as (type, (1,)) / '(1,)type'.
  _np_qint8 = np.dtype([("qint8", np.int8, 1)])
/usr/local/lib/python3.5/dist-
packages/tensorflow/python/framework/dtypes.py:517: FutureWarning: Passing
(type, 1) or '1type' as a synonym of type is deprecated; in a future version of
numpy, it will be understood as (type, (1,)) / '(1,)type'.
  _np_quint8 = np.dtype([("quint8", np.uint8, 1)])
/usr/local/lib/python3.5/dist-
packages/tensorflow/python/framework/dtypes.py:518: FutureWarning: Passing
(type, 1) or '1type' as a synonym of type is deprecated; in a future version of
numpy, it will be understood as (type, (1,)) / '(1,)type'.
  _np_qint16 = np.dtype([("qint16", np.int16, 1)])
/usr/local/lib/python3.5/dist-
packages/tensorflow/python/framework/dtypes.py:519: FutureWarning: Passing
(type, 1) or '1type' as a synonym of type is deprecated; in a future version of
numpy, it will be understood as (type, (1,)) / '(1,)type'.
  _np_quint16 = np.dtype([("quint16", np.uint16, 1)])
/usr/local/lib/python3.5/dist-
```

```
packages/tensorflow/python/framework/dtypes.py:520: FutureWarning: Passing
   (type, 1) or '1type' as a synonym of type is deprecated; in a future version of
   numpy, it will be understood as (type, (1,)) / '(1,)type'.
     _np_qint32 = np.dtype([("qint32", np.int32, 1)])
   /usr/local/lib/python3.5/dist-
   packages/tensorflow/python/framework/dtypes.py:525: FutureWarning: Passing
   (type, 1) or '1type' as a synonym of type is deprecated; in a future version of
   numpy, it will be understood as (type, (1,)) / '(1,)type'.
     np_resource = np.dtype([("resource", np.ubyte, 1)])
   /usr/local/lib/python3.5/dist-
   packages/tensorboard/compat/tensorflow_stub/dtypes.py:541: FutureWarning:
   Passing (type, 1) or '1type' as a synonym of type is deprecated; in a future
   version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
     _np_qint8 = np.dtype([("qint8", np.int8, 1)])
   /usr/local/lib/python3.5/dist-
   packages/tensorboard/compat/tensorflow_stub/dtypes.py:542: FutureWarning:
   Passing (type, 1) or '1type' as a synonym of type is deprecated; in a future
   version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
     _np_quint8 = np.dtype([("quint8", np.uint8, 1)])
   /usr/local/lib/python3.5/dist-
   packages/tensorboard/compat/tensorflow_stub/dtypes.py:543: FutureWarning:
   Passing (type, 1) or '1type' as a synonym of type is deprecated; in a future
   version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
     _np_qint16 = np.dtype([("qint16", np.int16, 1)])
   /usr/local/lib/python3.5/dist-
   packages/tensorboard/compat/tensorflow_stub/dtypes.py:544: FutureWarning:
   Passing (type, 1) or '1type' as a synonym of type is deprecated; in a future
   version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
     _np_quint16 = np.dtype([("quint16", np.uint16, 1)])
   /usr/local/lib/python3.5/dist-
   packages/tensorboard/compat/tensorflow_stub/dtypes.py:545: FutureWarning:
   Passing (type, 1) or '1type' as a synonym of type is deprecated; in a future
   version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
     _np_qint32 = np.dtype([("qint32", np.int32, 1)])
   /usr/local/lib/python3.5/dist-
   packages/tensorboard/compat/tensorflow stub/dtypes.py:550: FutureWarning:
   Passing (type, 1) or '1type' as a synonym of type is deprecated; in a future
   version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
     np_resource = np.dtype([("resource", np.ubyte, 1)])
[2]: x = np.random.uniform(-512,512,(100000,2))
   y = np.array([(-xi[0]-47)*sin(sqrt(abs(xi[0]/
     \rightarrow 2 + (xi[1] + 47))) - xi[0] * sin(abs(xi[0] - xi[1] - 47)) for xi in x] + np.random.
    \rightarrownormal(0,0.3,100000)).reshape(100000,1)
[3]: x_train, x_test, y_train, y_test = train_test_split(x,y,train_size=0.8,_
    →random_state=10)
   print(x_train.shape,y_train.shape,x_test.shape,y_test.shape)
```

```
#Normalize input
x_train /= 512
x_test /= 512
```

(80000, 2) (80000, 1) (20000, 2) (20000, 1)

- [4]: SGD(nesterov=True)
- [4]: <keras.optimizers.SGD at 0x7ff43e3d6b38>

```
[5]: #Single layer models
    t_1 = []
    metrics_1 = []
    model = Sequential()
    model.add(Dense(32, input dim=2, activation='relu',__
     →kernel initializer='random uniform'))
   model.add(Dense(1, activation='linear'))
    model.compile(optimizer='SGD', loss='mean_squared_error')
    print("training model")
    start = time.time()
    model.fit(x_train, y_train, epochs=2000, batch_size=1000, verbose=0)
    ttaken = time.time()-start
    t_1.append(ttaken)
    metrics_1.append(model.evaluate(x_test,y_test))
    print("model 1 done")
    model = Sequential()
    model.add(Dense(64, input dim=2, activation='relu',__
     →kernel initializer='random uniform'))
    model.add(Dense(1, activation='linear'))
    model.compile(optimizer='SGD', loss='mean_squared_error')
    print("training model")
    start = time.time()
    model.fit(x_train, y_train, epochs=2000, batch_size=1000, verbose=0)
    ttaken = time.time()-start
    t 1.append(ttaken)
    metrics_1.append(model.evaluate(x_test,y_test))
    print("model 1 done")
    model = Sequential()
    model.add(Dense(128, input_dim=2, activation='relu', __
     →kernel_initializer='random_uniform'))
    model.add(Dense(1, activation='linear'))
    model.compile(optimizer='SGD', loss='mean_squared_error')
    print("training model")
    start = time.time()
```

```
model.fit(x_train, y_train, epochs=2000, batch_size=1000, verbose=0)
ttaken = time.time()-start
t_1.append(ttaken)
metrics_1.append(model.evaluate(x_test,y_test))
model = Sequential()
model.add(Dense(256, input_dim=2, activation='relu',_

→kernel_initializer='random_uniform'))
model.add(Dense(1, activation='linear'))
model.compile(optimizer='SGD', loss='mean_squared_error')
print("training model")
start = time.time()
model.fit(x_train, y_train, epochs=2000, batch_size=1000, verbose=0)
ttaken = time.time()-start
t_1.append(ttaken)
metrics_1.append(model.evaluate(x_test,y_test))
model = Sequential()
model.add(Dense(512, input_dim=2, activation='relu', __
 →kernel_initializer='random_uniform'))
model.add(Dense(1, activation='linear'))
model.compile(optimizer='SGD', loss='mean_squared_error')
print("training model")
start = time.time()
model.fit(x_train, y_train, epochs=2000, batch_size=1000, verbose=0)
ttaken = time.time()-start
t 1.append(ttaken)
metrics_1.append(model.evaluate(x_test,y_test))
training model
WARNING:tensorflow:From /usr/local/lib/python3.5/dist-
packages/keras/backend/tensorflow_backend.py:422: The name tf.global_variables
is deprecated. Please use tf.compat.v1.global_variables instead.
20000/20000 [========= ] - 1s 33us/step
model 1 done
training model
20000/20000 [======== ] - 1s 34us/step
model 1 done
training model
20000/20000 [=========== ] - 1s 34us/step
training model
20000/20000 [=========== ] - 1s 35us/step
training model
20000/20000 [=========== ] - 1s 35us/step
```

```
[7]: print("Metrics for layer 1: ",metrics_1)
print("Time taken for layers 1: ",t_1)
```

Metrics for layer 1: [88273.018634375, 88272.895859375, 88272.5790875, 88048.9421625, 88018.190434375]
Time taken for layers 1: [370.7395372390747, 363.43489813804626, 363.1855764389038, 363.3981685638428, 366.1117813587189]

```
[8]: #Double Layer Models
   t_2 = []
   metrics_2 = []
   model = Sequential()
   model.add(Dense(128, input_dim=2, activation='relu', u
    →kernel_initializer='zeros', use_bias=False))
   model.add(BatchNormalization())
   model.add(Dense(128, activation='relu',kernel_initializer='zeros',u
    →use_bias=False))
   model.add(BatchNormalization())
   model.add(Dense(1, activation='linear', use_bias=False))
   model.compile(optimizer='SGD', loss='mean_squared_error')
   print("training model")
   start = time.time()
   model.fit(x_train, y_train, epochs=2000, batch_size = 1000, verbose=0)
   ttaken = time.time()-start
   t 2.append(ttaken)
   metrics_2.append(model.evaluate(x_test,y_test))
   model = Sequential()
   model.add(Dense(32, input_dim=2, activation='relu', kernel_initializer='zeros', __

use_bias=False))
   model.add(BatchNormalization())
   model.add(Dense(256, activation='relu',kernel_initializer='zeros',_
    →use bias=False))
   model.add(BatchNormalization())
   model.add(Dense(1, activation='linear', use_bias=False))
   model.compile(optimizer='SGD', loss='mean_squared_error')
   print("training model")
   start = time.time()
   model.fit(x_train, y_train, epochs=2000, batch size = 1000, verbose=0)
   ttaken = time.time()-start
   t_2.append(ttaken)
   metrics_2.append(model.evaluate(x_test,y_test))
   model = Sequential()
```

```
model.add(Dense(64, input_dim=2, activation='relu', kernel_initializer='zeros', u
 →use_bias=False))
model.add(BatchNormalization())
model.add(Dense(256, activation='relu', kernel initializer='zeros',
 →use bias=False))
model.add(BatchNormalization())
model.add(Dense(1, activation='linear', use_bias=False))
model.compile(optimizer='SGD', loss='mean_squared_error')
print("training model")
start = time.time()
model.fit(x_train, y_train, epochs=2000, batch size = 1000, verbose=0)
ttaken = time.time()-start
t 2.append(ttaken)
metrics_2.append(model.evaluate(x_test,y_test))
model = Sequential()
model.add(Dense(128, input_dim=2, activation='relu', __
→kernel_initializer='zeros', use_bias=False))
model.add(BatchNormalization())
model.add(Dense(256, activation='relu',kernel_initializer='zeros',_

use_bias=False))
model.add(BatchNormalization())
model.add(Dense(1, activation='linear', use bias=False))
model.compile(optimizer='SGD', loss='mean_squared_error')
print("training model")
start = time.time()
model.fit(x_train, y_train, epochs=2000, batch size = 1000, verbose=0)
ttaken = time.time()-start
t_2.append(ttaken)
metrics_2.append(model.evaluate(x_test,y_test))
model = Sequential()
model.add(Dense(256, input_dim=2, activation='relu', __
 →kernel_initializer='zeros', use_bias=False))
model.add(BatchNormalization())
model.add(Dense(256, activation='relu',kernel_initializer='zeros',_
→use_bias=False))
model.add(BatchNormalization())
model.add(Dense(1, activation='linear', use_bias=False))
model.compile(optimizer='SGD', loss='mean_squared_error')
print("training model")
start = time.time()
model.fit(x train, y train, epochs=2000, batch size = 1000, verbose=0)
ttaken = time.time()-start
t 2.append(ttaken)
metrics_2.append(model.evaluate(x_test,y_test))
```

```
training model
    20000/20000 [========= ] - 1s 52us/step
    training model
    20000/20000 [=========== ] - 1s 57us/step
    training model
    20000/20000 [============ ] - 1s 56us/step
    training model
    20000/20000 [============ ] - 1s 59us/step
    training model
    20000/20000 [============ ] - 1s 59us/step
 [9]: print("Metrics for layer 2: ",metrics_2)
    print("Time taken for layers 2: ",t_2)
    Metrics for layer 2: [88287.0532375, 88274.058721875, 88288.43178125,
    88276.85150625, 88275.260884375]
    Time taken for layers 2: [778.1950402259827, 758.079925775528,
    773.7233598232269, 764.1095430850983, 781.5058348178864]
[10]: #Triple Layer Models
    t_3 = []
    metrics_3 = []
    model = Sequential()
    model.add(Dense(32, input_dim=2, activation='relu', kernel_initializer='zeros',u
     →use_bias=False))
    model.add(BatchNormalization())
    model.add(Dense(32, activation='relu', kernel_initializer='zeros', u
     →use_bias=False))
    model.add(BatchNormalization())
    model.add(Dense(256, activation='relu', kernel_initializer='zeros', u
     →use_bias=False))
    model.add(BatchNormalization())
    model.add(Dense(1, activation='linear'))
    model.compile(optimizer='SGD', loss='mean_squared_error')
    print("training model")
    start = time.time()
    model.fit(x_train, y_train, epochs=2000, batch_size=1000, verbose=0)
    ttaken = time.time()-start
    t_3.append(ttaken)
    metrics_3.append(model.evaluate(x_test,y_test))
    model = Sequential()
    model.add(Dense(32, input_dim=2, activation='relu', kernel_initializer='zeros', __
     →use_bias=False))
```

model.add(BatchNormalization())

```
model.add(Dense(64, activation='relu', kernel_initializer='zeros', u
 →use_bias=False))
model.add(BatchNormalization())
model.add(Dense(256, activation='relu', kernel_initializer='zeros', __
 →use_bias=False))
model.add(BatchNormalization())
model.add(Dense(1, activation='linear'))
model.compile(optimizer='SGD', loss='mean_squared_error')
print("training model")
start = time.time()
model.fit(x_train, y_train, epochs=2000, batch_size=1000, verbose=0)
ttaken = time.time()-start
t 3.append(ttaken)
metrics_3.append(model.evaluate(x_test,y_test))
model = Sequential()
model.add(Dense(64, input_dim=2, activation='relu', kernel_initializer='zeros',_
 →use_bias=False))
model.add(BatchNormalization())
model.add(Dense(64, activation='relu', kernel_initializer='zeros',_

use_bias=False))
model.add(BatchNormalization())
model.add(Dense(256, activation='relu', kernel_initializer='zeros',
 →use_bias=False))
model.add(BatchNormalization())
model.add(Dense(1, activation='linear'))
model.compile(optimizer='SGD', loss='mean_squared_error')
print("training model")
start = time.time()
model.fit(x_train, y_train, epochs=2000, batch_size=1000, verbose=0)
ttaken = time.time()-start
#Ignore the error below-due to a wrong variable name (t instead of t 3 in the
 →next cell). It does not affect the source. Network takes too long to train
 →it again (on an average, each model takes close to 30 minutes on 2 NVDIAL
 →P100s):D
training model
```

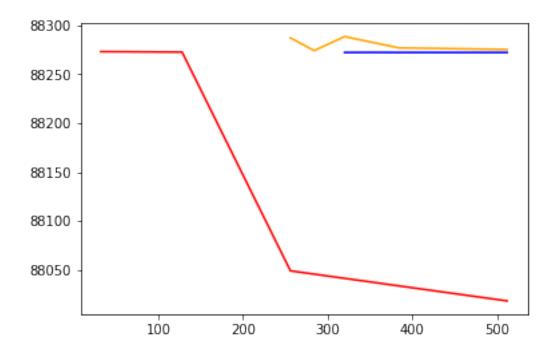
```
training model
20000/20000 [========] - 1s 68us/step
training model
20000/20000 [========] - 1s 72us/step
training model
```

⊔ →------

NameError: name 't' is not defined

```
[11]: t_3.append(ttaken)
     metrics_3.append(model.evaluate(x_test,y_test))
     model = Sequential()
     model.add(Dense(32, input_dim=2, activation='relu', kernel_initializer='zeros', __
      →use bias=False))
     model.add(BatchNormalization())
     model.add(Dense(128, activation='relu', kernel_initializer='zeros', u
      →use_bias=False))
    model.add(BatchNormalization())
     model.add(Dense(256, activation='relu', kernel_initializer='zeros', __
      →use bias=False))
     model.add(BatchNormalization())
     model.add(Dense(1, activation='linear'))
     model.compile(optimizer='SGD', loss='mean_squared_error')
     print("training model")
     start = time.time()
     model.fit(x_train, y_train, epochs=2000, batch_size=1000, verbose=0)
     ttaken = time.time()-start
     t 3.append(ttaken)
     metrics_3.append(model.evaluate(x_test,y_test))
     model = Sequential()
     model.add(Dense(64, input_dim=2, activation='relu', kernel_initializer='zeros', __
     →use_bias=False))
     model.add(BatchNormalization())
     model.add(Dense(128, activation='relu', kernel_initializer='zeros', __
     →use bias=False))
     model.add(BatchNormalization())
     model.add(Dense(256, activation='relu', kernel_initializer='zeros', u
     →use_bias=False))
     model.add(BatchNormalization())
     model.add(Dense(1, activation='linear'))
```

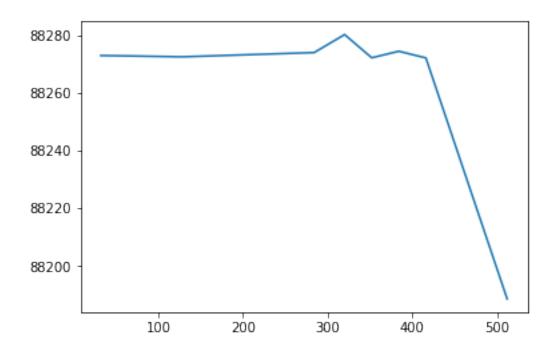
```
model.compile(optimizer='SGD', loss='mean_squared_error')
    print("training model")
    start = time.time()
    model.fit(x_train, y_train, epochs=2000, batch_size=1000, verbose=0)
    ttaken = time.time()-start
    t_3.append(ttaken)
    metrics_3.append(model.evaluate(x_test,y_test))
    20000/20000 [========= ] - 2s 77us/step
    training model
    20000/20000 [========== ] - 2s 76us/step
    training model
    20000/20000 [========
                                  ======== ] - 2s 83us/step
[14]: print("Metrics for layer 3: ",metrics_3)
    print("Time taken for layers 3: ",t_3)
    Metrics for layer 3: [88272.1808375, 88272.254046875, 88272.182946875,
    88272.196721875, 88272.183859375]
    Time taken for layers 3: [1003.4113006591797, 987.1585192680359,
    1003.2690584659576, 1016.3088991641998, 1017.4656870365143]
[15]: nhu_1 = [32,64,128,256,512]
    nhu_2 = [256, 284, 320, 384, 512]
    nhu_3 = [320, 352, 384, 416, 512]
[16]: #Plot #Layers vs RMSE
    plt.plot(nhu_1,metrics_1,color='red')
    plt.plot(nhu_2,metrics_2,color='orange')
    plt.plot(nhu_3,metrics_3,color='blue')
    plt.show()
```



1.1 RMSE vs No. of Layers:

We can see in the above graph that the RMSE is the least when we use a single, shallow layer of 512 hidden units over a deep, 3-layer network. This result is counterintuitive- although we expect deeper networks to learn more features and perform better, this looks like deep the deep network overfits the training data, and hence performs poorly on the test set. An interesting observation: The RMSE for a three layer network is more or less the same irrespective of the number of nodes used in each layer.

1.2 RMSE vs number of hidden units



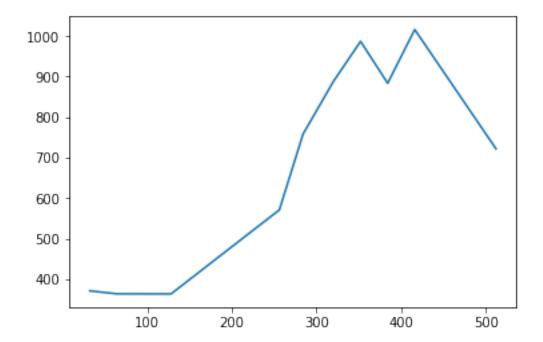
1.3 Numer of parameters vs Training Time:

```
[24]: x_t = [32,64,128,256,284,320,352,384,416,512]

y_t = t_1[0:3] + [(t_1[3]+t_2[0])/2] + [t_2[1]] + [(t_2[2]+t_3[0])/2] + [t_3[1]] + [(t_2[3]+t_3[2])/2] + [t_3[3]] + [(t_1[4]+t_2[4]+t_3[4])/3]
plt.plot(x_t,y_t)
```

[370.7395372390747, 363.43489813804626, 363.1855764389038]

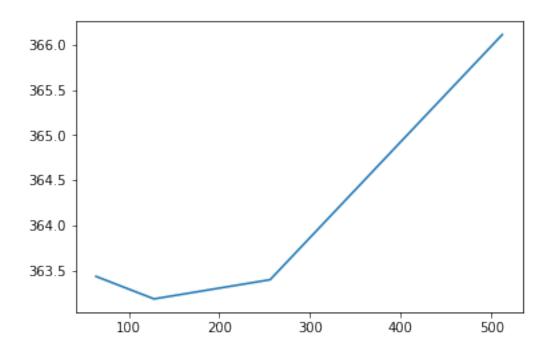
[24]: [<matplotlib.lines.Line2D at 0x7ff358b84f28>]



The above plt on No. of Training Units vs Time is NOT a true reflection of the behaviour as the number of layers in each step vary. Having said that, we can observe that within a lyer, as the number of neurons increases, the training time increases. Eg: the chart below for a single layer neural network:

```
[29]: x_t1 = [64,128,256,512]
plt.plot(x_t1,t_1[1:])
```

[29]: [<matplotlib.lines.Line2D at 0x7ff358a9a780>]



[]: