

1. Introduction

The aging of our society is encouraging an institutional effort towards the early detection of diseases [1]. As checkups and screenings become more common, there is a need for better, less invasive diagnostic methods that reduce the risks and discomfort to the patient.

This is the goal of optical biopsy: a collective name for advanced endomicroscopy methods allowing real-time, *in-situ* diagnosis of tissue malignancies without the need of excision and histopathological analysis. One of the enabling technologies for optical biopsy is optical coherence tomography (OCT), an imaging method which allows the retrieval of depth information of a sample from its backscattered light. Due to its non-invasive nature and long working distance it found its first uses in ophthalmology, but it is currently under research in an expanding variety of endoscopic applications.

The first endoscopic OCT implementations were restricted to side viewing, single modality OCT catheter-endoscopes that sampled the tissue by translating [2] or rotating [3] [4] the probe to acquire *in-vivo* 2D cross sections through the lumen. This scanning method, displacing the entire catheter, resulted in poor dimensional accuracy and speed. This can be solved by performing the scanning within the probe. Earlier works demonstrated this approach using Coherent Fiber Bundles (CFB) to create forward viewing endoscopes, where individual cores in the CFB were scanned sequentially to perform OCT imaging. The advantage of this method is that the scanning mechanism is located outside the body, which allows the endoscope tip to be relatively compact. As a tradeoff, the final image quality acquired with such systems suffer from poor SNR (signal-to-noise ratio) due to the CFBs multi-mode behavior and distinct inter-core coupling [5]. Furthermore, these systems are unsuitable for flexible endoscopes due to the rigidity of CFBs.

A new mechanism, the *image plane fiber scanner* [6], allowed forward-viewing video endoscopes with diameters under 1 mm within thin, flexible catheters. These devices use the concept of mechanical resonance to amplify the subtle movement of a piezoelectric actuator into a large displacement of the tip of an optical fiber oscillating in its first resonant mode. If the tip of the scanner is placed at the image plane of an optical system, as depicted in figure 1, the lateral displacement of the fiber will image the object plane.

Although this scanning method can be extended to OCT [?], the high resonance frequency of the fiber, typically in the range of several kilohertz, make it difficult to sample the spectral information fast enough. Although it is possible to decrease the resonance frequency by using a longer fiber or a weight on its

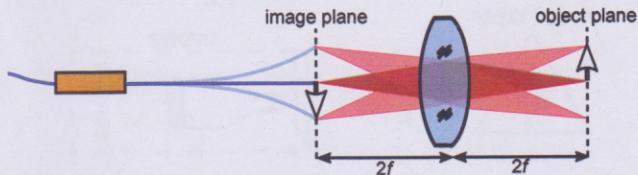


Figure 1. Working principle of the image plane fiber scanner.

tip [7], this approach significantly increases the length of the device.

This work demonstrates a novel topology of fiber scanner which is optimized for OCT, namely the fourier plane fiber scanner. This topology enables shorter OCT endoscopes with higher spatial sampling with shorter rigid tip length. Furthermore, it performs telecentric scanning, which reduces vignetting in the outer areas of the image and avoids distortions in the reconstructed 3D images.

2. Requirements of OCT scanners

The presented probe is optimized for Swept-Source Optical Coherence Tomography (SS-OCT). This type of OCT uses a Michelson interferometer in which the reference arm is fixed while the sample arm illuminates a portion of a sample and collects the backscattered light, as depicted in Figure 2. This light originates from a narrowband laser with the ability to tune its wavenumber.

The optical path difference between each layer of the sample and the reference arm in the interferometer induces a change in the intensity detected by the photodiode. The variation of this intensity versus the wavenumber of the laser creates an interferogram, whose Fourier transformation encodes the reflectivity information a transversal column of the sample, named A-scan. This process can be performed in real time with speeds typically around 100 kHz. By scanning the position of the laser beam in a 1D line, several A-scans can be assembled in a 2D cross section or B-scan. If several B-scans are acquired sequentially by 2D scanning, it is possible to reconstruct a 3D volume of the sample or C-scan.

The requirements of the optical system and the scanner can be pointed out from the previous description:

First, in order to obtain volumetric images, a 2D scanner has to be integrated into the probe. As the temporal sampling of OCT systems is typically constrained, the scanner should displace the focus position slow enough so that the spatial sampling k_{sampling} is at least double than the maximum optical frequency of the system k_{opt} ,

$$k_{\text{sampling}} > 2 k_{\text{opt}}. \quad (1)$$

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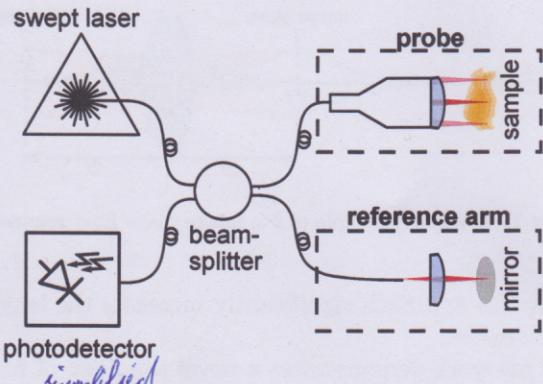


Figure 2. Fiber-based swept-source OCT system. Light originating from a swept-source laser is coupled to a interferometer, where the optical path difference between the sample and the reference arm creates an interferogram which is measured in a photodetector.

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and thus fulfilling the Nyquist criterium.

Second, the depth of field (DoF) of the focused beam should be several millimeters to enable a long penetration depth, usually in the 2-4 mm range. Thus, a low numerical aperture (NA) is preferred, ranging from 0.02 to 0.05.

Further characteristics are also desirable: smaller probe diameters enable their use in new applications, shorter probes enable flexible-tip endoscopes, which can orient the field of view, and telecentric imaging ease the quantitative analysis of the acquired data.

3. Fourier plane fiber scanners

The scanner proposed in this work fulfills the above-mentioned requirements by implementing a Fourier plane fiber scanner (FPFS) topology.

Compared with the image plane fiber scanner, depicted in Figure 1, the FPFS has a GRIN lens glued to the tip of the fiber, significantly reducing the resonance frequency of the vibrating cantilever and also collimating the laser beam. The fiber scanner is then positioned such that the lateral and angular movement of the scanner behaves as the beam angles that can be observed in the collimated region of a classical telecentric $4f$ optical system, as illustrated in Figure 3. As can be observed in this figure, at any point of the oscillation the output beam coming from the GRIN lens points to a fixed virtual radiant source. This is fulfilled if the bending shape of the scanner is linear with the amplitude and thus, the ratio of the GRIN lens angle θ to its vertical displacement y is kept constant $y = d \cdot \tan \theta \simeq d \cdot \theta \Rightarrow \frac{\theta}{y} = \text{const}$.

4. Mechanical design

Fiber scanners use mechanical resonance to amplify the subtle movement of a piezoelectric actuator into a large

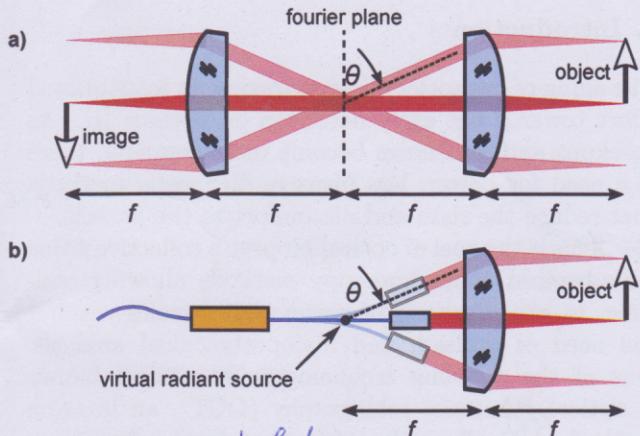


Figure 3. Working principle of the fourier plane fiber scanner. a) Illustration of a classical telecentric system. The height of the object is translated into an angle θ in the collimated region between the two lenses. This angle is again translated into a corresponding image height by the second lens. b) Illustration of the OCT beam path using a fiber scanner in first resonance mode. The movement of the GRIN lens due to the fiber scanner and the distance between the GRIN lens and the focusing lens creating the same optical behavior as it can be observed in a classical telecentric system.

displacement of the tip of an optical fiber (oscillating in its first resonant mode). As in any resonant system, the geometrical and mechanical characteristics of the flexible cantilever of the FPFS fully define its operating frequency range, and with it, constrain the way the object can be imaged. In the following paragraphs the behavior of the fiber scanner is mechanically modeled and this information used to choose the most relevant fabrication parameters leading to a resonant frequency adequate for OCT.

4.1. Piezoelectric tube actuators

A piezoelectric tube is a solid state actuator consisting of a tube made of radially polarized piezoelectric material with inner and outer electrodes. The outer metallization of the tube is divided in four quarter electrodes, which generate a radial electric field in the sandwiched portion of the piezoelectric material. If a voltage difference is applied to two opposite electrodes of the tube, one side will contract while the other will expand due to the piezoelectric effect. This behavior is modeled linearly as $\epsilon = d_{31}E$ [8], where ϵ represents the in-plane strain, d_{31} the piezoelectric strain coefficient, and E the out-of-plane electric field magnitude. This asymmetry creates a bending moment across the axis of the tube, inducing its deformation. If one end of the actuator is kept static, the tip of the actuator will deflect and tilt according to the applied voltage. The deflection of the tip of the tube reacts linearly with the applied voltage, and in case of bipolar operation,

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estimated by [9] as

$$\Delta y = V \frac{2\sqrt{2}d_{31}L^2}{\pi Dh}, \quad (2)$$

where V is the voltage applied to each opposing electrode, d_{31} is the piezoelectric strain coefficient of the material in direction perpendicular to the polarization direction, L is the length of the tube, D its outer diameter and h the thickness of its wall. Thus, longer tubes with a thinner diameter and wall thickness maximize the deflection of the tip. With these requirements, *Physik Instrumente (PI) GmbH* was able to manufacture a piezoelectric tube with 800 µm external diameter, 500 µm internal diameter and 3.7 mm long using *PIC 151* material. The deflection of this actuator is in the order of 20 nm/V.

4.2. Analysis of the resonant beam

The piezoelectric actuator couples mechanical energy into the cantilever of the scanner formed by a optical fiber segment to which a GRIN lens is glued, as depicted in Figure 4a.

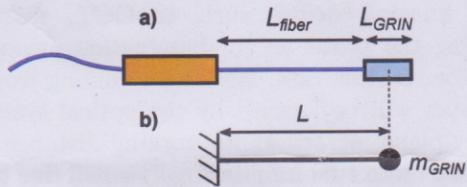


Figure 4. a) Schematic drawing of the piezoelectric scanner, composed of a piezoelectric tube, fiber and GRIN lens. b) Simplified mechanical diagram obtained by modeling the fiber as a weightless cantilever and the GRIN lens as a point mass.

The fiber-GRIN assembly can be modeled as a point-loaded, fixed-free cantilever where the weight of the GRIN lens is concentrated in its center of gravity, as represented in Figure 4b.

Now, by applying the ideal mass-spring harmonic resonator equation, the resonance frequency can be estimated as

$$f_{res} = \frac{1}{2\pi} \sqrt{\frac{K_{cantilever}}{m_{GRIN}}} \quad (3)$$

where $K_{cantilever}$ represents the elastic constant of the fiber cantilever. Considering it as a fixed-free, point loaded cantilever, its spring constant can be calculated as

$$K_{cantilever} = \frac{3EI}{L^3} = \frac{3\pi E_{fiber} r_{fiber}^4}{L^3} \quad (4)$$

following the Euler-Bernoulli theory [10] and considering that the moment of inertia of the cylindrical fiber is given by $I_{fiber} = \frac{\pi}{4}r^4$.

This frequency can be reduced in different ways: increasing the cantilever length L , decreasing the radius of the fiber r_{fiber} or increasing the mass at the

you have a reduction of 62% for a GRIN lens on the tip, regardless of how the lens look like? ; -)

tip m_{GRIN} . First, by having a GRIN lens attached at the tip, the resonance frequency is reduced by a factor of 62% when compared to a bare fiber scanner. Furthermore, by choosing a fiber with a cladding diameter of 80 µm instead of the standard 125 µm, the resonance frequency can be lowered by an extra factor of 60%, as the sensitivity of the resonance frequency to the diameter of the fiber is quadratic.

When selecting the length of the scanner, there are two details to consider. First, the maximum displacement of the 350 µm GRIN lens is limited by the walls of the housing to usually a small deflection. Within that small displacement we want to achieve the maximum angular deflection of the GRIN lens to maximize the FOV. This can be achieved by using shorter fiber lengths, which induces a smaller radius of curvature. This exhibits a trade-off with the density of sampling $k_{sampling}$, which is increased with slower scanning coming from longer fiber. To balance those terms, we chose a total scanner length of 4.5 mm, which results in a resonance frequency of 770 Hz and a maximum angular deflection of 5°.

4.3. COMSOL simulation

In order to validate the theoretical analysis of the previous section, a multiphysics finite element analysis was performed using *COMSOL*. The actuator was modeled as a radially polarized piezoelectric material (*PIC 151*) and the rest of the structure as fused silica. The excitation voltage is a sinusoidal symmetrical potential between the top and bottom electrodes of the tube. Note that, as the system undergoes small deflections, it is simulated assuming linear behavior without incurring in important deviations [11].

As the first step, the resonant frequency of the system is simulated. An *Eigenfrequency* study calculates the first mode resonance at 762 Hz, which closely matches the analytical estimation of 770 Hz. The mode shape at resonance is shown in Figure 5, where it can be observed that the actuator and the base of the fiber are almost static, confirming the resonant behavior of the scanner.

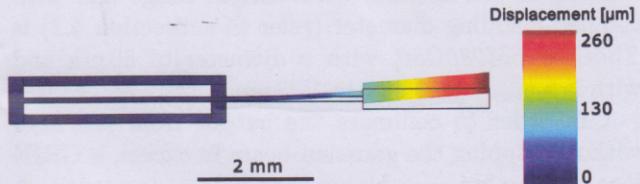


Figure 5. COMSOL simulation showing a cross section of the scanner maximum deflection at resonance for an actuation voltage of ± 75 V. The deformed structure is color coded showing the total displacement from the rest position (shown outlined).

Note that, as the system is working close to

Miniaturized fourier-plane fiber-scanner for OCT endoscopy

resonance, it is challenging to simulate the oscillation amplitude, as it depends on its damping factor which should be obtained experimentally. Thus, for the simulation, this value was chosen to fit the expected deflection.

Let us discuss this on Monday

5. Optical design

5.1. Geometrical optics

In a Fourier plane scanner, the numerical apertures and focal lengths of the scanning and objective lens are related by the diameter of the beam in the intermediate region between both lenses. Thus, based on the schematic of Figure 6, the following geometrical optics

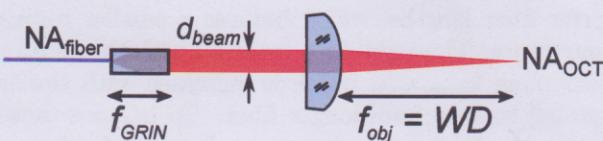


Figure 6. Optical diagram for the scanner at rest position indicating the main parameters.

relations are obtained: $d_{\text{beam}} \approx 2 \cdot f_{\text{GRIN}} \cdot \text{NA}_{\text{fiber}}$ and $d_{\text{beam}} \approx 2 \cdot f_{\text{obj}} \cdot \text{NA}_{\text{OCT}}$. By combining them together,

$$f_{\text{GRIN}} \cdot \text{NA}_{\text{fiber}} = f_{\text{obj}} \cdot \text{NA}_{\text{OCT}} \quad (5)$$

the main design equation for the scanner is obtained. Note that these equations use a small angle approximation valid for small NA: $\tan[\sin^{-1}(\text{NA})] \approx \text{NA}$. In this case, as any NA is smaller than 0.25, the error of this simplification is smaller than 2%.

5.2. Selection of components

The design equations that were obtained in the previous section relate all the optical components together. Therefore, once the desired NA is chosen, there is only one free variable available. In this case, the major constraint is given by the commercial availability of the single mode fiber, so the selection of the rest of the components will follow from it.

The only commercially available single mode fiber working in the necessary wavelength range and with thinned cladding diameter (refer to subsection 4.2) is Thorlabs SM980G80, with a diameter of 80 μm and with $\text{NA}_{\text{fiber}} = 0.18$ at $\lambda = 1.33 \mu\text{m}$.

In order to collimate the output from the fiber without clipping the gaussian beam in excess, a GRIN lens with an NA_{GRIN} higher than NA_{fiber} is needed. A good fit from the GRINTECH catalog is GT-LFRL-035-024-20-CC (1550), with an $\text{NA}_{\text{GRIN}} = 0.20$ and $f_{\text{GRIN}} = 0.91 \text{ mm}$.

Now, by using the relation in Equation 5 we can design $f_{\text{objective}}$ by choosing an adequate NA_{OCT} . To preserve a high depth of field (DOF), allow enough

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space for the beamsplitter and a long working distance, a narrow NA_{OCT} is preferred – in the range of 0.020 – 0.025. By choosing an intermediate NA_{OCT} of 0.022, the focal length of the objective lens ~~can be selected~~ by

$$f_{\text{obj}} = f_{\text{GRIN}} \frac{\text{NA}_{\text{fiber}}}{\text{NA}_{\text{OCT}}} = 0.91 \text{ mm} \frac{0.18}{0.022} = 7.5 \text{ mm.} \quad (6)$$

~~can be selected. The manufacturing of this lens was performed by Optik+ with a plano-convex spherical geometry.~~

The field of view (FOV) can be now calculated considering the maximum angular deflection of the GRIN lens in the tip of the scanning fiber by

$$h_{\max} = f_{\text{obj}} \cdot \tan \theta_{\max} = 7.5 \text{ mm} \cdot \tan 5^\circ = 0.66 \text{ mm,} \quad (7)$$

equivalent to a FOV of 1.2 mm for a θ_{\max} of $\pm 5^\circ$, as calculated in section subsection 4.2.

5.3. Analysis of the lateral resolution

Once the components and NA ~~is~~ chosen, it is of particular interest to calculate the expected lateral resolution of such a system.

To understand the optical modeling of a laser scanned imaging device such as OCT, we begin considering the probe as an illumination device, i.e. a projector. In this case, laser light coming from the optical fiber will be focused by the optical system in an object plane located at its working distance. The focused spot won't be infinitesimally small due to two reasons: first, as in any optical system, diffraction takes place and blurs it with its $\text{PSF}_{\text{optics}}(\mathbf{r})$, defined by the NA and the wavelength of the focused beam. Furthermore, the gaussian intensity distribution at the core of the fiber has a certain extent, characterized by its Mode Field Diameter (MFD). Once projected in the image plane, the MFD will be magnified by the optical system by a factor of $1/M$, where M is the magnification of the beam defined as $f_{\text{fiber}}/f_{\text{objective}}$. This gaussian spot can be conceptually considered as the PSF due to the extended core of a fiber PSF_{core} .

Thus, the projected spot, ~~whose~~ distribution is determined by the extended source of the fiber and the magnification and diffraction of the optical system, can be considered as the illumination PSF, calculated by convolution as

$$\text{PSF}_{\text{ill}}(\mathbf{r}) = \text{PSF}_{\text{core}}(\mathbf{r}M) * \text{PSF}_{\text{optics}}(\mathbf{r}) \quad (8)$$

or equivalently, the illumination MTF

$$\text{MTF}_{\text{ill}}(\mathbf{k}) = \text{MTF}_{\text{core}}(\mathbf{k}/M) \cdot \text{MTF}_{\text{optics}}(\mathbf{k}) \quad (9)$$

following the PSF-MTF relationship. This behavior can be observed in Figure 7a, where MTF_{core} and $\text{MTF}_{\text{optics}}$ are simulated according to the design values of this work.

The next step considers the detection or collection of the backscattered light. If all the light coming from

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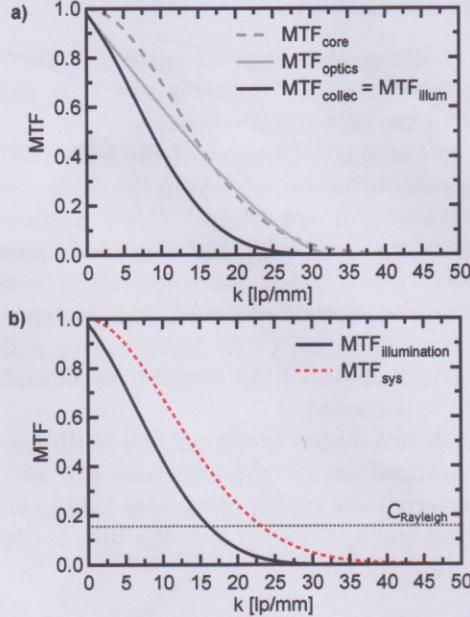


Figure 7. a) Simulated MTF of the illumination or collection of a single point using the proposed optical system. The MTF is limited by the finite size of the fiber core and the diffraction of the optical system. b) MTF of the imaging system, calculated as the convolution of illumination and detection MTFs. The theoretical resolution of such system according to the Rayleigh contrast $C_{Rayleigh} = 0.152$ [12]) is 23.3 line pairs/mm or 43 μm .

the fiber is projected in the PSF_{ill} , we can use the Helmholtz reciprocity property of light to state that the photons originating within this PSF will be collected by the fiber and detected by the photodiode. Thus, the detection PSF is equivalent to the illumination PSF,

$$PSF_{det}(r) = PSF_{ill}(r) = \quad (10)$$

$$= PSF_{core}(rM) * PSF_{optics}(r) \quad (11)$$

or equivalently,

$$MTF_{det}(k) = MTF_{ill}(k) = \quad (12)$$

$$= MTF_{core}(k/M) \cdot MTF_{optics}(k) \quad (13)$$

Considering now the complete imaging process of a confocal laser scanning microscope, a photon traveling through the fiber is projected inside the PSF_{ill} , with a higher probability of illuminating the focus position. After being scattered by the sample, it has a high probability of being collected by the detector, as it is also in the center of the PSF_{det} . It can be concluded that both PSFs are multiplied together, and thus the complete imaging system PSF given by

$$PSF_{sys}(r) = PSF_{ill}(r) \cdot PSF_{det}(r) \simeq PSF_{det}(r)^2 \quad (14)$$

or equivalently, using the autocorrelation - squaring equivalence between spatial and frequency domain

$$MTF_{sys}(k) = MTF_{ill}(k) * MTF_{det}(k) \simeq \quad (15)$$

$$\simeq AC[MTF_{det}(k)]. \quad (16)$$

These operations are numerically calculated in Figure 7b, leading to a theoretical resolution of 23.3 line pairs/mm or 43 μm .

6. Spiral Scanning

The OCT optical setup samples the object at only a single point. Thus, the focus point has to be 2D-scanned over the surface of the sample to obtain 3D OCT images. When using fiber scanners, the movement of the scanning fiber is constrained to harmonic oscillations within a frequency close to its resonance frequency f_{res} . This requirement limits the possible scanning patterns to harmonic movements close to f_{res} , excluding then raster scanning, which require at least an axis working out of resonance. Then, conventional alternatives are Lissajous [7] and spiral scanning. In order to ease the reconstruction of the image, this work implements the latter.*

The piezoelectric tube, which drives the scanner, has four outer gold electrodes to control the lateral movement of the scanner, as described in subsection 4.1. Two independent voltage sources control the vertical and horizontal movement of the actuator by addressing the corresponding pair of electrodes. If sine and cosine signals of the same frequency f_{drive} are used to drive the scanner, the GRIN lens will oscillate in a circle of constant radius. If now the amplitude of these signals is amplitude modulated with another sinusoidal signal of frequency f_{mod} , the resultant trajectory will be spiral, as illustrated in Figure 8.

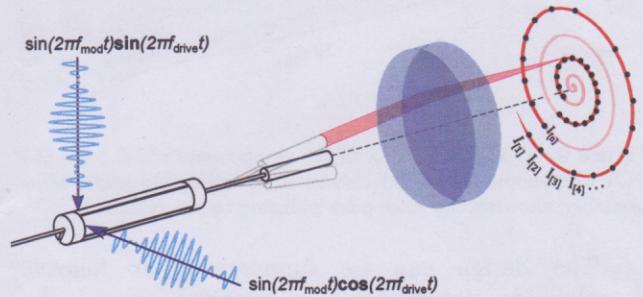


Figure 8. Schematic of the piezoelectric tube, fiber, GRIN and objective lens focusing the OCT beam (red) in a plane. The piezoelectric tube is driven with two independent amplitude modulated sine and cosine signals to generate a spiral pattern, used to acquire an image. The spiral trajectory has two different rings highlighted, where n black dots represent the sampling points of each ring. Notice that in the inner ring the sampling density is higher than in the outer one.

During the full period of the spiral pattern $T_{spiral} = f_{mod}^{-1}$, two complete frames are acquired, one while the spiral grows, another while it shrinks. The whole pattern can be divided in $N_{rings} = f_{drive}/f_{mod}$ individual rings, as depicted in Figure 8. The velocity

* try to avoid sentences like : ... as in this work
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at which the focus spot scans the image

$$v_{\text{spot}} = 2\pi r_{\text{ring}} f_{\text{drive}} \quad (17)$$

depends on the driving frequency f_{drive} and the radius of the ring r_{ring} . In order to fulfill the Nyquist theorem, this speed should be low enough so that the spatial sampling

$$k_{\text{sampling}} = \frac{f_{\text{sampling}}}{v_{\text{spot}}} = \frac{f_{\text{sampling}}}{2\pi r_{\text{ring}} f_{\text{drive}}} > 2 k_{\text{opt}} \quad (18)$$

is at least double the optical bandwidth k_{opt} . For a driving frequency f_{drive} of 770 Hz and a sampling rate f_{sampling} of 100 kHz, the image will be oversampled up to a field of view of 0.89 mm and slightly undersampled outside this area.

7. Fabrication and assembly

This section details the implementation of the probe shown in Figure 9, which serves as a demonstrator of the fiber scanner design and evaluation tool of the optical performance of the OCT beam path.

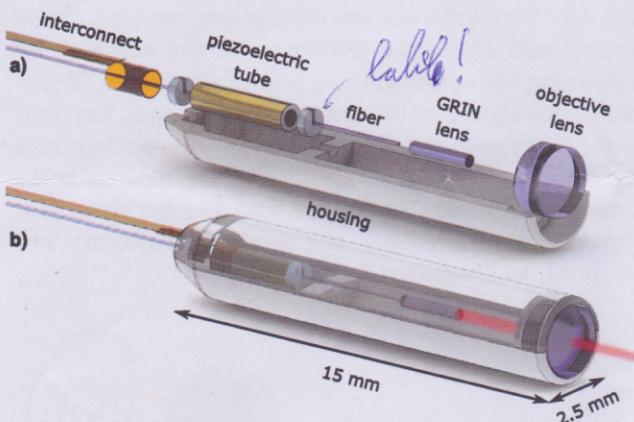


Figure 9. a) Exploded view of the components which form the OCT endoscopic probe. b) Render of the complete probe after assembly, showing the laser path pointing to the sample.

The design can be summarized as follows: A polyimide ribbon cable is wrapped around the piezoelectric actuator to address its electrodes and control the lateral movement of the scanner. A single mode fiber is centered in the piezoelectric tube and the GRIN lens bonded to the tip of this fiber. This arrangement enables a compact fiber scanner with a total length of 9 mm and a resonance frequency of 750 Hz optimized for an OCT system with an A-Scan repetition rate of 100 kHz. The scanner and the objective lens are then assembled in a 3D printed polymer housing.

7.1. Polyimide electrodes

The first challenge that appears in the manufacturing of the scanner lies in contacting the four external electrodes of the piezoelectric tube.

Due to the small diameter of the tube (800 µm), creating a reliable interface between the driving circuit and its electrodes is not trivial. Other piezosensor implementations use soft soldering and insulated copper wires [13–15], but the soldering process can damage the piezoelectric material, as it is exposed to temperatures above its Curie temperature and also increases the diameter of the actuator significantly, as a solder blob is needed.

Instead, this design uses a polyimide ribbon cable, which is wrapped around the piezotube and addresses its four external electrodes using vias. Its geometry, cross section and application over the tube is depicted in Figure 10.

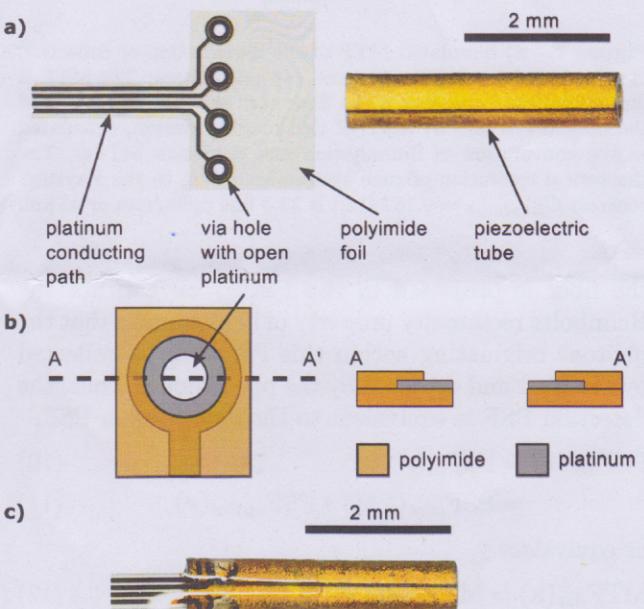


Figure 10. Polyimide electrode design. a) Left: Photo of the polyimide ribbon cable with four vias to contact the four gold electrodes of the piezoelectric tube. Right: Piezoelectric tube. b) Schematic of one via and its cross section. The platinum around the via is partly uncovered to improve the electrical connection between the cable and the piezoelectric tube. c) Photography of a polyimide ribbon cable, wrapped around the piezoelectric tube that is electrically connected through the vias by conductive glue.

The polyimide ribbon cables are manufactured using a cleanroom process summarized in Figure 11. This process is similar to the one developed for cuff electrodes for nerve stimulation [16] and consists of platinum tracks and via holes embedded in a polyimide substrate. One end of the cable is shaped to fit a zero insertion force (ZIF) connector while the other end can

be rolled around the piezoelectric tube, allowing the bonding to its gold electrodes using conductive glue (Araldite 2020 with 80% wt. silver particles).

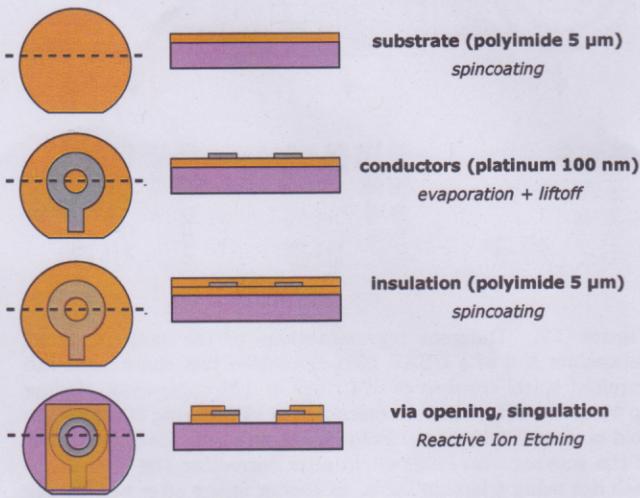


Figure 11. Polyimide electrodes

7.2. Fiber-GRIN bonding

The bonding of a single mode, 80 μm optical fiber to a GRIN lens was performed using a custom silicon microfabricated tool. This method allows a placement accuracy in the μm range, creating an optical and mechanical bond that operates reliably under the high mechanical stress found in a resonant scanner.

Prior OCT setups including GRIN lenses showed that they can cause problematic backreflections due to collimated incidence in the glass-air facet of the fiber. This problem was successfully avoided by a custom GRIN lens design with a 1° tilted exit facet. This solution, together with an special attention to the layout of the optical components, resulted in an optical system with backreflections below 0.02%.

7.3. 3D Printed housing

The scanner and optical components are assembled in a 3D printed polymer structure that also acts as housing. This manufacturing process allows more flexibility and faster design adjustments than conventional machining.

A *B9Creator* stereolithography printer together with a custom acrylic resin achieves a lateral resolution of 30 μm . Although this is a relatively poor resolution, the optical design of the probe allows for relatively high placement tolerances, as the beam is collimated in the region between GRIN lens and objective lens. This way, simple alignment structures which are 3D-printed within the housing allow the proper placement of all components.

7.4. Assembly

Let's talk about this section on Monday

The assembly is performed manually using the multiple alignment features of the housing. The exploded view in Figure 9 shows the placement of the components prior to assembly, followed by the final encapsulation. This process is summarized as follows:

- (i) The GRIN lens is aligned to the end of the fiber inside a micromachined silicon alignment tool and glued using index-matched optical adhesive.
- (ii) The GRIN-fiber assembly is slid through the piezotube and centered with laser cut FR-2 fittings, which are glued to the piezotube using cyanocrylate.
- (iii) The piezotube-fiber-GRIN assembly is placed in the bottom half of the housing and glued in place using cyanocrylate with help of the alignment structures.
- (iv) The planoconvex lens is placed in the bottom half of the housing and glued using UV-curable optical glue.
- (v) The probe is closed with the top half of the housing and sealed with UV-curable glue.

8. Experimental evaluation

8.1. Dynamic behavior of the scanner

The dynamic behavior of the scanner was measured by driving the scanner with a sweeping sinusoidal signal to a pair of electrodes and observing the amplitude of its oscillation using a position sensitive detector (PSD). The result, plotted in Figure 12a, shows the expected resonant behavior, but reveals two different resonant frequencies. This effect can be explained as follows: If a cantilever is rotationally symmetric, it will exhibit a single transversal resonant frequency. In this case, according to linear theory, if the base is excited in only one plane, the fiber will also only vibrate in that plane. But if a cantilever shows a small misalignment or non symmetric cross section – as expected in any real world implementation – it will exhibit two different frequency responses with peaks f_x and f_y , corresponding to two planes of symmetry or eigendirections x, y , as can be seen in the example from Figure 12a. Far away from resonance the difference between axes is minimal. But close to resonance, these nonlinear effects create a cross-plane instability in which excitation of the base of the resonator in the x direction can lead to oscillations in both x and y directions. This effect can be seen in the whirl plots of Figure 12b and was already identified in the first fiber scanner implementations [6].

In order to reduce the imaging distortions caused by whirling, the scanner operates at a working point WP slightly away from the resonance, but with a

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mechanical

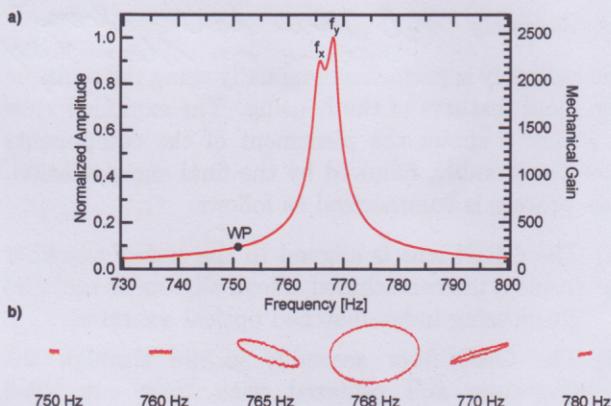


Figure 12. a) Dynamic behavior of the scanner under harmonic excitation. The two eigenfrequencies corresponding to the main axes of the scanner are marked as $f_x = 765.8 \text{ Hz}$ and $f_y = 768.1 \text{ Hz}$. The Working Point WP shows a gain of 220 at 752 Hz. The right axis shows the mechanical gain due to resonance, defined as the ratio of the displacement of the GRIN tip to the displacement of the piezoelectric tube tip. b) Whirl patterns obtained by exciting the scanner in the x direction with different harmonic frequencies while measuring the position of the fiber tip.

gain high enough to achieve the required amplitude of oscillation.

8.2. Laser scanning imaging

It is possible to use the OCT probe and optical system to perform laser scanning imaging (LSI). This 2D imaging modality, analogous to confocal microscopy, is used to assess the lateral resolution and depth of field of the probe. As OCT uses the concept of LSI to recreate volumetric images, these results are also representative for OCT imaging.

LSI is accomplished by coupling light originating from a laser source to the probe through a circulator, which transfers the backscattered light from the sample to a photodetector. While the probe scans an object with a spiral pattern defined by the driving voltage datapoints $(\mathbf{u}_x[n], \mathbf{u}_y[n])$, the data acquisition system (DAQ) samples a stream of intensities at the photodetector $\mathbf{I}[n]$, as shown in Figure 13a. As these signals are generated and acquired synchronously, we expect that the intensity $\mathbf{I}[i]$ corresponds to a point in object space linearly related to the driving voltage of the piezoelectric scanner: $(x, y) = K_{\text{mech}}(\mathbf{u}_x[i], \mathbf{u}_y[i])$, where K_{mech} is a mechanical constant.

If all the datapoints $\mathbf{I}[n]$ acquired during a full spiral are plotted as an intensity-coded dot located at the position $K_{\text{mech}}(\mathbf{u}_x[n], \mathbf{u}_y[n])$, the resultant image would look as in Figure 13a: distorted. Notice how the dot plot defines two overlaid whirling images. This proves that the previous assumption of linearity is not valid, and thus the relationship between $(\mathbf{u}_x[i], \mathbf{u}_y[i])$

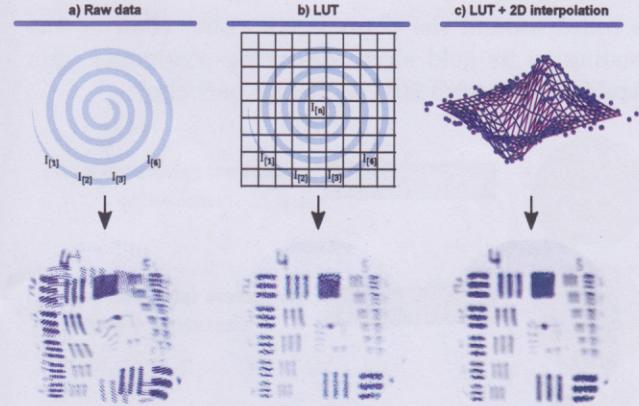


Figure 13. Different representations of the same acquired datapoints $\mathbf{I}[n]$ of a USAF 1951 resolution test chart. The full acquired spiral consists of 374 rings of 122 datapoints, adding up to 45500 datapoints measured at 91 kHz during 500 ms. The field of view is 1.1 mm. a: Point cloud assuming ideal movement of the scanner. b: Point cloud after correcting the position of each dot using a lookup table. c: Raster image after performing a 2D interpolation from the data in d.

and $(x[i], y[i])$ is neither linear nor simple. This is the result of whirling, as discussed in subsection 8.1. There are two general methods to overcome this problem:

The first one involves closed loop operation, where the current position of the scanner is measured inside the probe and used by the plotting system to correct for the distortion [17].

The open loop alternative, used in this work, assumes that the distortion pattern is constant for a given driving signal. Then, the distorted spiral pattern $(x[i], y[i])$ can be measured after the assembly of the probe using a position sensitive device (PSD) and stored as a calibration lookup table. Once this calibration step is performed, any further frame is plotted by assigning a position $(x[i], y[i])$ to every measured intensity $\mathbf{I}[n]$, as depicted in Figure 13b, resulting in a distortionless dot plot. This procedure can be performed in real time. with less distortion

The dot plots which are obtained from spiral scanners have the inconvenient of non-uniform sampling, as can be seen in Figure 13b. Thus, to ease the further processing of the acquired images, it is beneficial to convert the non-uniform dot plot into a cartesian raster image. This can be performed by 2D interpolation, resulting in Figure 13c. by postprocessing

8.3. Lateral resolution measurement

The optical performance of the scanner is qualitatively evaluated by capturing a SLI image of a USAF 1951 resolution test chart with a spiral scanning pattern. As can be seen in Figure 13c, element 4 of group 4 is resolved, indicating a resolution of 22 line pairs/mm or 45 μm .

mark 64E4 in the image

* independent from the scanning speed and pattern

A more robust measurement of the optical resolution can be obtained by manually scanning the focus of the probe over a sharp chromium edge of the test chart, the edge spread function (ESF) is obtained. By performing a spatial derivative followed by a Fourier transform of the ESF, the MTF can be obtained, plotted in Figure 14b. Based on this curve the lateral resolution of the OCT beam path was determined at 21 line pairs/mm or $47.6 \mu\text{m}$. This value shows a good agreement with the theoretical resolution, calculated in subsection 5.3 as 23.3 line pairs/mm or $43 \mu\text{m}$. The 10% deviation between these values can be explained by small misalignments of the optical components induced by the process tolerances of the 3D-printed housing and the assembly process.

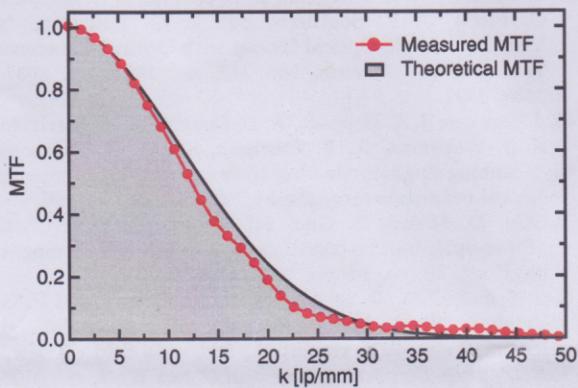


Figure 14. Experimental MTF obtained from the ESF compared with the theoretical limit using the theory from subsection 5.3.

8.4. Depth of field measurement

The depth of field (DOF) of the OCT imaging system can be determined by measuring how much light is backreflected upon a mirror while displacing it along the z axis. The results from this experiment are plotted in Figure 15, where a full width half maximum (FWHM) DOF of 3.5 mm is calculated.

8.5. OCT imaging

The OCT characterization was performed using a swept-source OCT system property of the Medical University Vienna. This system operates with a center wavelength of $1.34 \mu\text{m}$, a bandwidth of 37 nm and a theoretical axial resolution in air of $26.9 \mu\text{m}$.

The first OCT tests were performed as a proof of concept. Circular B-Scans of a colon polyp and a fingertip were captured with the single modality demonstrator, shown in Figure 16.

These preliminary results prove that OCT imaging is possible. But at the same time, the low SNR of

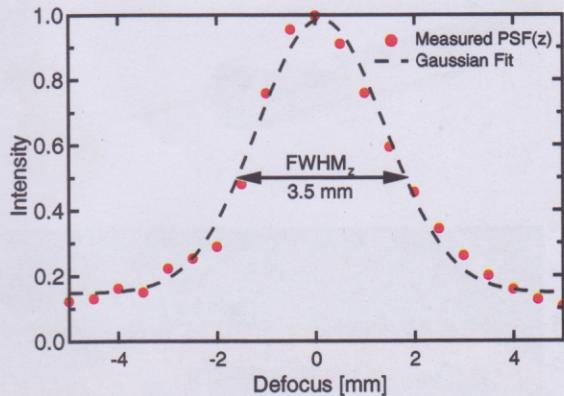


Figure 15. Measurement of the axial resolution of the single modality probe. The intensity of the light coupled back into the optical system after reflection on a mirror is plotted against the manual translation of the mirror by $\pm 4.5 \text{ mm}$ from the focal plane of the probe.

these images indicate that the designed system, which has a NA of 0.022, has problems collecting enough backscattered light. Therefore, future implementations of the probe could benefit from a higher NA. In that case, the resolution and collection of light of the system would be increased at the cost of a shorter working distance and a shorter depth of field.

9. Discussion

* while scanning

10. Conclusion

was

The main goal of this work is the realization of a novel fiber scanner optimized for 3D OCT imaging. The complete scanning engine has an outer diameter of 0.9 mm and a length of 9 mm, and features custom fabricated $10 \mu\text{m}$ thick polyimide flexible interconnect lines to address the four piezoelectric electrodes. This scanning engine was tested in a single modality, demonstrator probe with an external diameter of 2.5 mm and a total length of 15 mm, allowing the OCT imaging of a 1 mm field of view with a resolution of $45 \mu\text{m}$ using 1330 nm light.

To the best of our knowledge, the presented demonstrator probe is also one of the most compact implementation of an OCT microendoscope.

During this project, the behavior of fiber scanners was analyzed and several approaches were discussed and simulated. It was concluded that its implementation as fourier plane scanner using a GRIN lens as collimator and weight was optimal for OCT. A complete electro-mechano-optical analysis and simulation followed, allowing the optimization of the system to reach diffraction-limited resolution and a maximized field of view.

Due to the small diameter of the piezoelectric

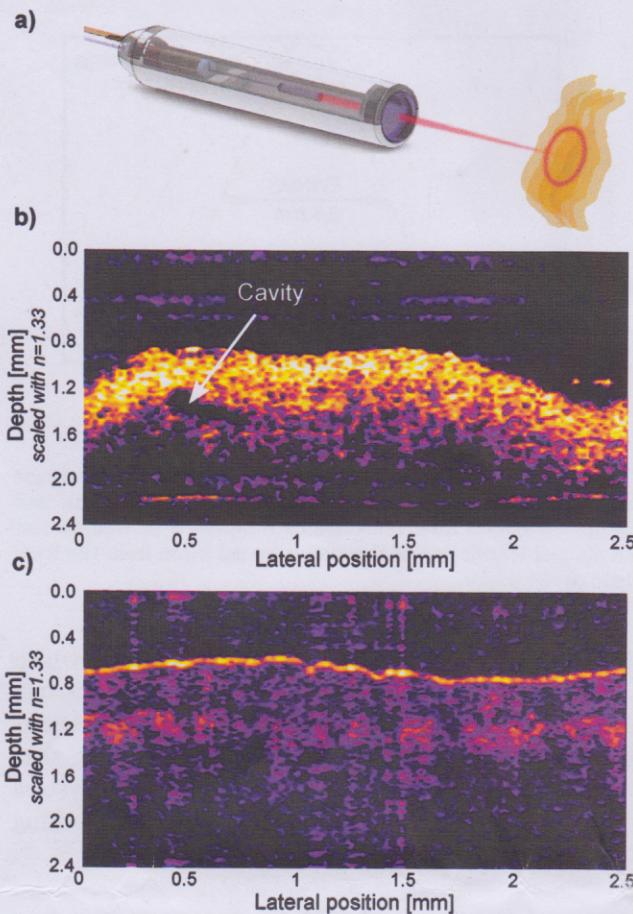


Figure 16. a) Illustration of the measurement arrangement for the circular B-Scan used as a proof of concept of OCT. b) Image of a circular OCT B-Scan of a colon polyp with a diameter $d = 0.8$ mm. Structural changes within the tissue can be detected and at the current state of the investigation the images suggest that blood vessels can be detected. c) Image of a circular OCT B-Scan of a human finger tip, where the epidermis, dermis and hypodermis can be tentatively differentiated.

tube used in the actuation ($800\text{ }\mu\text{m}$), the interface between the driving circuit and its electrodes involved the fabrication of a novel $10\text{ }\mu\text{m}$ thick polyimide ribbon cable that can be rolled around the tube and contacted to it using vias and conductive glue.

The assembly of the demonstrator probe was successfully achieved using alignment features integrated in a 3D-printed housing. This part was manufactured using a commercial, low cost stereolithographic resin printer that enabled quick iterations of the design.

Experimental measurements performed with the manufactured probe helped refining the assumptions used in the analytical calculation of the resolution of OCT systems. The resultant theoretical description, which closely matches experimental results, will help in the design of future OCT and confocal systems. Furthermore, the calibration method used in this work, which can operate in real time, reduces the imaging

*this method isn't
that new*

distortions to a minimum and enables the quantitative analysis of the acquired image. This enabled going one step further in cooperation with the Medical University Vienna, where the OCT imaging concept was proven, creating new opportunities for collaboration.

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