## ASSIGNMENT-3

Importance Sampling estimate of Ep(f(x)) is

$$\hat{\mu}_{q} = \frac{1}{n} \sum_{i=1}^{n} \frac{f(x_i) p(x_i)}{q(x_i)}, \quad x_i \sim q$$

, where q is a probability distribution such that q(x) > 0 whereever  $p(x) \neq 0$ .

$$E_{q}[\hat{u}_{q}] = E_{q} \left[ \frac{1}{n} \sum_{i=1}^{n} \frac{p(x_{i})}{q(x_{i})} f(x_{i}) \right]$$

$$= \frac{1}{n} \sum_{i=1}^{n} E_{q} \left( \frac{p(x_{i})}{p(x_{i})} f(x_{i}) \right)$$

$$= \frac{1}{n} \sum_{i=1}^{n} \int_{1}^{n} \frac{p(x_{i})}{q(x_{i})} dx_{i} dx_{i}$$

$$= \frac{1}{n} \sum_{i=1}^{n} E_{p}[f(x_{i})]$$

$$= E_{p}[f(x_{i})]$$

Blas =  $E_p[f(x)] - E_q[\hat{\omega}_q]$ = 0

Variance => Van, 
$$\left[\frac{1}{n} \sum_{i=1}^{n} \frac{p(x_i)}{q(x_i)} t(x_i)\right]$$
  
=  $\frac{1}{n^2} \left(\text{Van}_{n} \left[\sum_{i=1}^{n} \frac{p(x_i)}{q(x_i)} t(x_i)\right]\right)$   
=  $\frac{1}{n^2} \left(\frac{1}{n^2} \sum_{i=1}^{n} \frac{p(x_i)}{q(x_i)} t(x_i)\right)^{n} - E_{n} \left[\sum_{i=1}^{n} \frac{p(x_i)}{q(x_i)} t(x_i)\right]$   
=  $\frac{1}{n^2} \left(\frac{1}{n^2} \sum_{i=1}^{n} \frac{p(x_i)^{n-1}}{q(x_i)^{n-1}} t(x_i)^{n-1} - E_{n} \left[\frac{1}{n^2} \sum_{i=1}^{n} \frac{p(x_i)^{n-1}}{q(x_i)^{n-1}} t(x_i)\right]$   
=  $\frac{1}{n^2} \left(\frac{1}{n^2} \sum_{i=1}^{n} \frac{p(x_i)^{n-1}}{q(x_i)^{n-1}} t(x_i)^{n-1} - \mu^{n-1} \right)$ 

$$= \frac{1}{n^{2}} \sum_{i=1}^{n} \left( \int \frac{P(x_{i})^{2} f(x_{i})^{2}}{q(x_{i})} dx_{i} - u^{2} \right)$$

$$= \frac{1}{n^{2}} \sum_{i=1}^{n} \left( \int \frac{P(x_{i})^{2} f(x_{i})^{2}}{q(x_{i})} dx_{i} - u^{2} \right)$$

$$= \frac{1}{n^{2}} \sum_{i=1}^{n} \left( \int \frac{P(x_{i})^{2} f(x_{i})^{2}}{q(x_{i})} dx_{i} - u^{2} \right)$$

$$= \frac{1}{n^{2}} \sum_{i=1}^{n} \left( \int \frac{P(x_{i})^{2} f(x_{i})^{2}}{q(x_{i})} - u^{2} \right)$$

$$= \frac{1}{n^{2}} \sum_{i=1}^{n} \left( \int \frac{P(x_{i})^{2} f(x_{i})^{2}}{q(x_{i})} - u^{2} \right)$$

$$= \frac{1}{n^{2}} \sum_{i=1}^{n} \left( \int \frac{P(x_{i})^{2} f(x_{i})^{2}}{q(x_{i})} - u^{2} \right)$$

$$= \frac{1}{n^{2}} \sum_{i=1}^{n} \left( \int \frac{P(x_{i})^{2} f(x_{i})^{2}}{q(x_{i})} - u^{2} \right)$$

02

Since Cutoulative distribution tunction Fx is monotonic we can say =>

$$P(F_{x}^{-1}(U) \leq \pi_{0})$$

$$= P(F_{x}^{-1}(U)) \leq F(\pi_{0})$$

$$= P(E) \leq F_{x}(\pi_{0})$$

$$= P(O \leq U \leq F(\pi_{0}))$$

$$= F(\pi_{0})$$

$$= F(\pi_{0})$$

$$= F(\pi_{0})$$

Hence Fx1(U) has density p

03)

X is sampled from a distribution

U is sampled from U fo, A

Let Z be the sampled Randon variable using the afforing

$$F_{z}(z) = P(z < z) = P\left(x < z \mid U < P(x) \over q(x)\right) = P\left(x < z \cdot U < \frac{P(x)}{q(x)}\right)$$

$$P\left(U < \frac{P(x)}{q(x)}\right)$$

$$P(x < 3, 0 < \frac{b(x)}{d(x)}) = \int_{-\infty}^{\infty} b(x < 3) \cdot U(0 < \frac{b(x)}{d(x)}) \times = x \int_{-\infty}^{\infty} b(x) dx = 1$$

$$= \int_{-\infty}^{\infty} \frac{b(x)}{d(x)} d(x) dx = \int_{-\infty}^{\infty} \frac{b(x)}{d(x)} dx = 1$$

$$= \int_{-\infty}^{\infty} \frac{b(x)}{d(x)} d(x) dx = \int_{-\infty}^{\infty} \frac{b(x)}{d(x)} dx = 1$$

$$= \int_{-\infty}^{\infty} \frac{b(x)}{d(x)} d(x) dx = \int_{-\infty}^{\infty} \frac{b(x)}{d(x)} dx = 1$$

Here Zno

$$p(x) = \frac{p'(x)}{Z}$$
,  $p'(x)$  is unnormalized.

X ng and Un uniform To, kg(x)]

Let Sampled R.V be Z

$$P(\Omega < \tilde{b}(\alpha)) := \int_{-\infty}^{\infty} b(\Omega < \tilde{b}(\alpha) | X = \alpha) d(\alpha) d\alpha = \int_{-\infty}^{\infty} \frac{k d(\alpha)}{k d(\alpha)} d\alpha$$

we wow that - i) \$ \$ (x) du = Z

$$P(U < p(\alpha)) = \frac{Z}{K}$$

$$P_{Z}(z) = P(z < z) = P(x < z | U < \widetilde{P}(x)) = P(x < z, U < \widetilde{P}(x))$$

$$P(U < \widetilde{P}(x))$$

$$P(x < y, U < \beta(x)) = \int_{-\infty}^{\infty} P(x < y, U < \beta(x) | x = x) q(x) du$$

$$= \int_{-\infty}^{\infty} \frac{\beta(x)}{\beta(x)} q(x) du = \int_{-\infty}^{\infty} \frac{\beta(x)}{\beta(x)} dx = \int_{-\infty}^{\infty} \frac{\beta(x)}$$

Thuy Y Mp. 9r means some as drawly samples from p(m)

$$P(x_{j}=\alpha_{i} \mid X_{j}=\alpha_{j}, N=h) = \frac{P(X=\alpha_{j}, N=h)}{P(X=\alpha_{j}, N=h)}$$

$$= \frac{P(X=\alpha_{j}, N=h)}{\sum_{\alpha_{i}} P(X=\alpha_{j}, N=h)}$$

$$= \frac{P(X=\alpha_{j}, N=h)}{\sum_{\alpha_{i}} P(X=\alpha_{j}, N=h)}$$

$$= \frac{P(X=\alpha_{j}, N=h)}{\sum_{\alpha_{i}} P(X=\alpha_{i}, N=h)}$$

$$P(X_{1}=X_{1}|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_{1}=X_{1},|X_$$

#### Gibbs\_RBM

#### April 20, 2017

```
In [40]: import numpy as np

    d,m = 10,20

    x = (np.random.rand(d,1) > 0.5)
    h = (np.random.rand(m,1) > 0.5)
    W = np.random.rand(d,m) - 0.5

    max_iter = 10000
    for i in range(max_iter):
        ph = 1 / (1 + np.exp(-(W.T @ x)))
        h = ph > 0.5
        px = 1 / (1 + np.exp(-(W @ h)))
        x = px > 0.5
```

## MTEL

LSTMs were designed to solve. Printshing gradient problem of Recurrent Neural Networks, because towning long-town dependencies. They combat this using gating mechanism.

Each LSTM Unit consists of

> Input, output and forget gates.

(i) Input Gate: Delines how much of the newly computed state for the convient input we want to let through

(+) Forget gate: Defined how much of the previous state we want to let through

(a) Output Gate: Dethner how much on the Internal state has to be exposed to higher layers and next time step

(9) Candidate Hidden State: Computed based on the current input and previous hidden state.

(a) Internal menory: Combination of previous memory CH multiplied by torget gate and g.

(ht) Hidden state:

# GRUS

GRU has 2 gates

Reset Gate (1): Determine how to combine new Inputs with previous memory.

r = 0 (00+ 1/2 + H+1 Wx)

Update Gate(=): Determines how much of the previous memory to neep arround

== o (02+ h+1W2)

1/29 = tanh (ac U) + (he-107) W) ht = (1-2)09+ 20hb-1

### DIFFERENCE

- 1 GRU has two gard, LSTM has three gard
- That is present in LSTMs.
- @ Input and output gara are coupled by an update gare 24 owner gare? ond is applied directly to the previous hidden stare
- Que Bon't apply second nonlinearity while computy output in GRUS