

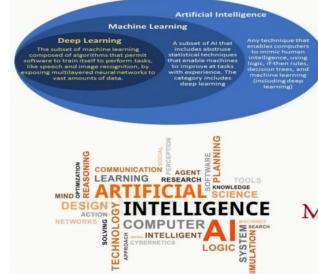
# Motion Analytics & Diabetic Foot Ulcer using Deep Learning Models



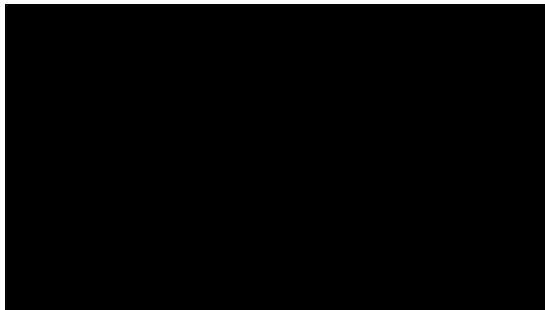
Dr. Chandra Prakash



## AI- ML Terminology



# Artificial Intelligence



# Computational Intelligence and Smart Motion Research (CISM) @SVNIT



## PROJECTS UNDER CISMR

**Project Title:** Computational Techniques based investigation for Diabetic foot ulcers complications (CISMR)  
**Funding Agency:** DST- Science and Engineering Research Board (SERB) under EMEQ scheme, GoI

## Pose Estimation and Human Gait Analysis

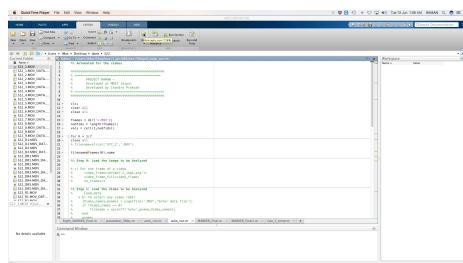
## **Sign Language Interpreter Using machine learning techniques**

## **Emotion Classification Using Human Gait Analysis**

**Prediction of Freezing of Gait in Parkinson's Disease**  
Objective: The aim of the project is to exploring techniques for predicting proactively FOG condition



## Motion Rehabilitation





## Computational Intelligence and Smart Motion Robotics (CISMR)

- 3 D Printer
- Bipedal Robot
- Foot pressure sensor
- IR Camera



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## Projects @ CISMR



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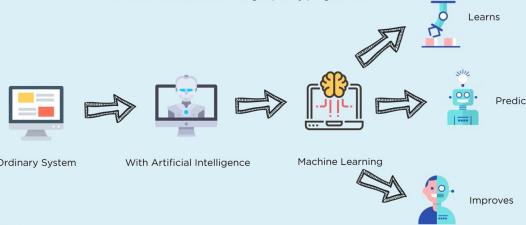
- Let's Deep Dive into Motion analytics and Deep learning models

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## What is Machine learning

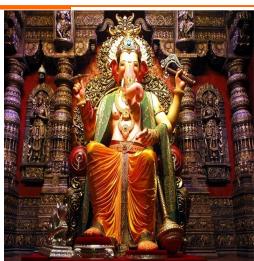
Machine learning is the science of making computers learn and act like humans by feeding data and information without being explicitly programmed!



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## Can You Recognize these Pictures ?



Portrait or a sculpture ???

- If Yes, How do you Recognize it?

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## Learning



*Learning is constructing or modifying representations of what is being experienced.*  
-- McCarthy, 1968

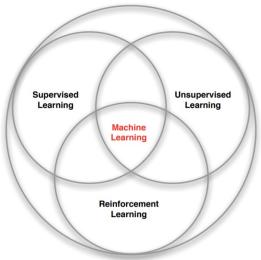
15



## Machine learning Type:

With respect to the feedback type to learner:

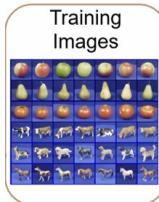
- **Supervised learning :**
  - Task Driven ([Classification](#))
- **Unsupervised learning :**
  - Data Driven ([Clustering](#))
- **Reinforcement learning**
  - Self learning (reward based)



16      Image credit: UCL Course of RL

## Supervised Learning

- Apply a prediction function to a feature representation of the image to get the desire output



$$f(\text{apple}) = \text{"apple"} \\ f(\text{tomato}) = \text{"tomato"} \\ f(\text{cow}) = \text{"cow"}$$

→ Slide credit: L. Lazebnik

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## Supervised Learning



Cars

Testing:  
What is this?



Motorcycles

- linear regression
- logistic regression
- Perceptron
- Naive Bayes
- Neural Networks
- Decision trees; K-Nearest Neighbor
- Support Vector Machine (SVM)

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## Un-Supervised learning



Unlabeled images (all cars/motorcycles)

### Clustering



Which Group  
It belongs to ??



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## Reinforcement / Self Learning



Unlabeled images (random internet images)



Testing:  
What is this?



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## Human Learning Process

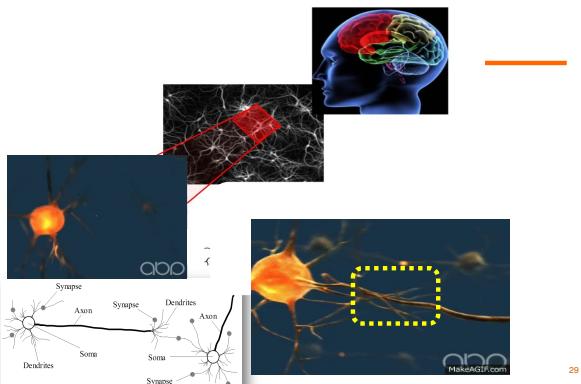
Locate people in this photo



Add these numbers

2403343781289312
+ 2843033712837981
+ 2362142787897881
+ 3256541312323213
+ 9864479802118978
+ 8976677987987897
+ 8981257890087988
= ?

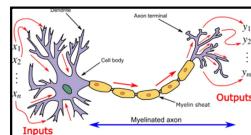
26



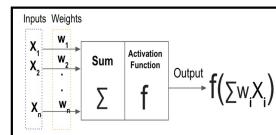
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## Artificial Neural Network

- Consists of a number of very simple processors, also called **neurons**.
  - Analogous to the biological neurons in the brain.
- Neurons are connected by weighted links passing signals from one neuron to another.
- The output signal is transmitted through the neuron's outgoing connection.
- The outgoing connection splits into a number of branches that transmit the same signal.
  - The outgoing branches terminate at the incoming connections of other neurons in the network.



Source: Wikipedia



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## Example : Learning in a Human Way

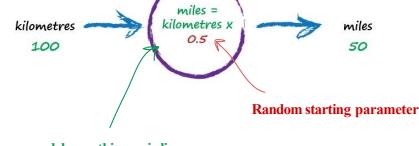


$$f(\text{apple}) = \text{"apple"}$$

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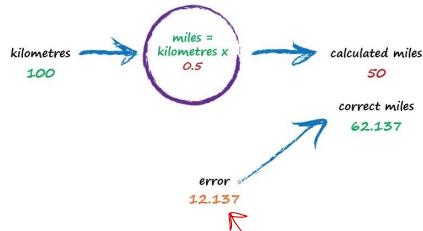
## Example : Learning in a Human Way



32



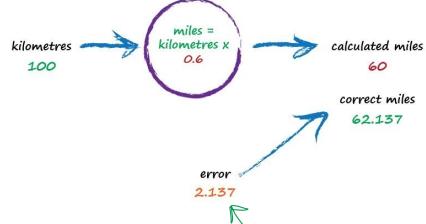
## Example : Learning in a Human Way



33



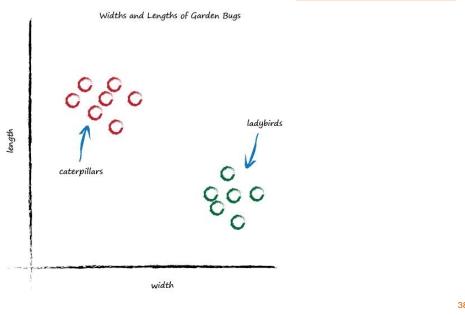
## Example : Learning in a Human Way



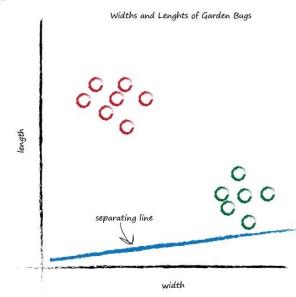
34



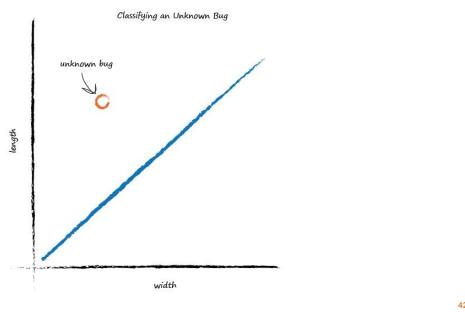
## Example : Learning in a Machine Way



## Example : Learning in a Machine Way



## Example : Learning in a Machine Way



## Example : Learning in a Machine Way

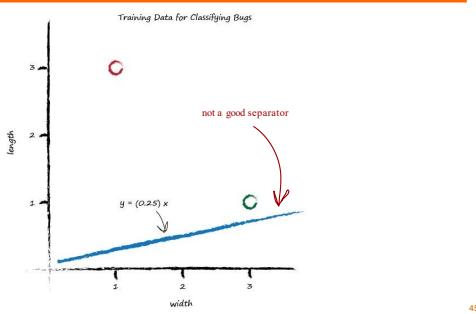
**Classifying** things is kinda like **predicting** things.

Example	Width	Length	Bug
1	3.0	1.0	ladybird
2	1.0	3.0	caterpillar

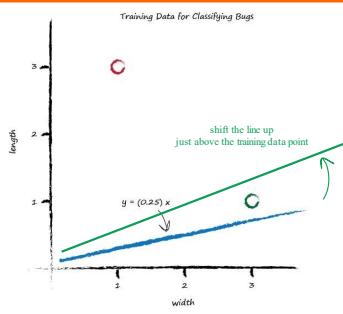
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## Example : Learning in a Machine Way

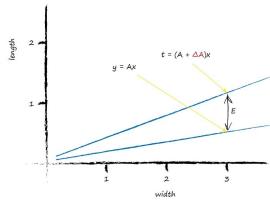


## Example : Learning in a Machine Way





## Example : Learning in a Machine Way



error = target - actual

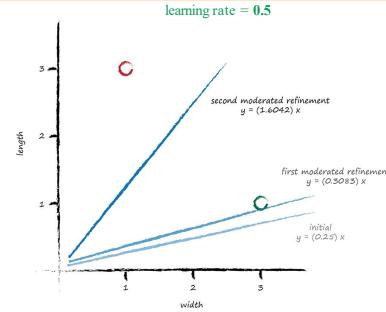
$$E = (A + \Delta A)x - Ax$$

$$\Delta A = E / x$$

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## Example : Learning in a Machine Way



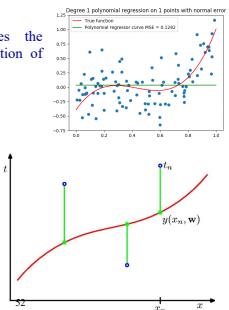
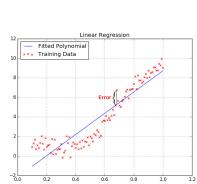
51



## Example : Learning in a Machine Way

- How to choose ??

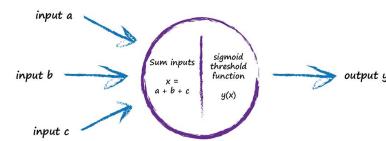
- Loss function : measures the squared error in the prediction of  $y(x)$  from  $x$ .



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## When we have more than one input?

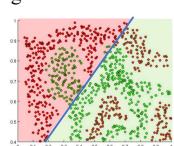


53

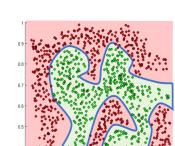


## Need of Activation functions

- The purpose of activation functions is to introduce non-linearities into the network
- A neural network without an activation function is essentially just a linear regression model.



Linear Activation functions produce linear decisions no matter the network size

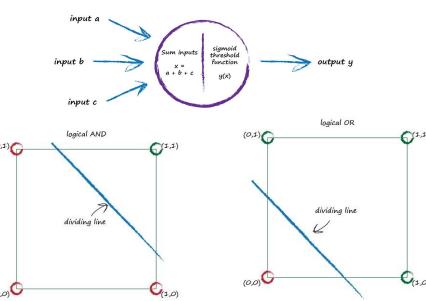


Non-linearities allow us to approximate arbitrarily complex functions

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## Single Neuron /Perceptron



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## Features

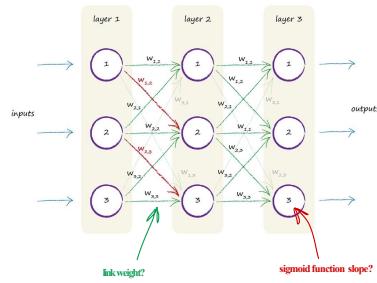
- The features are the elements of your input vectors.
- The number of features is equal to the number of nodes in the input layer of the network

Category	Features
Housing Prices	No. of Rooms, House Area, Air Pollution, Distance from facilities, Economic Index city, Security Ranking etc.
Spam Detection	presence or absence of certain email headers, the email structure, the language, the frequency of specific terms, the grammatical correctness of the text etc.
Speech Recognition	noise ratios, length of sounds, relative power of sounds, filter matches
Cancer Detection	Clump thickness, Uniformity of cell size, Uniformity of cell shape, Marginal adhesion, Single epithelial cell size, Number of bare nuclei, Bland chromatin, Number of normal nuclei, Mitosis etc.
Cyber Attacks	IP address, Timings, Location, Type of communication, traffic details etc.
Video Recommendations	Text matches, Ranking of the video, Interest overlap, history of seen videos, browsing patterns etc.
Image Classification	Pixel values, Curves, Edges etc.

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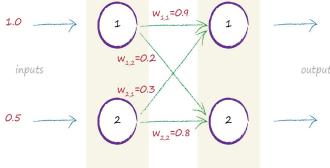
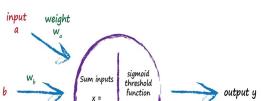
## Where Does The Learning Happen?



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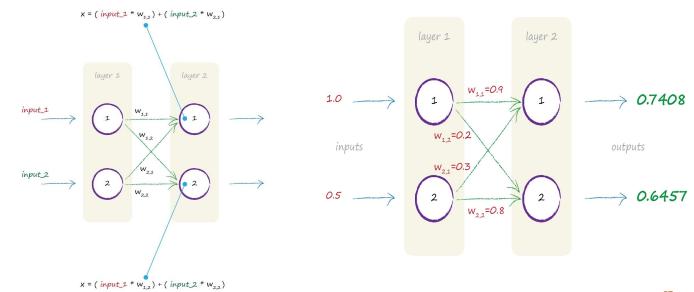
## Feeding Signals Forward



66



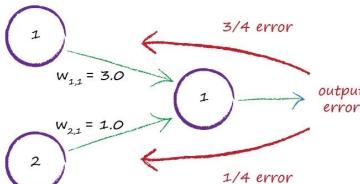
## Feeding Signals Forward



67



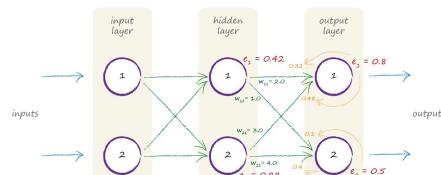
## Network Error



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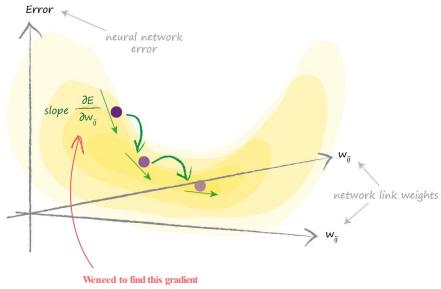
## Internal Error



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## Climbing Down the Network Error Landscape



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## Updating the Weights

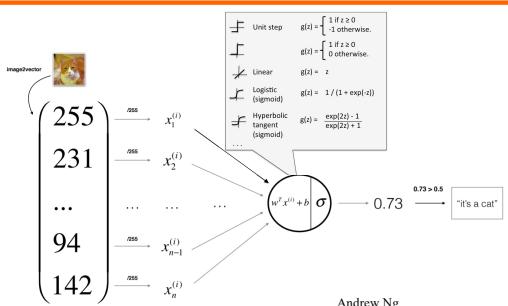
$$\text{new } w_{jk} = \text{old } w_{jk} - \alpha \cdot \frac{\partial E}{\partial w_{jk}}$$

move  $w_k$  in the opposite direction to the slope  
remember that learning rate

80



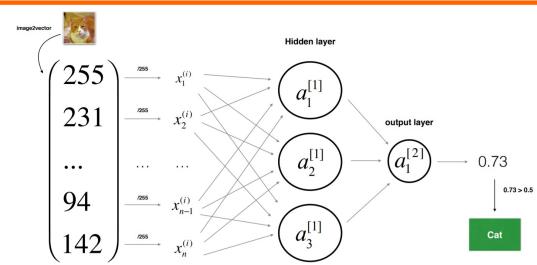
## Logistic Regression as a Neural Network



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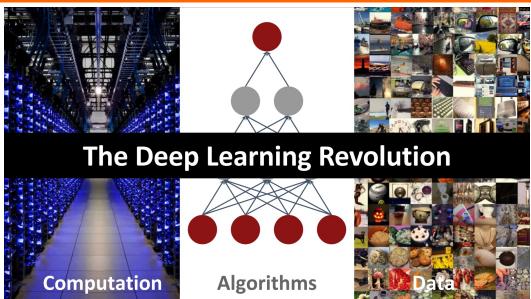
## Neural Network (1 hidden layer)



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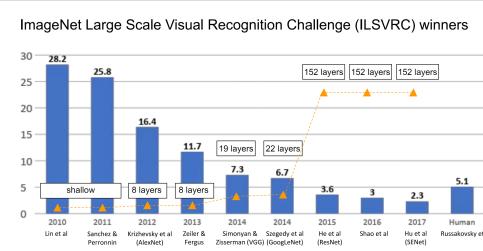
## The Deep Learning Revolution



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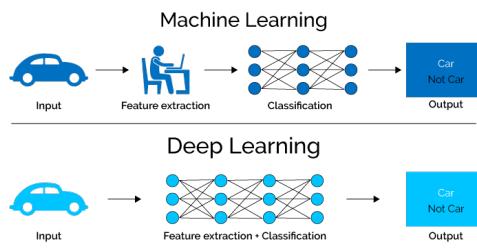
## Vision and Deep Learning



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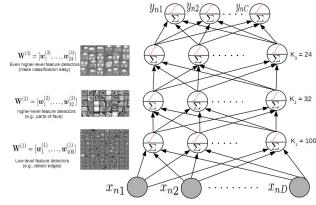
## Traditional ML vs Deep Learning



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## Neural Networks: The Features Learned

- Deep neural networks are good at detecting features at multiple layers of abstraction
- The connection weights between layers can be thought of as feature detectors or filters



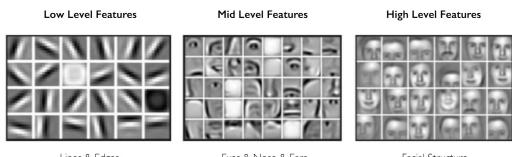
- Lowest layer weights detect generic features, higher level weights detect more specific features
- Features learned in one layer are composed of features learned in the layer below

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## Why Deep Learning ?

- Hand engineered features are time consuming, brittle and not scalable in practice.
- Can we learn the underlying features directly from data?



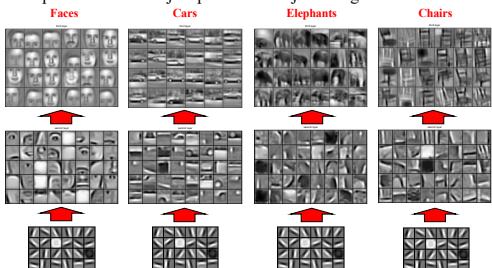
99



## Learning of object parts

In deep learning, feature learning replaces feature engineering

Examples of learned object parts from object categories



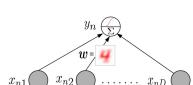
100



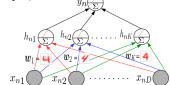
## Why Are Deep Neural Network Learned Features Helpful?



- A single layer model will learn an average feature detector



- An MLP can learn multiple feature detectors (even with a single hidden layer)

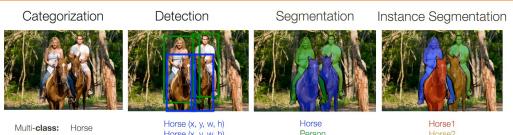


- Therefore even a single hidden layer helps capture subtle variations in the inputs

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## Computer Vision Problems



Multi-label: Horse, Church, Toothbrush, Person

Horse (x, y, w, h), Person (x, y, w, h)



Segmentation

Horse Person



Horse1 Person1 Horse2 Person2

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## Applications

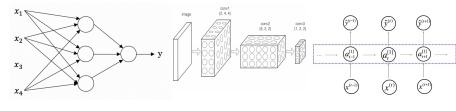
### Deep Learning/AI APPLICATIONS



Few Popular Applications: Precision Agriculture, Learner Profiling, Video Captioning, Exploring Patterns from Satellite Images, Image detection in Healthcare, Identifying specific markers in Genomes, Creating Art and Music, Recommendations, behavior prediction,

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## Deep Network Examples



- Stacked Autoencoders (multilayer neural net with target output = input)
- Stacked restricted Boltzmann machine

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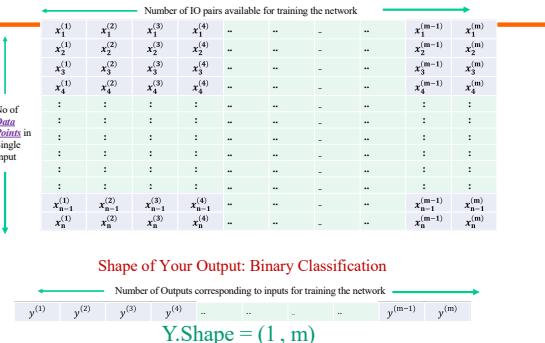
## Color Image (8X8X3) pixels



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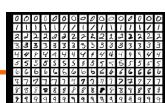
## Shape of Your Input: X (n x m)



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## MNIST Dataset

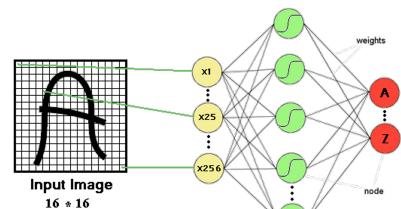


- MNIST dataset of handwritten digits
  - Categories: 10 digit classes
  - Source: Scans of handwritten zip codes from envelopes
  - Size: 60,000 training images and 10,000 test images, grayscale, of size 28 x 28
  - Normalization: centered within the image, scaled to a consistent size
    - The assumption is that the digit recognizer would be part of a larger pipeline that segments and normalizes images.
- In 1998, Yann LeCun and colleagues built a conv net called LeNet which was able to classify digits with 98.9% test accuracy.
  - It was good enough to be used in a system for automatically reading numbers on checks.

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## Multi-layer perceptron and Vision

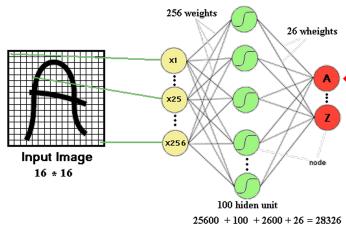


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## Even a simple 16x16 image

- $256 \times 100 + 100 \text{ bias} + 100 \times 26 \text{ output neurons} + 26 \text{ bias} = 28236$
- the number of trainable parameters becomes extremely large



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## ImageNet

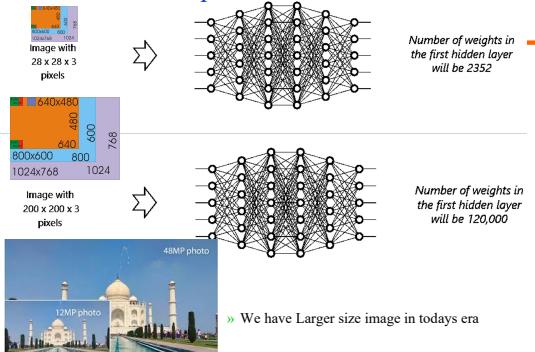


- ImageNet is the modern object recognition benchmark dataset. It was introduced in 2009, and has led to amazing progress in object recognition since then. [<http://image-net.org/download> ]
- Used for the ImageNet Large Scale Visual Recognition Challenge (ILSVRC), an annual benchmark competition for object recognition algorithms
- Design decisions
  - Categories: Taken from a lexical database called WordNet
    - WordNet consists of synsets, or sets of synonymous words
    - They tried to use as many of these as possible; almost 22,000 as of 2010
    - Of these, they chose the 1000 most common for the ILSVRC
    - The categories are really specific, e.g. hundreds of kinds of dogs
  - Size: 1.2 million full-sized images for the ILSVRC
  - Source: Results from image search engines, hand-labeled by Mechanical Turkers
    - Labeling such specific categories was challenging; annotators had to be given the WordNet hierarchy, Wikipedia, etc.
  - Normalization: none, although the contestants are free to do preprocessing

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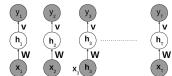
## With Deep Neural Network



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## Some Limitations of Feedforward Networks

- Require a huge number of parameters
  - The consecutive layers are fully connected)
- Not ideal for data that exhibit locality structure, e.g., (e.g., images, sentences)
  - Kind of works but would be better to exploit locality in the data more explicitly
- Doesn't have a memory, so not ideal when modeling sequence of observations



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## Motivation

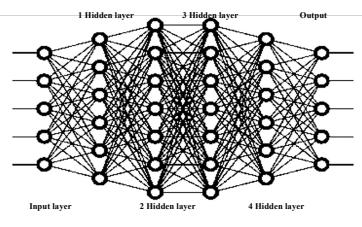
WHY WE NEED CONVOLUTIONAL NEURAL NETWORKS?

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## Deep NN: Too many parameters

- We know it is good to learn a small model.
- From this fully connected model, do we really need all the edges?
- Can some of these be shared?



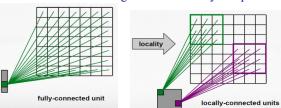
115



## Feature Extraction Using Convolution

- Fully Connected Networks

- Fully connect all the hidden units to all the input units.
- With small images it was computationally feasible to learn features on the entire image.
- But, with larger images learning features it is very computationally expensive



- Locally Connected Networks

- Restrict the connections between the hidden units and the input units,
  - Allow each hidden unit to connect to only a small subset of the input units.
  - Each hidden unit connects to only a small contiguous region of pixels.
- This idea of having locally connected networks also draws inspiration from how the early visual system is wired up in biology.
  - Neurons in the visual cortex have localized receptive fields (i.e., they respond only to stimuli in a certain location).

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## Can you recognize ??



learned features over small patches sampled randomly from the larger image

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## Basic Idea of Convolution

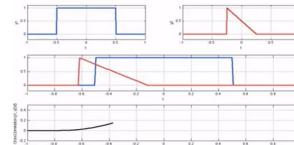


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## What is Convolutions ????

- Dictionary meaning
  - a thing that is complex and difficult to follow.
- In mathematics convolution is a mathematical operation on two functions that produces a third function expressing how the shape of one is modified by the other. The term convolution refers to both the result function and to the process of computing it. [Wikipedia]



$$\begin{array}{c} x[n] \rightarrow \text{Linear System} h[n] \rightarrow y[n] \\ x[n] * h[n] = y[n] \\ (f * g)(t) \triangleq \int_{-\infty}^{\infty} f(t-\tau)g(\tau) d\tau. \end{array}$$

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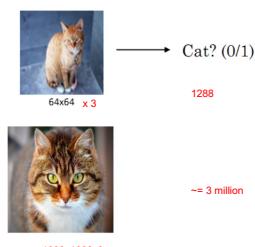


## Convolutional Neural Networks (CNN)

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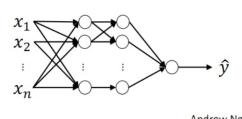
## Deep Learning on large images



1288



~3 million

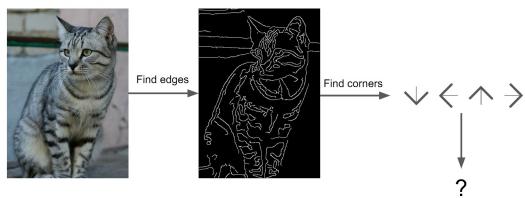


Andrew Ng

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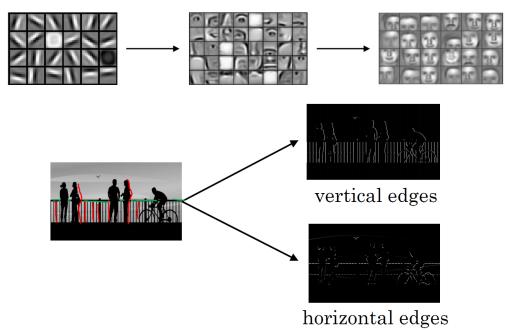
### Attempts have been made though edge detection



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### Computer Vision Problem



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### Vertical Edge Detection

$$\begin{array}{|c|c|c|c|c|} \hline
 1 & 1 & 1 & 0 & 0 \\ \hline
 0 & 1 & 1 & 1 & 0 \\ \hline
 0 & 0 & 1 & 1 & 1 \\ \hline
 0 & 0 & 1 & 1 & 0 \\ \hline
 0 & 1 & 1 & 0 & 0 \\ \hline
 \end{array}$$

5x5 Matrix

$$\begin{array}{|c|c|c|} \hline
 1 & 0 & 1 \\ \hline
 1 & 0 & 1 \\ \hline
 1 & 0 & 1 \\ \hline
 \end{array}$$

3x3 Filter

$$\begin{array}{|c|c|c|c|c|} \hline
 & & & & \\ \hline
 \end{array}$$

4x4

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### Vertical Edge Detection

$$\begin{array}{|c|c|c|c|c|} \hline
 1_{x3} & 1_{x0} & 1_{x1} & 0 & 0 \\ \hline
 0_{x0} & 1_{x1} & 1_{x0} & 1 & 0 \\ \hline
 0_{x1} & 0_{x0} & 1_{x1} & 1 & 1 \\ \hline
 0 & 0 & 1 & 1 & 0 \\ \hline
 0 & 1 & 1 & 0 & 0 \\ \hline
 \end{array}$$

Image

$$\begin{array}{|c|c|c|} \hline
 4 & & \\ \hline
 \end{array}$$

Convolved Feature

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### Vertical Edge Detection

$$\begin{array}{|c|c|c|c|c|c|} \hline
 10 & 10 & 10 & 0 & 0 & 0 \\ \hline
 10 & 10 & 10 & 0 & 0 & 0 \\ \hline
 10 & 10 & 10 & 0 & 0 & 0 \\ \hline
 10 & 10 & 10 & 0 & 0 & 0 \\ \hline
 10 & 10 & 10 & 0 & 0 & 0 \\ \hline
 10 & 10 & 10 & 0 & 0 & 0 \\ \hline
 \end{array}$$

\*

$$\begin{array}{|c|c|c|} \hline
 1 & 0 & -1 \\ \hline
 1 & 0 & -1 \\ \hline
 1 & 0 & -1 \\ \hline
 \end{array}$$

=

$$\begin{array}{|c|c|c|c|c|} \hline
 & & & & \\ \hline
 \end{array}$$

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### Vertical and Horizontal Edge Detection

$$\begin{array}{|c|c|c|} \hline
 1 & 0 & -1 \\ \hline
 1 & 0 & -1 \\ \hline
 1 & 0 & -1 \\ \hline
 \end{array}$$

Vertical

$$\begin{array}{|c|c|c|} \hline
 1 & 1 & 1 \\ \hline
 0 & 0 & 0 \\ \hline
 -1 & -1 & -1 \\ \hline
 \end{array}$$

Horizontal

$$\begin{array}{|c|c|c|c|c|} \hline
 10 & 10 & 10 & 0 & 0 & 0 \\ \hline
 10 & 10 & 10 & 0 & 0 & 0 \\ \hline
 10 & 10 & 10 & 0 & 0 & 0 \\ \hline
 0 & 0 & 0 & 10 & 10 & 10 \\ \hline
 0 & 0 & 0 & 10 & 10 & 10 \\ \hline
 0 & 0 & 0 & 10 & 10 & 10 \\ \hline
 \end{array}$$

\*

$$\begin{array}{|c|c|c|} \hline
 1 & 1 & 1 \\ \hline
 0 & 0 & 0 \\ \hline
 -1 & -1 & -1 \\ \hline
 \end{array}$$

=

$$\begin{array}{|c|c|c|c|c|} \hline
 & & & & \\ \hline
 \end{array}$$

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This is **convolution function** in image processing

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## CNNs Vs. ANNs

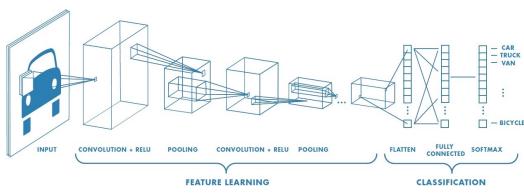
- ANNs suffer from **curse of dimensionality** when it comes to high resolution images
- We use filters (receptive fields) to exploit **spatial locality** by enforcing a local connectivity pattern between neurons of adjacent layers
  - Parameter Sharing
  - Sparsity of connection

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## Neural network with many convolutional layers

- Natural images have the property of being "stationary", meaning that the statistics of one part of the image are the same as any other part.
- This suggests that the features that we learn at one part of the image can also be applied to other parts of the image, and we can use the same features at all locations.

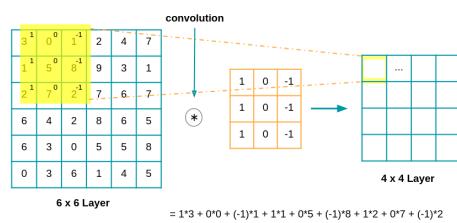


- 3 Layer in a convolutional network:
  - Convolution (CONV)
  - Pooling (POOL)
  - Fully connected (FC)

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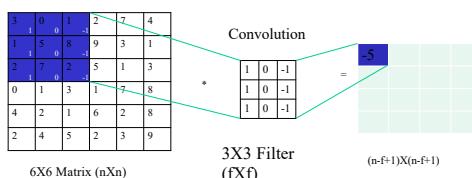
## Convolution Example: Vertical Edge Detection



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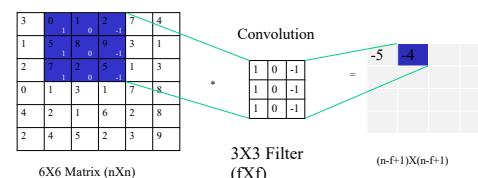
## Convolution Example



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## Convolution Example



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## Convolution Example

$6 \times 6 \text{ Matrix (n} \times \text{n)}$

3	0	1	2	-1	4
1	5	8	9	3	1
2	7	2	5	1	3
0	1	3	1	7	8
4	2	1	6	2	8
2	4	5	2	3	9

$3 \times 3 \text{ Filter (f} \times \text{f)}$

1	0	-1
1	0	-1
1	0	-1

$\text{Convolution}$

$(n-f+1) \times (n-f+1)$

-5	-4	0	8
-10	-2	2	3
0	-2	-4	-7
-3	-2	-3	-16

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## Convolution: Detecting Vertical edges

$6 \times 6 = 36$

10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0

$* \quad \begin{bmatrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix}$

0	30	30	0
0	30	30	0
0	30	30	0
0	30	30	0

$4 \times 16$

0	30	30	0
0	30	30	0
0	30	30	0
0	30	30	0

- In case of ANN # parameter to train =  $36 \times 16 = 576$
- In case of CNN # parameter to train = 9

The role of the ConvNet is to reduce the images into a form which is easier to process, without losing features which are critical for getting a good prediction.

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## Convolution : Filter Weights

Operation	Filter	Convolved image
Identity	$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$	
Edge detection	$\begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$	
Sobel Filter	$\begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix}$	
Scharr Filter	$\begin{bmatrix} 3 & 0 & -3 \\ 10 & 0 & -10 \\ 3 & 0 & -3 \end{bmatrix}$	
Sharpen	$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$	
Box blur (averaging)	$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$	
Gaussian blur (smoothing)	$\begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$	

Convolutional Neural Networks automatically estimates the weights of the filter

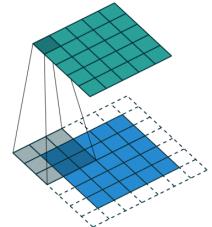
- Learn them

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## Padding

- Two problems
  - Shrinking output
  - Through away info from edges: Pixel at the corner are used much lesser than the pixel at middle
- Padding is used to preserve the original dimensions of the input
- Zeros are added to outside of the input
- Number of zero layers depend upon the size of the kernel



0	0	0	0	0	0	0
0	1	1	1	0	0	0
0	0	1	1	1	0	0
0	0	0	1	1	1	0
0	0	1	1	1	0	0
0	0	0	1	0	0	0
0	0	0	0	0	0	0

x1	x2	x3
x1	x2	x3
x1	x2	x3

5 x 5 (with padding)

2	2	3	1	1
2	2	4	3	3
1	2	3	4	1
1	2	3	1	1

5 x 5



## Padding

$n \times n = 6 \times 6 - 6 \times 6 \text{ Padding (p)} = 1$

$f : 3 \times 3$

$(n-f+1) \times (n-f+1) \text{ to } (n+2p-f+1) \times (n+2p-f+1)$

Valid to same

$4 \times 4 - 6 \times 6$

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## Valid and Same convolutions

- Valid convolutions
  - No padding
  - $(n \times n) * (f \times f) = (n-f+1) \times (n-f+1)$
  - $(6 \times 6) * (3 \times 3) = 4 \times 4$

### Same convolutions

- Pad so that output size is the same as the input size.
- $(n+2p-f+1) \times (n+2p-f+1)$
- $(n+2p-f+1) = n$

$$p = \frac{f-1}{2}$$

If  $f=5 ; 5 \times 5$  therefore  $p=2$

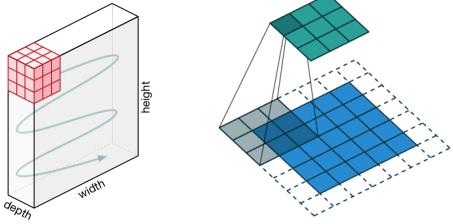
$f$  is usually odd.

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## Strided Convolutions

- Stride defines the number of nodes a filter moves between two consecutive convolution operations
- Likewise, we have a stride to define the same when applying pooling
  - When the stride is 1 then we move the filters to 1 pixel at a time.
  - When the stride is 2 then we move the filters to 2 pixels at a time and so on.



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## Stride

Stride = 3 (Here)

Convolution

$$\begin{matrix} 3 & 0 & 1 & 2 & 7 & 4 \\ 1 & 5 & 8 & 9 & 3 & 1 \\ 2 & 7 & 2 & 5 & 1 & 3 \\ 0 & 1 & 3 & 1 & 7 & 8 \\ 4 & 2 & 1 & 6 & 2 & 8 \\ 2 & 4 & 5 & 2 & 3 & 9 \end{matrix} * \begin{matrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{matrix} = \begin{matrix} -5 & 8 \end{matrix}$$

6X6 Matrix (nXn)      3X3 Filter (fXf)

6X6 Matrix (nXn)

3X3 Filter (fXf)

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## Stride

Stride = 3 (Here)

Convolution

$$\begin{matrix} 3 & 0 & 1 & 2 & 7 & 4 \\ 1 & 5 & 8 & 9 & 3 & 1 \\ 2 & 7 & 2 & 5 & 1 & 3 \\ 0 & 1 & 3 & 1 & 7 & 8 \\ 4 & 2 & 1 & 6 & 2 & 8 \\ 2 & 4 & 5 & 2 & 3 & 9 \end{matrix} * \begin{matrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{matrix} = \begin{matrix} -5 & 8 \end{matrix}$$

6X6 Matrix (nXn)      3X3 Filter (fXf)

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## Stride

Stride = 3 (Here)

Convolution

$$\begin{matrix} 3 & 0 & 1 & 2 & 7 & 4 \\ 1 & 5 & 8 & 9 & 3 & 1 \\ 2 & 7 & 2 & 5 & 1 & 3 \\ 0 & 1 & 3 & 1 & 7 & 8 \\ 4 & 2 & 1 & 6 & 2 & 8 \\ 2 & 4 & 5 & 2 & 3 & 9 \end{matrix} * \begin{matrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{matrix} = \begin{matrix} -5 & 8 \\ -3 & 16 \end{matrix}$$

6X6 Matrix (nXn)      3X3 Filter (fXf)

6X6 Matrix (nXn)

3X3 Filter (fXf)

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## Stride

Stride = 3 (Here)

Convolution

$$\begin{matrix} 3 & 0 & 1 & 2 & 7 & 4 \\ 1 & 5 & 8 & 9 & 3 & 1 \\ 2 & 7 & 2 & 5 & 1 & 3 \\ 0 & 1 & 3 & 1 & 7 & 8 \\ 4 & 2 & 1 & 6 & 2 & 8 \\ 2 & 4 & 5 & 2 & 3 & 9 \end{matrix} * \begin{matrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{matrix} = \begin{matrix} -5 & 8 \\ -3 & 16 \end{matrix}$$

6X6 Matrix (nXn)      3X3 Filter (fXf)

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## Channels: Convolutions over volumes

Padding = 0 Stride = 1

Convolution

$$\begin{matrix} \text{Red} & \text{Blue} & \text{Green} \\ \text{Matrix} & \text{Filter} & \text{Result} \end{matrix} * \begin{matrix} \text{Yellow} \\ \text{Matrix} \end{matrix} = \begin{matrix} \text{4x4} \end{matrix}$$

6X6 Matrix      3X3 Filter      4x4

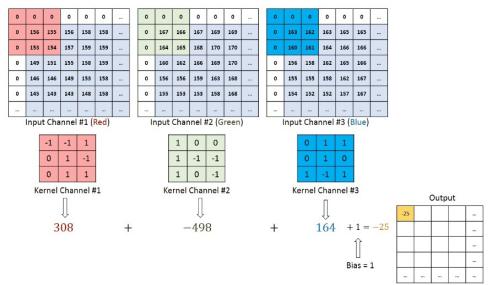
6X6 Matrix

Padding = 0 Stride = 1

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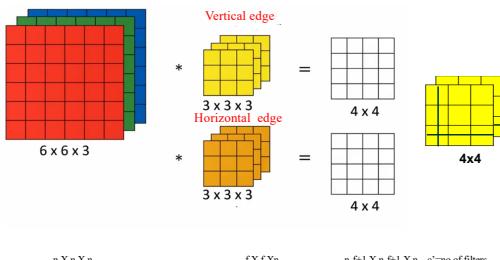


## Convolutions on RGB image

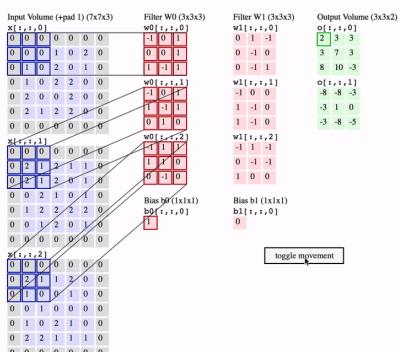


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## Convolutions with Multiple filter (depth/channels)



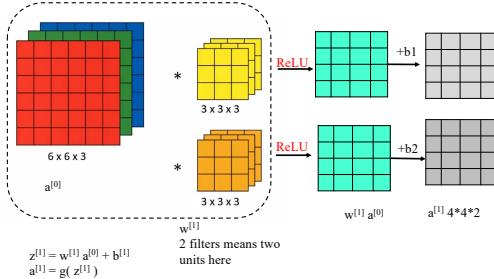
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## One layer of a convolutional network



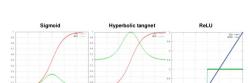
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## Non Linearity (ReLU)

- ReLU stands for Rectified Linear Unit for a non-linear operation. The output is  $f(x) = \max(0, x)$ .
- Why ReLU is important :
  - ReLU's purpose is to introduce non-linearity in our ConvNet.
  - Result should be non-negative linear.

- Other non linear functions
  - tanh or
  - sigmoid

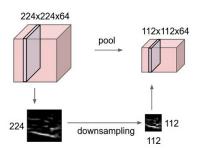


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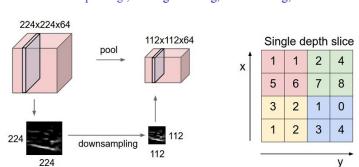


## Pooling [Downsampling] Layer

- Used to downsample the representation-size after convolution step
- Pooling layers section would reduce the number of parameters when the images are too large.
- Spatial pooling also called subsampling or downsampling which reduces the dimensionality of each map but retains important information.
- Ensures robustness against minor rotations, shifts, corruptions in the image
- Popular approaches:
  - Max-pooling , Average Pooling, Sum Pooling, etc

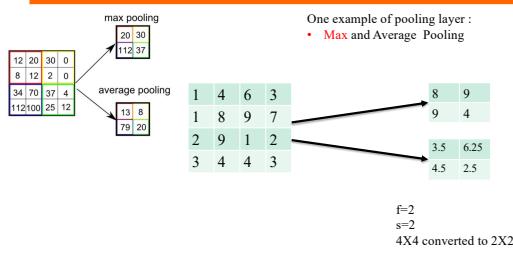


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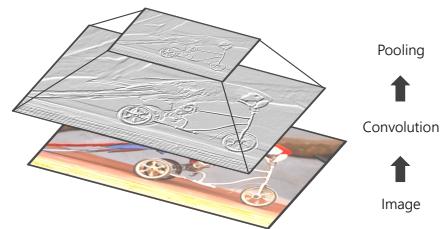


## Pooling Layer



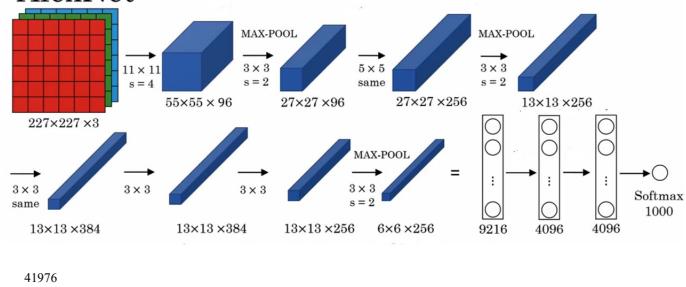
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## A Basic Module of the CNN



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## AlexNet



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## Other Deep Learning Modules

- Oxford VGG Model
- Google Inception Model
- Microsoft ResNet Model
- Xception: Deep Learning with Depthwise Separable Convolutions
  - [Chollet, F. (2017). Xception: Deep learning with depthwise separable convolutions. In Proceedings of the IEEE conference on computer vision and pattern recognition (pp. 1251-1258).]
- EfficientNet: Rethinking Model Scaling for Convolutional Neural Networks
  - [Tan, M., & Le, Q. V. (2019). Efficientnet: Rethinking model scaling for convolutional neural networks. arXiv preprint arXiv:1905.11946.]
- Google's word2vec Model
- Stanford's GloVe Model

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"You need a lot of a data if you want to train/use CNNs"

if less data how to proceed ??

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## Exercise

Design a model to detect pedestrians on night-time images



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## What we have discussed so far

- In the classic supervised learning scenario
  - If we want to train a model for some task A and Domain A
  - Eg: **Task/Domain A:** Train a model to detect pedestrians on night-time images
    - we assume that we are provided with labeled data for the same task and domain.
    - We train a model A on this dataset and expect it to perform well on unseen data of the same task and domain.
  - On another occasion, when given data for some other task or domain B,
  - Eg: **Task/Domain B:** Train a model to detect pedestrians on day-time images
    - we require again labeled data of the same task or domain that we can use to train a new model B so that we can expect it to perform well on this data.

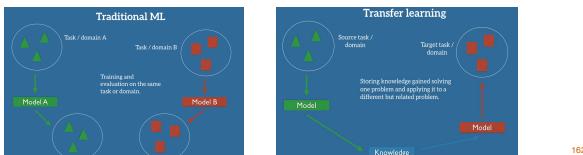


## Eg: Cycle riding



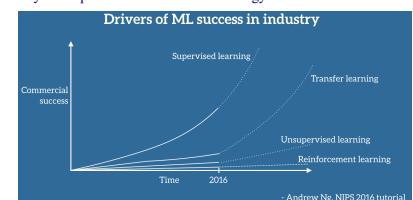
## What can be done

- If we want to train a model to detect pedestrians on night-time images,
- We could **apply a model that has been trained on a similar domain**, e.g. on day-time images.
- Transfer learning**
  - allows us to deal with these scenarios by leveraging the already existing labeled data of some related task or domain.
  - We try to store this knowledge gained in solving the source task in the source domain and apply it to our problem of interest.
  - Try to exploit what has been learned in one task to improve generalization in another.
  - We transfer the weights that a network has learned at "task A" to a new "task B."



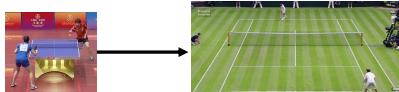
## Why it is popular

- It can train deep neural networks with comparatively **little data**.
- Useful in the data science field as most real-world problems typically do not have millions of labeled data points to train such complex models.
  - million examples for image recognition task, lot of data to learn a low level features, while for the radiology task we have 100 examples , lot of knowledge learned from image recognition task may be helpful to transferred for radiology task.



## When to Use Transfer Learning?

- Situation where what has been learned in one setting is exploited to improve generalization in another setting.



- Task A and B have the same input x**
- You have a lot more data for Task A than Task B.**
- Low level features from A could be helpful for learning B.**

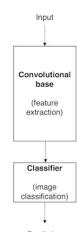
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## Convolutional neural networks

A typical CNN has two parts:

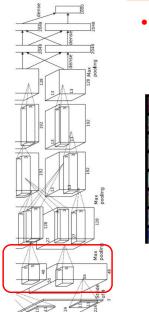
- Convolutional base:**
  - Composed by Stack of convolutional and pooling layers.
  - The main goal of the convolutional base is to generate features from the image.
- Classifier:**
  - Composed by fully connected layers.
  - The main goal of the classifier is to classify the image based on the detected features.
  - A fully connected layer is a layer whose neurons have full connections to all activation in the previous layer.



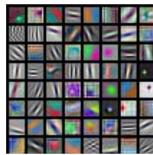
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## Transfer Learning with CNNs



- **Convolutional base** its lower layers
  - refer to general features,



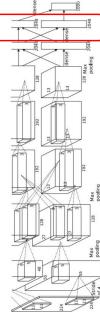
AlexNet:  
64 x 3 x 11 x 11

Source : Fei-Fei Li, CS231n Convolutional Neural Networks for Visual Recognition, 2020

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## Transfer Learning with CNNs



- **Classifier part**- higher layers of
  - specialised features



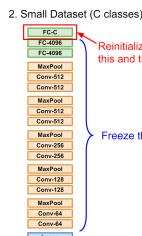
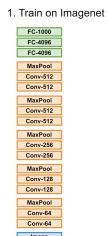
Test image L2 Nearest neighbors in **feature space**

Source : Fei-Fei Li, CS231n Convolutional Neural Networks for Visual Recognition, 2020

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## Transfer Learning with CNNs



Finetuned from AlexNet

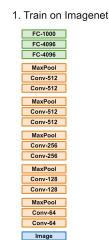
Danabalan et al., "DeCAF: A Deep Convolutional Activation Feature for Generic Visual Recognition", ICML 2014

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Source : Fei-Fei Li, CS231n Convolutional Neural Networks for Visual Recognition, 2020



## Transfer Learning with CNNs



Danabalan et al., "DeCAF: A Deep Convolutional Activation Feature for Generic Visual Recognition", ICML 2014  
Razavian et al., "Feature Extraction with a Deep Convolutional Network for Image Classification", arXiv preprint arXiv:1404.1792, 2014  
Krizhevsky, Nair, and Hinton, "Learning Feature Hierarchies for Scene Recognition", CoRR, 2014

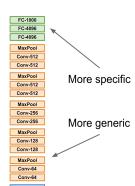
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Source : Fei-Fei Li, CS231n Convolutional Neural Networks for Visual Recognition, 2020



## Transfer Learning Process

1. Select a pre-trained model
  - <https://keras.io/api/applications/>
2. Classify your problem according to the Size-Similarity Matrix
3. Fine-tune model.
4. Classifiers on top



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## RESEARCH PROJECT

- **Project Title:** Computational Techniques based investigation for Diabetic foot ulcers complications
- **Funding Agency:** Department of Science and Technology (DST) - Science and Engineering Research Board (SERB)
- **Duration:** 3 Years



Science and Engineering Research Board  
Statutory Body Established through an Act of Parliament: SERB Act 2008  
Government of India



## Diabetes : Facts and Figure

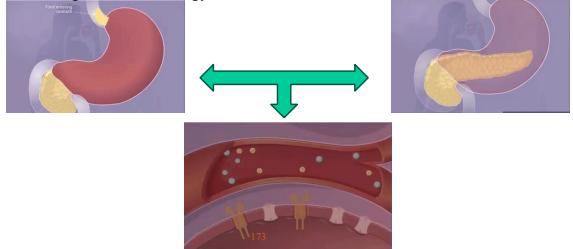


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## INTRODUCTION: Diabetes

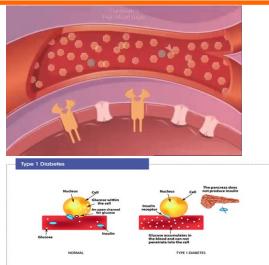
- **Diabetes mellitus (DM):** Diabetes is a **disorder of metabolism**, in which there is **Glucose** in the bloodstream in enormous amounts and the body is not able to convert this glucose into energy.



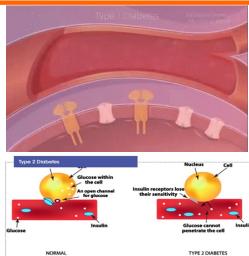
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## TYPES OF DIABETES



**Type 1 Diabetes:**  
Insulin-producing cell become dysfunctional or are destroyed by Immune System.



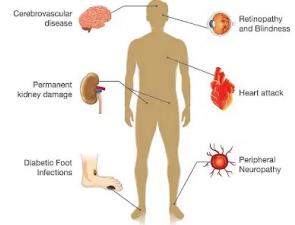
**Type 2 Diabetes:**  
Body either resist the effect of insulin or does not produce enough insulin.

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## COMPLICATIONS OF DIABETES MELLITUS

- **Microvascular** → Physiology Difficult to deal with
  - Retinopathy
  - Nephropathy
  - Neuropathy
- **Macrovascular** → Can see it Can treat it
  - Coronary Macrovascular Disease (CAD)
  - Stroke risk
  - Peripheral Artery Disease (PAD)



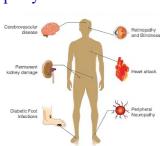
**Physiology:** The chemistry and physics behind basic body functions, from how molecules behave in cells to how systems of organs work together

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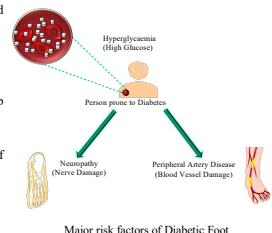
## Extent: Diabetic

- Long-term complications of diabetes include nephropathy leading to
  - Renal (kidneys) failure
  - Retinopathy with potential loss of vision
  - Peripheral neuropathy with risk of foot ulcers
  - Amputations
  - Charcot disease
  - etc.



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- One of the major complications patients with poorly managed long-term DM face is developing a **Diabetic Foot Ulcer (DFU)**.
- 19% to 34% of diabetics will develop a DFU during their lives.
- Up to 20% of patients with a DFU will require lower limb amputation.
- Up to 80% of these patients will die within 5 years of amputation.[4]
- Major factors that predispose individuals to DFUs:[5]
  - Diabetic Peripheral Neuropathy (DPN)
  - Peripheral Arterial Disease (PAD)



Major risk factors of Diabetic Foot

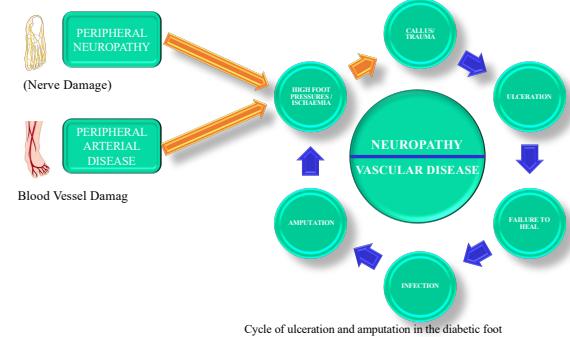
- Diabetic foot is characterized by a classical triad of **neuropathy**, **ischemia**, and **infection**. [6]

- **Peripheral Arterial Disease (PAD):**

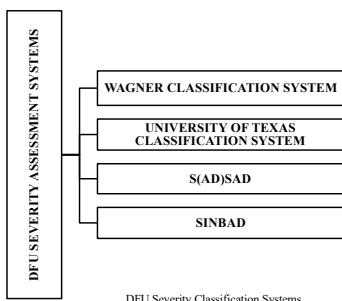
- PAD leads to **ischemia** by narrowing or blocking arteries in the lower limbs, which reduces blood flow to the feet.
- Impaired tissue healing
- Increases the risk of **infection**
- Development of diabetic foot ulcers.



### CYCLE OF ULCERATION AND AMPUTATION IN THE DIABETIC FOOT



### SYSTEMS TO ASSESS SEVERITY OF DFU

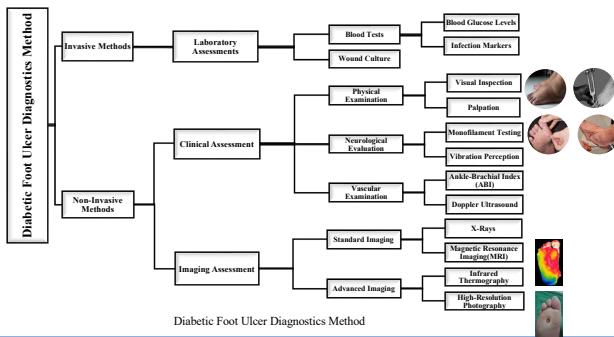


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### FOOT RISK CATEGORIES



### LITERATURE SURVEY: DIABETIC FOOT ULCER DIAGNOSIS METHOD



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### ADVANCED IMAGING TECHNIQUE FOR EARLY DETECTION OF DIABETIC FOOT



Infrared Thermography: What the human eye cannot see[10]

#### THERMOGRAPHY

- Infrared thermography is a **noncontact tool** that maps surface **temperature** of an object in a non contact and remote manner [9].
- The image generated by IR radiation is referred to as **thermogram**.
- Medical IR diagnostics uses the fact that many pathological processes in the human organs manifest themselves as **local changes in heat production** and also as changes in **blood flow pattern** of affected organs or tissues [9].

## ADVANCED IMAGING TECHNIQUE FOR EARLY DETECTION OF DIABETIC FOOT

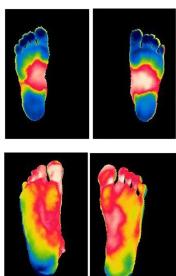


Fig 12: Thermal image of the foot-control, Thermal image of the foot-Diabetic [11]

The use of IRT can be divided in four different categories [11]:

- Independent limb temperature analysis-** temperature analysis is performed on each limb separately;
- Asymmetric analysis-** in healthy subjects there is a contralateral symmetry in the skin temperature distribution and consider that an asymmetry in this distribution can be an indicator of an abnormality;
- Temperature distribution analysis-** similar skin temperature distribution on the feet of healthy individuals comparing to varying temperature variation on diabetic individuals;
- External stress analysis-** the reaction of the body thermoregulation system under the application of thermal and/or physical stress, such as putting the feet into cold water or running.

## DFU ANALYSIS ML APPROACHES

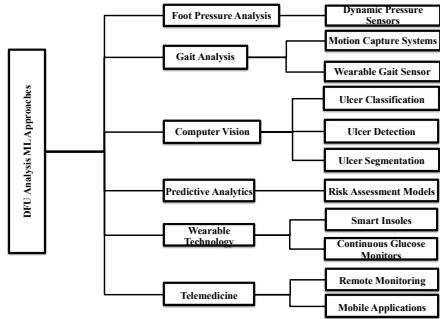


Fig 13: DFU Analysis ML Approaches

## Diabetic Foot Ulcer (DFU)

- Approximately 15% of all people with diabetes will be affected by a foot ulcer during their lifetime.
- Foot ulceration is very common in Diabetic Mellitus. As the **tissue doesn't get enough energy and oxygen** so as to heal wounds, this complicates the situation and later leads to amputation.
- This **can be avoided if we can detect it at an early stage** and provide the patient the required treatment.



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## Wound and Diabetic

- Diabetic foot ulcers typically have a thick rim of keratinized tissue surrounding the wound



Blisters are associated with friction and shear  
Callus is associated with increased pressure and bleeding

- Mechanism of ulcer developing from repetitive or excessive **mechanical stress**



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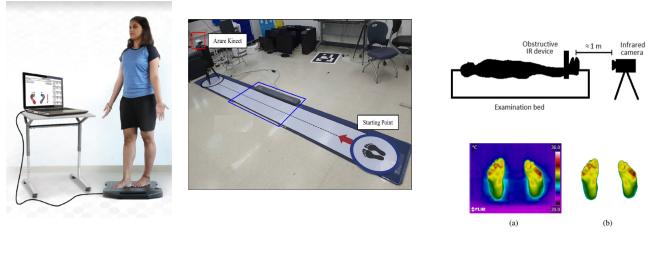
## Diabetic foot

- >60% of all amputations involve diabetes in US
- 9-20% of ulcerations end in amputation
- ~84% of lower extremity amputations are preceded by ulceration
- Every year around 1,00,000 legs are amputated due to diabetes in India
- Indications for Amputation
  - Uncontrollable infection or sepsis
  - Inability to obtain a plantar grade, i.e., foot that can tolerate weight bearing
  - Non-ambulatory patient
- Decision not always straightforward
- Early detection of diabetic foot prevent amputation.



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## A) FOOT PRESSURE B) VISION BASED C) THERMOGRAPHY



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## Research Paper



Home > Robotics, Control and Computer Vision > Conference paper  
A Pilot Study for Profiling Diabetic Foot Ulceration Using Machine Learning Techniques

Issue Date: 15 October 2023

Conference: First Online, 29 Nov 2023

130 Accesses

Part of the Lecture Notes in Electrical Engineering book series (LNEE, volume 1009)

Abstract

Early diagnosis of risk of diabetic foot ulceration (DFU) may allow for earlier care to avoid foot ulcers, amputation, and death. Thermography is a non-invasive imaging technique that is used to detect thermal changes in the diabetic foot. This study illustrates the comparative analysis of ML techniques (KNN, Naive Bayes, Decision Tree, Random Forest, Logistic Regression, SVM, Ada Boost) when performed on the publicly available thermogram database with 125 diabetic and 45 non-diabetic subjects. SVM and Random forest provide better

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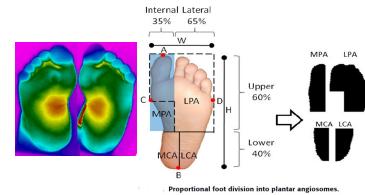
## Dataset

- **Plantar Thermogram Database** for the Study of Diabetic Foot Complications
- Available on IEEE dataport
- Source : <https://ieee-dataport.org/open-access/plantar-thermogram-database-study-diabetic-foot-complications>

- composed of 167 plantar thermograms
  - 122 diabetic subjects
  - 45 non-diabetic subjects.

- The dataset consist of features

- Age,
- Weight,
- Height,
- IMC,
- General (for both left and right foot),
- LCA (for both left and right foot),
- LPA (for both left and right foot),
- MCA (for both left and right foot),
- MPA (for both left and right foot),
- TCI (for both left and right foot)



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## Methodology

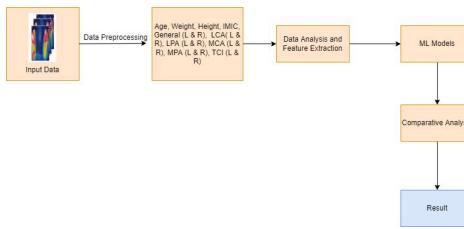


Fig: Approach first which work on detailed Thermogram dataset for subjects

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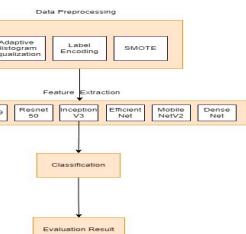


Fig: Approach second which work on Plantar Thermal Image dataset of subjects

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## Traditional Machine Learning Approach :Result

ML Technique	Accuracy	Accuracy with 10 fold	Parameter
KNN	95.68	93.49	n_neighbors=16, metric= euclidean
Naive Bayes	76.47	93.41	-
Decision Tree	97.39	93.41	criterion=gini , max_depth=11
Random Forest	95.65	95.18	criterion=gini , max_depth=7
Logistic Regression	93.93	93.45	-
SVM	98.25	95.22	C=1, gamma=0.1, Kernel= sigmoid

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## Result

- Study also include work on different train-test ratio to compare and find optimal split and corresponding accuracy.

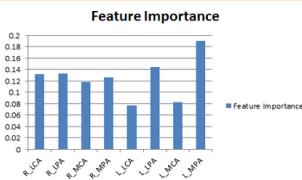
CASE 1	CASE 2	CASE 3	CASE 4	CASE 5
Training 10	Testing 90	Training 30	Testing 70	Training 50
KNN	72.84	93.16	94.04	94.11
Naive Bayse	86.09	<b>95.72</b>	92.85	76.47
Decision Tree	92.71	92.3	<b>96.42</b>	<b>94.11</b>
RandomForest	<b>94.08</b>	92.3	95.23	<b>94.11</b>
Logistic Regression	<b>94.03</b>	<b>95.72</b>	92.85	<b>100</b>
SVM	92.05	94.87	91.66	92.15

CASE 1	CASE 2	CASE 3	CASE 4	CASE 5
KNN	72.84	93.16	94.04	94.11
Naive Bayse	86.09	<b>95.72</b>	92.85	76.47
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Logistic Regression	<b>94.03</b>	<b>95.72</b>	92.85	<b>100</b>
SVM	92.05	94.87	91.66	92.15

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## Results



- The analysis done on the Plantar thermogram data set, it can be inferred that Random forest is giving better accuracy results and MPA angiosome region can be taken for finding early DFU symptoms for future work.

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## Result

- Second approach implementation of Deep Learning Model on Plantar Thermogram dataset

Model with Softmax	Precision	Sensitivity	F1- Score	Accuracy
VGG16	97	85	91	91
VGG19	95	87	91	93
ResNet50	77	92	84	96
InceptionV3	78	78	78	77
EfficientNet	80	78	76	71
MobileNetV2	81	85	81	83
DenseNet	78	78	81	83

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## Conclusion and Future Work

- The best approach detect the diabetic foot at an early stage is the Random Forest, SVM and Ada Boost compared to the Deep Learning Models implemented by Transfer Learning using Imagenet followed by classifier.
- The study also shows the region with higher feature importance that can further be worked to detect early DFU in particular angiosome

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NIT Delhi

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- Email :
  - [cprakash@coed.svnit.ac.in](mailto:cprakash@coed.svnit.ac.in)
- Webpage :
  - <https://cprakash86.wordpress.com/>

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THANK YOU

Any Questions?

- Email :
  - [cprakash@coed.svnit.ac.in](mailto:cprakash@coed.svnit.ac.in)
  - [cse.cprakash@gmail.com](mailto:cse.cprakash@gmail.com)
- Webpage :
  - <https://cprakash86.wordpress.com/>

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