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Assignment 2 Operating System

CODE MODIFICATION REPORT

1. makefile (line 3)

```
3. CS333_PROJECT ?= 2
```

2. makefile (line 21)

```
CS333_UPROGS += #_date _time _ps
```

3. p2-test.c (line 12-14)

```
//#define CPUTIME_TEST
//#define GETPROCS_TEST
//#define TIME_TEST
```

4. proc.c (line 9-11)

```
#ifdef CS333_P2
#include "pdx.h"
#endif //CS333 P2
```

5. proc.c (line 159-162)

```
#ifdef CS333_P2 //project2
  p->cpu_ticks_total = 0;
  p->cpu_ticks_in = 0;
#endif // CS333_P2
```

6. proc.c (line 188-191)

```
#ifdef CS333_P2
  p->uid = DEFAULT_UID;
  p->gid = DEFAULT_GID;
  #endif // CS333_P2
```

7. proc.c (line 265-268)

```
#ifdef CS333_P2
```

```
np->uid = curproc->uid;
np->gid = curproc->gid;
#endif
```

8. proc.c (line 410-412)

```
#ifdef CS333_P2
p->cpu_ticks_in = ticks;
#endif // CS333_P2
```

9. proc.c (line 452-455)

```
#ifdef CS333_P2
  p->cpu_ticks_total += (ticks - p->cpu_ticks_in);
#endif // CS333 P2
```

10. proc.c (line 583-626)

```
uint elapsed s;
  uint elapsed_ms;
  elapsed ms = ticks - p->start_ticks;
  elapsed_s = elapsed_ms / 1000;
  elapsed_ms = elapsed_ms % 1000;
  uint elapsed_cpu_s;
  uint elapsed_cpu_ms;
  uint ppid;
  if(p->parent){
    ppid = p->parent->pid;
  else{
    ppid = p->pid;
  elapsed_cpu_ms = p->cpu_ticks_total;
  elapsed_cpu_s = elapsed_cpu_ms / 1000;
  elapsed_cpu_ms = elapsed_cpu_ms % 1000;
  char* zero = "";
  if(elapsed_ms < 100 && elapsed_ms >= 10)
    zero = "0";
  if(elapsed_ms < 10)</pre>
    zero = "00";
```

```
char* cpu zero = "";
if(elapsed cpu ms < 100 && elapsed cpu ms >= 10)
  cpu_zero = "0";
if(elapsed cpu ms < 10)</pre>
  cpu_zero = "00";
cprintf(
  "\n%d\t%s\t%s%d\t%s%d\t%s%d\t%d.%s%d\t%d.%s%d\t%s\t%d\t",
  p->pid,
  p->name, "
 p->uid, "
  p->gid, "",
  ppid,
  elapsed s, zero, elapsed ms,
  elapsed_cpu_s, cpu_zero, elapsed_cpu_ms,
  state_string,
 p->sz
```

11. proc.c (line 1000-1033)

```
uint elapsed s;
  uint elapsed_ms;
  elapsed_ms = ticks - p->start_ticks;
  elapsed_s = elapsed_ms / 1000;
  elapsed ms = elapsed ms % 1000;
  uint elapsed cpu s;
  uint elapsed_cpu_ms;
  uint ppid;
  if(p->parent){
    ppid = p->parent->pid;
  else{
    ppid = p->pid;
  elapsed_cpu_ms = p->cpu_ticks_total;
  elapsed_cpu_s = elapsed_cpu_ms / 1000;
  elapsed_cpu_ms = elapsed_cpu_ms % 1000;
  char* zero = "";
  if(elapsed_ms < 100 && elapsed_ms >= 10)
    zero = "0";
  if(elapsed ms < 10)</pre>
```

```
zero = "00";
char* cpu_zero = "";
if(elapsed cpu ms < 100 && elapsed cpu ms >= 10)
  cpu_zero = "0";
if(elapsed_cpu_ms < 10)</pre>
  cpu zero = "00";
cprintf(
  "\n%d\t%s\t%s%d\t%s%d\t%s%d\t%d.%s%d\t%d.%s%d\t%s\t%d\t",
  p->pid,
  p->name, "
 p->uid, "
  p->gid, "",
  ppid,
  elapsed_s, zero, elapsed_ms,
  elapsed_cpu_s, cpu_zero, elapsed_cpu_ms,
  state_string,
 p->sz
```

12. proc.h (line 53-54)

```
uint uid;
uint gid;
```

13. syscall.c (line 113-119)

```
#ifdef CS333_P2
extern int sys_getuid(void);
extern int sys_getgid(void);
extern int sys_getppid(void);
extern int sys_setuid(void);
extern int sys_setgid(void);
#endif // CS333_P2
```

14. ps.c (file baru)

```
#ifdef CS333_P2
#include "types.h"
#include "user.h"
#include "uproc.h"

#define MAX 16
int
```

```
main(void)
 struct uproc *proc = malloc(sizeof(struct uproc)*MAX);
 int proc num = getprocs(MAX, proc);
 printf(1, "PID\tName\t\tUID\tGID\tPPID\tElapsed\tCPU\tState\tSize\n");
 int i;
 for(i = 0; iiii<+){</pre>
   struct uproc current proc = proc[i];
   uint elapsed_ticks = current_proc.elapsed_ticks;
   uint elapsed s = elapsed ticks/1000;
    uint elapsed ms = elapsed ticks%1000;
   uint elapsed cpu ticks = current proc.CPU total ticks;
    uint elapsed_cpu_s = elapsed_cpu_ticks/1000;
    uint elapsed cpu ms = elapsed cpu ticks % 1000;
    char* zero = "";
    if(elapsed ms < 100 && elapsed ms >= 10)
      zero = "0";
   if(elapsed ms < 10)
      zero = "00";
    char* cpu zero = "";
    if(elapsed_cpu_ms < 100 && elapsed_cpu_ms >= 10)
      cpu zero = "0";
    if(elapsed_cpu_ms < 10)</pre>
      cpu_zero = "00";
   printf(
      1,
      "%d\t%s\t\t%d\t%d\t%d\t%d.%s%d\t%s\t%d\n",
     current_proc.pid,
      current proc.name,
      current proc.uid,
      current proc.gid,
      current proc.ppid,
      elapsed_s, zero, elapsed_ms,
      elapsed_cpu_s, cpu_zero, elapsed_cpu_ms,
      current proc.state,
      current proc.size
   );
 free(proc);
```

```
exit();
}
#endif
```

15. syscall.c (line 112-119)

```
#ifdef CS333_P2
extern int sys_getuid(void);
extern int sys_getgid(void);
extern int sys_getppid(void);
extern int sys_setuid(void);
extern int sys_setgid(void);
extern int sys_setgid(void);
extern int sys_getprocs(void);
#endif // CS333_P2
```

16. syscall.c (line 149-156)

```
#ifdef CS333_P2
  [SYS_getuid] sys_getuid,
  [SYS_getgid] sys_getgid,
  [SYS_getppid] sys_getppid,
  [SYS_setuid] sys_setuid,
  [SYS_setgid] sys_setgid,
  [SYS_getprocs] sys_getprocs,
#endif //CS333_P2
```

17. syscall.c (line 189-195)

```
#ifdef CS333_P2
  [SYS_getuid] "getuid",
  [SYS_getgid] "getgid",
  [SYS_getppid] "getppid",
  [SYS_setuid] "setuid",
  [SYS_setgid] "setgid",
  [SYS_getprocs] "getprocs",
#endif //CS333_P2
```

18. syscall.h (line 26-30)

```
#define SYS_getuid SYS_date+1
#define SYS_getgid SYS_getuid+1
#define SYS_getppid SYS_getgid+1
#define SYS_setuid SYS_getppid+1
#define SYS_setgid SYS_setuid+1
```

19. sysproc.c (line 112-148)

```
#ifdef CS333_P2
int
sys_getuid(void)
 return myproc()->uid;
int
sys_getgid(void)
 return myproc()->gid;
int
sys_getppid(void)
 if(myproc()->pid == 1)
   return myproc()->pid;
 return myproc()->parent->pid;
int
sys_setuid(void)
 int tmp;
 if(argint(0,&tmp) < 0 || tmp > 32767 || tmp < 0)
   return -1;
  myproc()->uid = (uint)tmp;
  return 0;
int
sys_setgid(void)
 int tmp;
  if(argint(0,&tmp) < 0 || tmp > 32767 || tmp < 0)
   return -1;
  myproc()->gid = (uint)tmp;
  return 0;
#endif
```

20. time.c (file baru)

```
#ifdef CS333_P2
#include "types.h"
#include "user.h"
```

```
int main(int argc, char *argv[]){
    if(argc == 1) {
      printf(1, "(null) ran in 0.00\n");
    } else {
      int start = uptime();
      int pid = fork();
      if (pid > 0) {
        pid = wait();
      } else if (pid == 0) {
        exec(argv[1], argv+1);
        printf(1, "ERROR: Unknown Command\n");
        kill(getppid());
        exit();
      } else {
        printf(1, "ERROR: Fork error return -1\n");
      int end = uptime();
      int timelapse = end - start;
      int seconds = timelapse/1000;
      int ms = timelapse%1000;
      char *msZeros = "";
      if (ms < 10) {
        msZeros = "00";
      } else if (ms < 100) {
        msZeros = "0";
      printf(
        1,
        "%s ran in %d.%s%d\n",
        argv[1],
        seconds,
        msZeros,
        ms
      );
    exit();
#endif // CS333 P2
```

```
#ifdef CS333_P2
uint getuid(void); // UID of the parent process
uint getgid(void); // GID of the parent process
uint getppid(void); // process ID of the parent process
int setuid(uint); // set UID
int setgid(uint); // set GID
int getprocs(uint max, struct uproc* table);
#endif // CS333_P2
```

22. usys.S (line 34-38)

```
SYSCALL(getuid)
SYSCALL(getgid)
SYSCALL(getppid)
SYSCALL(setuid)
SYSCALL(setgid)
```

23. defs.h (line 1-3)

```
#ifdef CS333_P2
#include "uproc.h"
#endif
```

24. defs.h (line 130-132)

```
#ifdef CS333_P2
int getprocs(uint max, struct uproc* upTable);
#endif //CS333_P2
```