

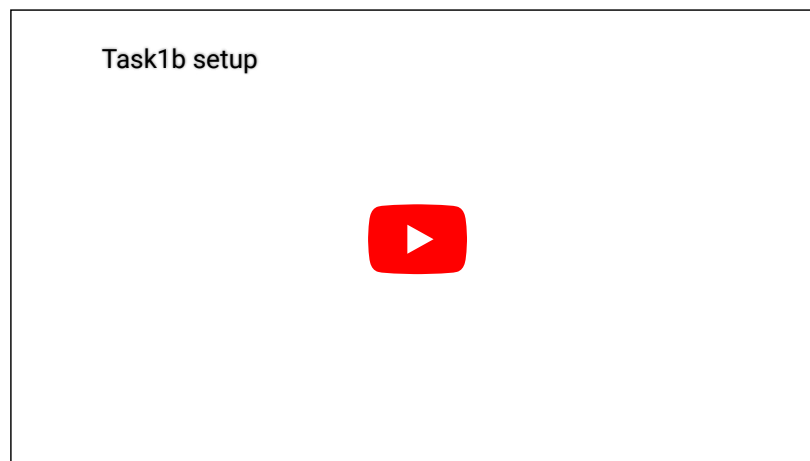


## Task 1B Setup simplified

We have modified how the initial setup is done for Task 1B, since many are facing difficulty in setup we want to ease this problem so they can focus on the main problem statement more.

Instead of creating the workspace and directory structure, you can clone the setup. Below is the link for github repository

Setup video:



```
cd eyrc_hb/  
git clone https://github.com/eYantra-Robotics-Competition/eYRC-2023_Hologlyph_Bots.git  
cd hb_task1b_ws  
colcon build  
source install/setup.bash  
ros2 launch hb_task_1b gazebo.launch.py
```



Now,

- you can add 2 more wheels by following the Task section of [Creating the package and Robot Description](#) page. (frankly this is kinda optional)
- more importantly create the controller for go to goal by following [Controller](#) page.

