$$m:=Y_{x,i}$$
 $u_i-(u+\theta_{m,i})$ $m:=i=1,2,...N$

$$P_i=Y_{k,i}$$
 $w_i-(u+\theta_{p,i})$ P_i
At steady state, m_i , $p_i=0$

$$\Rightarrow Y_{x,i} U_i = (u + \theta_{m,i}) m_i^*
Y_{L,i} W_i^* = (u + \theta_{p,i}) p_i^*$$

$$m_i^* = \frac{Y_{x,i}u_i}{u + \theta_{m,i}}$$
, $m_i^* = K_{x,i}u_i$ $K_{x,i} = \frac{Y_{x,i}}{u + \theta_{m,i}} = 0.575$ (nmol/grw)

$$P_i^* = \frac{Y_{\nu,i} \, \omega_i}{M + \Phi_{P_i} i} - \Phi$$

Put @ in O

$$=) P_{i}^{*} = \underbrace{Y_{X,i}(\overline{U_{i}}(K_{t,i}R_{t,T})(\overline{U_{i}})}_{T_{L,i}K_{L,i}(M+\theta_{P,i})(M+\theta_{m,i})}$$

ろ, b)

$$P_i^* \simeq K_{x,i} K_{1,i} U_i U_i^* = \left(\frac{Y_{x,i}}{u_{+} \theta_{m,i}}\right) \left(\frac{k_{bi} R_{l,T}}{\tau_{l,i} K_{l,i} (u_{+} \theta_{l,i})}\right) U_i W_i^*$$

=> Using data and file from Prelim 1,

the plot will be shown by using Jupyter notebook
(python)

(uploaded on Github)