Rideshare Automatic Matching SystemRidematching Android app utilizing aSTEP

Project Report SW605F16

Aalborg University Department of Computer Science



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Aalborg University http://www.cs.aau.dk

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STUDENT REPORT

Title		
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Project Title

Theme:

Scientific Theme

Project Period:

Spring Semester 2016

Project Group:

SW605F16

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Copies: 1

Page Numbers: 45

Date of Completion:

April 27, 2016

Abstract:

Here is the abstract

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Preface

Here is the preface. You should put	your signa	atures at the end of the preface.
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Chapter 1 Introduction

Commuters are causing traffic jams in dense areas traveling similar routes, this project embarks the task of informing the individual commuters of other commuters traveling a similar path, so that they could share vehicle. A such task also seeks to reduce the commuters impact on the environment.

1.1 Project environment

This project is part of a collaboration project, and Spatio-TEmporal data management Platform (aSTEP), of the SW6F16 semester. The semester goal is to develop a location based service with accompanying applications that utilizes the service.

The aSTEP project is developed in 10 teams in the span of 4 sprints. The sprints are synchronization points of the project groups, and this report will contain documentation of each sprint chronologically. There are four sprints in the project period. The first sprint is analysis and collaboration development, the second and third are development sprints, and the fourth is intended for test and finalization. The 10 project groups are assigned to their respective tasks, with 7 project groups developing the core aSTEP service, while the remaining 3 are developing applications utilizing the system.

1.2 Problem domain

The problem domain of this project is to design and develop a solution which utilize the aSTEP system, and can identify and help drivers and passengers with arranging ridesharing. The solution's goal is to provide ridesharing suggestions to the users of the solution. When referring to the term ridesharing in this report, it is referred to as the action of private persons sharing a car for the whole or a part of a route. This definition is covered by the terms carpool and ad hoc ridesharing by doi:10.1080/01441647.2011.621557.

The intention of this project is to produce a android app that utilizing the aSTEP system and based on historical location data should ease the possibility of using and arranging carpool-style ridesharing.

The scope of such a project can be large and therefore it is chosen early to that the main focus will be to design and implement the basic system which then later can be expanded on. This focus revolves around develop and implementing an algorithm that can be utilized to asses if two users of the system should be paired for ridesharing. Hence the purpose of the application will be to propose appropriate candidates for ridesharing. Furthermore, other parts of the application such as graphical user interface is not prioritized, but is developed to be functional enough for test and practical purposes.

Such an application could be beneficial for the users in several ways. There could be environmental and economical savings, as the number of polluting cars driven is reduced as described in [doi:10.1080/01441647.2011.621557]. The application would ideally decrease trafical problems such as traffic jam and thereby also being timesaving, and causing less frustration for the drivers.

There are some potential for both social, environmental and economical benefits, as the app allows people meet each other and thus reduce the use of cars, gasoline and the load on the road system.

The future aspect of this solution seem bright since it easily should modified to work for autonomous vehicles.

To define the actual problem, as to initiate the research and development, a concrete formulation is made.

1.3 Problem Statement

Sharing rides is advantageous in economical and environmental sense, but it is made tedious and difficult due to the lack of knowledge of other people sharing the same or similar commute routes as explained in [doi:10.1080/01441647.2011.621557]. This leads to the following problem statement.

How can one design and develop an app that automatically suggests ride sharing companions, based on common locations in origin and destination, utilizing the aSTEP platform?

The problem statement is split into several requirements in different areas.

1.4 Requirement Specification

To provide a clear direction of the solution and to state the success criteria, this section contains the requirements for the solution. The requirements are divided into two main categories: functional and nonfunctional requirements. The requirements are sorted in the MoSCoW structure, enabling the project group to solve the highest prioritized requirements first, hence developing a solution that fulfills the core purpose before adding additional functionality.

add reasoning and source of MSCW categories + functional/non-functional

1.4.1 Functional requirements

Functional requirement are requirements directly related to the tasks and operations of the developed application.

Must-have requirements

These are the requirements the solution must fulfill to be acceptable.

Graphical user interface

The application must have a graphical user interface (GUI), as user must be able to operate the application them selves. The GUI must be intuitive, as user may have different experience with using mobile applications.

User accounts, including login and registration.

Unique user accounts is required as it serve as a identifier for each user, using the system. With user accounts, store personal information, and compare user based on the data. It will also provide function for displaying user to other users.

Communication with the aSTEP core.

As the project is a part of the bigger system aSTEP, there mush be a relation to the developed platform. The communication would be storing data in the aSTEP database and using user management also implemented on the platform.

User location tracking and storage.

As the application must track users as they move around, location sensors must be polled, usually GPS. The application should track users commute. This data should be stored in the aSTEP database.

Automatically determine regular routes.

Automatically determine regular routes the user take. Regular routes should be saved for later comparison. Discarding routes that are not used often.

Automatic ride sharing recommendations.

A automatically comparison with other users routes must be computed. When two

regular routes are found similar, each user must be notified of such, whiteout any user input.

Should-have requirements

The requirements in this subsection are requirements that are important, but not regarded as highly critical.

Give the user option to specify wherever they have a car or not.

Some users might not have a car, and that should be considered as people whiteout car would need to be treated differently from those who have.

Enable user to blacklist other users.

Giving they are frequent users of the application, and have a bad experience with either a driver or passenger, they should be able to blacklist them.

Suggest rides with user who only drives a subset of the way from A to B.

Giving users the option to drive with people who do not have the same source and destination, will increase the pool of which users to suggest, as user can tag alongpart of the ride.

Could-have requirements

These are the lowest realistic requirements.

Ride reservation or request from, to, time.

Reserve rides with other users. This includes both regular commutes and commutes users would do rarely.

Would-have requirements

The following requirements are only considered when all other requirements are satisfied, but initially regarded as tasks to be solved in future projects.

Inform users of their environmental and economical savings due to their use of the solution. Provide detailed information of how much fuel users save, how much money saved based on fuel prices, and how much CO2 that is not released into the environment.

1.4.2 Non-functional requirements

The nonfunctional requirements for the solution are stated here.

Must-have requirements

These are the requirements the solution must fulfill to be acceptable.

Development cooperation with the other aSTEP project groups.

The development of the app must be done in cooperation with the other aSTEP project groups.

1.4. Requirement Specification

User privacy

The application must respect user privacy, especially in regards to whom have access to a user location data and general user data. A solution will be developed in collaboration with other groups of the aSTEP project. The solution should consider elements such as, database storage, user management and other developers.

Should-have requirements

The requirements in this subsection are requirements that are important, but not regarded as highly critical.

Aesthetics matching other aSTEP project applications

The application must be of the same design and guidelines as the other applications developed for aSTEP.

Could-have requirements

These are the lowest realistic requirements.

Placeholder

find requirement

Would-have requirements

The following requirements are only considered when all other requirements are satisfied, but initially regarded as tasks to be solved in future projects.

find requirement

Chapter 2 Group Role

The aSTEP is a multi-group semester project, and consists of several parts. This project group is responsible for developing an app that utilizes the aSTEP core, and contribute to the development of the interface of the core.

Insert some shit figures of the aSTEP core structure draft.

Chapter 3 Sprint 1

The first sprint concerns with getting the project started, both the aSTEP project as a whole and the ridesharing project described in this chapter. Thus the first sprint will be spent on organizing the collaboration with the other project groups and setting the direction for the project. This means that the two contributing parts of sprint 1 will be the initial analysis and overall design.

3.1 Analysis

Ridesharing is an activity which has had phases of popularity in recent history according to doi:10.1080/01441647.2011.621557. They describe the current phase as the technology-enabled ridematching phase which started in 2004. In this phase, the integration of the internet, mobile phones, and social media into ridesharing services reduces the barrier to entry for new potential passengers and drivers. doi:10.1080/01441647.2011.621557 also list incentives for ridesharing in the current phase, which are the following

- "Focus on reducing climate change, growing dependence on foreign oil, and traffic congestion
- Partnerships between ridematching software companies and regions and large employers
- Financial incentives for green trips through sponsors
- Social networking platforms that target youth
- Real-time ridesharing services" [doi:10.1080/01441647.2011.621557].

This presents a broad overview of why ridesharing became popular again after 2004. Because technologies play a vital role in the current phase, a selection of popular commercial services will be examined a long with some scientific papers to get a comprehension of the state of the art in the field. The main focus of this project will be on real-time and dynamic ridesharing which **amey2011real** defined as "rideshare service relying heavily on mobile phone technologies".

3.1.1 Scientific Papers

The problems of automating ridesharing through modern technology has already been studied with different approaches. The following sections account for some of which the project group found the most interesting and relevant to the problem statement.

doi:10.1080/01441647.2011.621557, amey2011real sees technology as one of the most important factors in the present and future of dynamic ridesharing.

ShuoMa2013 developed an algorithm for taxi services and improved throughput of passengers by 25% and reduced the distance a single taxi had to drive by 13%, at six requests for rides per taxi. Especially interesting in their paper, is the approach of a grid representation of a road network, to avoid shortest path calculations between points on a map, and instead approximate distance based on cells in the grid. The paper states that the solution also utilizes the user's smartphone to collect location data and act as a user interface.

ghoseiri2011real researched what properties might matter when matching driver and passengers. They focused on preferences which influence whether you want to drive with a person or not. The preferences can be properties such as gender or pet friendliness. They developed functions that can assess if a passenger and driver match, based on location, preferences, passenger and/or driver detour as the most important factors [**ghoseiri2011real**]. This algorithm might be useful in this project solution.

Actual choices and influences regarding algorithm design for ridematching will be addressed in the design phase in Section 3.2.

3.1.2 Commercial Solutions

Corporate and community solutions are quite different from the academic field solutions. The main focus seems to be centered more around taxi alternatives. The are plenty of services around the world, with the two biggest international services in this field as of 2015 seems to be Uber and Lyft[ridehail]. There are also several services with some or all of their focus in Denmark, most notable is services like <u>Haxi and Drivr</u>. These services work mostly in a similar way:

- 1. A customer request a ride through an smartphone app or a web interface
- 2. The backend of the service sends the request to one or more appropriate drivers
- 3. A driver accepts the request, and dispatches

Since the mentioned services are commercial and closed-source, actual information about the service's design or architecture is not available. Drivr has two interesting feature in comparison to their opponents, that is a web interface for fleet manage-

source

ment and business which provides administration and expense control of employee taxi travels.

Besides these taxi-like services, there also exist services that focus on traditional ridesharing between private people, where money is not earned. Here exist both local and international services. These services give the opportunity to either offer a lift, request a ride and the possibility to connect drivers and passengers. These services are usually free, but some of them charge a small fee when connecting people. Some of the more notable are GoMore and iRideshare.

source

The smartphones have automatized much of the labor concerning organizing ridesharing and act as a central component in the analyzed systems. However, we still see an opportunity to utilize the smartphone even further in a service that arranges rides between users, thus decreasing the actual required user actions.

add arguments

3.2 Design

The temporary design is based on the preliminary analysis of sprint 1, and will outline the main features of the design, concerning system structure and components, and the user interface.

add metatext

3.2.1 System design

This section contains documentation of the system design, consisting of the structural and behavioral design.

add metatext

Structual Design

The overall structural design of the system is based on the analysis of the first iteration.

To exploit availability of sensors on the mobile phone and computational power of the server, the system is developed in two parts: the phone application and an extension of the route system in the aSTEP system which handles the analysis and comparison of routes. The two parts have their own delegated responsibilities, and will perform the necessary tasks, enabling the system to deliver the service.

define solution service in analysis/problem?

The application, hereafter referenced as the app, is the program executed on a mobile device, and will gather location data and serve as the user interface.

The solution is assumed to require much processing power and to access location data to analyze the possible combinations of routes. Computing the route combinations in an app would require that each user has a copy of every other users' routes. This is a serious privacy concern as this would enable other applications to leach on to the aSTEP system a gather data about when people are home and where they live. Other concerns include, for calculating the best routes a lot of processing is required draining the battery and producing heat.

clean up battery and privacy references

When under the assumption that a central server can handle the analysis of the routes, the application need only to supply the server with location data to analyze.



Figure 3.1: The overall structure.

A background service would enable the location data sampling and transfer to a server. As seen in Figure 3.2 the Observer class' main goal is to observe what activity the user is currently doing. In Google's API for android applications this is already a feature, so this will be used. If the activity is driving, the background service starts to store the locations with the RouteBuilder class. Locations are also a part of Google's API and includes longitude, latitude and a time stamp. When the Observer detects that the user stops driving, the Observer sends the route to the server.

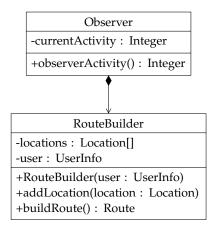


Figure 3.2: The small process which should run at all time to build the routes.

On the server, the route is stored in a database and accessed by the RouteStabilityAnalyser. This analyzer takes the route and compares it to other routes by the same user, to determine whether this route is a regular occurrence, and hence a stable route.

If the RouteStabilityAnalyser determines that the route is stable, the information is

stored in the database with when this route is expected to occur. The server then uses the RouteSimilarityAnalyser to find matches for the new <u>StableRoute</u>. The matches are stored and new matches are transmitted to the appropriate devices to inform the users of a new match.

does not need to be a new stable route??

fix: "This package should be an isolated system within the server."

The application acts as an interface to the background process for the user. This is where the user logs in and can see an overview of candidates for car pooling.

This is the start of a project that will be further developed upon and expanded in the future, emphasizing the importance of reusing the server, to reduce the amount of specialized server resources. By isolating parts that are specific to the rideshare app on the server, most of this system would be reusable. The best example of this is the RouteAnalyser from Figure 3.3. The RouteAnalyzer filter routes according to its concrete implementation. After the filtering, the RouteAnalyser uses the strategy pattern to determine how to compare the routes. This enables other projects to develop their own filters and comparison functions in later projects.

To reduce the search space, a weekly stability was decided upon. This means that the RouteStabilityAnalyser can be limited to analyze one to two months of data. This will be further tested and evaluated in another chapter.

did we?

reference to test and evaluation

add arguments

3.2.2 User Interface Design

The user interface (UI) provides interaction methods between the user and the app. As the priority of this project is functionality with regards to data collection and route generation and comparison, the UI will not be developed together with users, nor allocated excessive resources. The UI is developed for practical purposes, like testing, and to lay the basis for further development, but is still held to some standard which will be documented in the following text.

Design language

The design language is the general look and appearance of a system. This is the foundation for the impressions and feels of the user, and affects the user experience. The design language is selected in collaboration with another aSTEP project group, SW604F16.

The user interface is designed to achieve the following usability characteristics [DIS2014]:

Learnability

- Utility
- Safety
- Effectiveness

The UI is designed to comply with the Google's Material design guidelines [materialDesign], being "bold, graphic, intentional". Some of the Material design properties are stated in the following list, compiled of citations from the design guidelines [materialProperties]:

- 1. Material has varying x & y dimensions (measured in dp) and a uniform thickness (1dp).
- 2. Material casts shadows. Shadows result naturally from the relative elevation (z-position) between material elements.
- 3. Content is displayed on material, in any shape and color. Content does not add thickness to material.
- 4. Input events cannot pass through material.
- 5. Material cannot pass through other material. For example, one sheet of material cannot pass through another sheet of material when changing elevation.
- 6. Material grows and shrinks only along its plane.
- 7. Material never bends or folds.
- 8. Material can be spontaneously generated or destroyed anywhere in the environment.

Adhering the material design guidelines makes the app achieve a similar aesthetic and usage method as other apps in the Android eco-system. The design language aims to make the interface clean and simple, regarding colors and input methods.

User interface

The design drafts in Figure 3.5 reflect the necessary functions and the previously described design language.

As the user needs a user profile in the aSTEP system to use the app, the users must be able to login if they already have a user profile, or create a new user profile.

Several views are necessary to support the different parts of the app. The app needs a view for login, registering, presentation of matches, and a settings screen, as can be seen in the figures in Figure 3.6.

3.2. Design

As the application must have communication to the aSTEP server, which have an requirement of registration of users, it is necessary to have a register and login screen in the application. The username will be used as a identifier for the user, and it will be used both for the aSTEP server, but also for the application it self. It will be the identifier to differ between each user, and ensure users are matched up with other users correctly when comparing routes.

The application must have a main screen, and it is chosen that should be the route match list. On this screen the user will be presented a list of other users, which most likely is a good match. The users listed should be in an descending order, with the highest rated match at the top. A short description about the users and match should be displayed, such as the users full name, phone number, the match score, and what day of the week the user drive the relevant route.

A settings screen is needed because the users should have the option to change there initial information from when they registered. The settings screen also server as a screen where users can specify their preferences. Such information is, wherever the users have a car with X numbers of seats and if the users is looking for, or giving a lift. In addition should there exist a navigation drawer from where the user can navigate around the application.

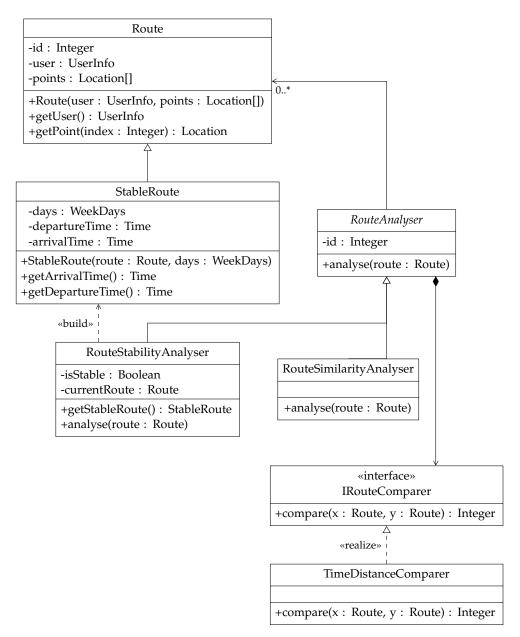


Figure 3.3: The structure of the system inside the server. This package should be an isolated system within the server.

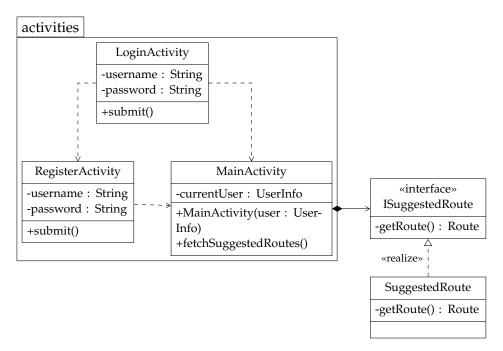


Figure 3.4: The class structure of the application.

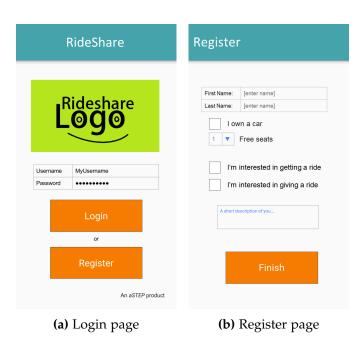


Figure 3.5: Draft of the login and registering pages of the app.

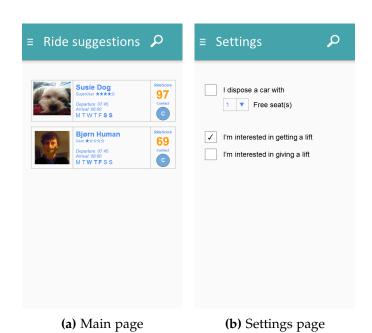


Figure 3.6: Draft of the views in the app.

Chapter 4 Sprint 2

Whereas the main topic of sprint 1 was an overall analysis and collaboration agreement, the topic of sprint 2 is design and development based on the results of sprint 1. The sprint intentions are to develop a route comparison algorithm that can be implemented in the aSTEP system, and to develop an app that has basic functionality, to be advanced and improved upon in sprint 3.

This chapter contains documentation of the analysis, design, implementation and test phases of the algorithm and app development performed in sprint 2.

4.1 Analysis

This section contains the analysis of app functionality, Android app development, Rideshare Automatic Matching SYstem (Ramsy) algorithms and communication with the aSTEP system.

4.1.1 App functionality

The app user interface is a low priority task during this project. However, the app needs basic functionality, according to the requirements.

To be able to separate different routes, and to assign them to their respective users, there has to be a user management system, so that each user has its own ID.

The user should also be informed with relevant information of ride matches, so that the user can make a decision of sharing a ride or not.

The user of the application should also be able to adjust their settings. The settings are preferences regarding different properties of ride sharing. The user should be able to decide if it wants to get a ride or give a ride or both. There are also properties of the user itself, like a description and a picture, that other users can access to decide if they want to share a ride with the named user.

4.1.2 Android Development Platform

When developing Android applications one of the first choices to consider is which API levels to target [usesSDK]. The "API Level is an integer value that uniquely identifies the framework API revision offered by a version of the Android platform." according

to Android Developers [usesSDK]. The distribution of the Android version levels are shown in 4.1.

"The manifest file presents essential information about your app to the Android system, information the system must have before it can run any of the app's code.", according to Android Developers [androidManifest]. The manifest requires to specify the API level for three definitions: minimum, target and maximum. The target and max versions requires few consideration to determine. The "targetSdkVersion" reflects the version to which the app is developed and tested against, without enabling compatibility behaviors. The "maxSdkVersion" reflects the highest API level that an app is designed to run. Both of these are set to the highest API level available during the start of the development, which is API version 23.

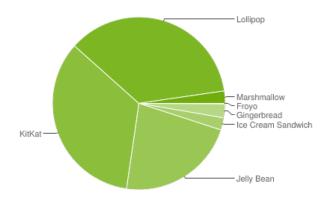


Figure 4.1: Android version distribution, March 2016 [androidDashboard]

The last API level which needs to be specified is the "minSdkVersion". This entry specifies the lowest API level which an app supports. A cause of this is that every device with an API level lower than the specified minSdkVersion will not be compatible with the app. Supporting older API versions requires development efforts, typically implementing functionality though the Android Support Library [androidSL]. For this project we choose to target a higher API level for to simplify the development process. At the time of writing, the platform version distribution sum of API levels greater than or equal to 21 (Android Lollipop) is 35,3%. API version 21 is chosen as the minSdkVerison, the main reason for this choice is to minimize development time for user interface, as API level 21 added support for Android's new material design style [android5API]. Refraining from further backwards compatibility allows the project focus to be on the functionality of the app.

4.1.3 Periodic Tasks

When the app is installed the program needs to run a task periodically to cache locations. **friesen2015android** writes about how this can be done in the Android API with the AlarmManager and the JobSchedular.

AlarmManager In the first Android version (API 1) the AlarmManager was created to handle alarms. They implemented it as a general class which can call any task after a given period has passed. The alarm can then be set to be reoccuring which means that we can use this to cache location data in a set interval.

JobSchedular In Android 5.0 (API 21) an alternative to the AlarmManager was implemented, the JobSchedular. This functions in a similar way as the AlarmManager, but tries to bach the jobs together and fire them at the same time. This means that the device can save power by avoiding going to sleep just to wake a short moment later. The sacrefice is precision. While the AlarmManager has the option to occur at a exact time, the JobSchedular does not. This is needed to give the AlarmManager enough control to effeciently bach the jobs together.

Because the timing of the location data is less important than the constant stream of data the JobSchedular. This has the advantages of saving power making it more likely that the device will stay powered for the duration of the trip. And by extention giving a complete route.

Something is missing

4.1.4 Algorithms for ridesharing

4.1.5 Communication with aSTEP

To be able to utilize the aSTEP system, the communication protocol and functions must be analyzed. The analysis is based on the current development and planning of the API and other functions.

The status and intended functions are established in collaboration with the other project groups responsible for the aSTEP system side of the development. The main groups we are involved with are the user management group and outdoor location based services groups.

The design of the aSTEP system at this point is consisting of an API that apps and services can communicate with, and a backend with user management and location based services, which is stored in a database system. However, the only

LBS	UM
GetAllEntitiesInArea	Create user
GetAllEntitiesInTimePeriod	Get token
Get All Group Memebers Location And Name	Update password
GetAllFriendsInArea	Edit privacy settings
GetAllFriendsInRadius	Allow user2 to access user1's info
GetAllGroupMembersInArea	
GetAllGroupMembersInRadius	
PostLocationData	

Table 4.1: Currently planned aSTEP API functions.

relevant part for the Ramsy solution for us is the API, as the lower level of the aSTEP core is administrated by other groups.

The aSTEP system will store information regarding location data, and basic user information. The data stored in the aSTEP system, relevant to this project solution, is:

- Location data consisting of userID, routeID, a set of GPS coordinates and timestamp.
- Username
- Password

The aSTEP user management system does not provide storage of data regarding contact information for aSTEP users. The only information stored is a username and password to keep the aSTEP core as simple as possible. Additional information that is required to make the app work as intended is each of the app groups own responsibility. The aSTEP users is made to ensure the correct permissions is giving to the correct user, to ensure the appropriate data is returned to each user. An API call can not be done without the user first being authenticated with a valid login.

The communication with aSTEP is done through a REST API over Hypertext Transfer Protocol, decided in agreement between the aSTEP project groups. REST is an abbreviation of REpresentational State Transfer, and is a communications design often used in for HTTP-communication[REST]. Accordingly, the communication is performed by making queries to the aSTEP system. All communication must be done as a request from the device, where the aSTEP server then will respond.

At the current stage of the development of aSTEP, the following API functions are available form user management and location services:

When using the aSTEP API it should be ensure to use the correct calls in the right

reference this table. Add information about the functions.

way. The API is providing a POST-request under the name "PostLocationDat", as listed in 4.1, which is the method to use when sending location data to the aSTEP core. When using this POST it is important to ensure the correct parameters is used. The call will accept location data as an coordinate consisting of longitude and latitude, a precision value, and a value representing time of day in milliseconds.

4.1.6 Requirements for the second sprint

Sprint two is the first of the two middle sprints that have implementation as the primary focus. In this section, the main issues to be solved in the current iteration will be presented.

Route Matching Algorithm

In this sprint, the algorithm for comparing routes must be researched and developed. It should be developed to an extent so that it is constructed as pseudocode of the algorithm, to be handed over to another aSTEP group, and be implemented in the aSTEP system.

User Data

User information such as username, password, and login token, must be analyzed to figure out where this information should be stored, and how it should be handled regarding communication between the application and the aSTEP server.

RideShare app

A base for the functionalities for the Ramsy application should be implemented. The implementation should include a working including of the Google Play Services and the application should be able to collect and store location data. The application should also have functionality to run as a background services, so that location data can be collected at all times.

System Architecture and Communication

Communication between the Ramsy application and aSTEP server should also be researched and an implementation of the communication should be initialized in this iteration, ensuring the next iteration will have a base for communication. It should be considered how to handle storing the collected location data and how much should be stored where, either on the device or on the aSTEP server.

Mock Data

If there is spare time during the sprint, it should be considered to acquire mock up location data related to mock up users. This data could be used in the third iteration to test if the algorithm works as intended.

4.2 Design

This section contains documentation of the design of the rideshare solution. The parts to be designed in this sprint are the overall system design, reflecting the changes in the aSTEP system, and the algorithms to generate stable routes and route matches.

4.2.1 System design

In the first iteration, the Ramsy system was designed to consist of two parts: The Ramsy app and the aSTEP system. Because the aSTEP does not provide the anticipated services, such as storing basic user information, this data must be stored elsewhere. This forces a redesign of the system. This section contains descriptions of the redesign of the different parts, and a definition of their respective responsibilities.

The aSTEP system still provides the functionality to store locations and route history for users. The Ramsy app continues to collect device location data. The Ramsy solution will need additional data storage to fulfill the defined system requirements, because the Ramsy users need to be able to contact each other, to make the Ramsy app usable.

The aSTEP system is supposed to be kept as generalized and modular as possible, and when combined with the lacking user information storage, app specific data could also be stored together with the user information. The app specific data is information, such as match scores between routes.

A solution that we regards as appropriate for the task is using a custom solution server, to utilize together with the Ramsy app and aSTEP system. The Ramsy server could store the extra user data and connect the user to the aSTEP user ID, so that each Ramsy solution user has a unique aSTEP user, with contact information stored on the Ramsy server.

The Ramsy server has two main purposes. Firstly, to store additional information about the system users, and secondly to store the score for previously assessed scores between given stable routes. The different purposes and responsibilities of the parts depicted in Figure 4.2 will be elaborated in the following text.

The Ramsy application continues to be responsible for the interaction with the user as well as collecting the location data needed to track routes and recommend ride partners. The app communicates with both the Ramsy server and the aSTEP server through their respective API's.

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4.2. Design

The API and server associated with the aSTEP system will be responsible for saving and retrieving location and route data for each user in the system. The aSTEP system is also responsible for the basic user profile, consisting of a userID and a password. A user profile is used to identify location data, and to store other users' permissions to access the actual user's location data. The Ramsy server will be used to store additional information regarding users and routes. The user information that will be stored, is the additional contact information.

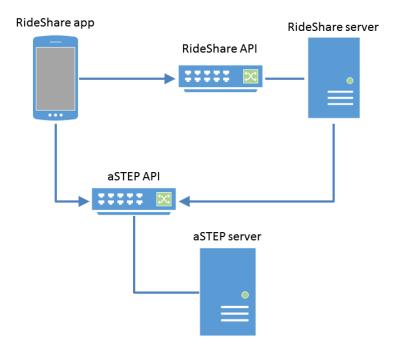


Figure 4.2: System design, including all major parts of the solution.

Beyond storing scores for route matches and additional user info the Ramsy server will also be responsibly for sending request to the aSTEP server, concerning calculations about stable routes and route matches. To be able to gain access to each user's location data from aSTEP, the Ramsy server has to store some sort of login information. The aSTEP system provides a login token, so that a password does not need to be stored on the Ramsy server.

The final system design developed in the second iteration, described in this section, can be seen in Figure 4.2.

User	Departure	Arrival	Distance
Alice	07:20	07:55	36.5 km
Bob	07:35	07:50	14 km
Carol	08:05	08:30	15 km
Eve	07:30	07:50	18 km

Table 4.2: The four users departure and arrival times as well as their distances.

4.2.2 Algorithm

The system uses a custom developed algorithm to determine whether two routes are a good fit. This algorithm is loosely based on a simplified version of **ghoseiri2011real**, with regards to the process of the evaluation of a match. In the paper, the algorithm considers multiple aspects when assessing matches, such as smoking, gender and age preferences. The criteria are practical to some extent, but the focus of the Ramsy system are the time and distance criteria. A position is spatial-temporal, whereas a location is a spatial point and a time is a temporal point. A route is a chronological list of positions. A disadvantages of the algorithm presented here is that the distance is calculated as a euclidean distance rather than a map distance. This would be a obvious place for future improvements to the algorithm.

To illustrate how the algorithm should work for different routes an example is introduced. The example can be seen in Figure 4.3. The example introduces four

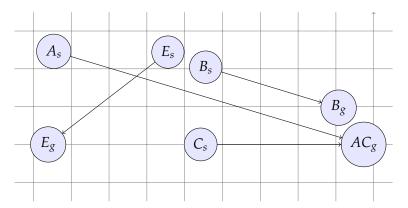


Figure 4.3: Alice, Bob, Carol and Eve's stable routes. Each grid represent a 5×5 km area.

users, each with one stable route in this example. In addition to the location of their routes, we also have their departure and arrival times that can be seen in Table 4.2.

For this example, the goal will be to find out if any route matches with Alice's route $\{A_s - A_g\}$.

Time Distance Analyser Algorithm

To serve as an example, the algorithm should assess the score of The outcome should be a score representing if Alice, on the way through route r, picking up person should pick up some of the persons Bob, Carol or Eve, for each of their routes.

The score

The expected outcome is Bob will match reasonable in both distance and time difference and hence be given a score indicating a match. Carol is expected to match reasonable in distance as well but will lack a match comparing travel times and therefore not produce a match. Comparing with Eve a somewhat match on time is expected while the distance will be way off. The score represents the match of the routes of Alice and each of the other, and should be expressed as a decimal value from 0 to 1 which tells how good the match is. 0 represents a bad match, a major detour or not compatible times, and 1 represents a perfect match, and requires no detour. A comparison will be made for r_1 against r_2 . To summarize, the algorithm takes a route r and two positions to compare against; start (s), and goal (g) as arguments. The algorithm then returns a decimal value between 0 and 1.

Time Distance Analyser Algorithm

In the algorithm, there are two aspects to be evaluated: Time; time and distance. These are assumed to be evaluated by two sub algorithms that both takes the route and two points as input and return a value from 0 to 1 depending on how closely they match.

If either time or distance is deemed unacceptable they are being assessed a score of 0, thus the whole match is unacceptable and given the a final score of 0. From the scores of the sub algorithms, the final score can be expressed as the average score $\frac{d+t}{2}$, where d is the distance score and t is the time score. To increase flexibility of the algorithm, two constants are introduced d_{γ} and t_{γ} . These constants enables weighting of the time and distance score independent of each other by expanding the expression to $\frac{d\times d_{\gamma}+t\times t_{\gamma}}{d_{\gamma}+t_{\gamma}}$.

For our example we simply set both d_{γ} and t_{γ} to 1.

The final algorithm can be seen in Algorithm 1. Line 2 and 3 are calls to the algorithms that solve the subproblems of scoring the time and location, and line 4 to 8 is the logic described in the previous paragraph.

Algorithm 1 Time Distance Analyser Pseudocode

Require:

```
let d_{\gamma} be the modifier for distance in \mathbb{R}_{>0}
let t_{\gamma} be the modifier for time in \mathbb{R}_{>0}

1: function TIMEDISTANCEANALYSER(r, s, g)

2: d \leftarrowDISTANCEANALYSER(r, s, g)

3: t \leftarrowTIMEANALYSER(r, s, g)

4: if d > 0 \land t > 0 then

5: return \frac{d \times d_{\gamma} + t \times t_{\gamma}}{d_{\gamma} + t_{\gamma}}
```

6: **else** 7: **return** 0 8: **end if**

9: end function

The following sections will cover the sub algorithms. First, the distance analyser algorithm will be described, followed by the time analyser algorithm.

Distance analyser

The distance analyser algorithm takes a route and two end points and assesses the score for the detour when only considering the distance. To do this, it is required to define how long the longest acceptable detour should be. The algorithm also needs a way of calculating the distance between two discrete locations, which can be performed by the function for euclidean distances. This leads to the following algorithm, where the symbol $\mathbb L$ is used to denote the set of all possible locations:

$$\begin{aligned} dist: \mathbb{L} \times \mathbb{L} &\to \mathbb{R}_{\geq 0} \\ a, b &\mapsto \sqrt{(a_{latitude} - b_{latitude})^2 + (a_{longitude} - b_{longitude})^2} \end{aligned}$$

The distance analyser algorithm, as seen in Algorithm 2, finds the points on the route that are closest to the start and end points. From those points, the algorithm approximates the detour required to take by the driver to pick up the passenger. The approximation assumes that the driver's new route distance will be the original length plus the distances to the passengers start point and goal point. This assumption does not represent every detour and thus this is an area for future optimization.

Algorithm 2 Distance Analyser pseudocode

Require:

let β be the largest acceptable detour length in $\mathbb{R}_{>0}$

```
1: function DistanceAnalyser(r, s, g)
2: let r_s be the closest point to s in r
3: let r_g be the closest point to g in r
4: d_s \leftarrow dist(r_s, s) \triangleright Pickup detour distance
5: d_g \leftarrow dist(r_g, g) \triangleright Set off detour distance
6: return 1 - \frac{d_s + d_g}{\beta}
7: end function
```

The final score for the distance analyser is calculated by taking the total detour length and dividing it by the length of the largest acceptable detour. This results in a value between 0 and 1 when the detour is less than the largest detour, and greater than one when the detour is longer. The value is inverted by subtracting it from 1 to make greater values better matches, as required by Algorithm 1. If the value is greater than the acceptable detour length, the inversion in the return statement will generate a negative value, hence causing Algorithm 1 to return a result representing no match.

In the example introduced in the beginning of this chapter, the longest detour is set to be 25% of Alice's total commute and Alice's route is modeled as the line $y = \frac{4}{7} - \frac{2x}{7}$. It is assumed that Alice's route have tracking points continuously in the line, and therefore a line to point distance calculation is used in this example, this means r_s and r_g will be calculated simultaneously as the distance is calculated. This gives the the results seen showed in Table 4.3 when applying the distance Algorithm 2.

User	d_s	d_g	return value
Bob	3.57 km	1.85 km	0.550
Carol	4.12 km	0 km	0.609
Eve	9.62 km	4.12 km	-0.505

Table 4.3: The detour distance for Alice compared to the other users as well as the score of the DistanceAnalyser for each route.

Table 4.3 presents the results for the distance analyser. The algorithm assesses the best results for Carol, followed by Bob while Carol yields a negative result since Alice's detour becomes longer than the acceptable 25%.

Time analyser

The time analyser algorithm works similarly to the distance analyser algorithm. It is also designed to take two points and a route as input and to return a score representing the time differences.

When determining time difference two things should be taken into consideration; the detour duration and the existing differences in time. The detour duration can be approximated by multiplying the detour distance with the time it takes to travel a distance unit.

Each position in each driver's route has a timestamp for when the location was visited. This can be used to determine the relative time distance between two points by using the following function:

time:
$$\mathbb{L} \times \mathbb{L} \to \mathbb{R}_{\geq 0}$$

 $a, b \mapsto |a_{time} - b_{time}|$

The calculated detour time and relative time difference enables an approximation of the inconvenience the ridesharing is for the participants in the potential match. From the driver's perspective, the route starts at the normal time minus the detour duration, this is to still arrive on the usual time at the destination. This makes the detour the only inconvenience in regards to time. If the passenger has to arrive earlier than otherwisethe driver, the driver would also have to take that into consideration, thus making the relative time distance the inconvenience in addition to the detour.

From the passenger's perspective, the opposite is true when it comes to the relative time. It is only an inconvenience when the driver must set them off before they need to arrive.

It is also worth noting that if the relative time is the same as the detour time, the only inconvenience for the driver is the detour.

The formula for the total inconvenience when taking both participants into account is then defined as the following:

$$|d-t|+d$$

where d is the detour time and t is the relative time.

Algorithm 3 shows the pseudocode for the time analyser algorithm. Line 2 to 4 is are reminiscent of line 2 to 5 in Algorithm 2 with the difference that it they sums the detours and multiplies the result with the distance to time conversion. Line 5

Algorithm 3 Time Analyser pseudocode

Require:

let δ be the acceptable time difference in $\mathbb{R}_{>0}$ let γ be the translation from distance to time in $\mathbb{R}_{>0}$

```
1: function TIMEANALYSER(r, s, g)
2: let r_s be the closest point to s in r
3: let r_g be the closest point to g in r
4: d \leftarrow (dist(r_s, s) + dist(r_g, g)) \times \gamma \triangleright The total detour time 5: t \leftarrow max(time(r_s, s), time(r_g, g)) \triangleright The largest time difference 6: return 1 - \frac{|d-t|+d}{\delta}
7: end function
```

assigns the greatest time difference between the closest points to t. The reason for choosing the greatest value is to use a pessimistic approach, so that the real delay will not be worse than the calculated.

For the Alice example, defining the speed as constant through the whole route is preferable to keep it—the example more simple. Alice travels 36.5 km in 35 minutes, this gives a pace of $\frac{35min}{36.5km}=0.959\frac{min}{km}$. For this example the acceptable time difference is set to 15 minutes $\delta=15$. The time analyser algorithm is applied to the example with the aforementioned data, the result can be seen in Table 4.4.

User	d	t	return value
	5m:12s		
Carol	3m:57s	35m	-0.75
Eve	13m:11s	18m	0.10

Table 4.4: The detour time and time difference for Alice compared to the other users as well as the score of the TimeAnalyser for each route.

In the results from the example in Table 4.4, it can be seen that Bob receives a relatively high score, while Carol's score is below zero, and Eve is just within the acceptable range.

With the scores from the two subalgorithms, Algorithm 1 is able to assess the matches' final scores. The final results of the algorithm example can be seen in Table 4.5.

The results in Table 4.5 shows that with the set detour limits in distance and time the only compatible match for Alice is Bob with a score of 0.59. Although Carol scored acceptably in distance, the difference in time is unacceptable, scores

User	d	t	return value
Bob	0.550	0.63	0.59
Carol	0.609	-0.75	0
Eve	-0.505	0.10	0

Table 4.5: The result for Alice's match compatibility to the other users calculated by the Time Distance Analyser.

acceptable in the distance analyser, the time difference is unacceptable thus assessed a score of 0. Eve scores below 0 in the distance parameter and is therefore also given a final score of 0.

The two modifiers d_{γ} and t_{γ} were set to 1 in this example, but these modifiers, along with the acceptable detours in time and distance, can be adjusted to adapt scores if the given outputs do not reflect the expected outcomes or the users' actual willingness to share rides in a given situation.

Complexity

Considering the complexity of the three algorithm, the Time Distance Analyser complexity is only dependent on the calls on lines 2 and 3, while the rest of the algorithm is input independent. Line 2-3 are the calls to the two sub algorithms.

In the Distance Analyser Algorithm 2 line 2 and 3 is where the whole route should be iterated through, the complexity of this sub algorithm is O(|r|) where |r| is the number of positions in route r. Line 4 to 6 perform arithmetic operations that run in constant time, and can be ignored when describing the asymptotic notation.

For Time Analyser the complexity is the same as in Distance Analyser because of the similarity of the first few lines and the last lines are simple arithmetic operations. The exceptions are *dist*, *time*, and *max*. *time* and *dist*, which both are described earlier, are considered to be O(1) operations. *max* takes two values, compares them and returns the largest of the two. This is also a constant operation and with that, we can determine that the Time Analyser algorithm is O(|r|).

Thus we have that the main algorithm is O(|r|), the number of locations in a route.

4.2.3 Location

In order to be able to locate a user and to construct routes, it is necessary to collect location data. The location data should only be collected under certain circumstances, such as when the user is driving in a vehicle. Such collection of location data can be done by using already existing services, such as the Google Play Service.

Location data in RideShare is only useful if it is formatted in GPS coordinates, stored in a collection that represents a route from A to B. There are several ways to collect location data. One of them is by developing a component to do so on the android device. Another way is to use already existing services, such as one of the Google Play Services.

To use Google Play Services, a client library much be included in the app, which will communicate via inter-process communication to the Google Play Services which is already existing on every android device. When the application is connected to the Google Play Services, it will automatically receive silent updates regularly, to acquire new features and bug fixes to the used services. This is illustrated in Figure 4.4[GapiOverview].

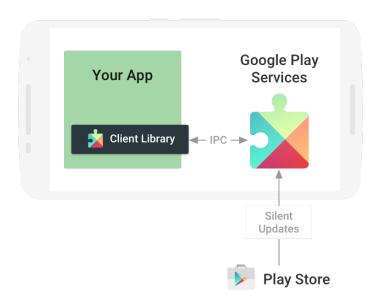


Figure 4.4: Google Play Services communication[GapiFigure]

The Google Play Services are restricted, and are not supporting devices with Android versions lower than 2.3. This limits the backwards compatibility, but the app is already restricted to Android 5 and newer, and has no influence on the target audience.

The Google Play Services will allow the application to collect location data, but it is not doing so solely using the GPS in the device. The location service utilizes both network location and GPS to estimate a position as precise as possible [GapiLocation]. To ensure the collected location data is relevant, it is needed to

store data only when the user is traveling by vehicle. The Google Play Services provides a service to determine the user's activity, called Activity recognition.

Activity recognition is a service that uses several sensors on the device to determine what kind of activity the user is currently performing, therein driving, walking, etc. The service will return a probability level from 1 to 100, where 100 is certain that a user is performing the activity. The activity recognition will be used to prevent unnecessary data will be stored on the database. When a user is in a vehicle with a probability level above 75 %, data should be stored and used for computations.

placeholder

placeholder

The application must be running in the background while the device is turned on, for it to be able to differ between the users activity at all times and collect data. It is chosen only to collect location data from the location services every two minutes, while in a vehicle, to reduce energy consumption. Every location collected during the driving activity must be appended to a list that represents an entire route when the driving activity ends.

When the activity change from vehicle to any other activity, the application will send the list of locations to the RideShare server, where it will take over the processing.

4.3 Implementation

4.3.1 JobScheduler

The JobScheduler was chosen as the scheduler for the background service in Section 4.1.3. The JobScheduler works by scheduling Intents, that are operations to be performed. An Intent that is not yet executed, is called a PendingIntent. When a PendingIntent is finally executed, variables in the systems may have been changed, hence the context might not be the correct, therefore a PendingIntent also requires a reference to the context when it was created. This is performed to ensure that permissions given to the app are still available when the job is executed. A job is a PendingIntent as described in Section 4.1.3 and a set of requirements for when the intent should be executed.

When a job is handed to the JobScheduler, information about the nature of the scheduling is also provided. This includes requirements that needs to be fulfilled before the job can run, how often the job should be executed, and how precise the timing of the job should be.

```
1 JobScheduler jobScheduler = (JobScheduler) getSystemService(JOB_SCHEDULER_SERVICE \leftrightarrow );
```

4.3. Implementation

```
JobInfo.Builder builder = new JobInfo.Builder(1, new ComponentName(getPackageName←
    (), RideShareService.class.getName()));
builder.setPeriodic(10000);
int response = jobScheduler.schedule(builder.build());
```

Listing 4.1: The implementation of jobScheduler.

Listing 4.1 presents the implementation of jobScheduler in the MainActivity of the app.

In the app, the job is implemented as an extension to the JobService class which provides the required interface for the JobScheduler called RideShareService. The class reroutes the call by the JobScheduler to a Handler class. This Handler class, as described by the official documentation [handler], allows the service to send a runnable object to the threads message queue.

The implementation makes the location gathering be performed as a background service every 10 seconds. The interval is temporary, and will serve to test the implementation.

Location Gathering 4.3.2

To get the user location in the background service, the Google Play Services is describe BGS before this utilized. The Google Play Services provides necessary location data, due to the integration on the platform.

First, to retrieve location information, the manifest.xml file must be edited as to acquire permissions to the course and fine location. When the manifest is set up correctly, the actual location retrieving can be performed. This is done by adding the following lines to the manifest:

```
<uses-permission android:name="android.permission.ACCESS_COARSE_LOCATION"/>
<uses-permission android:name="android.permission.ACCESS_FINE_LOCATION"/>
```

The location is retrieved by utilizing the GoogleApiClient, then converted to an aSTEP location format. This prepares the location data to be sent to the aSTEP system.

ensure this is documented

Google API Client

The GoogleApiClient is built and connected to when the JobService is created, hence performed in the onCreate() method, as the JobService thread only exists for the execution time of the contents. The GoogleApiClient is disconnected in the method onDestroy() when the thread is terminated.

The onConnected(Bundle bundle) method is called when the Google API Client is ready. When the client is ready, the getCurrentGLocation(), which can be seen in 4.2, is called, and the returned Android Location is stored in currentGLocation. The current Google location can then be stored in an aSTEP object, that later can be transmitted to the aSTEP system.

Listing 4.2: onConnected()

Get Location

The getCurrentGLocation() returns the last known location, according to the googleApiClient, in the Android Location format. Before the location is gathered, because the target API is 23, the method needs to confirm the permissions required to acquire location data. This is performed on line 6 and 7 seen on 4.3. The device location is gathered through the FusedLocationApi.getLastLocation() method, using the googleApiClient as argument.

```
1
    private Location getCurrentGLocation() {
2
       Location tempGLocation = null;
3
       // Support Android M type permission handling
4
5
       try {
         if \quad (\texttt{ActivityCompat.checkSelfPermission} \, (\texttt{context} \, , \, \, \texttt{Manifest.permission} \, . \, \hookleftarrow)
6
              ACCESS_FINE_LOCATION) != PackageManager.PERMISSION_GRANTED &&
7
         {\tt ActivityCompat.checkSelfPermission(context, Manifest.permission.} \leftarrow
              ACCESS_COARSE_LOCATION) != PackageManager.PERMISSION_GRANTED) {
8
            Log.d("BGS-LOC", "pass permission test");
9
            \texttt{tempGLocation} = \texttt{LocationServices.FusedLocationApi.getLastLocation} ( \hookleftarrow
                 googleApiClient);
10
11
         // Get the current googleApiClient/LocationServices location
12
         \texttt{tempGLocation} = \texttt{LocationServices.FusedLocationApi.getLastLocation} ( \hookleftarrow
              googleApiClient);
14
15
       }catch (Exception ex){
16
17
18
    return tempGLocation;
19
```

Listing 4.3: getCurrentLocation

Convert to aSTEP location

The aSTEP location format contains the essential location information: latitude, longitude, accuracy, and a timestamp. The 4.4 takes an Android location format data, creates an aSTEP location instance based on the argument location, and returns the aSTEP location.

```
private ASTEPLocation convertToAstepLocation(Location gLocation) {
   Log.d("BGS-LOC", "convertToAstepLocation");
   ASTEPLocation aLocation = new ASTEPLocation(gLocation.getLatitude(),
   gLocation.getLongitude(),
   gLocation.getAccuracy(),
   gLocation.getTime());
   return aLocation;
}
```

Listing 4.4: ASTEPLocation()

4.4 Test

Chapter 5 Sprint 3

Metatext for the third iteration

5.1 Analysis

5.1.1 Requirements for the third sprint

Sprint four is...

some requirement placeholder

- 5.2 Design
- 5.3 Implementation
- **5.4** Test

Chapter 6 Sprint 4

Metatext for the fourth iteration

6.1 Analysis

6.1.1 Requirements for the fourth sprint

Sprint four is...

some requirement placeholder

- 6.2 Design
- 6.3 Implementation
- 6.4 Test

Chapter 7 Summary

7.1 Reflection

Some to come here

7.2 Conclusion

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7.3 Future Work

Fix it.

Appendix A Appendix A name

Here is the first appendix