```
1 CreateModel(H, G, step)
 2 Let M be an empty m \times m matrix with m = 2|H|
 з foreach b \in B do
       g \leftarrow G(b).first
      L(b) \leftarrow \mathbf{NearestState}(H, g)
 5
 6 Let d \leftarrow G.first.date
 7 Let l \leftarrow G.last.date
 s while d \leq l do
       for
each b \in B do
            g \leftarrow G(b, d)
10
            n \leftarrow \mathbf{NearestState}(H,g)
11
12
           if n \in D \land L(b) \in D then
             n \leftarrow L(b)
13
            else if n \in D \wedge L(b) \in H then
14
             n \leftarrow L(b).departure
15
            increment(M, L(b), n)
16
            L(b) \leftarrow n
17
       d \leftarrow \operatorname{Add}(d, step)
18
19 Normalize M
20 return M
```