

MODULE - 4

Design synchronous mod-6 counter counting sequence is 000, 001, 100, 110, 111, 101, 000 etc by obtaining its minimal sum equ. using SR flip-flop : Application table :

| Q_a | Q_b^+ | S | R |
|-------|---------|-----|-----|
| 0 | 0 | 0 | - |
| 0 | 1 | 1 | 0 |
| 1 | 0 | 0 | 1 |
| 1 | 1 | 1 | 0 |

Excitation table :

Present state Next state outputs

| Q_a | Q_b | Q_c | Q_a^+ | Q_b^+ | Q_c^+ | S_a | R_a | S_b | R_b | S_c | R_c |
|-------|-------|-------|---------|---------|---------|-------|-------|-------|-------|-------|-------|
| 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | - | 0 | - | 1 |
| 0 | 0 | 1 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | - | 0 |
| 1 | 0 | 0 | 1 | 1 | 0 | - | 0 | 1 | 0 | - | 0 |
| 1 | 1 | 0 | 1 | 1 | 1 | - | 0 | - | 0 | - | 1 |
| 1 | 1 | 1 | 1 | 0 | 1 | - | 0 | 0 | 1 | - | 0 |
| 1 | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 0 | - | 0 | 1 |

| S_a | $Q_a \setminus Q_b Q_c$ | 01 | 11 | 10 | R_a | $Q_a \setminus Q_b Q_c$ | 01 | 11 | 10 |
|-------|-------------------------|----|----|----|-------|-------------------------|----|----|----|
| 0 | 0 | 1 | - | - | 0 | - | 0 | - | - |
| 1 | - | 0 | - | - | - | 1 | 0 | 1 | 0 |

$$S_a = \bar{Q}_a Q_c$$

$$R_a = Q_a \bar{Q}_b Q_c$$

| $S_b \backslash S_c$ | 00 | 01 | 11 | 10 |
|--------------------------|----|----|----|----|
| $S_a \backslash Q_b Q_c$ | 0 | 0 | - | - |
| 0 | 0 | 0 | - | - |
| 1 | 0 | 0 | - | - |

| $R_b \backslash S_b S_c$ | 00 | 01 | 11 | 10 |
|--------------------------|----|----|----|----|
| $S_a \backslash Q_b Q_c$ | 0 | - | - | - |
| 0 | 0 | - | - | - |
| 1 | 0 | - | - | - |

$$S_b = \bar{Q}_a \bar{Q}_c$$

$$R_b = \bar{Q}_c$$

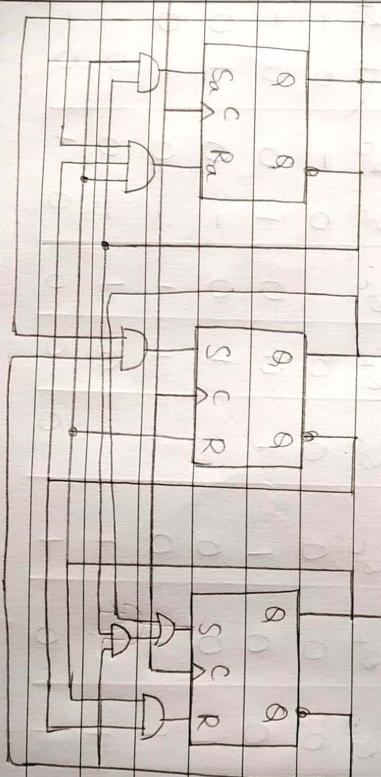
| $S_c \backslash S_b S_c$ | 00 | 01 | 11 | 10 |
|--------------------------|----|----|----|----|
| $S_a \backslash Q_b Q_c$ | 0 | 0 | - | - |
| 0 | 0 | 0 | - | - |
| 1 | 0 | 0 | - | - |

| $R_c \backslash S_b S_c$ | 00 | 01 | 11 | 10 |
|--------------------------|----|----|----|----|
| $S_a \backslash Q_b Q_c$ | 0 | 0 | - | - |
| 0 | 0 | 0 | - | - |
| 1 | 0 | 0 | - | - |

$$S_c = \bar{Q}_a \bar{Q}_c + Q_b$$

$$R_c = \bar{Q}_b \bar{Q}_c$$

Q_A Q_B Q_C



Realize 3 bit binary synchronous up-counter
using JK flip flop.

Application table :

| Q | Q^+ | J | K |
|-----|-------|-----|-----|
| 0 | 0 | 0 | - |
| 0 | 1 | 1 | - |
| 1 | 0 | - | 1 |
| 1 | 1 | - | 0 |

Excitation table

| Q_1 | Q_2 | Q_3 | Q_1^+ | Q_2^+ | Q_3^+ | J_1 | K_1 | J_2 | K_2 | J_3 | K_3 |
|-------|-------|-------|---------|---------|---------|-------|-------|-------|-------|-------|-------|
| 0 | 0 | 0 | 0 | 0 | 1 | 0 | - | 0 | - | 1 | - |
| 0 | 0 | 1 | 0 | 1 | 0 | 0 | - | 1 | - | - | 1 |
| 0 | 1 | 0 | 0 | 1 | 1 | 0 | - | - | 0 | 1 | - |
| 0 | 1 | 1 | 1 | 0 | 0 | 1 | - | - | 1 | - | 1 |
| 1 | 0 | 0 | 1 | 0 | 1 | - | 0 | 0 | - | 1 | - |
| 1 | 0 | 1 | 1 | 1 | 0 | - | 0 | 1 | - | - | 1 |
| 1 | 1 | 0 | 1 | 1 | 1 | - | 0 | - | 0 | 1 | - |
| 1 | 1 | 1 | 0 | 0 | 0 | - | 1 | - | 1 | - | 1 |

| J_1 | $Q_2 Q_3$ | K_1 |
|-------|---------------|--|
| 0 | 0 0 0 1 11 10 | $Q_1 \backslash Q_2 Q_3$ 0 0 0 1 11 10 |
| 0 | 0 0 1 0 1 0 | 0 - - - - - |

| J_1 | $Q_2 Q_3$ | K_1 |
|-------|-----------|-----------|
| 1 | 1 - - | 1 0 0 1 0 |
| - | - - - | 0 1 0 1 0 |

$$J_1 = Q_2 Q_3$$

$$Q_1 \backslash Q_2 Q_3 0 0 0 1 11 10$$

$$Q_1 \backslash Q_2 Q_3 0 0 1 0 1 0$$

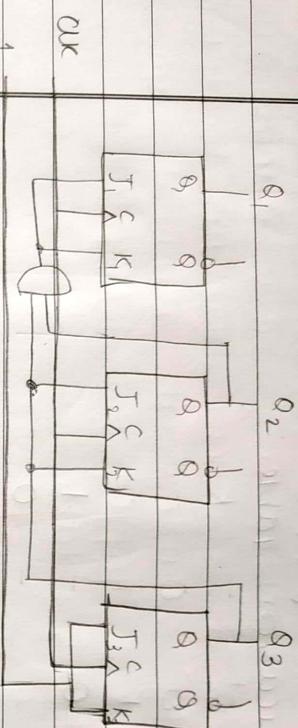
$$Q_1 \backslash Q_2 Q_3 0 1 1 0 1 1$$

$$Q_1 \backslash Q_2 Q_3 1 1 1 1 1 1$$

$$J_2 = Q_3$$

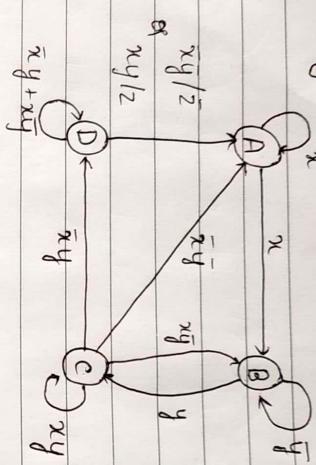
$$K_2 = Q_3$$

$$J_g = K_g = 1$$



state diagrams tables :

These are tabular forms of state diagram.



State table :

| Present Sear | Next state | 00 | 01 | 10 | 11 | z | 01 | z | 10 | z | 00 | Step 3: |
|-----------------|---------------|----|----|----|----|---|----|---|----|---|----|---------|
| A | A | 0 | 0 | 0 | 0 | 0 | B | 0 | B | 0 | 0 | Step 4: |
| B | B | 0 | 0 | 0 | 0 | 0 | C | 0 | C | 0 | 0 | 00 |
| C | C | 0 | 0 | 0 | 0 | 0 | D | 0 | D | 0 | 0 | 00 |
| D | D | 0 | 0 | 0 | 0 | 0 | A | 1 | D | 0 | 0 | 00 |

Transmission table

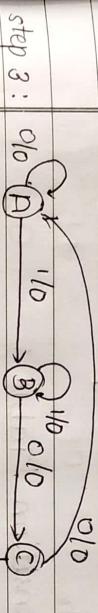
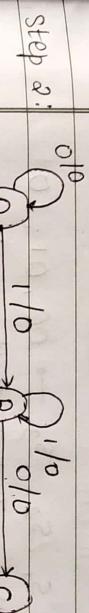
Construct a mealy state diagram that will detect input sequence 10110 step 5: when input pattern is detected Z is asserted high . Write the state diagram

$$x = 10110110110$$

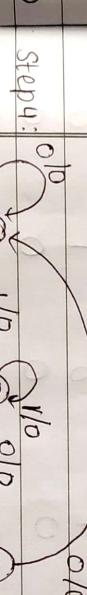
$$z = 00001000001$$



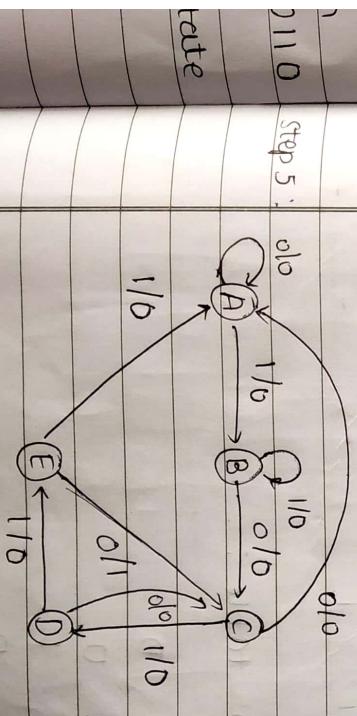
Step 1: A is the initial stage with input = 0 as seen as it detects high bit change that state from A to B



0
Z
0

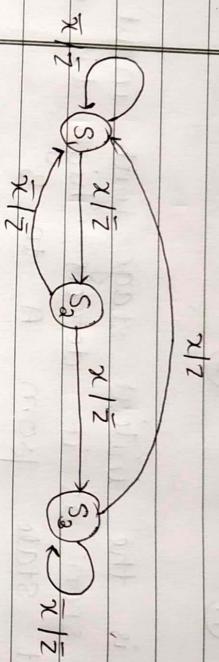


0
0
Step 4:
0



route

Realize the few state diagram using
D-kupfer. ii) JK FLF



3 states $S_1, S_2, S_3 \rightarrow 00, 01, 10$
 $x \rightarrow \text{input}$ $z \rightarrow \text{output}$

State transition Table

| Passenger state | 1/P | Next state | 0/P |
|-----------------|-----|------------|----------------|
| A | B | X | A ⁺ |
| 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 0 |

Excitation table

| | | | | |
|---|---|---|---|---|
| - | - | - | - | 0 |
| - | - | 0 | 0 | 1 |
| - | 0 | - | 0 | - |
| 1 | 1 | 0 | - | 0 |
| 1 | 1 | 0 | 0 | 0 |
| 1 | 1 | - | 0 | 0 |

—

E/E Inputs

$$A \quad B \quad x \quad A^+ \quad B^+ \quad Z \quad D_A \quad D_B$$

$$0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0$$

$$0 \quad 0 \quad 1 \quad 0 \quad 1 \quad 0 \quad 0 \quad 1$$

$$0 \quad 1 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0$$

$$0 \quad 1 \quad 1 \quad 0 \quad 0 \quad 0 \quad 1 \quad 0$$

$$1 \quad 0 \quad 0 \quad 1 \quad 0 \quad 0 \quad -1 \quad 0$$

$$1 \quad 0 \quad 1 \quad 0 \quad 0 \quad 1 \quad 0 \quad 0$$

$$1 \quad 1 \quad 0 \quad -1 \quad -1 \quad -1 \quad -1 \quad -1$$

D/P

Z

O

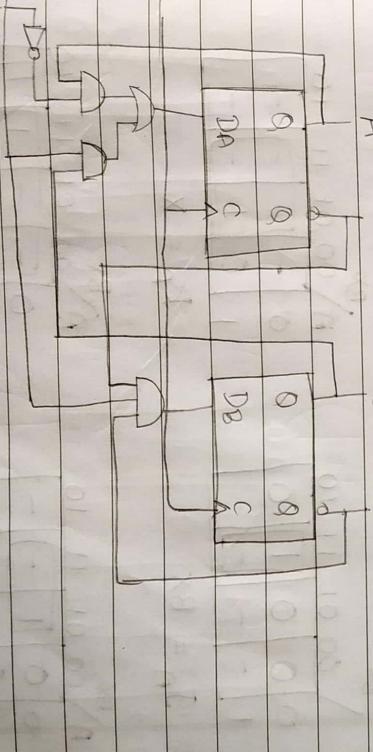
O

$$D_A = Bx + A\bar{x}$$

$$D_B = \bar{A}\bar{B}x$$

A

B



X

Y

Application table for JK

| Q | Q^+ | J | K |
|-----|-------|-----|-----|
| 0 | 0 | 0 | - |
| 0 | 1 | 1 | - |
| 1 | 0 | - | 1 |
| 1 | 1 | - | 0 |

CLK

Excitation table :

| A | B | X | A^+ | B^+ | Z | J_A | K_A | J_B | K_B |
|---|---|---|-------|-------|---|-------|-------|-------|-------|
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | - | 0 | - |
| 0 | 0 | 1 | 0 | 1 | 0 | 0 | - | 1 | - |
| 0 | 1 | 0 | 0 | 0 | 0 | - | - | - | 1 |
| 0 | 1 | 1 | 1 | 0 | 0 | 1 | - | - | 1 |
| 1 | 0 | 0 | 1 | 0 | 0 | - | 0 | 0 | - |
| 1 | 0 | 1 | 0 | 0 | 1 | - | 1 | 0 | - |
| 1 | 1 | 0 | - | - | - | - | - | - | - |
| 1 | 1 | 1 | - | - | - | - | - | - | - |

X

A

| | | | |
|----|----|----|----|
| 00 | 01 | 11 | 10 |
| 0 | 0 | 0 | 1 |
| 0 | 1 | 1 | 0 |
| 1 | 1 | 0 | 0 |

B

| | | | |
|----|----|----|----|
| 00 | 01 | 11 | 10 |
| 0 | 0 | 1 | 1 |
| 0 | 1 | 0 | 0 |
| 1 | 1 | 0 | 0 |

$J_A = BX$

$K_A = X$

A

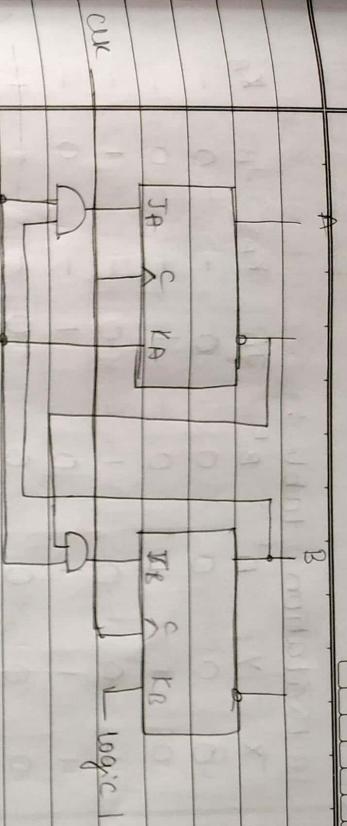
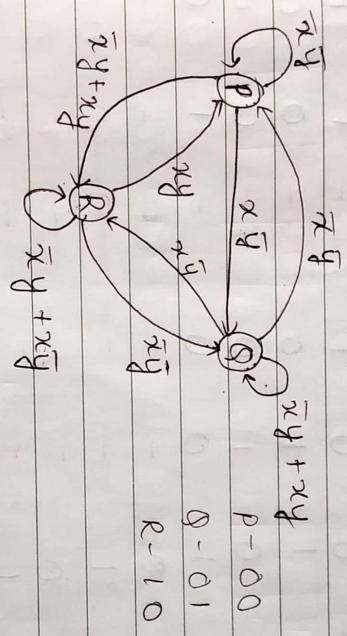
| | | | |
|----|----|----|----|
| 00 | 01 | 11 | 10 |
| 0 | 0 | 1 | 1 |
| 0 | 1 | 0 | 0 |
| 1 | 1 | 0 | 0 |

B

| | | | |
|----|----|----|----|
| 00 | 01 | 11 | 10 |
| 0 | 0 | 1 | 1 |
| 0 | 1 | 0 | 0 |
| 1 | 1 | 0 | 0 |

$J_B = \bar{A}X$

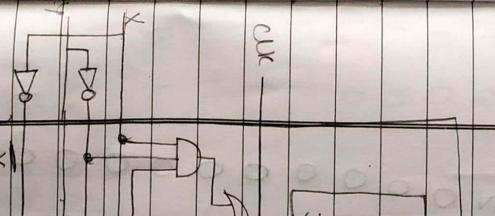
$K_B = 1$



Excitation table

$$J_A = \bar{B} Y + B X \bar{Y} \quad K_A = \bar{X} \bar{Y} + X Y$$

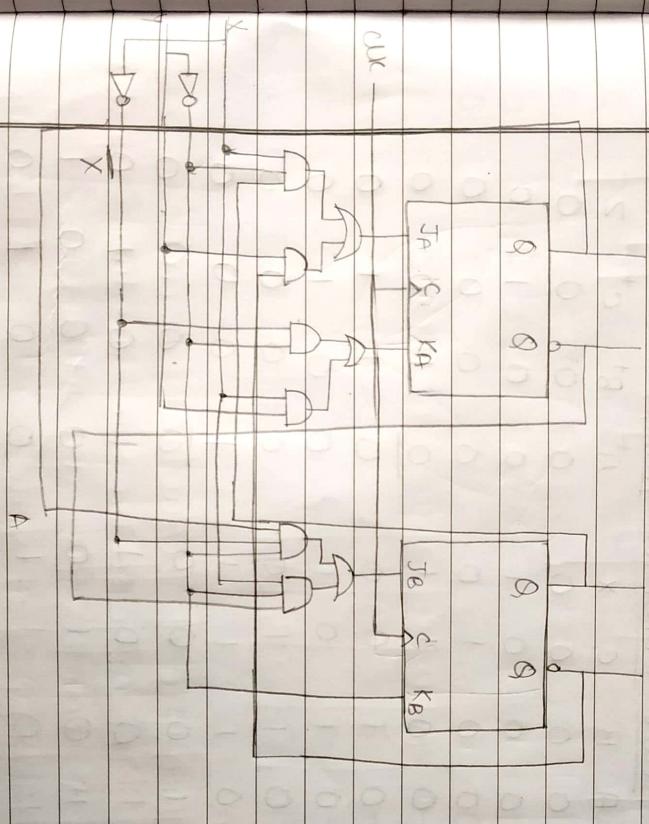
$$J_B = \begin{pmatrix} AB & 0 \\ 0 & C \end{pmatrix}$$



| AB | $X\bar{Y}$ | 00 | 01 | 11 | 10 | AB | $X\bar{Y}$ | 00 | 01 | 11 | 10 |
|------|------------|-------|----------|----------|----------|--------|------------|-----------|--------|--------|----------|
| 00 | 0_0 | 0_1 | 0_3 | 1_2 | ∞ | 01 | $-\bar{0}$ | -1 | -3 | -1 | ∞ |
| 01 | -4 | -5 | -7 | -6 | 0_1 | 1_4 | 0_5 | 0_7 | 1_6 | 1_4 | 0_2 |
| 11 | -12 | -13 | -15 | -14 | 1_1 | -1_4 | -1_3 | -1_5 | -1_4 | -1_5 | -1_4 |
| 10 | 1_8 | 0_9 | 0_{11} | 0_{10} | 1_0 | -1_8 | -1_9 | -1_{11} | -1_0 | -1_9 | -1_0 |

$$J_B = A\bar{X}\bar{Y} + \bar{A}X\bar{Y}$$

$$K_B = \bar{Y}$$



$$\begin{matrix} Q & Q^+ & T \\ 0 & 0 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{matrix}$$

Implement state diagram show that using D-kip flop.

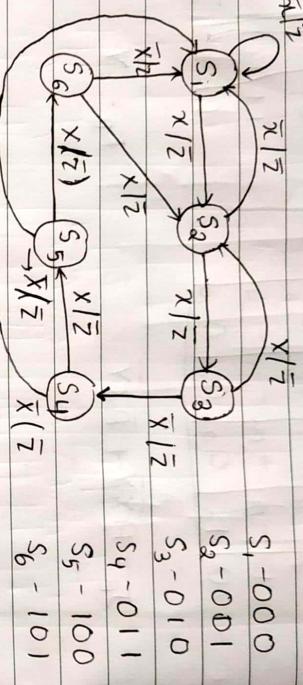
$\bar{A} \bar{B} \bar{C}$

A B C
0 0 0
0 0 0
0 0 0

Excita

$S_1 - 000$
 $S_2 - 001$
 $S_3 - 010$
 $S_4 - 011$
 $S_5 - 100$
 $S_6 - 101$

0 0 0
0 0 0
0 0 0
0 0 0
0 0 0
0 0 0



state transition table:

| A | B | C | X | A^+ | B^+ | C^+ | Z |
|---|---|---|---|-------|-------|-------|---|
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 1 | 0 | 0 | 0 | 1 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 1 | 0 | 0 | 0 | 1 | 1 | 0 |
| 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 1 | 1 | 0 | 0 | 0 | 0 | 1 |
| 0 | 1 | 1 | 1 | 1 | 0 | 1 | 0 |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | 0 | 0 | 1 | 0 | 1 | 0 | 0 |
| 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 |
| 1 | 0 | 1 | 1 | 0 | 0 | 1 | 0 |
| 1 | 1 | 0 | 0 | - | - | - | 1 |
| 1 | 1 | 0 | 1 | - | - | - | 0 |
| 1 | 1 | 1 | 0 | - | - | - | 1 |
| 1 | 1 | 1 | 1 | - | - | - | 0 |

$AB \backslash$

00 00

00 00

01 01

01 01

11 11

11 11

10 10

10 10

$$T_A = A \\ AB \backslash$$

00

01

11

10

Excitation table :

| A | B | C | X | A^+ | B^+ | C^+ | T_A | T_B | T_C |
|---|---|----|----|-------|-------|-------|-------|-------|-------|
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | -1 | 0 | 0 | -1 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| 0 | 1 | -1 | 0 | -1 | 0 | 0 | 0 | 1 | 1 |
| 0 | 1 | 1 | 0 | 0 | -1 | 0 | 0 | -1 | 1 |
| 0 | 1 | 0 | 0 | 0 | 1 | -1 | 0 | 0 | 1 |
| 0 | 1 | 0 | -1 | 0 | 0 | 1 | 0 | -1 | 1 |
| 0 | 1 | -1 | 0 | 0 | 0 | 0 | -1 | 1 | 1 |
| 0 | 1 | 1 | -1 | 0 | 0 | 0 | 1 | -1 | 1 |
| 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |
| 0 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 |
| 0 | 1 | -1 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 0 | 0 | -1 | 0 | 0 | -1 | 1 |
| 0 | 1 | 0 | -1 | 0 | 0 | 1 | 0 | 0 | 1 |
| 0 | 1 | -1 | 0 | 0 | 0 | 0 | -1 | 1 | 1 |
| 0 | 1 | 1 | -1 | 0 | 0 | 0 | 1 | -1 | 1 |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | 0 | 0 | -1 | 0 | 0 | -1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| 1 | 0 | -1 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| 1 | 0 | 1 | 0 | 0 | -1 | 0 | 0 | 1 | 0 |
| 1 | 0 | -1 | 0 | 0 | 0 | 1 | 0 | 0 | 1 |
| 1 | 0 | 1 | -1 | 0 | 0 | 0 | 1 | -1 | 0 |
| 1 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 |
| 1 | 0 | -1 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| 1 | 0 | 1 | 0 | -1 | 0 | 0 | 0 | -1 | 1 |
| 1 | 0 | -1 | 0 | 0 | 0 | 0 | -1 | 1 | 1 |
| 1 | 0 | 1 | -1 | 0 | 0 | 0 | 1 | -1 | 1 |

$\begin{matrix} CX \\ AB \end{matrix}$

$\begin{matrix} CX \\ AB \end{matrix}$

$$\begin{array}{|c|c|c|c|} \hline AB & CX & AB & CX \\ \hline 00 & 0 & 0 & 0 \\ \hline 00 & 0 & 0 & 0 \\ \hline 01 & 0 & 0 & -1 \\ \hline 01 & - & - & - \\ \hline 11 & 1 & 0 & 1 \\ \hline 11 & 0 & 1 & 1 \\ \hline 10 & 0 & 1 & 1 \\ \hline \end{array}$$

$$T_A = AX + AC + BCX$$

$\begin{matrix} CX \\ AB \end{matrix}$

$\begin{matrix} CX \\ AB \end{matrix}$

$$\begin{array}{|c|c|c|c|} \hline AB & CX & AB & CX \\ \hline 00 & 0 & 1 & -1 \\ \hline 00 & 1 & 1 & -1 \\ \hline 01 & 1 & -1 & -1 \\ \hline 01 & - & - & - \\ \hline 11 & 0 & 1 & -1 \\ \hline 11 & 0 & -1 & -1 \\ \hline 10 & 0 & 1 & -1 \\ \hline \end{array}$$

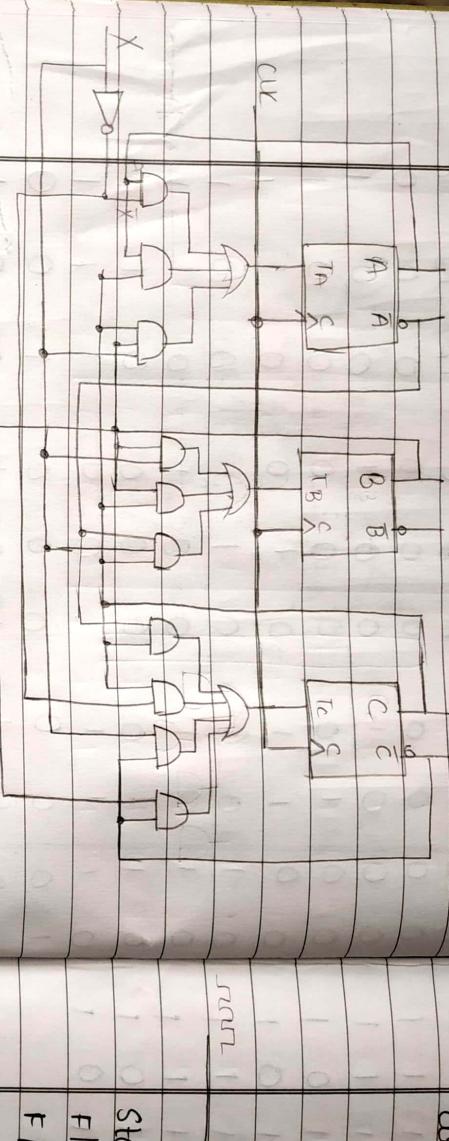
$$T_B = BX + BC + \bar{A}CX$$

$\begin{matrix} CX \\ AB \end{matrix}$

$\begin{matrix} CX \\ AB \end{matrix}$

$$\begin{array}{|c|c|c|c|} \hline AB & CX & AB & CX \\ \hline 00 & 1 & 1 & -1 \\ \hline 00 & 1 & -1 & -1 \\ \hline 01 & 1 & 1 & -1 \\ \hline 01 & - & - & - \\ \hline 11 & 0 & 1 & -1 \\ \hline 11 & 0 & -1 & -1 \\ \hline 10 & 0 & 1 & -1 \\ \hline \end{array}$$

$$T_C = \bar{A}C + \bar{C}X + \bar{C}X + \bar{B}\bar{C}$$



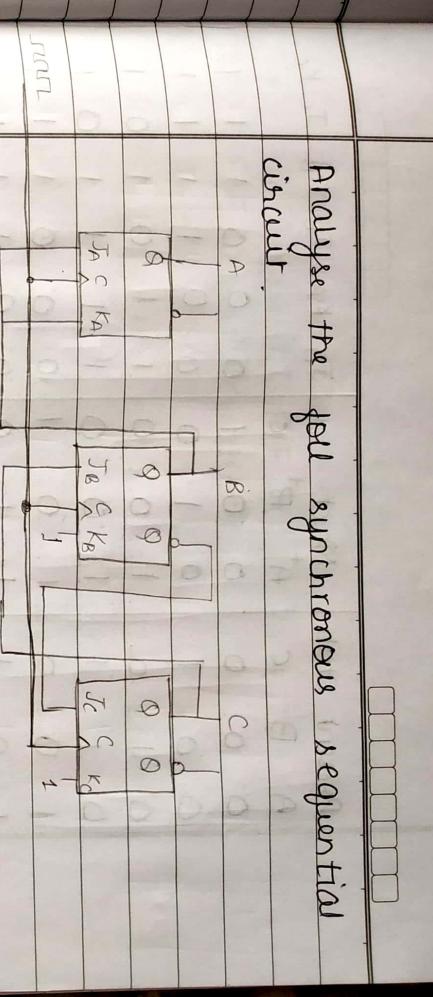
| $AB\backslash CX$ | 00 | 01 | 11 | 10 | $Z = \text{clk } AC\bar{X}$ |
|-------------------|----|----|----|----|-----------------------------|
| 00 | 0 | 0 | 0 | 0 | 0 |
| 01 | 0 | 0 | 0 | 0 | 0 |
| 11 | - | - | - | - | 0 |
| 10 | 0 | 0 | 0 | 1 | 1 |

Analysis of sequential circuits

The procedure to analysis synchronous counter is as follows:

1. Identify the state variable (F/F output)
2. Identify F/F types
3. write F/F input equations
4. construct the k-map using the F/F eqn
5. Fill the excitation table using the k-map & the functioned table of F/F.
6. write state diagram from excitation table.

Analyse the full synchronous sequential circuit.



State variable - A, B, C

F/F type - JK flip flop

F/F input equations:

$$\begin{aligned} J_A &= B & K_A &= \bar{B} \\ J_B &= C & K_B &= 1 \\ J_C &= \bar{B} & K_C &= 1 \end{aligned}$$

K-map: J_A / K_A

| A\BC | J_A | | | |
|------|-----|----|----|----|
| | 00 | 01 | 11 | 10 |
| 0 | 0 | 0 | 1 | 1 |
| 1 | 0 | 1 | 0 | 0 |

J_B

| A\BC | J_B | | | |
|------|-----|----|----|----|
| | 00 | 01 | 11 | 10 |
| 0 | 0 | 0 | 1 | 0 |
| 1 | 0 | 1 | 0 | 1 |

J_C

K-map: J_A / K_A

| A\BC | J_A | | | |
|------|-----|----|----|----|
| | 00 | 01 | 11 | 10 |
| 0 | 1 | 1 | 0 | 0 |
| 1 | 1 | 1 | 0 | 0 |

(3)

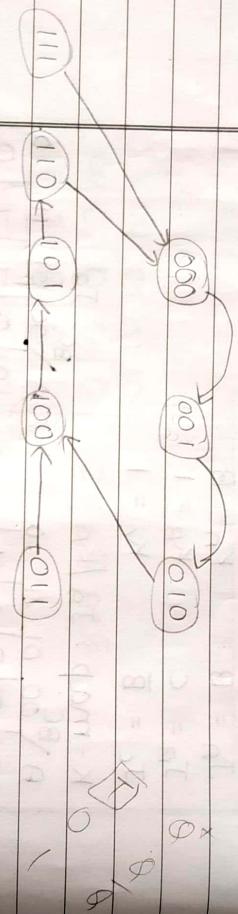
q_μ²

on
ion

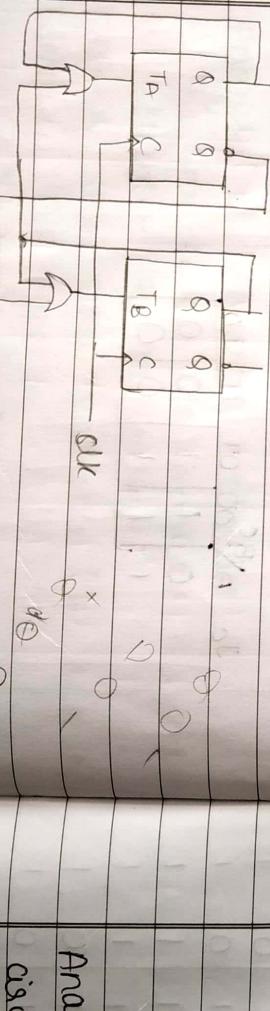
| Init | Present State | Next State | J_A | K_A | J_B | K_B | J_C | K_C | Sta |
|------|---------------|------------|-------|-------|-------|-------|-------|-------|----------------|
| A | B | C | A^+ | B^+ | C^+ | | | | F1 |
| 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | F1 |
| 0 | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 1 | F/F |
| 0 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 0 | T _A |
| 0 | 1 | 1 | 1 | 0 | 0 | 1 | 1 | 0 | T _B |
| 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | A/ 0 |
| 1 | 0 | 0 | - | 0 | 1 | 0 | 0 | 1 | - |
| 1 | 0 | 1 | - | 1 | 0 | 0 | 1 | 1 | - |
| 1 | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | - |
| 1 | 1 | 1 | 0 | 0 | 0 | 1 | 1 | 0 | 1 |

Ex
Pres

A
0



Analyse the full synchronous circuit



Ana
circ

T_c , K_c

state variables - A, B

F/F type - T F/F

F/F input equations :

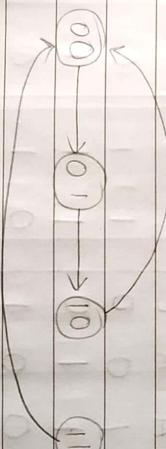
$$T_A = A + B$$

$$T_B = B + \bar{A}$$

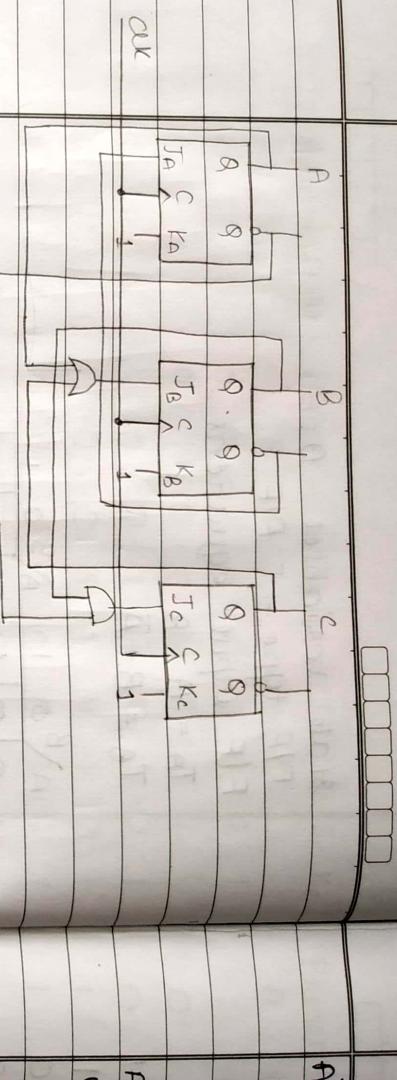
| $A \setminus B$ | 0 | 1 | $\bar{A} \setminus \bar{B}$ | 0 | 1 |
|-----------------|-------|-------|-----------------------------|-------|-------|
| 0 | 0 1 | 0 1 | 1 0 | 1 0 | 1 1 |
| 1 | 1 1 | 1 0 | 0 0 | 0 1 | 1 1 |

Excitation table :

| Present | Next | T_A | \bar{T}_B |
|---------|------|-------|-------------|
| A | B | A^+ | B^+ |
| 0 | 0 | 0 | 1 |
| 0 | 1 | 1 | 0 |
| 1 | 0 | 0 | 0 |
| 1 | 1 | 0 | 1 |



Analyse 4 bit synchronous sequential circuit.



State variable - A, B, C

FF type - JK

FF input equations

$$J_A = \overline{B} \quad K_A = K_B = K_C = 1$$

$$J_B = A + C$$

$$J_C = \overline{A}B$$

Excitation table

| Present | Next | J_A | K_A | J_B | K_B | J_C | K_C |
|---------|------|-------|-------|-------|-------|-------|-------|
| A | B | C | A^+ | B^+ | C^+ | | |
| 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 0 | 1 | 1 | 0 | 1 | 1 | 1 |
| 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 |
| 0 | 1 | 1 | 0 | 0 | 0 | 1 | 1 |
| 1 | 0 | 0 | 0 | 1 | 1 | 1 | 1 |
| 1 | 0 | 1 | 0 | 1 | 1 | 1 | 0 |
| 1 | 1 | 0 | 0 | 0 | 0 | 1 | 0 |
| 1 | 1 | 1 | 0 | 0 | 1 | 1 | 0 |

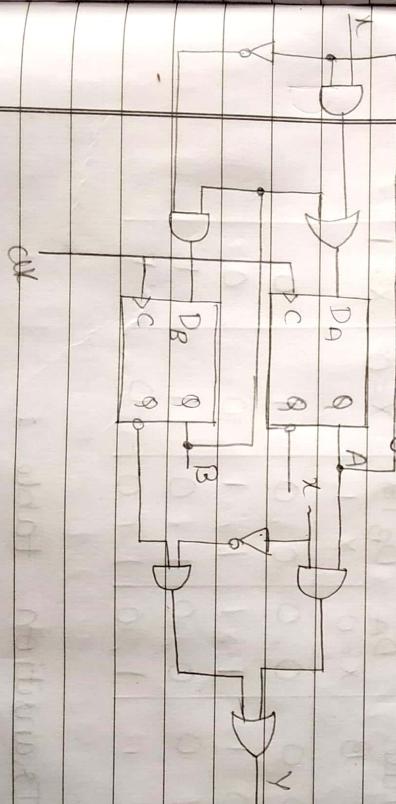
| A | B | C | Q0 | Q1 | Q2 | Q3 |
|---|---|---|----|----|----|----|
| 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 1 | 1 | 1 | 0 | 0 | 0 |
| 1 | 1 | 0 | 0 | 1 | 1 | 0 |

| A | B | C | Q0 | Q1 | Q2 | Q3 |
|---|---|---|----|----|----|----|
| 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| 0 | 1 | 1 | 1 | 1 | 1 | 0 |
| 1 | 1 | 0 | 1 | 1 | 1 | 1 |

| A | B | C | Q0 | Q1 | Q2 | Q3 |
|---|---|---|----|----|----|----|
| 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 |

Analyse the sequential circuit by writing input & output equations, state table and state diagram.

K_c



state variable - A B

F/F type - D

F/F input eqn?

$$D_A = xA + B$$

$$D_B = \overline{A}B$$

ffr output eqn

$$Y = AX + \bar{B}\bar{x}$$

Present
A

| A | B | X | uA | $\bar{A}B$ | $\bar{B}\bar{x}$ | D _A | D _B | Y | 0 |
|---|---|---|----|------------|------------------|----------------|----------------|----|----|
| 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 1 | -1 |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | -1 |
| 0 | 1 | 0 | 0 | 1 | 0 | -1 | -1 | 0 | 1 |
| 0 | 1 | 1 | 0 | 1 | D | -1 | -1 | 0 | 1 |
| 1 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 |
| 1 | 0 | 1 | 1 | 0 | 0 | -1 | 0 | -1 | 1 |
| 1 | 1 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 1 |
| 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 1 | 1 |

Excitation table :

| Present State | Excitation | | Output Y | |
|---------------|-------------------------|-------------------------|---------------------------|---------------------------|
| | D _A $x=0$ | D _B $x=1$ | F _{ffr} $x=0$ | F _{ffr} $x=1$ |
| 0 0 | 0, 0 | 0, 0 | -1 | 0 |
| 0 1 | 1, 1 | 1, 1 | 0 | 0 |
| 1 0 | 0, 0 | 1, 0 | 1 | -1 |
| 1 1 | 1, 0 | 1, 0 | 0 | 1 |

Transition table :

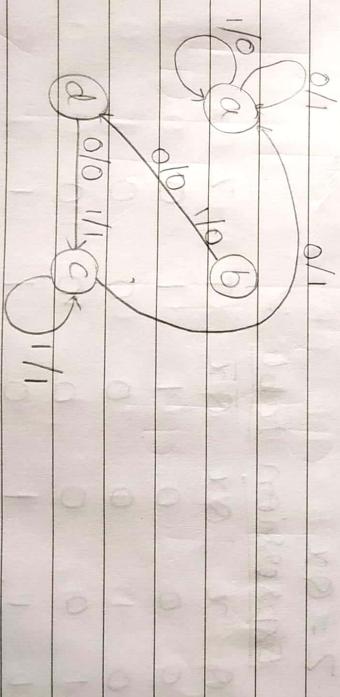
| Present state | Next state | output Y | |
|---------------|------------|-------------------------|-----------|
| A | B | P^* B^* $F\Theta A$ | For input |
| 0 | 0 | 0 0 0 0 | X=0 X=1 |
| 0 | 1 | 1 1 1 0 | X=0 X=1 |
| 1 | 0 | 0 0 1 0 | X=1 X=0 |
| 1 | 1 | 1 0 1 0 | X=1 X=0 |

State table assignment

Assume 00-a, 01-b, 10-c, 11-d.

State table

| Present state | Next state | Output | | |
|---------------|------------|--------|-----|-----|
| S | x=0 | x=1 | x=0 | x=1 |
| a | a | a | 1 | 0 |
| b | d | d | 0 | 0 |
| c | a | c | 1 | 1 |
| d | c | c | 0 | 1 |



Analyse following sequential circuit shown in

present
exit

Fig below and obtain
F/F input Σ_x , output Σ^Q

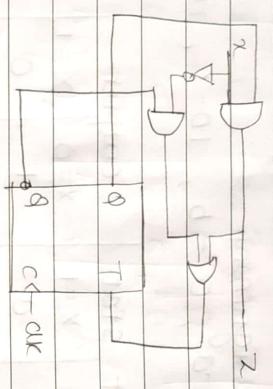
Q

i.) Transition eqn

ii.) Transition table

iii.) State table

v.) Draw state diagram



Present
exit

Q

1

St

a

b

St

Present
exit

Q

0

1

St

a

b

Present
exit

Q

0

1

St

a

b

Present
exit

Q

1

0

St

a

b

Present
exit

Q

0

1

St

a

b

Present
exit

Q

1

0

St

a

b

Present
exit

Q

0

1

St

a

b

Present
exit

Q

1

0

St

a

b

Present
exit

Q

0

1

St

a

b

Present
exit

Q

1

0

St

a

b

Present
exit

Q

0

1

St

a

b

Present
exit

Q

1

0

St

a

b

Present
exit

Q

0

1

St

a

b

Present
exit

Q

1

0

St

a

b

Present
exit

Q

0

1

St

a

b

Present
exit

Q

1

0

St

a

b

Present
exit

Q

0

1

St

a

b

Present
exit

Q

1

0

St

a

b

Present
exit

Q

0

1

St

a

b

Present
exit

Q

1

0

St

a

b

Present
exit

Q

0

1

St

a

b

Present
exit

in

Excitation Table :

Present Excitation Output Z
 $T_{\text{for } x=0}$ $x=1$ $x=0$ $x=1$

| | | | |
|---|---|---|---|
| 0 | 1 | 0 | 0 |
| 1 | 0 | 1 | 0 |

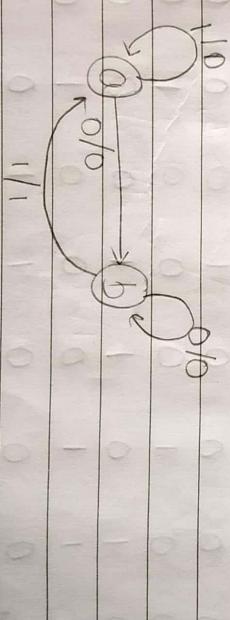
Transition table :

| Present Q | Next Q^+ | Output Z |
|-----------|------------|----------|
| 0 | 1 | $x=0$ |
| 1 | 0 | $x=1$ |

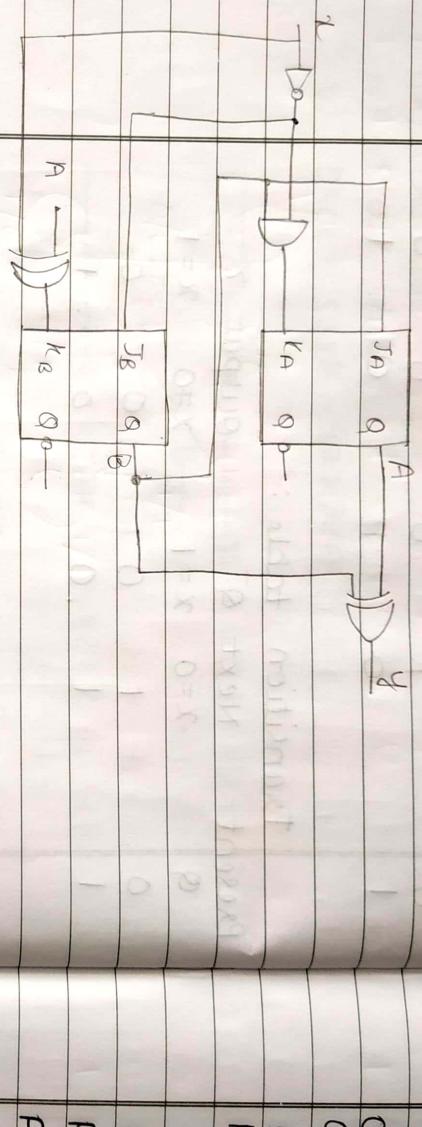
State assignment $\rightarrow a = 0 \quad b = 1$

State table

| Present State | Next state | Output Z |
|---------------|------------|----------|
| a | b | $x=1$ |
| b | a | $x=0$ |



Construct the excitation table, transition table state table & state diagram for a Moore sequential circuit shown



F/F equations

$$J_A = B \quad K_A = \bar{x}B$$

$$J_B = \bar{x} \quad K_B = A \oplus x = A\bar{x} + \bar{A}x$$

$$Y = A \oplus B = A\bar{B} + \bar{A}B$$

Expression table :

| A | B | x | \bar{x} | \bar{B} | \bar{x} | $A\bar{x}$ | $\bar{A}x$ | AB | $\bar{A}\bar{B}$ |
|---|---|-----|-----------|-----------|-----------|------------|------------|------|------------------|
| 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 0 |
| 0 | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 1 | 0 |
| 0 | 1 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 0 |
| 1 | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 0 | 1 |
| 1 | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| 1 | 1 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 1 |
| 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| J_A | K_A | J_B | K_B | Y |
|-------|-------|-------|-------|-----|
| 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | 0 | 1 | 0 |
| 1 | 1 | 1 | 0 | 1 |
| 1 | 0 | 0 | 1 | 1 |
| 0 | 0 | 1 | 1 | 1 |
| 0 | 0 | 0 | 0 | 1 |
| 1 | 1 | 1 | 1 | 0 |
| 1 | 0 | 0 | 0 | 0 |

Excitation table

| Present | | Excitation JK | | Output Y | |
|---------|---|---------------|--------|----------|-------|
| A | B | $X=0$ | $X=1$ | $X=0$ | $X=1$ |
| 0 | 0 | 00, 10 | 00, 01 | 0 | 0 |
| 0 | 1 | 11, 10 | 10, 01 | 1 | 1 |
| 1 | 0 | 00, 11 | 00, 00 | 1 | 1 |
| 1 | 1 | 11, 11 | 10, 00 | 0 | 0 |

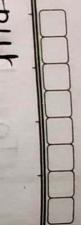
Transition table :

| Present | | Next State $A^+ \& B^+$ | | Output Y | |
|---------|---|-------------------------|-------|----------|-------|
| A | B | $X=0$ | $X=1$ | $X=0$ | $X=1$ |
| 0 | 0 | 0 1 | 0 0 | 0 | 0 |
| 0 | 1 | 1 1 | 1 0 | 1 | 1 |
| 1 | 0 | 1 1 | 1 0 | 1 | 1 |
| 1 | 1 | 0 0 | 1 1 | 0 | 0 |

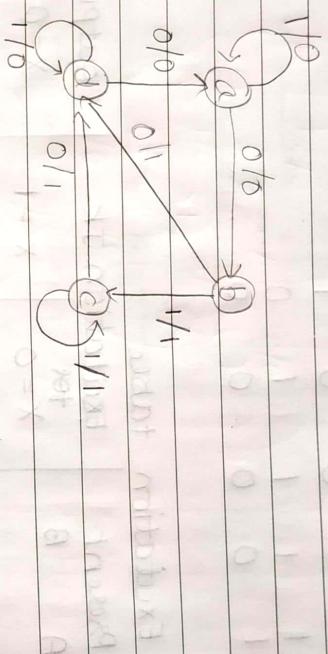
State assignment $\rightarrow a \rightarrow 00 \quad b \rightarrow 01$

$C \rightarrow 10 \quad d \rightarrow 11$

State diagram:

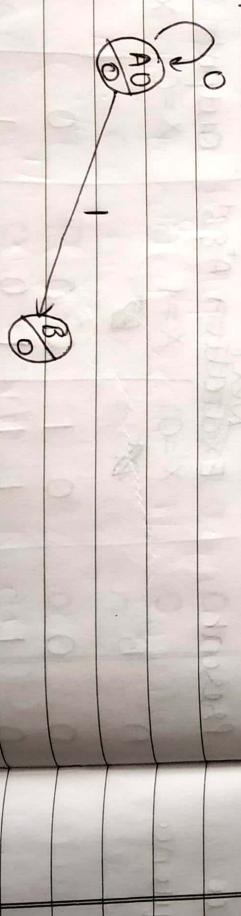


| Present | Next | Output | |
|---------|------|--------|-------|
| A | B | X = 0 | X = 1 |
| 0 | a | b | a |
| 0 | b | d | c |
| 1 | c | d | c |
| 1 | d | a | d |



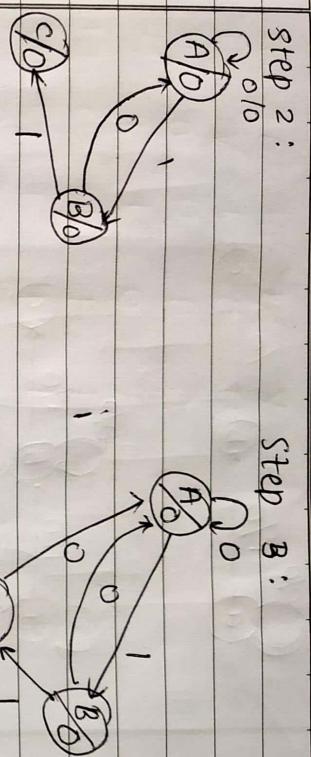
Draw a state diagram of a meze machine to output a one if the input has been 1 for 3 consecutive clock cycles.

Step 1:

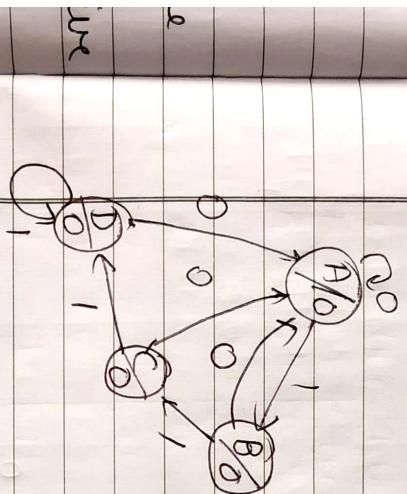


Step 2 :

Step 3 :

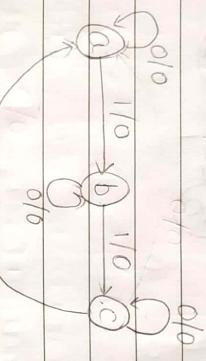
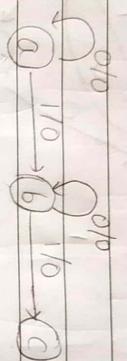
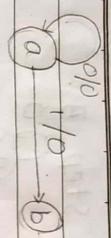


Step 4 :

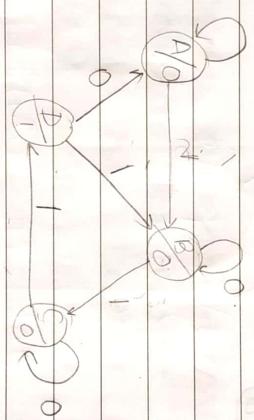


Draw state diagram of mealy machine whose O/P is 1 for every 3rd i/p being 1 not necessarily consecutive but nor overlap.

X = 01010 11101011
0000010001000

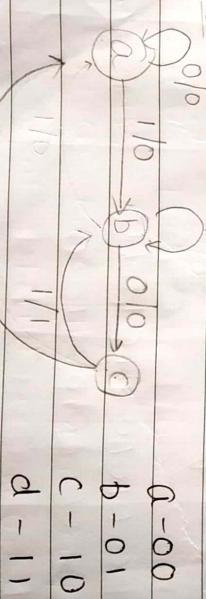


1110 1110 1111



Design mealy type sequence
detector to detect serial input sequence

q 101.



0/10

state transition table :

present state i/p Next state o/p

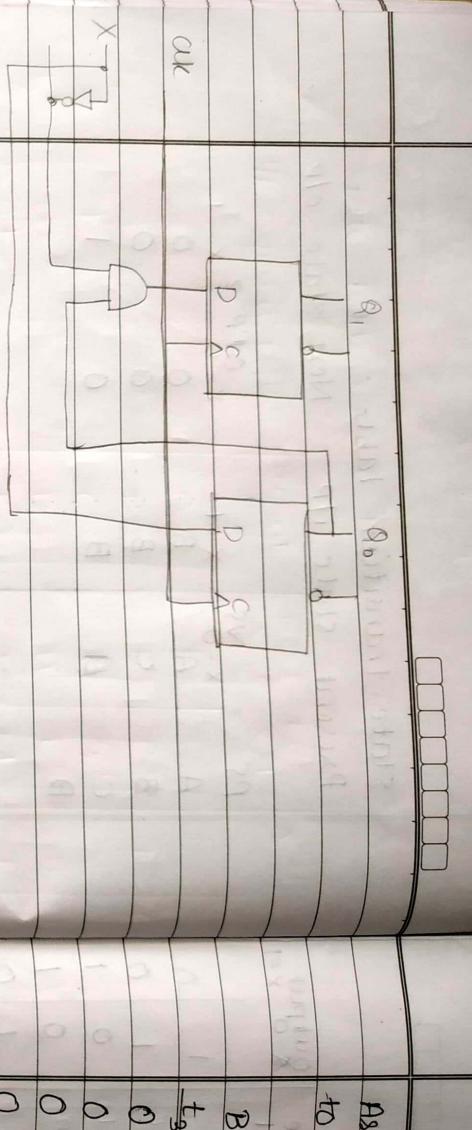
| PS | $X=0$ | $X=1$ | $X=0'P = Z$ | $X=1$ |
|----|-------|-------|-------------|-------|
| A | A | B | 0 | 0 |
| B | C | B | 0 | 0 |
| C | A | B | 0 | 1 |
| D | . | . | . | . |

| PS | $X=0$ | $X=1$ | output Z |
|-------------------------------|-------|-------|----------|
| Q ₁ Q ₀ | 00 | 01 | 0 |
| 01 | 00 | 01 | 0 |
| 00 | 01 | 00 | 0 |
| 01 | 10 | 01 | 0 |
| 10 | 00 | 01 | 0 |
| 00 | 01 | 00 | 1 |

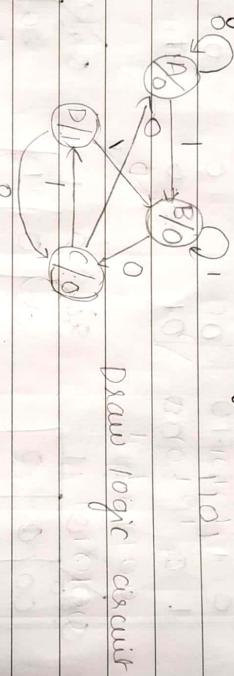
| Q ₁ Q ₀ | X | 0 | 1 | Q ₁ Q ₀ | X | 0 | 1 | Q ₁ Q ₀ | X | 0 | 1 |
|-------------------------------|---|----|----|-------------------------------|----|----|---|-------------------------------|---|---|---|
| 00 | 0 | 0 | 00 | 0 | 0 | 00 | 0 | 00 | 0 | 0 | 0 |
| 01 | 0 | 0 | 01 | 0 | 0 | 01 | 0 | 01 | 0 | 0 | 0 |
| 11 | - | - | 11 | - | - | 11 | - | 11 | - | - | - |
| 10 | 0 | 10 | 01 | 1 | 10 | 01 | 1 | 10 | 1 | 1 | 1 |

$$Q_1^+ = Q_0 \bar{X} \quad Q_0^+ = X \quad Z = Q_1 X$$

$$D_A = Q_0 \bar{X} \quad D_B = X$$



Design Mealy machine for sequence 101.



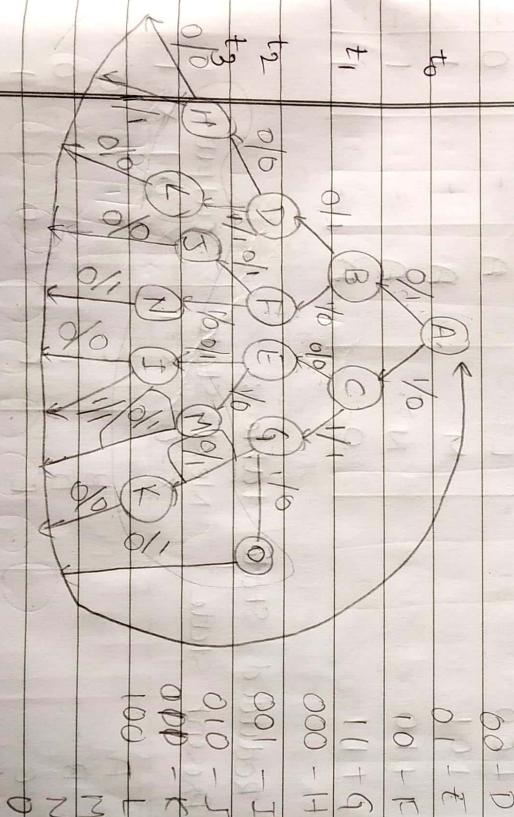
- Guidelines for state assignment.
- States which have in same next state for a given input should be given adjacent assignments.
 - States which are the next stage of the same state should be given adjacent assignments.
 - States which have the same output for a given input should be given adjacent assignment.

Assign a sequential circuit to convert BCD
to excess 3 code.

$B\bar{C}\bar{D}$

Excess - 3

| t_3 | t_2 | t_1 | t_0 | t_3 | t_2 | t_1 | t_0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| 0 | 0 | 0 | 1 | 0 | 1 | 0 | 0 |
| 0 | 0 | 1 | 0 | 0 | 1 | 0 | 1 |
| 0 | 0 | 1 | 1 | 0 | 1 | 1 | 0 |
| 0 | 1 | 0 | 0 | 0 | 1 | 1 | 1 |
| 0 | 1 | 1 | 0 | 1 | 0 | 0 | 1 |
| 0 | 1 | 1 | 1 | 1 | 0 | 1 | 0 |
| 0 | 0 | 0 | 0 | 1 | 0 | 1 | 0 |
| 0 | 0 | 0 | 1 | 1 | 0 | 0 | 1 |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |



$H \equiv I \equiv J \equiv K \equiv L$
 $E \equiv F \equiv G$
 $M \equiv N \equiv O$

State table :

| Time | ip sequence Received | Present State | Next State $X=0$ | Next State $X=1$ | Output $X=0$ | Output $X=1$ |
|-------|----------------------|---------------|---------------------|---------------------|-----------------|-----------------|
| t_0 | reset | A | B | C | 1 | 0 |
| t_1 | 0 | B | D | F | 1 | 0 |
| | 1 | C | E | G | 0 | 1 |
| t_2 | 00 | D | H | L | 0 | 1 |
| | 01 | E | I | M | - | 0 |
| | 10 | F | J | N | - | 0 |
| | 11 | G | K | O | - | 0 |
| t_3 | 000 | H | A | A | 0 | 1 |
| | 001 | I | A | A | 0 | 1 |
| | 010 | J | A | - | 0 | 1 |
| | 011 | K | A | - | 0 | 1 |
| | 100 | L | A | - | 0 | 0 |
| | 101 | M | A | - | 1 | 0 |
| | 110 | N | A | - | 1 | 1 |
| | 111 | O | A | - | 1 | 1 |

Reduced state table :

| Present state | Next state $X=0$ | Next state $X=1$ | output $X=0$ | output $X=1$ |
|---------------|---------------------|---------------------|-----------------|-----------------|
| A | B | C | 1 | 0 |
| B | D | E | 1 | 0 |
| C | E | F | 0 | 1 |
| D | H | H | 0 | 1 |
| E | H | M | 1 | 0 |
| H | A | A | 0 | 1 |
| M | A | - | 0 | 1 |

| $Q_1 Q_2 Q_3$ | 000 | 001 | 010 | 011 | 100 | 101 | 110 | 111 |
|---------------|-----|-----|-----|-----|-----|-----|-----|-----|
| 0 | A | B | C | D | E | F | G | H |
| 1 | M | N | O | P | Q | R | S | T |
| Q_1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 |
| Q_2 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 1 |
| Q_3 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 |

State table :
Present State Next State Output

| Q_1 | Q_2 | Q_3 | Q_1^+ | Q_2^+ | Q_3^+ | $X = 0$ | $X = 1$ |
|-------|-------|-------|---------|---------|---------|---------|---------|
| 0 | 0 | 0 | 1 | 0 | 0 | 101 | 0 |
| 0 | 0 | 1 | 1 | 1 | 1 | 110 | 0 |
| 0 | 1 | 0 | 1 | 0 | 1 | 110 | 1 |
| 1 | 0 | 0 | 1 | 1 | 0 | 011 | 0 |
| 1 | 0 | 1 | 0 | 1 | 1 | 010 | 1 |
| 1 | 1 | 0 | 0 | 1 | 1 | 010 | 0 |
| 1 | 1 | 1 | 1 | 0 | 0 | 111 | 0 |
| 0 | 1 | 0 | 0 | 0 | 0 | 000 | 1 |
| 0 | 1 | 0 | 0 | 0 | 0 | 000 | 0 |

| Q_3^X | Q_2^X | Q_1^X | 00 | 01 | 11 | 10 | Q_3^X | Q_2^X | Q_1^X | 00 | 01 | 11 | 10 |
|---------|---------|---------|----|----|----|----|---------|---------|---------|----|----|----|----|
| 00 | 1 | X | X | X | X | X | 00 | 0 | 0 | X | X | X | X |
| 01 | 0 | X | 0 | 0 | 0 | 0 | 01 | 0 | 0 | X | 0 | 0 | 0 |
| 11 | 0 | 0 | 0 | 0 | 0 | 0 | 11 | 1 | 1 | 1 | 1 | 1 | 1 |
| 10 | 1 | 1 | 1 | 1 | 1 | 1 | 10 | 1 | 1 | 1 | 1 | 1 | 1 |

$$Q_2^+ = \overline{Q}_2$$

$$Q_3^X = \overline{Q}_3$$

$$Q_2^X = \overline{Q}_2$$

| Q_3^X | Q_2^X | Q_1^X | 00 | 01 | 11 | 10 | 00 | 01 | 11 | 10 |
|---------|---------|---------|----|----|----|----|-----|-----|-----|-----|
| 00 | 0 | 1 | X | X | X | X | 101 | 100 | 010 | 001 |
| 01 | 0 | X | 0 | 0 | 0 | 0 | 101 | 100 | 010 | 001 |
| 11 | 1 | 0 | 1 | 1 | 1 | 1 | 101 | 100 | 010 | 001 |
| 10 | 0 | 0 | 0 | 0 | 0 | 0 | 000 | 000 | 010 | 001 |

Output : 0101001001001010

Output : 0010010100100101

Output : 0100100101001001

Output : 0010010100100101

Design sequential circuit to convert BCD
to Excess-3 using ROM.

Truth table

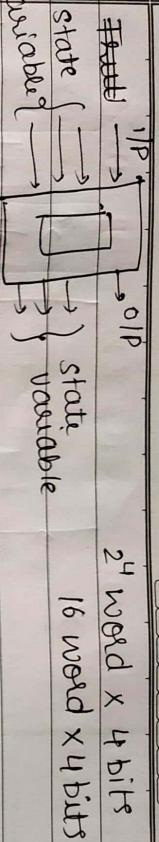
state diagram

state table

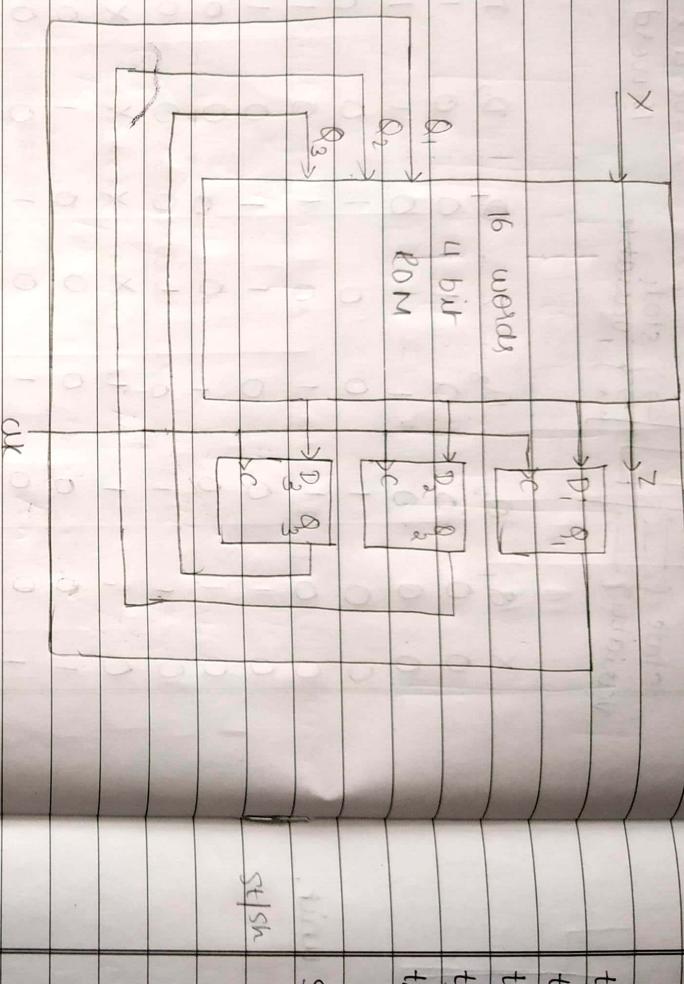
Reduced state table

Transition table :

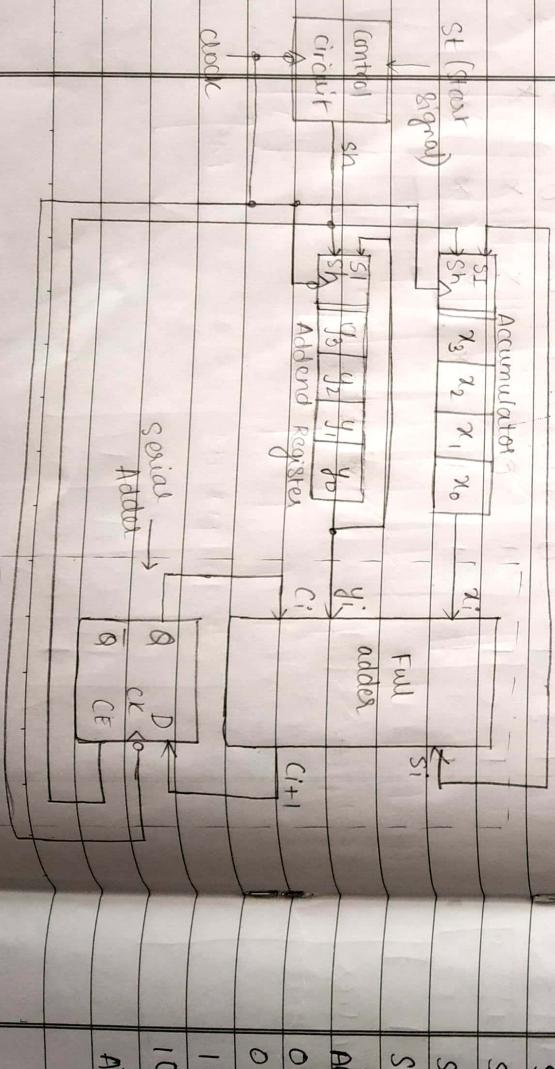
| Present | Next State | X = 0 | X = 1 |
|---------|------------|-------|-------|
| A → 000 | 001 | 010 | 1 |
| B → 001 | 011 | 100 | 1 |
| C → 010 | 100 | 100 | 0 |
| D → 011 | 101 | 101 | 0 |
| E → 100 | 101 | 110 | 1 |
| F → 101 | 000 | 100 | 0 |
| M → 110 | 000 | 0 | 1 |



| X | Q ₁ | Q ₂ | Q ₃ | Z | D ₁ | D ₂ | D ₃ |
|----|----------------|----------------|----------------|----|----------------|----------------|----------------|
| 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | 0 | 0 | 1 | -1 | 0 | -1 |
| 0 | 0 | 1 | 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | 1 | -1 | 0 | -1 | 0 | 1 |
| 0 | 0 | -1 | 0 | 0 | 1 | 0 | -1 |
| 0 | 0 | -1 | -1 | 0 | -1 | 0 | 1 |
| 0 | 0 | -1 | 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | -1 | 0 | 1 | 0 | 0 | 0 |
| 0 | 0 | -1 | -1 | X | X | X | X |
| -1 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| -1 | 0 | 0 | 1 | 0 | 1 | 0 | 0 |
| -1 | 0 | -1 | 0 | -1 | 1 | 0 | 0 |
| -1 | 0 | -1 | -1 | -1 | 1 | 0 | 1 |
| -1 | -1 | 0 | 0 | 0 | 1 | 1 | 0 |
| 1 | -1 | 0 | 1 | -1 | 0 | 0 | 0 |
| 1 | 1 | -1 | 0 | X | X | X | X |
| 1 | 1 | -1 | X | X | X | X | X |



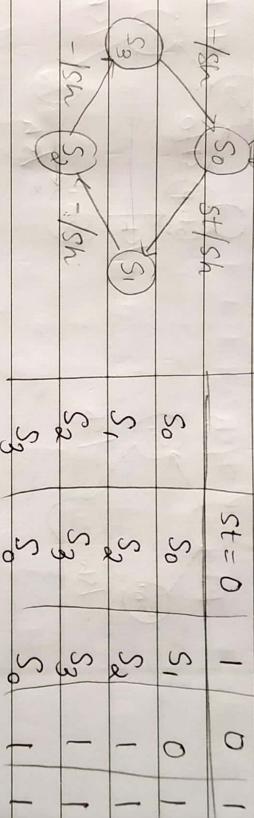
Block Diagram for serial Adder with Accumulator :



operation of serial Adder :

| | X | Y | C _i | S _i | C _{i+1} |
|----------------|------|------|----------------|----------------|------------------|
| t ₀ | 0101 | 0111 | 0 | 0 | 1 |
| t ₁ | 0010 | 1011 | 1 | 0 | 1 |
| t ₂ | 0001 | 1101 | 1 | - | 1 |
| t ₃ | 1000 | 1110 | 1 | 1 | 0 |
| t ₄ | 1100 | 0111 | 0 | (1) | (0) |

state graph for serial Adder control :



Derivations of control circuit Equations

| | AB | A ^t | B ^t | st | sh |
|----------------|----|----------------|----------------|----|----|
| S ₀ | 00 | 00 | 01 | 0 | 1 |
| S ₁ | 01 | 10 | 10 | 1 | 1 |
| S ₂ | 10 | 11 | 11 | 1 | 1 |
| S ₃ | 11 | 00 | 00 | 1 | 1 |

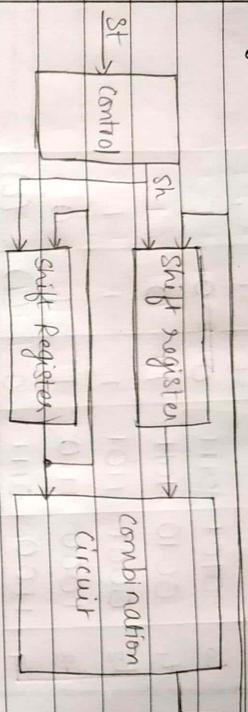
AB_{st} 0 1

AB_{sh} 0 1

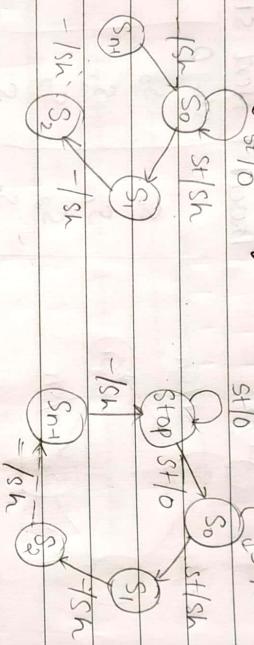
| | AB | 00 | 01 | 11 | 00 | 01 | 11 |
|----|----|----|----|----|----|----|----|
| 01 | 11 | 11 | 01 | 01 | 01 | 11 | 11 |
| 11 | 00 | 11 | 00 | 00 | 11 | 11 | 11 |
| 10 | 11 | 10 | 11 | 10 | 10 | 11 | 11 |

$$A^t = \bar{A}B + A\bar{B} \quad B^t = A\bar{B} + \bar{B}st \quad sh = st + B + A$$

Typical serial processing unit :



state graphs for serial processing unit.



Design of parallel multiplier

Block diagram for parallel binary multiplier



Eg :

Eg :

1101 → Multiplier

1011 → multiplicand

1101

1101

100111 → Partial Product

0000

100111

1101

010001111 → Product

State graph for multiplier control.

Initial state S_0 - /done

transitions:

$S_0 \rightarrow S_1$ st | load

$S_1 \rightarrow S_2$ M | Ad

M

$S_2 \rightarrow S_3$ M | Sh

M

$S_3 \rightarrow S_4$ M | Ad

M

$S_4 \rightarrow S_5$ M | Sh

M

$S_5 \rightarrow S_6$ M | Ad

M

$S_6 \rightarrow S_7$ M | Sh

M

$S_7 \rightarrow S_8$ M | Ad

M

$S_8 \rightarrow S_9$ M | Sh

M

$S_9 \rightarrow S_0$ M | Ad

M

plus

minus

Acc \rightarrow 000001011 \rightarrow M=1

Multiplicand 1101

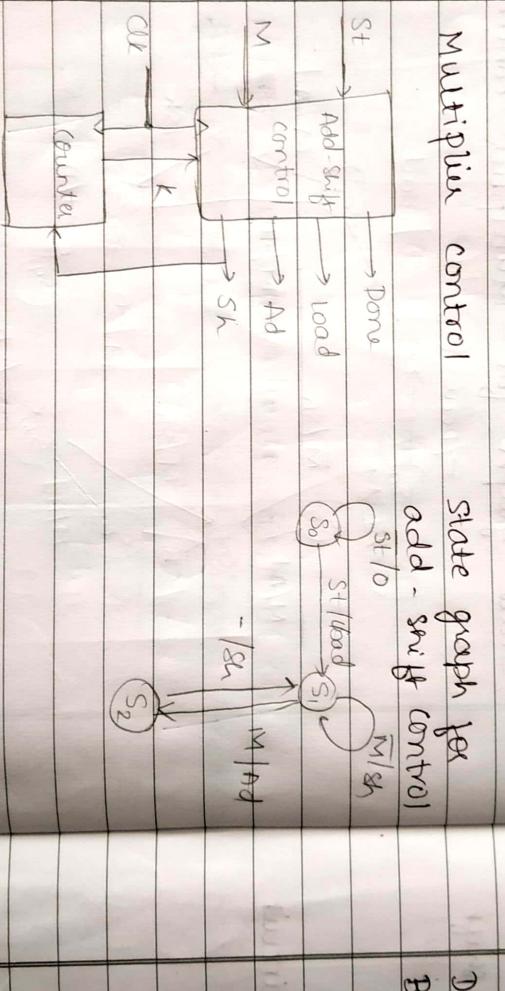
01101 \rightarrow Add

011011011 shift
001101101 \rightarrow M=1

1101

10011101 shift

| Acc | 00000 1011 → M=1 | time | stat |
|--------------|-------------------|-------|-------|
| Multiplicand | 1101 | t_0 | s_0 |
| | 0110 1011 → shift | t_1 | s_0 |
| | 0011 0110 → M=1 | t_2 | s_1 |
| | 1101 | t_3 | s_2 |
| | 1001 1101 → shift | t_4 | s_1 |
| | 0100 1110 → M=0 | t_5 | s_2 |
| | 0010 0111 → M=1 | t_6 | s_1 |
| | 1101 | t_7 | s_1 |
| Product | 0100 1111 | t_8 | s_2 |
| | 1000 1111 → shift | t_9 | s_2 |



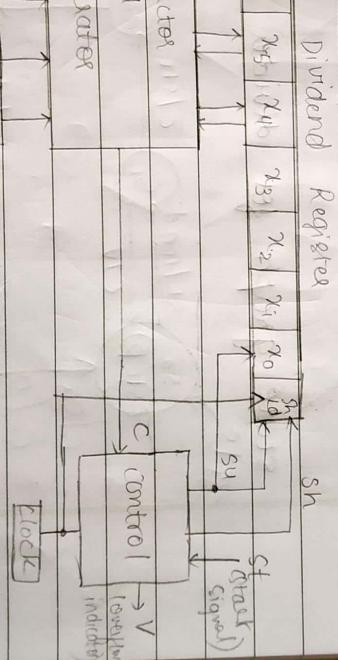
operation of Multiplier using a counter.

Diagram

00000 10111 10100

| Time | state | counter | product Register | st | M | K | load | Ad | sh | Dm |
|-------|-------|---------|---------------------|----|---|---|------|----|----|----|
| t_0 | s_0 | 00 | 000000000 | 6 | 0 | 0 | 0 | 0 | 0 | 0 |
| t_1 | s_0 | 00 | 000000000 | 1 | 0 | 0 | 1 | 0 | 0 | 0 |
| t_2 | s_1 | 00 | 000001011 | 0 | 1 | 0 | 0 | 1 | 0 | 0 |
| t_3 | s_2 | 00 | 011011011 | 0 | 1 | 0 | 0 | 0 | 1 | 0 |
| t_4 | s_1 | 01 | 001101101 | 0 | 1 | 0 | 0 | 1 | 0 | 0 |
| t_5 | s_2 | 01 | 10011101 | 0 | 1 | 0 | 0 | 0 | 1 | 0 |
| t_6 | s_1 | 10 | 010011110 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| t_7 | g_1 | 11 | 001001111 | 0 | 1 | 1 | 0 | 1 | 0 | 0 |
| t_8 | S_2 | 11 | 100111111 | 0 | 1 | 1 | 0 | 0 | 1 | 0 |
| t_9 | S_2 | 00 | 010001111 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |

Design of a Binary divider :
 Block diagram for parallel binary divider



$1010 \rightarrow$ quotient

~~divisor~~
~~1101~~
~~1101~~
~~001111~~
~~1101~~

10000111
 $\underline{+ 1101}$
 00101
 $\underline{+ 00101}$
 00000
 $\underline{+ 00101} \rightarrow$ Remainder

$x_8 \ x_7 \ x_6 \ x_5 \ x_4 \ x_3 \ x_2 \ x_1$

0 1 0 0 0 0 0 1 1 1 00

c = 0

0 1 1 0 1 0 0 0 0 1 1 1 0 shift sh=1

0 1 1 0 1 0 1 0 1 1 1 1 c = 1

0 0 0 1 1 1 1 1 1 1 1 1 1 shift sh=1

0 1 1 0 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

0 1 1 1 1 1 1 1 1 1 1 1 1 0 c = 0 shift

state graph for divider control circuit

m

$S_0 \xrightarrow{st/lload} S_1$

$S_1 \xrightarrow{\bar{c}/su} S_2$

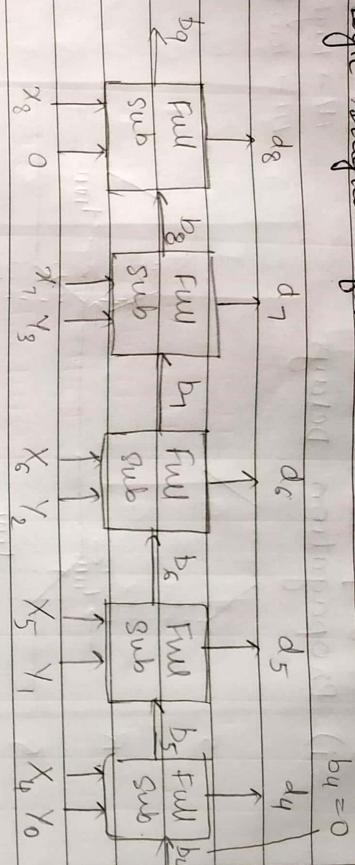
$S_2 \xrightarrow{c/su} S_3$

$S_3 \xrightarrow{\bar{c}/su} S_4$

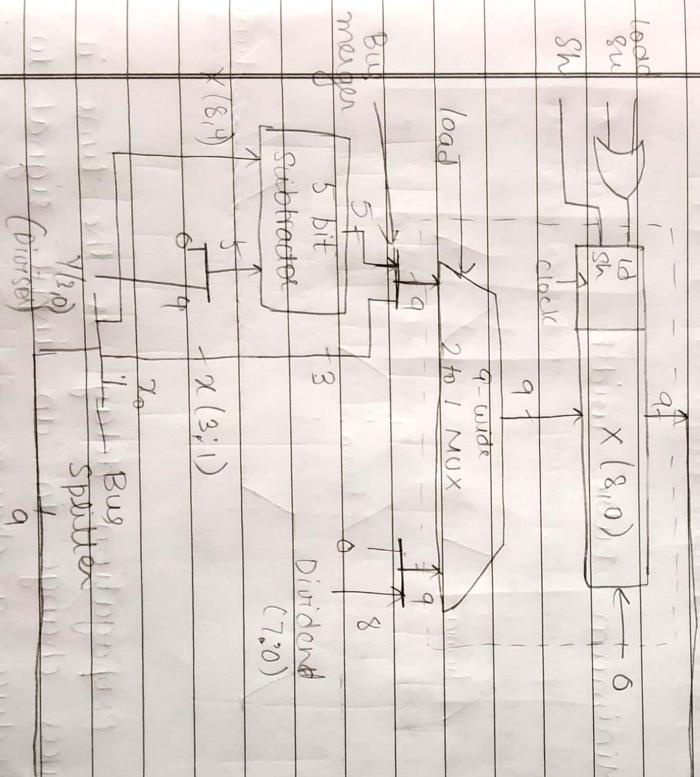
$S_4 \xrightarrow{c/su} S_0$

Remainder questions

Logic Diagram for 5-Bit Subtractor



Block diagram for divider using Bus Notation

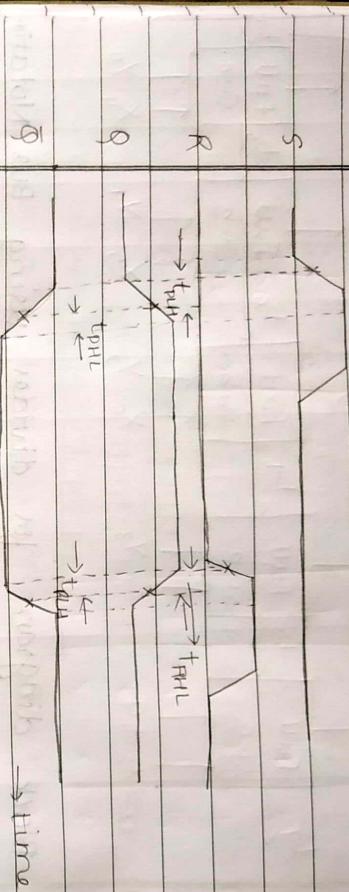


Timing considerations

i) Propagation Delays

$H_L \rightarrow H_L$: High to low
 $L_H \rightarrow L_H$: Low to high

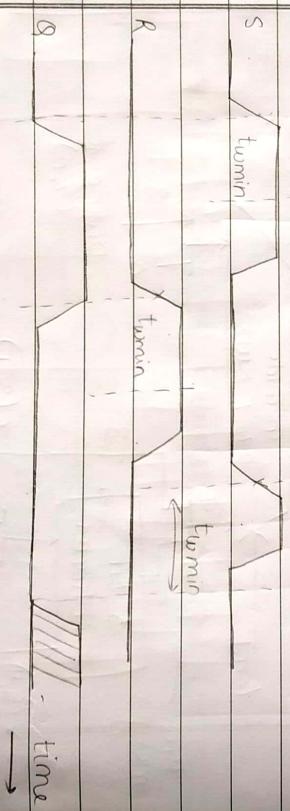
C



D

ii) Minimum pulse width

iii)

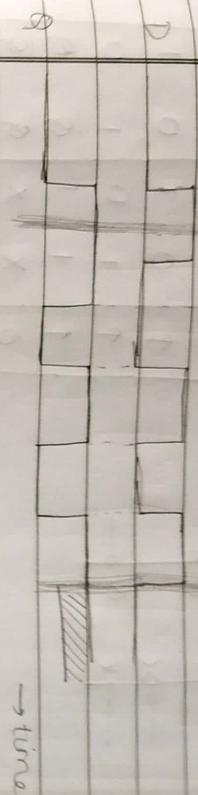


R

- i)
 Propagation delay is the time it takes change in an input signal to produce a change in an output signal

to low
high

D
C



i) It is a minimum amount of time a signal must be applied in order to produce desired result.

iii) The minimum time of input signal must be held fixed before the latching action the ~~tsu~~ is called the setup time.

The minimum time the input signal must be held fixed after the latching action t_h is called Hold time.

me

Edge triggered flip flop.

i) Positive Edge - triggered D - FF

signal

| | D | Q | C | D | Q | Q̄ |
|----|---|---|---|----|---|----|
| CK | ↑ | 0 | ↑ | 0 | 1 | |
| | 0 | X | ↑ | 1 | 0 | |
| | 1 | X | Q | Q̄ | | |

i) Positive Edge triggered JK FF

| C | J | K | Q | \bar{Q} |
|---|---|---|---|-----------|
| 1 | 0 | 0 | 0 | 1 |
| | 1 | 0 | 1 | 0 |
| | | 1 | 0 | 1 |
| | | | 1 | 0 |

ii) Negative Edge triggered T FF

| C | T | Q | \bar{Q} |
|---|---|---|-----------|
| 1 | 0 | 0 | 1 |
| | 1 | 0 | 1 |
| | | X | X |
| | | 0 | 1 |

iii) Negative Edge triggered T FF

| C | T | Q | \bar{Q} |
|---|---|---|-----------|
| 1 | 0 | 0 | 1 |
| | 1 | 0 | 1 |
| | | X | X |
| | | 0 | 1 |